INGENIC

PD_JZ4775_S2513B-15M Schematic Revision 1.2

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Schematic Description:

I.Net indetify explanation :

1. The red net identify is fixed-function net , to confirm all the function , It can not be modify
2. The blue net identify is I/O function net , to confirm the software consistency , not recommanded to change

II. Impedance explanation: the color of net should be control the impedance in the layout and manufacture accord to the following identification

Differential pairs Z0= 100 ohm	Differential pairs Z0= 90 ohm	Equilong BUS Z0= 50 ohm	RF Microstrip Z0= 50 ohm

III. PCB Layout about the trace width and surround with gnd explaction: it should be control in PCB Layout accord to the following identification

W>20mil	W>40mil	Surround with Gnd

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Data	Revision	Change
Nov.28 2013	Rev1.0	1. First released Revision
Mar.04 2014	Rev1.1	1. Connect U122.8 to WIFI_VDDIO for I2C interface 2. Disconnect U123.1 3. The power of R12&R13 pull up resistor change to VCC_SENSOR1V8 for power save 4. U123 change to M24256-DFCS6TP/K
Apr.23 2014	Rev1.2	1. Change the package of EEPROM U123 2. Change the location of C47 3. The power of R15&R16 pull up resistor change to TP_VDDD_1V8 for power save 4. Add resistor of R8 & R6 for I2C bus of NFC 5. Add ESD12&ESD13 for NFC ANT 6. Add R113 & NC R45

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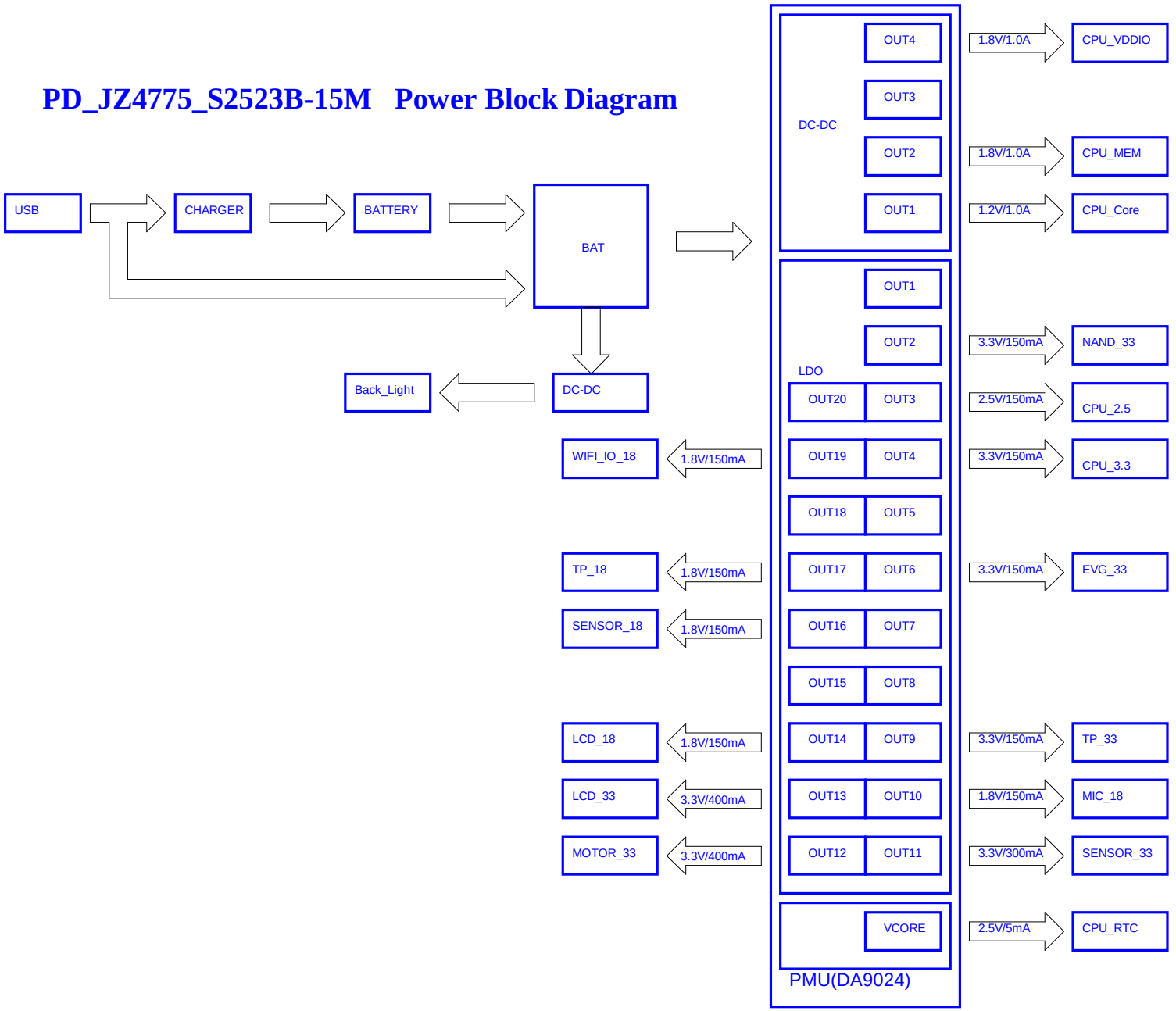
PD_JZ4775_S2523B-15M Power Block Diagram



