```
include/aerial_autonomy
/controller_hardware_connectors
/base_controller_hardware_connector.h
```
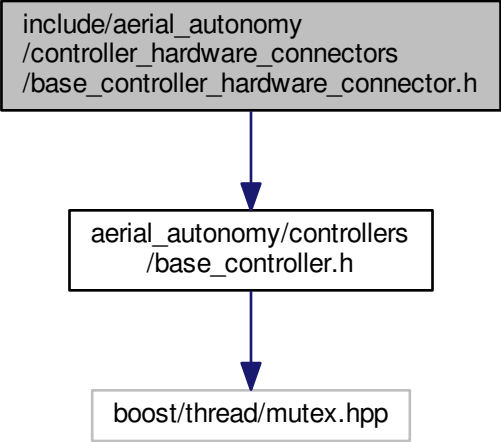
```
aerial_autonomy/controllers
/base_controller.h
```

```
boost/thread/mutex.hpp
```