

FPGA for interface fusion

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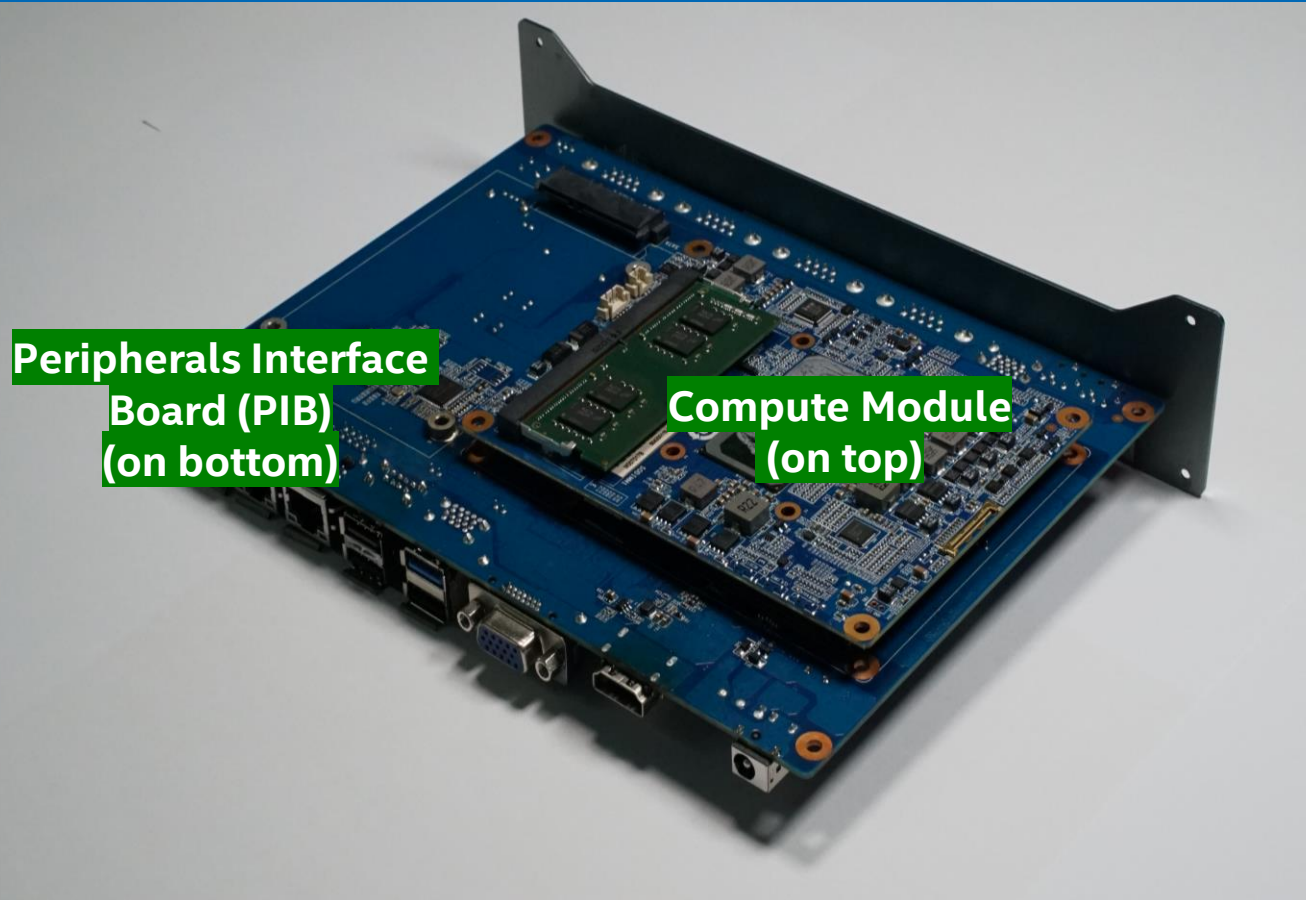
Agenda

- Intel Industrial Edge Module
- Peripherals interface board with FPGA
- Autonomous Mobile Robot application
 - Time synchronization



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Intel® Industrial Edge Module



Intel® Industrial Edge Module is a **modular Hardware** reference design based on Atom (Elkhart Lake) and Core (Whiskey Lake, Tiger Lake) platforms, optimized for **Industrial applications** such as control and vision.

