

Day 26

$$(a) \quad \vec{m}_r^{\text{co}} = \cancel{\vec{F}_{\text{net}}} + 2m\vec{\dot{r}} \times \vec{\Omega} + m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$$

$$m\vec{\ddot{r}} = 2m\langle \dot{y}\Omega, -\dot{x}\Omega, 0 \rangle + m\Omega^2\langle x, y, 0 \rangle$$

$$m\vec{\ddot{x}} = 2m\dot{y}\Omega + m\Omega^2 x$$

$$\boxed{\begin{aligned} \ddot{x} &= 2\dot{y}\Omega + \Omega^2 x \\ \ddot{y} &= -2\dot{x}\Omega + \Omega^2 y \end{aligned}}$$

(b)

$$\eta = x + iy$$

$$\dot{\eta} = \dot{x} + i\dot{y}$$

$$\ddot{\eta} = \ddot{x} + i\ddot{y}$$

$$\ddot{\eta} = 2\dot{y}\Omega + \Omega^2 x + i(-2\dot{x}\Omega + \Omega^2 y)$$

$$= 2\dot{y}\Omega + \Omega^2 x - 2\dot{x}\Omega i + \Omega^2 y i$$

$$= \underbrace{2\Omega(\dot{y} - i\dot{x})}_{-i\dot{\eta}} + \underbrace{\Omega^2(x + iy)}_{\eta}$$

$$\boxed{\ddot{\eta} = \Omega^2 \eta - i2\Omega \dot{\eta}}$$

Solution

$$\mathcal{N} = e^{-i\alpha t}$$

$$\dot{\mathcal{N}} = -i\alpha e^{-i\alpha t}$$

$$\ddot{\mathcal{N}} = -\alpha^2 e^{-i\alpha t}$$

$$-\alpha^2 e^{-i\alpha t} = \Omega^2 e^{-i\alpha t} - i2\Omega(-i\alpha e^{-i\alpha t})$$

$$-\alpha^2 = \Omega^2 - 2\Omega\alpha$$

$$\Omega^2 - 2\Omega\alpha + \alpha^2 = 0$$

$$(\Omega - \alpha)(\Omega - \alpha) = 0$$

$$\boxed{\Omega = \alpha}$$

$te^{-i\alpha t}$ is also a solution

General Solution:

$$\boxed{\mathcal{N} = C_1 e^{-i\alpha t} + C_2 t e^{-i\alpha t}}$$

$$(c) \quad t=0: \mathcal{N}_0 = C_1$$

$$t=0: \dot{\mathcal{N}} = -i\alpha C_1 e^{-i\alpha t} + C_2 \left[(t)(-i\alpha)(e^{-i\alpha t}) + e^{-i\alpha t} \right]$$

$$\dot{\mathcal{N}}_0 = -i\alpha C_1 + C_2$$

$$\mathcal{N}_0 = -i\alpha \mathcal{N}_0 + C_2$$

$$C_2 = \dot{\mathcal{N}}_0 + i\alpha \mathcal{N}_0$$

$$z_0 = x_0 + iy_0 \quad \dot{z}_0 = v_{x0} + iv_{y0}$$

$$C_1 = x_0 + iy_0$$

$$C_2 = v_{x0} + iv_{y0} + i\alpha(x_0 + iy_0)$$

$$\begin{aligned} C_2 &= v_{x0} + iv_{y0} + i\alpha x_0 - \alpha y_0 \\ &= -\alpha y_0 + v_{x0} + i(\alpha x_0 + v_{y0}) \end{aligned}$$

$$\begin{aligned} z &= (x_0 + iy_0)e^{-i\alpha t} + ((-\alpha y_0 + v_{x0}) + i(\alpha x_0 + v_{y0}))te^{-i\alpha t} \\ &= e^{-i\alpha t} \left(x_0 + (-\alpha y_0 + v_{x0})t + i(y_0 + (\alpha x_0 + v_{y0})t) \right) \end{aligned}$$

$$\alpha = \Omega$$

$$y_0 = 0$$

$$\begin{aligned} z &= e^{-i\Omega t} \left((x_0 + v_{x0}t) + i(v_{y0} + \Omega x_0t) \right) \\ &= (\cos \Omega t - i \sin \Omega t) \left((x_0 + v_{x0}t) + i(v_{y0} + \Omega x_0t) \right) \\ &= \cos \Omega t (x_0 + v_{x0}t) + \sin \Omega t (v_{y0} + \Omega x_0t) \\ &\quad + i(v_{y0} + \Omega x_0t) \cos \Omega t - i \sin \Omega t (x_0 + v_{x0}t) \end{aligned}$$

$$x(t) = \cos \Omega t (x_0 + v_{x0} t) + t (v_{y0} + \Omega x_0) \sin \Omega t$$

$$y(t) = -\sin \Omega t (x_0 + v_{x0} t) + t (v_{y0} + \Omega x_0) \cos \Omega t$$