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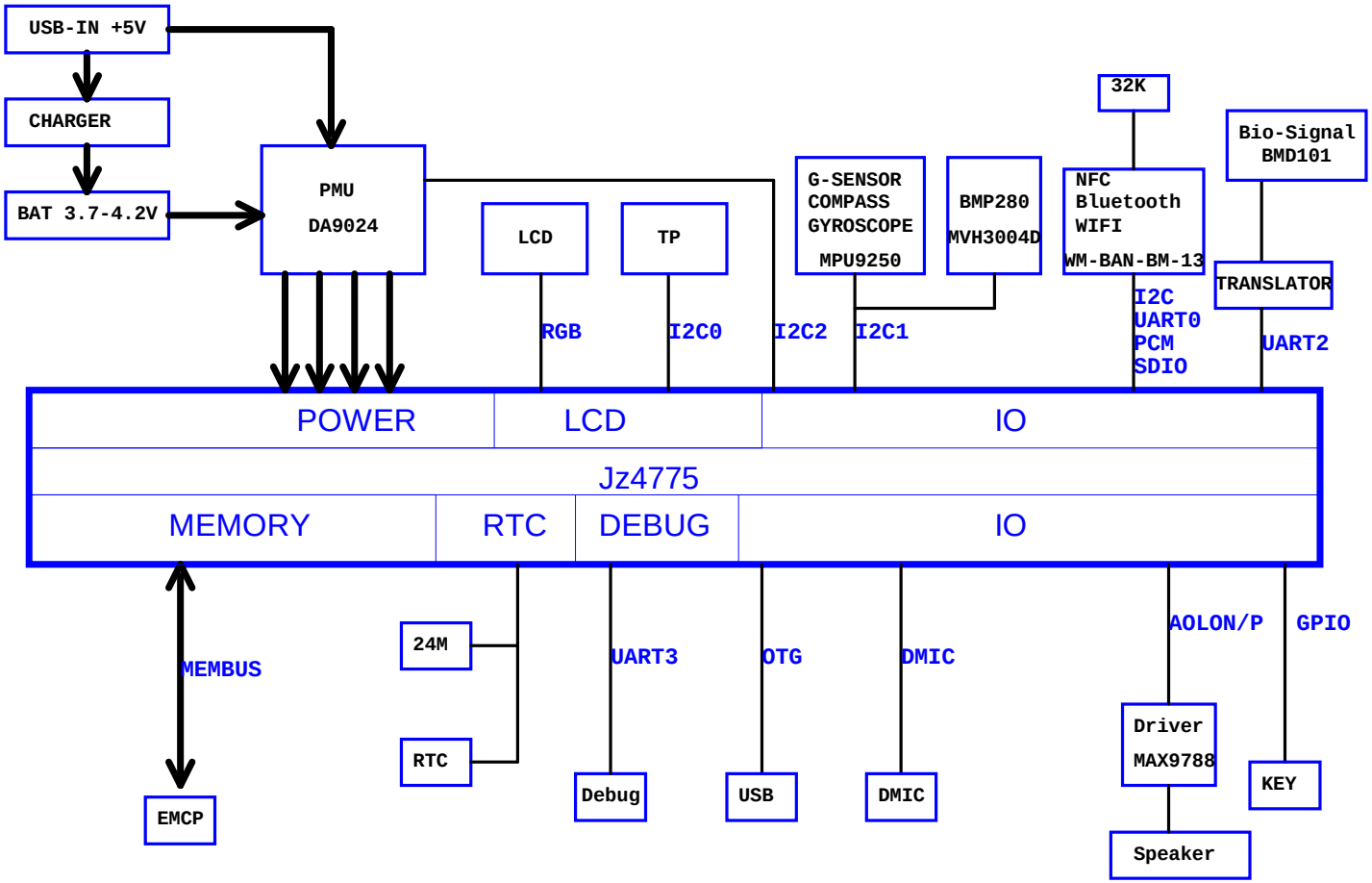
PD_JZ4775_S2523B-15M System Block Diagram