Benefits:

- **Modular Design:** Cost & time saving on I/O customization, high-mix & low-volume SKUs
- **Upgradable:** Superior experience of newer CPU on legacy I/O
- **Industrial Grade:** Industrial I/Os, Industrial connectors & fanless robust design

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Peripherals Interface Board – Powered by FPGA

CycloneV GT on board

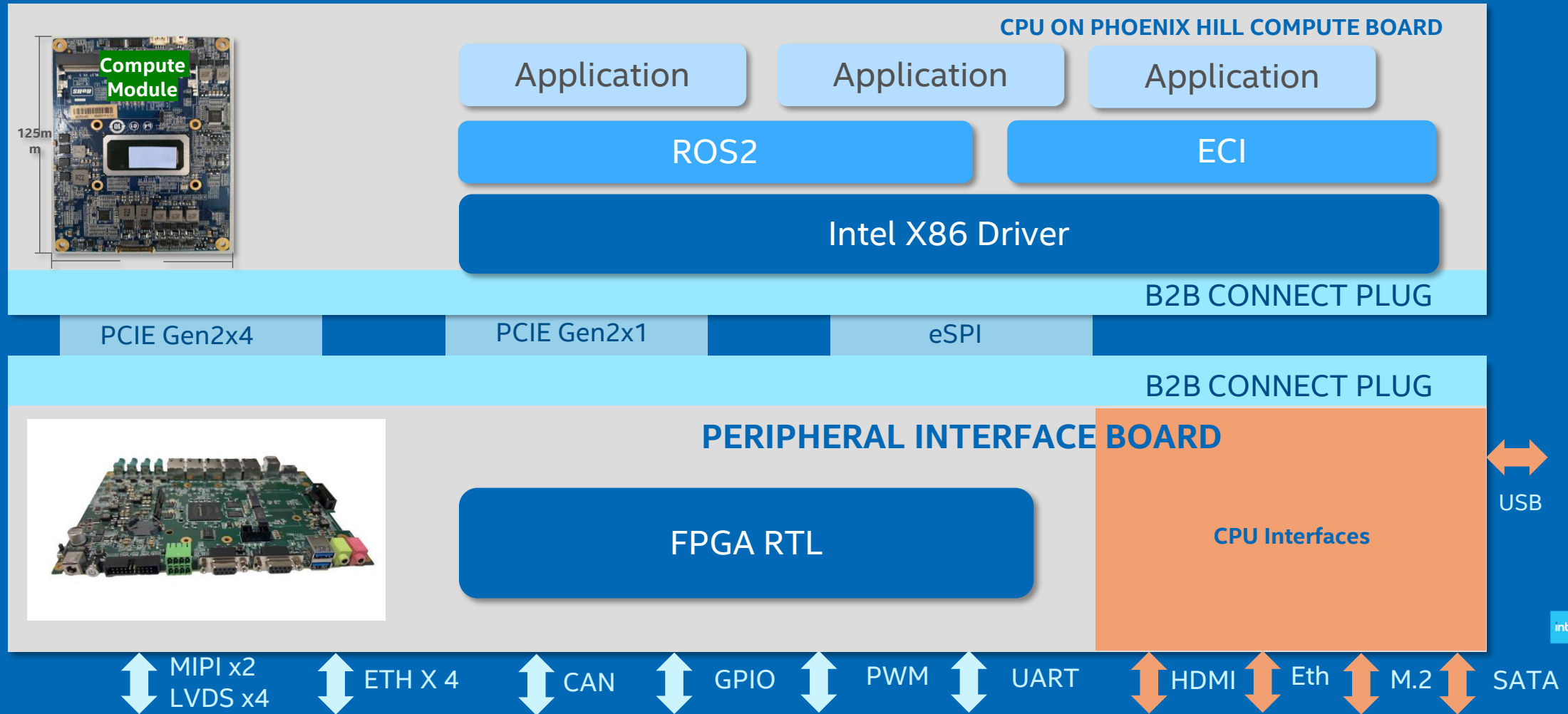


- Interface in Parallel
 - Sensor Interfaces
 - Ethernet ports
 - Control Ports
- Deterministic Computation
 - PLC Control
 - Motion Control
- Workload offload
 - Imaging Signal Processing
 - AI inference



