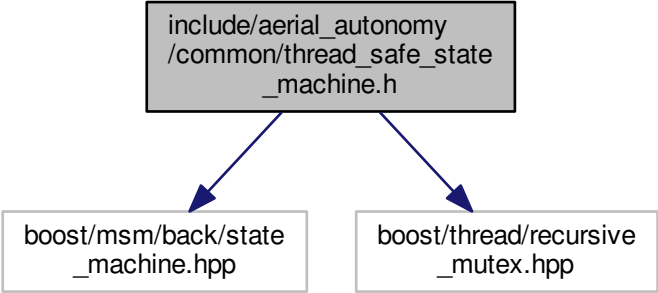


include/aerial\_autonomy  
/common/thread\_safe\_state  
\_machine.h



```
graph TD; A["include/aerial_autonomy  
/common/thread_safe_state  
_machine.h"] --> B["boost/msm/back/state  
_machine.hpp"]; A --> C["boost/thread/recursive  
_mutex.hpp"]
```

The diagram illustrates the include paths for the file `thread_safe_state_machine.h`. It is structured as a tree where the root node at the top branches into two child nodes below it. The root node is shaded gray, while the child nodes are white with gray borders. Blue arrows indicate the direction of the include relationships from the root to the children.

boost/msm/back/state  
\_machine.hpp

boost/thread/recursive  
\_mutex.hpp