W4 - Plan

- Summay for the papers
  - Deep MANTA: A Coarse-to-fine Many-Task Network for joint 2D and 3D vehicle analysis from monocular image
    - https://arxiv.org/pdf/1703.07570.pdf
  - Rethinking Reprojection: Closing the Loop for Pose-aware Shape Reconstruction from a Single Image. ICCV'17
    - https://arxiv.org/abs/1707.04682
  - CARLA
    - http://www.carla.org
  - [#]3D Bounding Box Estimation Using Deep Learning and Geometry
    - https://arxiv.org/pdf/1612.00496.pdf
  - 6 x 4 = 24H
- Course
  - Intro to CV
  - 12 L : 2B-L3, 2C-L1, 2C-L2, 2C-L3, 3A-L1, 3A-L2, 3B-L1, 3B-L2, 3B-L3, 3C-L1, 3C-L2, 3C-L3
  - 1.5 x 12 = 18H
- MIT 6.S094
  - http://selfdrivingcars.mit.edu/
  - 3L: L1, L2, L3
  - 3 x 3 = 9H
- [#]Convolutional Neural Networks
  - https://www.coursera.org/specializations/deep-learning
  - W1, W2, W3, W4
  - 5 x 4 = 20H

	Mon	Tue	Wed	Thu	Fri		Sun
Paper	Deep MANTA		Rethinking Reprojection		CARLA		
CV	2B-L3, 2C-L1	2C-L2, 2C-L3	3A-L1, 3A-L2,	3B-L1, 3B-L2	3B-L3, 3C-L1		3C-L2, 3C-L3
MIT 6.S094		L1		L2			L3
CNN	CH1	W1		W2			W3
Misc	Latex						