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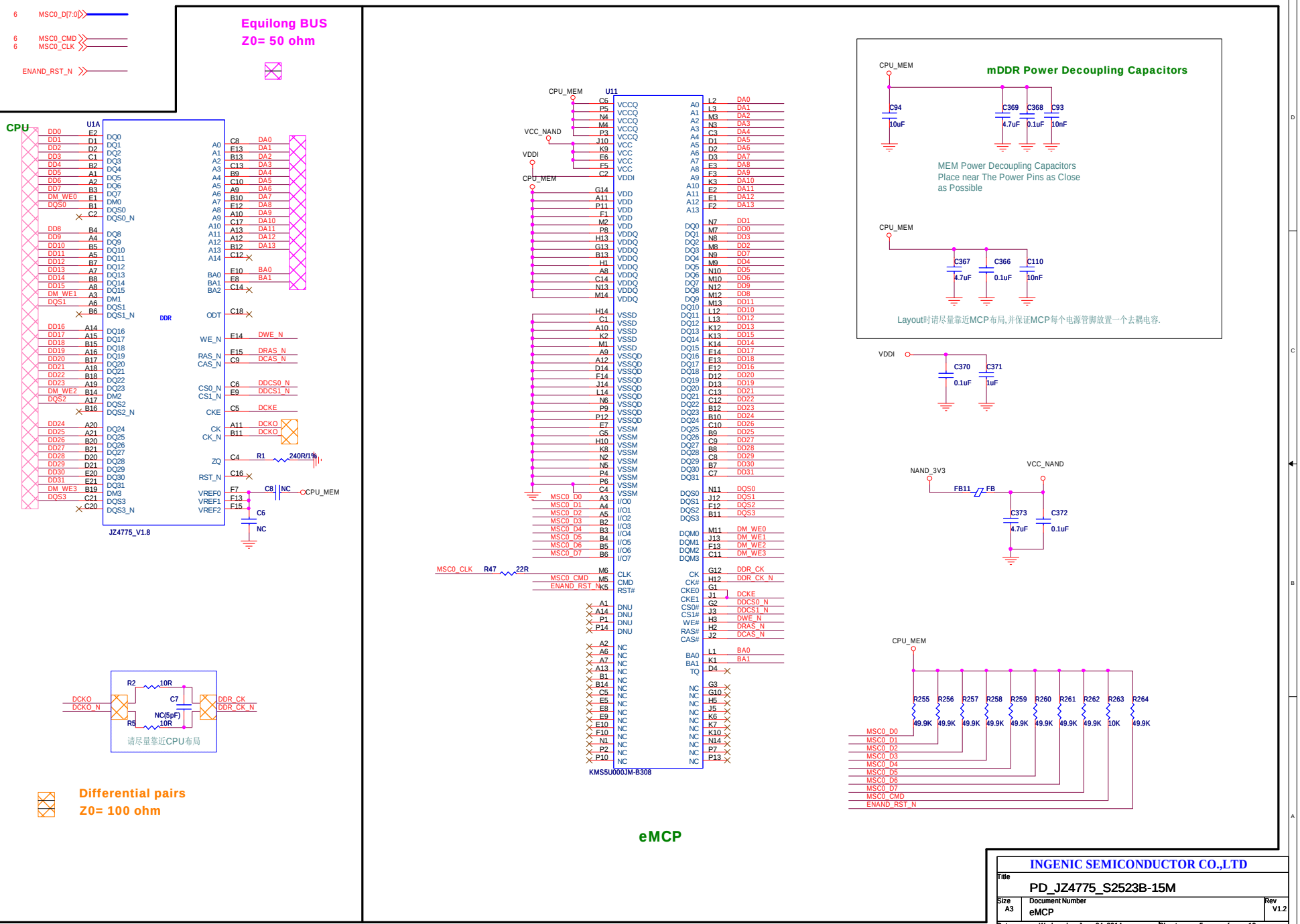