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System Diagram

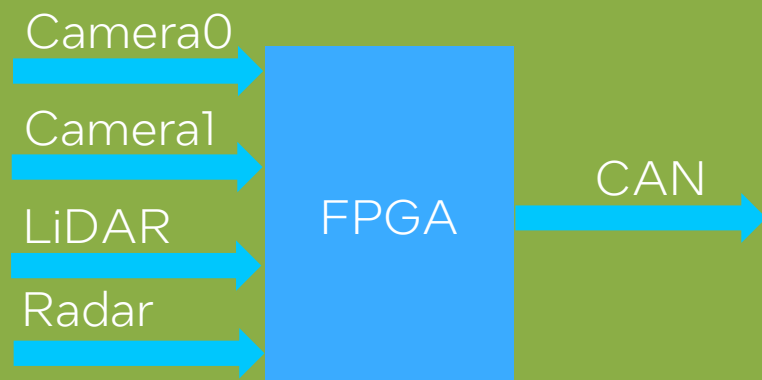


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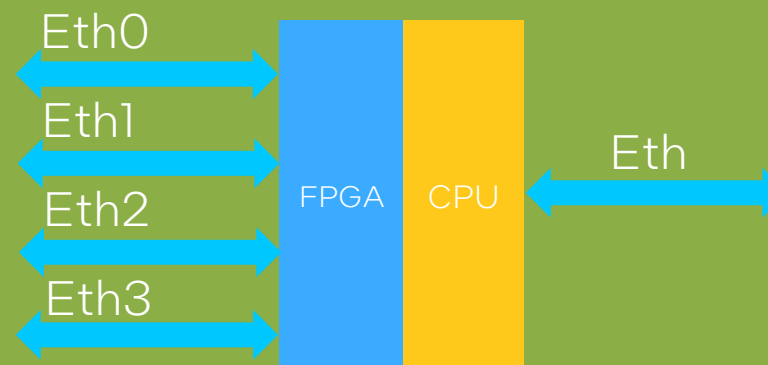
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Target Area

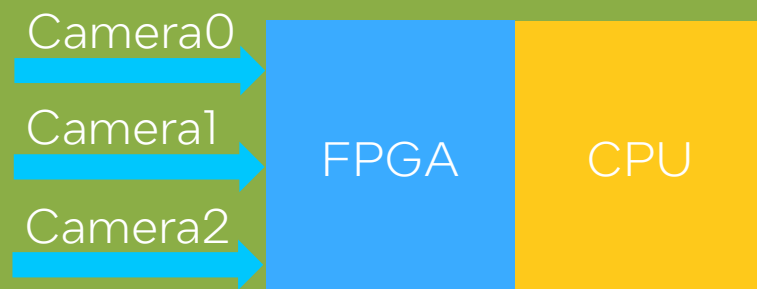
Autonomous Mobile Robot



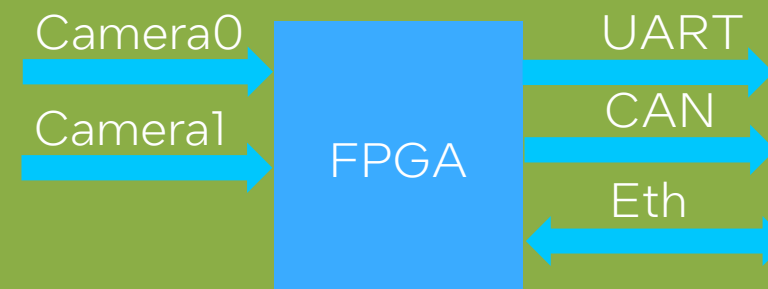
Industry Internet



Machine Vision



Vision Control



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Sensor Fusion in AMR



Requirement



FPGA

—Our Proposed Solution



Extended
Sensor Hub



Time
Synchronization

Trigger the sensor collection simultaneously to make sure the hard time synchronization between different sensors.



Image
Preprocessing

Future use for image preprocessing, using ISP, before sending to CPU for further processing.



Increased Demands

Increased demands on AMR in various application scenarios



Complex Environment

Increased complexity on the Moving environment.



Multisensor Required

No single sensor could solve all the problems.

Various
sensor



Time
Synchronization

- Need various sensors to assist on autonomous navigation accuracy and intelligent obstacle avoidance capability.
- Need time synchronization between sensor data to ensure the accuracy.

