Frame 0: Tracks

Subset 0 (depth 0)

Subset 1 (depth 1)

Subset 2 (depth 2)
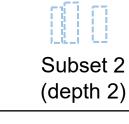
Pseudo-depth

Frame 1: detections

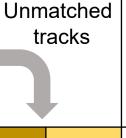Depth 0 < Depth 1 < Depth 2

Subset 0 (depth 0)

Subset 1 (depth 1)

Subset 2 (depth 2)

Unmatched tracks

Unmatched tracks

Unmatched detections

Unmatched detections