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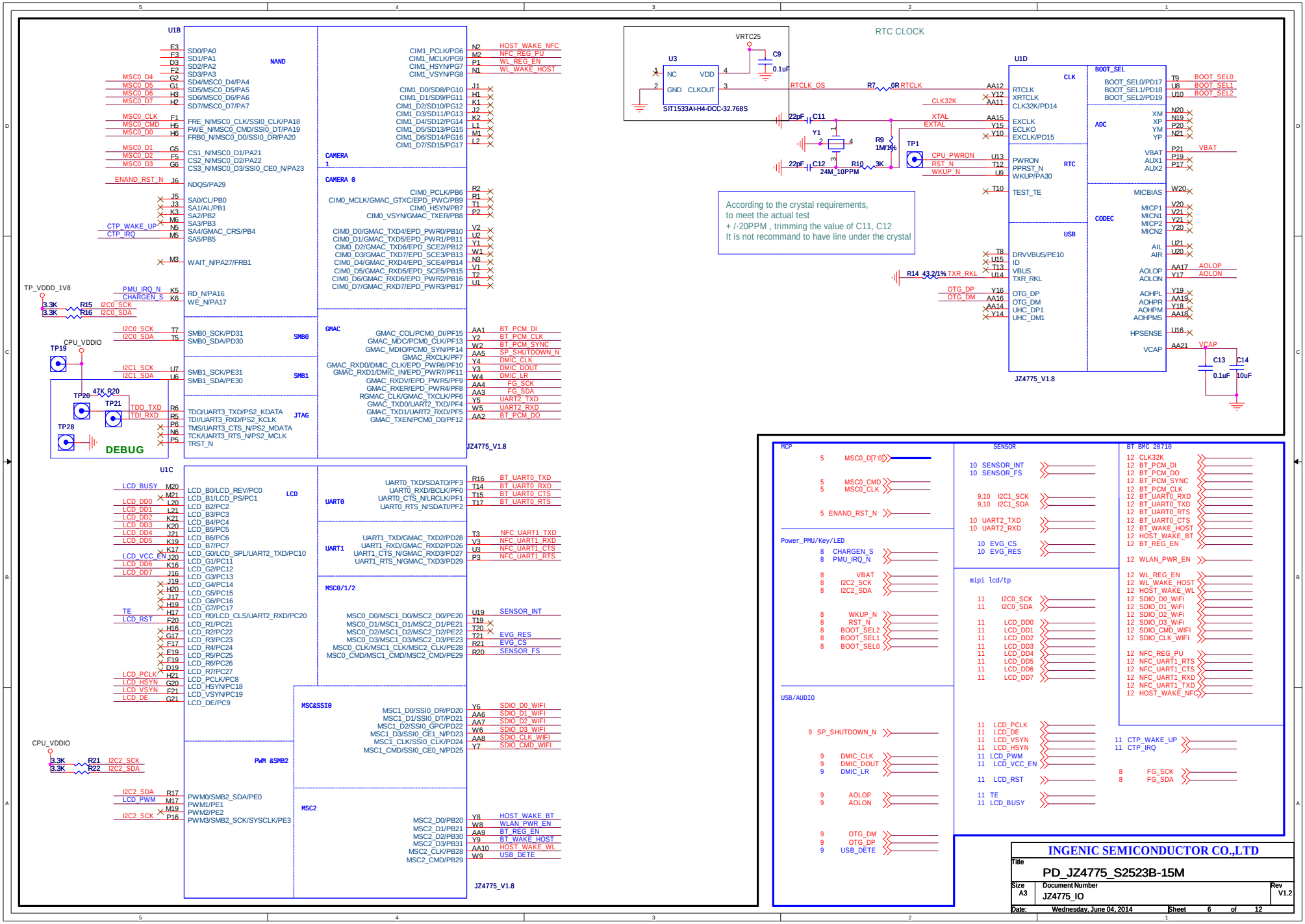

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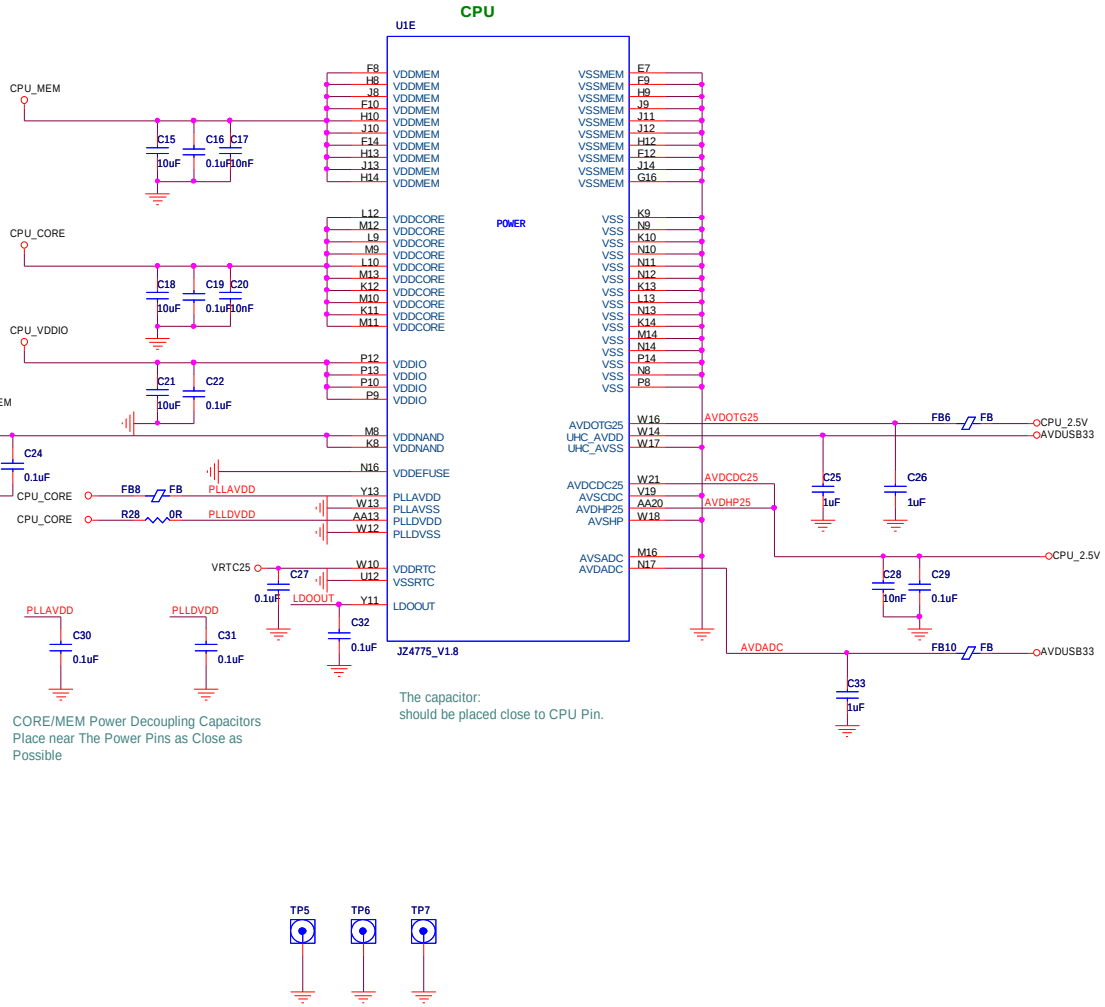

