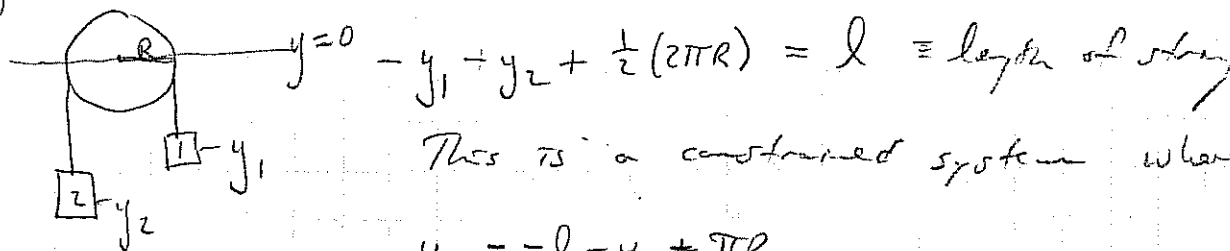


Example: Atwood's Machine

↑ +y



This is a constrained system where

$$y_2 = -l - y_1 + \pi R$$

$$\begin{aligned} K &= \frac{1}{2}m_1 v_1^2 + \frac{1}{2}m_2 v_2^2 \\ &= \frac{1}{2}m_1 \dot{y}_1^2 + \frac{1}{2}m_2 \dot{y}_2^2 \\ &= \frac{1}{2}m_1 \dot{y}_1^2 + \frac{1}{2}m_2 (-\dot{y}_1)^2 \\ &= \frac{1}{2}(m_1 + m_2) \dot{y}_1^2 \end{aligned}$$

$$\dot{y}_2 = -\dot{y}_1$$

Note that the tension was not required by using the Hamilton's Principle to solve the problem.

$$\begin{aligned} U_{\text{grav}} &= m_1 g y_1 + m_2 g y_2 \\ &= m_1 g y_1 + m_2 g (-l - y_1 + \pi R) \end{aligned}$$

$$U_{\text{grav}} = m_1 g y_1 - m_2 g y_1 - m_2 g l + m_2 g \pi R$$

$$L = T - U \rightarrow L = \frac{1}{2}(m_1 + m_2) \dot{y}_1^2 - (m_1 - m_2) g y_1 + m_2 g l - m_2 g \pi R$$

The action is a minimum if

$$\begin{aligned} q &\text{ is } y_1 \\ \dot{q} &\text{ is } \dot{y}_1 \end{aligned}$$

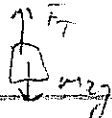
$$\frac{\partial L}{\partial y_1} = \frac{d}{dt} \frac{\partial L}{\partial \dot{y}_1}$$

$$\frac{\partial L}{\partial y_1} = -(m_1 - m_2) g$$

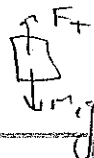
$$\frac{\partial L}{\partial \dot{y}_1} = (m_1 + m_2) \dot{y}_1$$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{y}_1} \right) = (m_1 + m_2) \ddot{y}_1$$

$$\begin{aligned} -(m_1 - m_2) g &= (m_1 + m_2) \ddot{y}_1 \\ \ddot{y}_1 &= \left( \frac{m_2 - m_1}{m_1 + m_2} \right) g \end{aligned}$$

From Newton's 2<sup>nd</sup> law,

$$F_T - m_2 g = m_2 a_{y2}$$



$$F_T - m_1 g = m_1 a_{y1}$$

$$\begin{aligned} a_{y1} &= -a_{y2} \\ -m_2 a_{y1} + m_2 g - m_1 g &= m_1 a_{y1} \\ a_{y1} &= \left( \frac{m_2 - m_1}{m_1 + m_2} \right) g \quad \checkmark \end{aligned}$$