

Notes of Basic Topolgy

Taper

November 17, 2016

Abstract

A note of Basic Topology, based on *Basic Topology* by M.A. Armstrong.

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There are several parts that I will skipped for convenience. Those include chapter 1 - Introduction, chapter 2 - Continuity, chapter 3 - Compactness and Connectedness, and chapter 4 - Identification Spaces. Below is some especially confusing part that I would like to note:

1 Special Notes

sec:Special-Notes

About map In book [1], a map is defined as a continuous function (page 32), which is confusing. In this note, I will not use this convention and will always states continuity clearly.

Basic facts about maps Assuming domain $f = X$, codomain $f = Y$.

$$f(U \cup V) = f(U) \cup f(V) \quad (1.0.1)$$

$$f(U \cap V) \subseteq f(U) \cap f(V) \quad (1.0.2)$$

$$f(U^c) \supseteq f(U)^c, \text{ i.e. } f(U)^c \subseteq f(U^c) \quad (1.0.3)$$

$$f^{-1}(U \cup V) = f^{-1}(U) \cup f^{-1}(V) \quad (1.0.4)$$

$$f^{-1}(U \cap V) = f^{-1}(U) \cap f^{-1}(V) \quad (1.0.5)$$

$$f^{-1}(U^c) = [f^{-1}(U)]^c \quad (1.0.6)$$

Smallest the Largest Topolgy The set of all possible topolgies on X is partially ordered by inclusion. For a certain characteristics \mathcal{C} , it is possible to have the smallest or the largest one.

The **smallest topolgy** \mathcal{T}_{\min} is the one such that, for any \mathcal{T}' satisfying \mathcal{C} , $\mathcal{T}_{\min} \subseteq \mathcal{T}'$. The **largest topolgy** \mathcal{T}_{\max} is the one such that, for any \mathcal{T}' satisfying \mathcal{C} , $\mathcal{T}' \subseteq \mathcal{T}_{\max}$. Synonyms of these two words are:

- Larger: stronger, finer.
- Smaller: weaker, coarser.

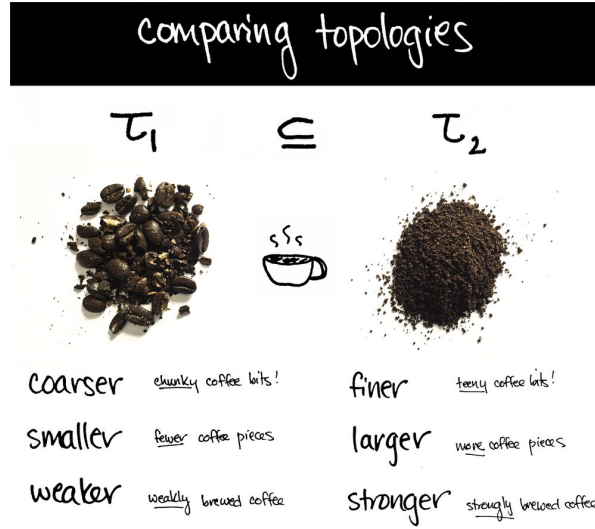


Figure 1: Comparing topologies and coffee (Credit: math3ma)

For example, assuming we have

$$f : X \rightarrow Y \quad (1.0.7)$$

where f is any function.

If X has topolgy \mathcal{T}_X , we ask then what kind of topolgy on Y will make f a continuous function. First, all $f^{-1}(V)$, with $V \in \mathcal{T}_Y$ should be open in X . So, the easiest choice is to make $\mathcal{T}_{Y,\min} = \{\emptyset, Y\}$, this is the smallest topolgy. Also, any set $V \in Y$ such that $f^{-1}(V) \notin \mathcal{T}_X$ should not be in \mathcal{T}_Y . Then the largest topolgy is $\mathcal{T}_{Y,\max} = \{V \subset Y | f^{-1}(V) \in \mathcal{T}_X\}$.

If Y has topolgy \mathcal{T}_Y , we also ask what kind of topolgy on X will make f a continuous function. First, all $V \in \mathcal{T}_Y$, their preimage $f^{-1}(V)$ must be in \mathcal{T}_X . So the smallest topolgy is $\mathcal{T}_{X,\min} = \{f^{-1}(V) | V \in \mathcal{T}_Y\}$. Than what about the largest topolgy? We consider, what kind of sets cannot be inside \mathcal{T}_X . First, can $(f^{-1}(V))^c = f^{-1}(V^c)$ be in \mathcal{T}_X ? Yes. Since unless the space is connected, there can be sets being both open and closed (other than X and \emptyset). Any other restrictions? No that I can think of. So, the

largest topolgy $\mathcal{T}_{X,\max} = 2^X$, the set of all subsets of X . (The notation 2^X is taken from the page 4 of book [2].