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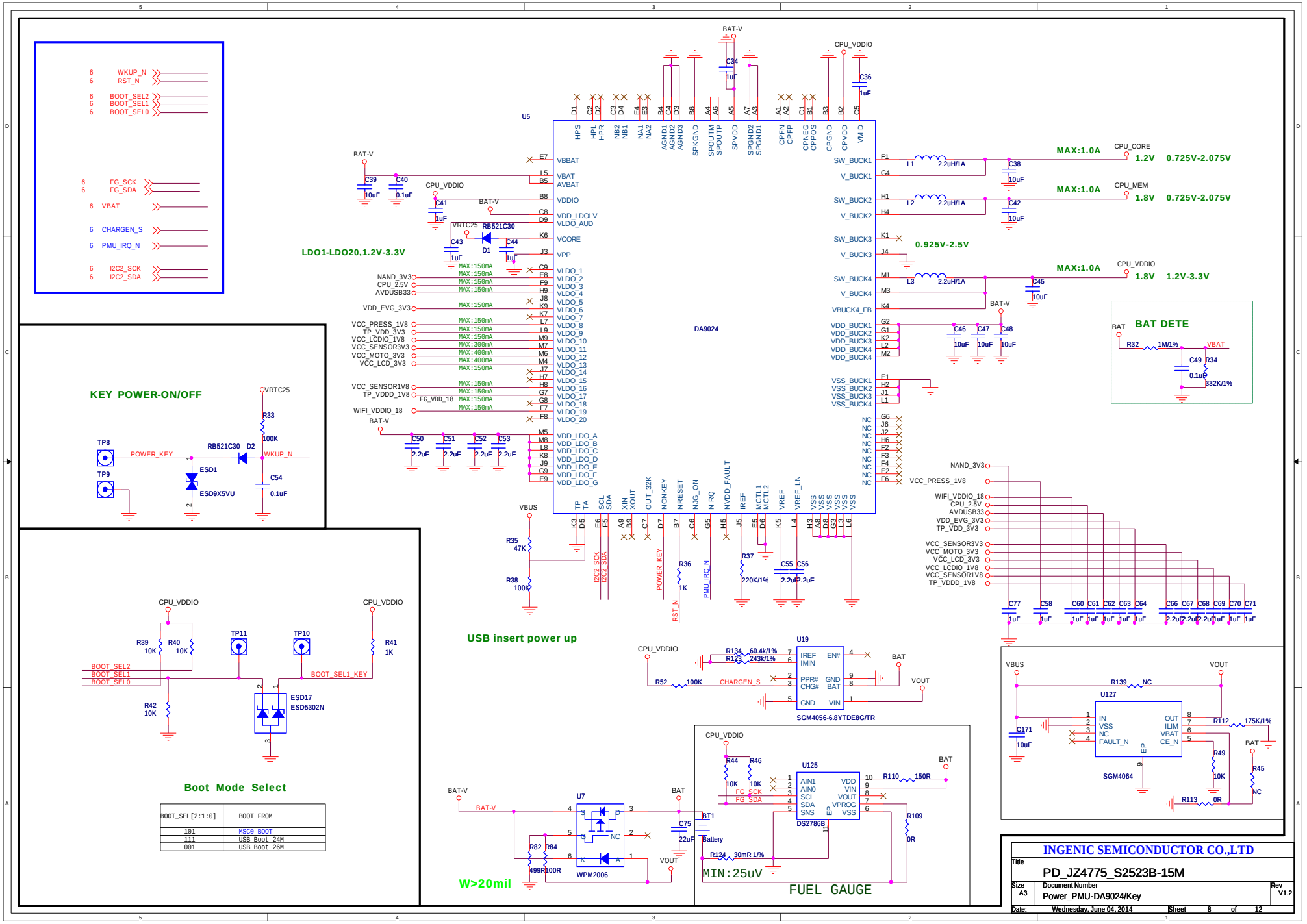

