5/3/2016 ELE 730 QIC890-T33 Lecture 1 0 Tue learn. uwaterloo. ca Fectures: EIT 3141, Tuesdays 8:30-11:20 am Patt 1: 8:30-9:45 am Part 2: 10:00-11:20 am Office Hours: Th 3-4 pm, QNC 4104. Problem Sets 4-5, 50% . S(t)=S(0) × (10-t) × 0. (if t < ts, 0 if t > ts Final Exam. 50% key words syllabus.

Tue.

1/3/2016

· Noise?

What is Noise?

Is Noise Bad or Good?

What are the synonyms of "Notse"?

- randomness deviations
- error fluctuations

Noise = Spontaneous fluctuations in currents, voltages and other physical quantities of a system under test. -> " limits" an ultimate sensitivity in any measurement

In 1998, R. Landauer "The noise is the signal." Nature 392,658 (1998)

* Why do we have "noise" in a system data?

· Noise: "statistical" quantity

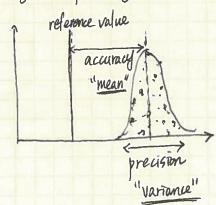
-> does not make sense to argue a single event at a certain time

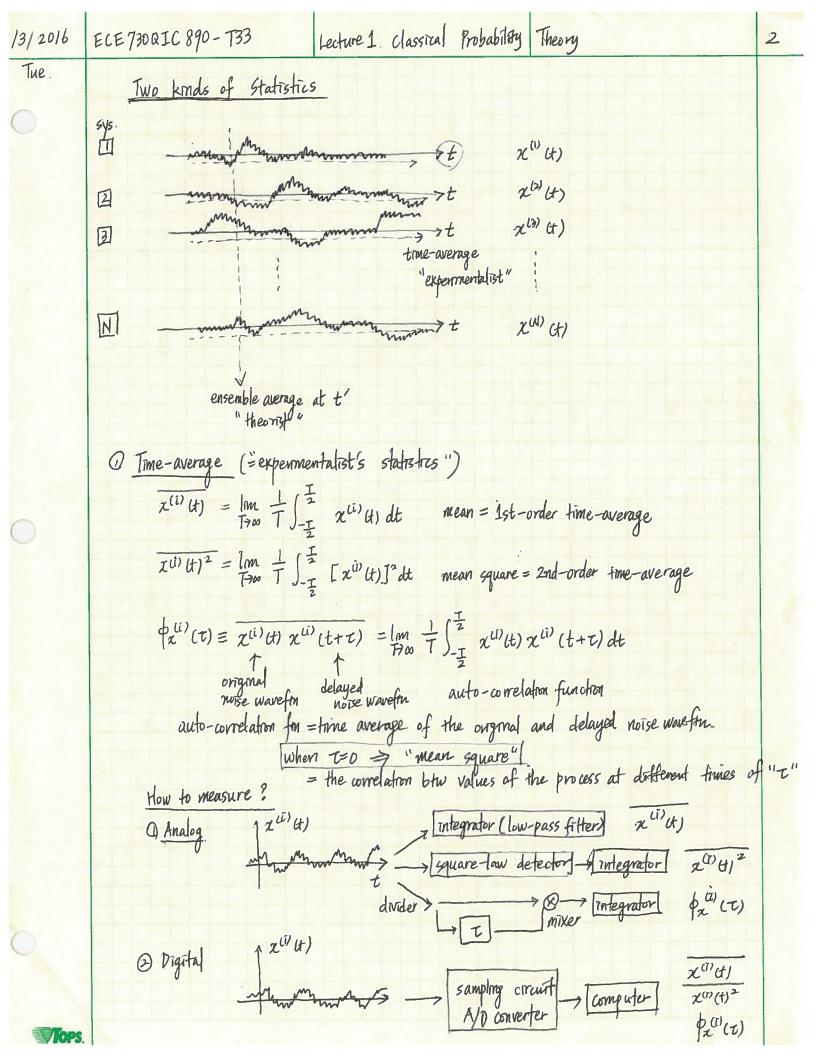
& Precision 15 Accuracy

precision = a description of "random errors" a measure of statistical variability the degree to which repeated measurements under uncharged condition to show the same results " reproducibility", " repeatability"

accuracy = a description of "systematic errors"

a measure of statistical bias the degree of closeness of measurements of a quantity





Tue.

5/3/2016

@ Ensemble-average (="theorist's statistics) "given t"

 $\langle \chi(t_1) \rangle = \lim_{N \to \infty} \frac{1}{N} \frac{1}{i=1} \chi^{(i)}(t_1) = \int_{-i\infty}^{\infty} \chi_1 p_1(\chi_1, t_1) d\chi_1$ mean = 1st-order ensemble average probability density fin.