A summary:

Table 1: Largest and Smallest Topolgies

$X \xrightarrow{f} Y$	Smallest	Largest
Given \mathcal{T}_X	$\mathcal{T}_{Y,\min} = \{\emptyset, Y\}$	$\mathcal{T}_{Y,\max} = \{V \subset Y \mid f^{-1}(V) \in \mathcal{T}_X\}$
Given \mathcal{T}_Y	$\mathcal{T}_{X,\min} = \{f^{-1}(V) \mid V \in \mathcal{T}_Y\}$	$\mathcal{T}_{X,\max} = 2^X$
No constraint	$\{\emptyset, X\}$	2^X

Facts about subspace/induced topolgy Let Y be a subspace of a topological space X wit induced topolgy.

Fact 1.1. A set $H \subseteq Y$ is open in Y if and only if $H = F \cap Y$ for some open set F in X .

Fact 1.2. A set $H \subseteq Y$ is closed in Y if and only if $H = F \cap Y$ for some closed set F in X .

Fact 1.3. A set H is open/closed in $X \Rightarrow H$ is open/closed in Y . But the converse may not be true. The converse statement depends on whether Y is open or closed in X .

2 Collection of Theorems in Chapter 4

a-of-Theorems-in-Chapter-4

Definition 2.1 (Identification Topology). Let X be a topological space and let \mathcal{P} be a family of disjoint nonempty subsets of X such that $\cup \mathcal{P} = X$. Such a family is usually called a partition of X . Let Y be a new space whose points are the members of \mathcal{P} . Let $\pi : X \rightarrow Y$ sends each point of X to the subset of \mathcal{P} . Define a topolgy \mathcal{T}_Y on Y to be the largest topolgy such that the π is continuous. This \mathcal{T}_Y is called the idetification topolgy. And Y is called the **identification space**.

$$\begin{array}{ccc} X & \longrightarrow & Y \\ & \searrow & \parallel \\ & & \mathcal{P} \end{array}$$

Theorem 2.1. Let Y be an idetification space defined as above and let Z be an arbitrary topological space. A function $f : Y \rightarrow Z$ is continuous if and only if the composition $f \circ \pi : X \rightarrow Z$ is continuous.

$$\begin{array}{ccccc} & & f \circ \pi & & \\ & \nearrow & & \searrow & \\ X & \xrightarrow{\pi} & Y & \xrightarrow{f} & Z \\ & \searrow & \parallel & & \\ & & \mathcal{P} & & \end{array}$$

Definition 2.2 (Identification Map). Let $f : X \rightarrow Y$ be an onto continous map and suppose that the topolgy on Y is the largest for which f is continuous. Then we call f an identification map.

The naming "identification map" is because:

Theorem 2.2. Any function $f : X \rightarrow Y$ gives rise to a partition of X whose members are the subsets $\{f^{-1}(y)\}$, where $y \in Y$. Let Y_* denote the identification space associated with this partition, and $\pi : X \rightarrow Y_*$ the usual continuous map.

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \downarrow \pi & & \\ \{f^{-1}(y)\} & \xlongequal{\quad} & Y_* \end{array}$$

If f is an identification map, then:

1. the spaces Y and Y_* are homeomorphic;
2. a function $g : Y \rightarrow Z$ is continuous if and only if the composition $g \circ f : X \rightarrow Z$ is continuous.

$$\begin{array}{ccccc} & & g \circ f & & \\ & \curvearrowright & & \curvearrowleft & \\ X & \xrightarrow{f} & Y & \xrightarrow{g} & Z \\ \downarrow \pi & & \parallel & & \\ \{f^{-1}(y)\} & \xlongequal{\quad} & Y_* & & \end{array}$$

Theorem 2.3. Let $f : X \rightarrow Y$ be an onto continuous map. If f maps open sets of X to open sets of Y , or closed sets to closed sets, then f is an identification map, i.e. \mathcal{T}_y is the largest topology such that f is continuous.

coro:idmap-coro

Corollary 2.1. Let $f : X \rightarrow Y$ be an onto continuous map. If X is compact and Y is Hausdorff, then f is an identification map.

Definition 2.3 (Torus). Torus is the uTorusquare $[0, 1] \times [0, 1]$, with 1. opposite edge identified, 2. four edge points identified.

Remark 2.1. The identification map and corollary 2.1 can be used to show that torus is homeomorphic to two copies of circles: $S^1 \times S^1$. This is mentioned in page 68 of [1].

Definition 2.4 (Cone CX). The cone of any space CX is formed from $X \times I$, where I is the unit interval $[0, 1]$, with certain identification. The identification shrinks all points in one surface into one point. This is discussed in page 68 of [1].

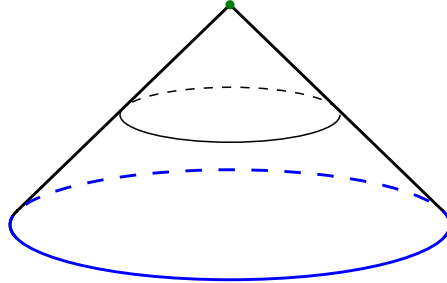


Figure 2: Cone of a Circle (Wikipedia)

Remark 2.2. There is another definition of cone CX when X is imbedded into \mathbb{E}^n , may be found on page 68 of [1]. Cone constructed in this way is called a geometric cone. It is made up of all straight line segments that join $v = (0, 0, \dots, 1) \in \mathbb{E}^{n+1}$ to some point of X .