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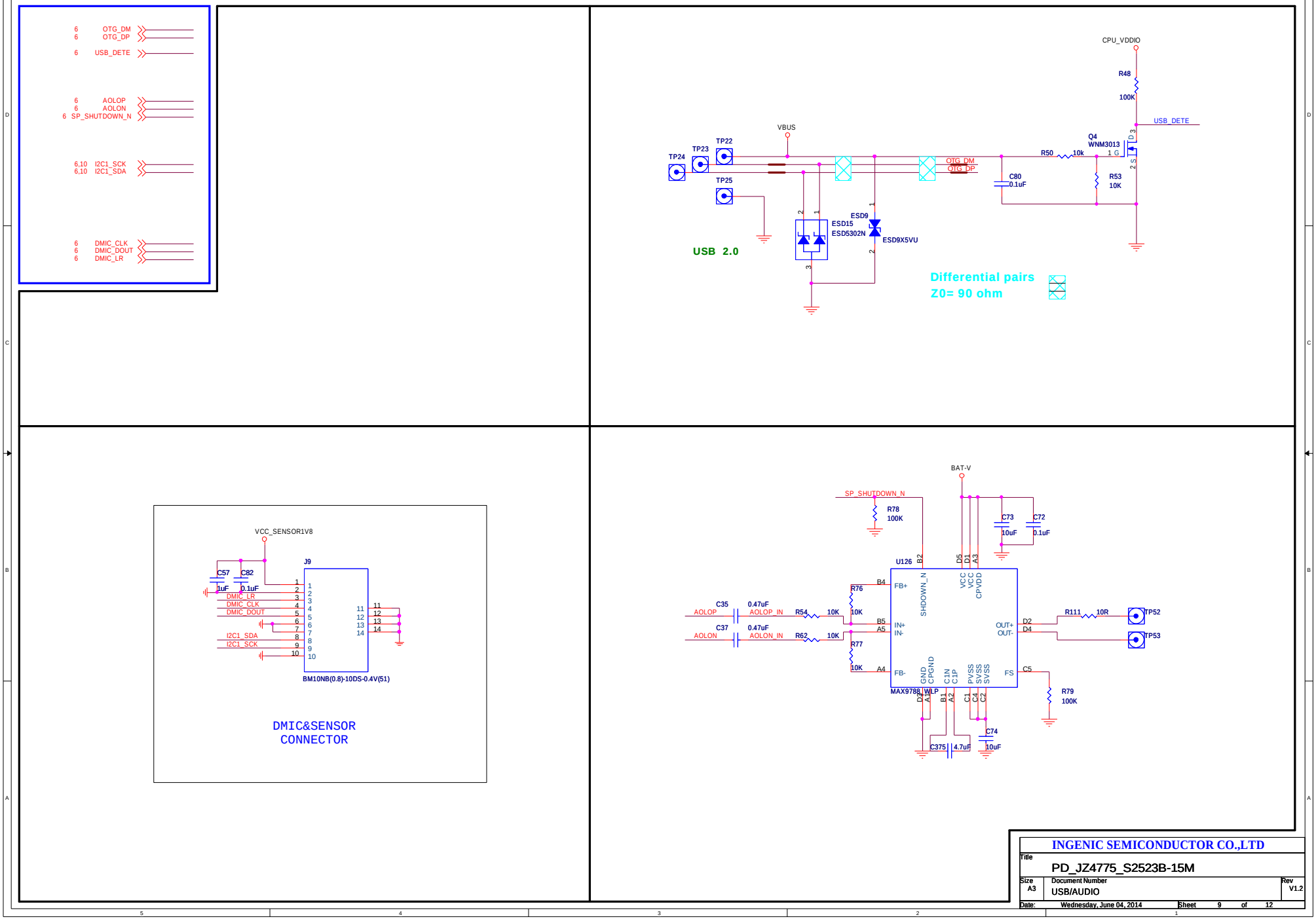

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6 SENSOR_FS

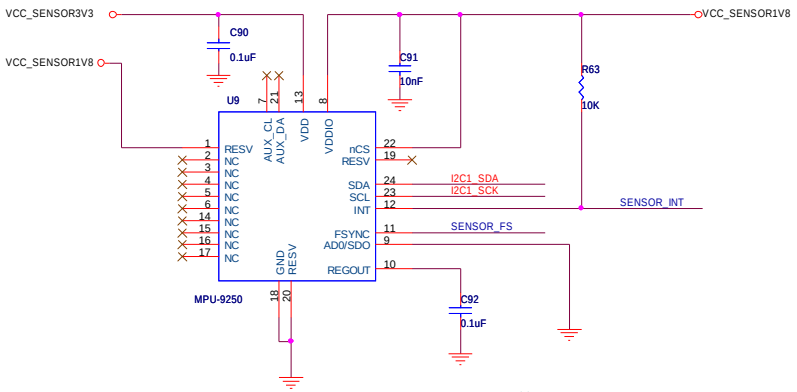
6 SENSOR_INT

6,9 I2C1_SCK
6,9 I2C1_SDA

6 EVG_CS
6 EVG_RES

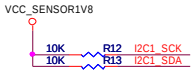
6 UART2_TXD
6 UART2_RXD

Gyroscope : 3.2mA / 8uA
Accelerometer: 450uA / 8uA
Magnetometer : 280uA / NO Parameter



