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                                                                                                  \begin{array}{c} in \overline{r}, \\ in \overline{r}, \\ tu j c \\ mn i \\ \vdots, \\ roz d leny \\ jed-\\ nok-\\ yad-\\ tov \\ sov \\ sov \\ and \\ and \\ sov \\ sov \\ and \\ dn \\ zdroje \\ U_d \\ U_d \\ U_d \\ B_d \overset{max}{\underset{}{=}} \\ 2\pi f L_{2,K} \\ L_{2,K} = \\ L_2(1- \end{array}
                                                                                                             k^2
                                                                                                        bloku-
jemu
                                                                                                  \begin{array}{l} mnii \\ \Delta U_{z}(t) \\ I_{z} \\ T \\ \vdots \\ I_{L}(t) = \\ I_{L} = \\ konst \\ k = \\ L_{2,K} \end{array}
                                                                                                                                                                                                                                                            \label{eq:control_control} \begin{array}{l} Control & Control \\ Control & Co
                                                                                                             s = \frac{t_z}{T}, s_{max} = \frac{1}{2}, protoet < \frac{T}{2}
\begin{array}{c} T, \\ \hline \\ t_z = \\ t_1 \\ T_2 \\ \hline \\ U_1 \\ t_1 \\ t_1 \\ U_d \\ t_1 \\ U_d \\ U_1 \\ t_1 \\ U_d \\ U_1 \\ t_1 \\ U_d \\ U_1 \\ U_2 \\ U_2 \\ v_1 \\ v_2 \\ v_2 \\ v_3 \\ v_4 \\ v_2 \\ v_4 \\ v_4 \\ v_2 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_5 \\ v_7 \\ v_7 \\ v_8 \\ v_
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 $\begin{array}{l} \frac{T}{t_z^2} = \\ \frac{T}{t_z^2} = \\ \frac{T}{t_z^2} > \\ \frac{T}{t_z^2} > \\ converter_topo.pdf[Propustnmnisakumulantlumivkouademagnetizanmvinutm]Propustnmnisakumulantlumivkouademagnetizanmvinutm]\\ \end{array}$