Lemma 2.1. *The geometric cone on X is homeomorphic to CX .*

Definition 2.5 (Quotient Space). Let X be a topological space, A be its subspace. Then X/A means the X with subspace A identified to a point.

1. the set A .
2. the individual points of $X \setminus A$.

Remark 2.3. In this notation, CX becomes $(X \times I)/(X \times \{1\})$.

Fact 2.1.

$$B^n/S^{n-1} \cong S^n \quad (2.0.8)$$

where \cong means homeomorphic. This is proved on page 69. Intuitively, this is like wrap a lower dimension ball surround the higher dimension ball.

Definition 2.6 ($f \cup g$). Let X, Y be subsets of a topological space and give each of X, Y , and $X \cup Y$ the induced topology. If $f : X \rightarrow Z$ and $g : Y \rightarrow Z$ are functions which agree on the intersection of X and Y , we can define

$$\begin{aligned} f \cup g : X \cup Y &\rightarrow Z \\ (f \cup g)(x) &= f(x), x \in X \\ (f \cup g)(x) &= g(x), x \in Y \end{aligned} \quad (2.0.9)$$

We say that $f \cup g$ are formed by 'glueing together' the functions f and g .

Lemma 2.2 (Glueing lemma (closed)). *If X and Y are closed in $X \cup Y$, and if both f and g are continuous, then $f \cup g$ are continuous.*

Similarly,

Lemma 2.3 (Glueing lemma (open)). *If X and Y are open in $X \cup Y$, and if both f and g are continuous, then $f \cup g$ are continuous.*

These two lemmas are seen as a special case of the following theorem, explained in page 70.

Define $X + Y$ to be the disjoint union of spaces X, Y . Define $j : X + Y \rightarrow X \cup Y$ which restrict to either X or Y is just the inclusion in $X \cup Y$.

Theorem 2.4. *If j is an identification map, and if both $f : X \rightarrow Z$ and $g : Y \rightarrow Z$ are continuous, then $f \cup g : X \cup Y \rightarrow Z$ is continuous.*

$$\begin{array}{ccccc} X + Y & \xrightarrow{j} & X \cup Y & \xrightarrow{f \cup g} & Z \\ & & \swarrow f & \nearrow g & \\ & X & & Y & \end{array}$$

This can be generalized as follows. Let $X_\alpha, \alpha \in A$ be a family of subsets of a topological space and give each X_α and the union $\cup X_\alpha$, the induced

topology. Let Z be a space and suppose we are given maps $f_\alpha : X_\alpha \rightarrow Z$, one for each α in A , such that if $\alpha, \beta \in A$,

$$f_\alpha \Big|_{X_\alpha \cap X_\beta} = f_\beta \Big|_{X_\alpha \cap X_\beta}$$

Define function $F : \cup X_\alpha \rightarrow Z$ by glueing together f_α . Let $\oplus X_\alpha$ be the disjoint union of spaces X_α . Let $j : \oplus X_\alpha \rightarrow \cup X_\alpha$ be similarly defined.

Theorem 2.5. *If j is an identification map, and if each f_α is continuous, then F is continuous.*

Note: When j is the identification map, then $\cup X_\alpha$ has the identification topology instead of the subspace topology. The two will be quite different, as discussed on page 70 to 71 of [1].

Definition 2.7 (Projective space P^n). A discussion of real P^n may be found on page 71.

Attaching maps and $X \cup_f Y$ Let:

$$Y \supseteq A \xrightarrow{f} X \quad (2.0.10)$$

where X, Y are topological spaces, f is continuous. We identify the disjoint union $X + Y$ using f , partitioning them into:

1. pairs of points $\{a, f(a)\}$ where $a \in A$;
2. individual points of $Y \setminus A$;
3. individual points of $X \setminus \text{Im}(f)$.

The result identification space is denoted $X \cup_f Y$, and f is called the attaching map. This process can also be viewed as:

$$X \cup_f Y = (X \amalg Y) / \{f(A) \sim A\} \quad (2.0.11)$$

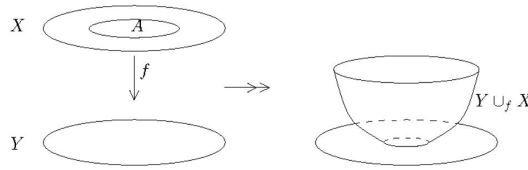


Figure 3: Attaching Space (credit: nLab)

Example 2.1. P^2 can be seen as attaching a closed disc D to the boundary of M , a Mobius strip, as discussed in page 72 of [1]. Geometrically, this simply shrinks the boundary of M into a point. And an ant travelling around this point can point out the direction just as in P^2 .

Remark 2.4. It is remarked that properties such as compactness, connectedness, and path-connectedness is inherited in identification. However, Hausdorff-ness is not. A counter example can be found in page 72 of [1].

sec:Anchor

3 Anchor

References

book

Singer.Thorpe

- [1] M.A. Armstrong. Basic Topology. 2ed.
- [2] I.M. Singer, J.A. Thorpe. Lecture Notes on Elementary Topology and Geometry. UTM.

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