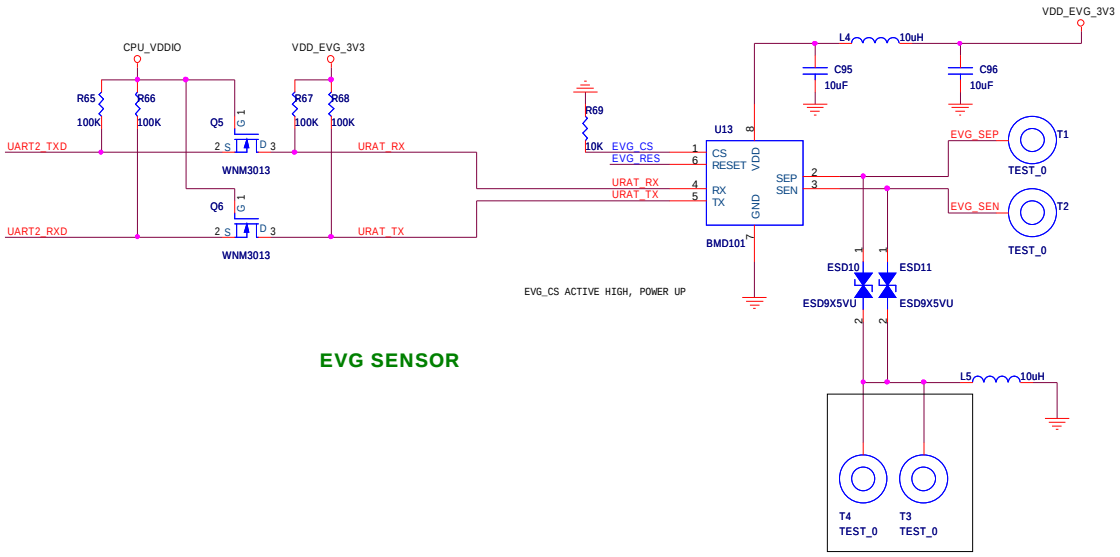
GYROSCOPE+GSENSOR+COMPASS

addr : 1101000



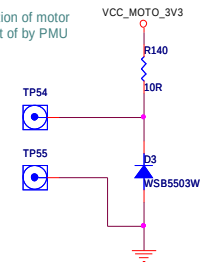
NOT SURE
Normal : 22.5uA
Pwrdown: 0.5uA

Normal : 24.4uA
Pwrdown: 0.6uA



EVG SENSOR

Accord to the specification of motor
to select the voltage out of by PMU



MOTOR

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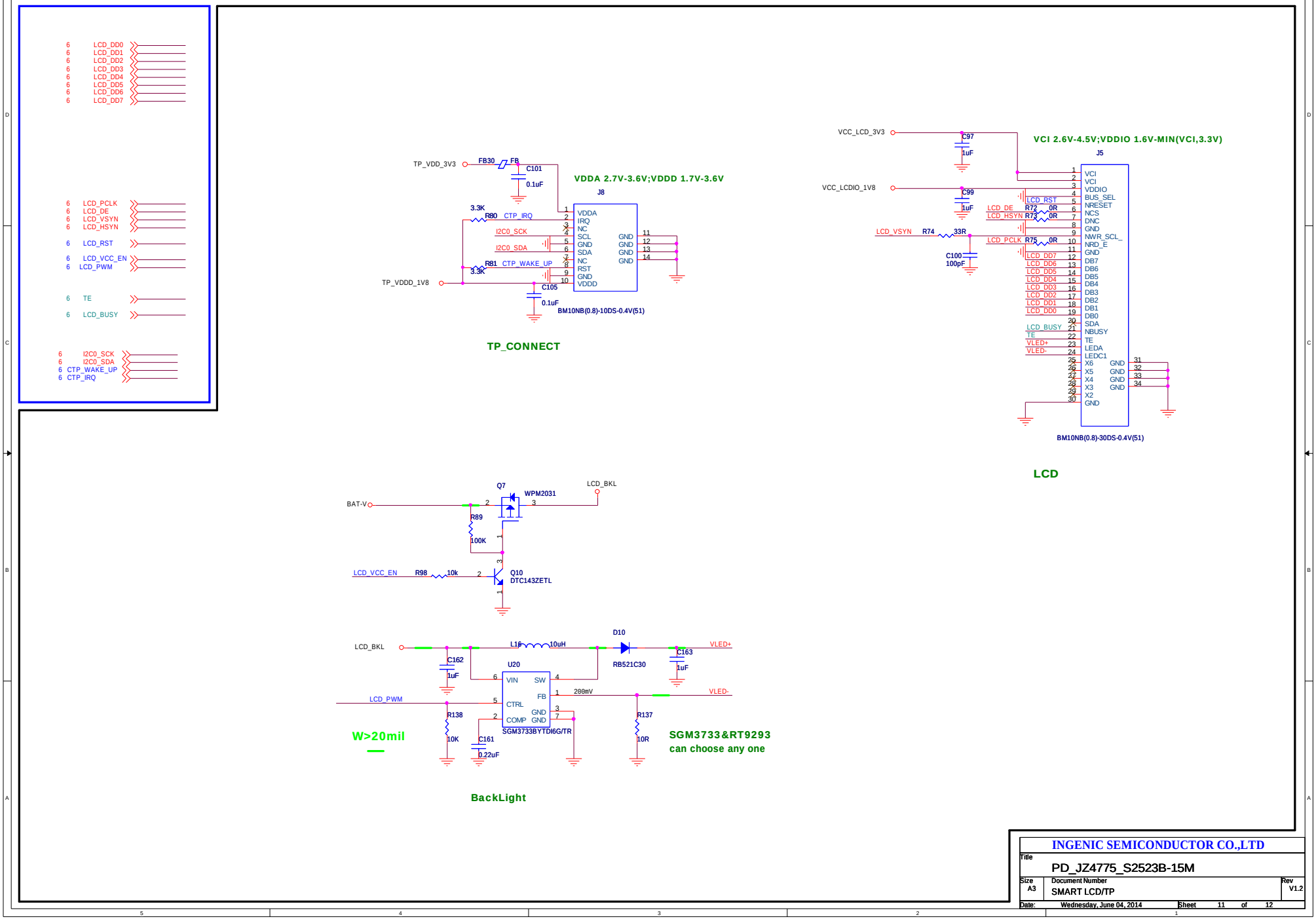