 $\langle x(t_1)^2 \rangle = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N} \left[x^{(i)}(t) \right]^2 = \int_{-\infty}^{\infty} x_1^2 p_i(x_1, t_1) dx_1$ mean square = 2nd-order ensemble at each square = 2nd-order ensemble ensemble at each square = 2nd-order ensemble ensembl

 $\langle 2 | t_1 \rangle x(t_2) \rangle = \lim_{N \to \infty} \frac{1}{N} \frac{X}{i=1} x^{(i)} (t_1) x^{(i)} (t_2) = \int_{-\infty}^{\infty} x_1 x_2 p_2(x_1, x_2; t_1, t_2) dx_1 dx_2$

Covariance = a measure of how much
2 random variables change
together

- * P1 (21, t1) = first-order probability density function of correlation coeff. = normalized version of the condition Pi(xi,ti)dxi: probability that x is found in the range between xi and xitdxi at ti
- · P2 (x1, t2, t4, t2) = second-order joint probability density function P2(x1, x2; t1, t2) dx1dx2: probability that x is found in the range both x1 and x1-dx, at and of is found in the range blu 1/2 and 1/2 tot2 at t2

(Theory) Fokker-Planck equation : calculation of Probability distributions ⇒ obtain the probability density functions P1 and P2.

Q: How can we close the gap between "Time-Average" and "Ensemble-Average"?

When is "theoretical predictions from ensemble averaging" equivalent to "experimental results" from time averaging?

[Need (Introduce)" Ergodicity" & "Statistical stationarity"

ensemble averaging and time averaging are identical for a statistically-stationary system different for a statistically-onstationary system

Introduce "Ergodicity" & " statistical stationary"

Tue

5/3/2016

Ergodiuty

in mothematics, a dynamical system has the same behavior averaged over time
as averaged over the space of all system's state (phase) in statisties, a random process for which the time average of one sequence of events

To the same as the ensemble average.

) When do we need "ergodicity"?

we have only I sample for af a stochastiz process instead of the entire ensemble if the process is ergodic, even w/ 1 sample ftn, all statistical information can be derived from time averaging

(1) Ergodic in the mean

$$\overline{\chi(t)} = \lim_{t \to \infty} \int_{-\frac{T}{2}}^{\frac{T}{2}} \chi(t) dt = \langle \chi(t) \rangle \text{ ensemble-average.}$$

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tome-independent.

: productly of mean ruplies the statementy of the mean (vice versa doesn't hold the truth.)

@ Ergodic in the autocorrelation

$$\varphi_{x}(\tau) = \frac{1}{2(t)}\frac{1}{2(t+c)} = \frac{1}{1}\frac{1}{2(t+c)}\frac{1}{2(t+c)}\frac{1}{2(t+c)}\frac{1}{2(t+c)}$$

Calculation of 2(t)

(a) $\frac{1}{2(t+c)}\frac{1$

Consider the example of the processes which are ergodic in the mean, the auto correlation or/and both.

3 Wiener-Khmtchme Theorem

Tue

3. Wiener-Khintchine theorem

Consider the ensemble-averaged autocorrelation fin.

(1) statistically-stationary process

$$\lim_{T \to \infty} \frac{1}{T} \int_{\infty}^{\infty} \left\langle 2_{T}(t+\tau) \times_{T}(t) \right\rangle dt = \lim_{T \to \infty} \frac{1}{2\pi} \int_{0}^{\infty} \frac{2(|X_{T}(\bar{\imath}\omega)|^{2})}{T} \cos(\omega \tau) d\omega$$

: Statis

@ statistically-nonstationary process

$$\frac{1}{T}\int_{-\infty}^{\infty}\langle x_{T}(t+z)|X_{T}(t)\rangle dt = \frac{1}{2\pi}\int_{0}^{\infty}\frac{2\langle |X_{T}(i\omega)|^{2}\rangle}{T}\cos(\omega c)d\omega$$

Wiener-Klimtchme theorem: the autocorrelation function of a wide-sense stationary random stationary: process has a specifical decomposition given by the power spectrum of that process.

 $\langle \phi_{\chi}(\tau) \rangle = \frac{1}{2\pi} \int_{0}^{\infty} S_{\chi}(\omega) \cos(\omega \tau) d\omega$

$$\langle \varphi_{z}(\tau, T) \rangle = \frac{1}{2\pi} \int_{0}^{\infty} S_{x}(\omega, T) \cos(\omega \tau) d\omega$$

5x(w) = 4 50 (px(t))xos(wg)dt.

$$S_{x}(\omega, T) = 4 \int_{0}^{T} \phi_{x}(\tau, T) \omega s(\omega \tau) d\tau$$

$$\frac{HW}{proof} S_{X}(\omega) = \lim_{T \to \infty} \frac{2\langle |X_{T}(\overline{\imath}\omega)|^{2} \rangle}{T}$$

Fourter Transform pairs stationary (2 0x(T) > (Sx(W)

non-stationary

(2 Px (T,T) > (Sx(w,T)