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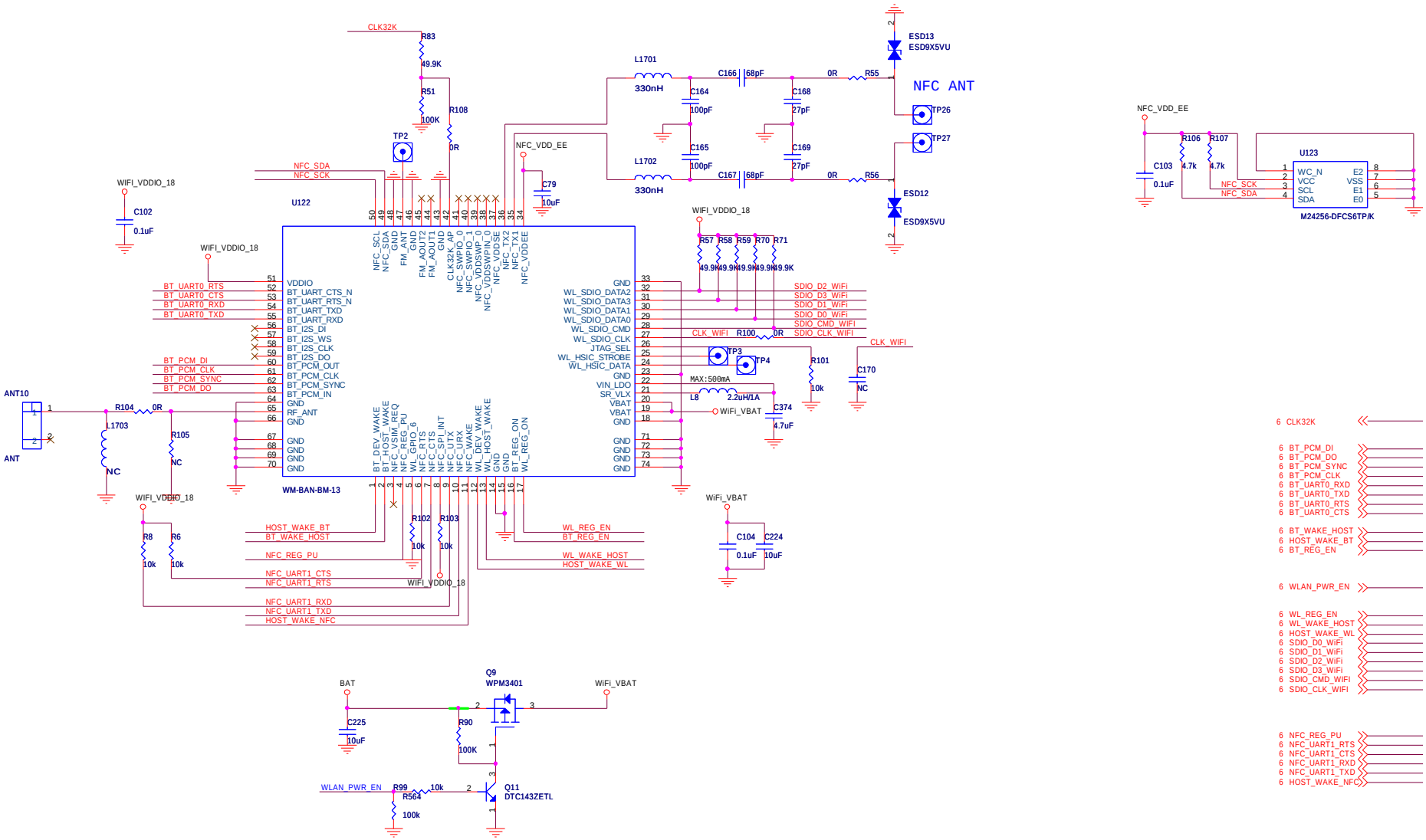

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