As-Is Solution

X86 CPU

✓ Connect to multi sensors and use soft time synchronization.

✗ Number of sensor connected is limited.

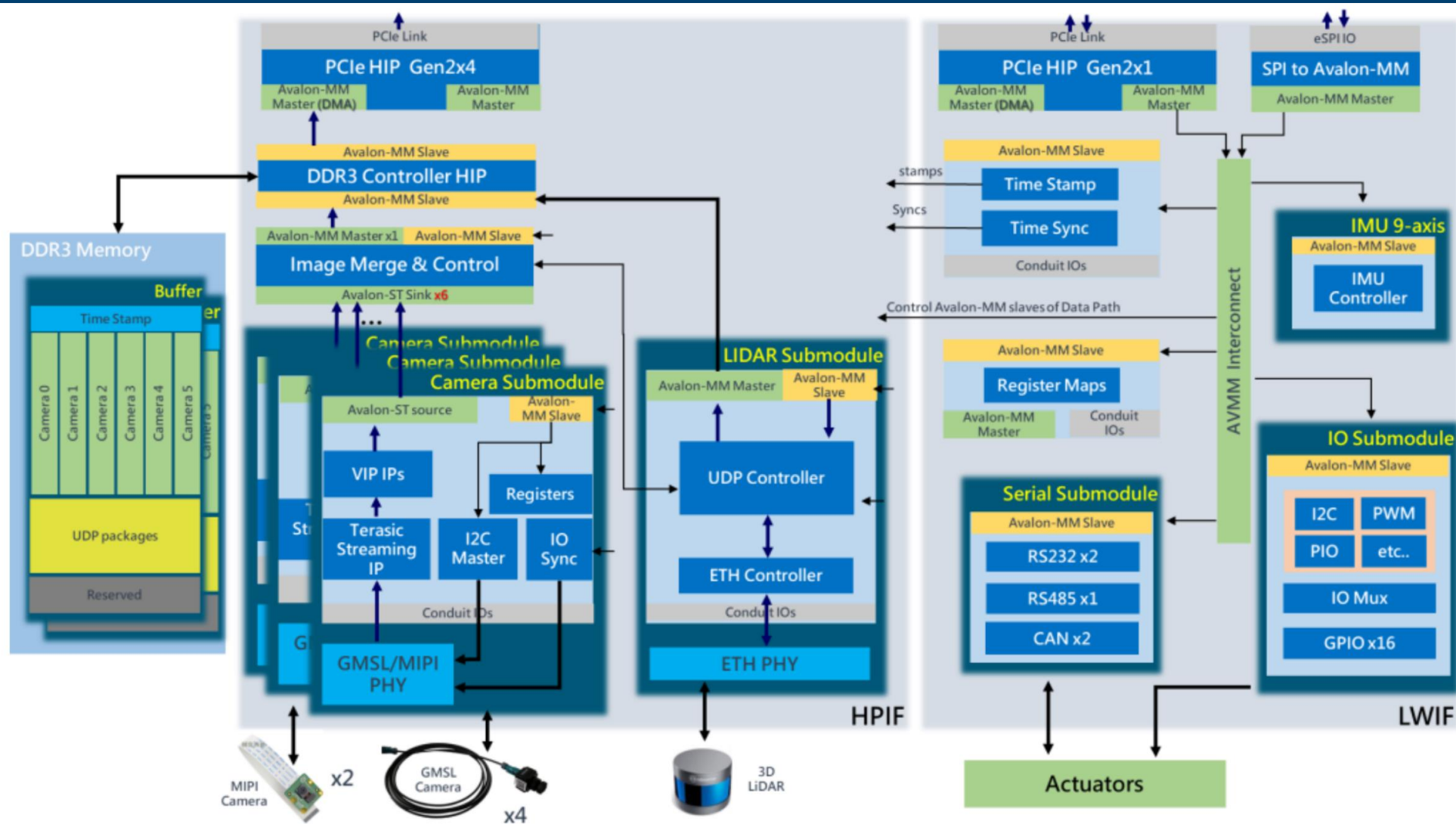
✗ Cannot sure accurate time synchronization.

MCU

✓ Connect to multi sensors

✗ Cannot sure accurate time synchronization

FPGA RTL Diagram



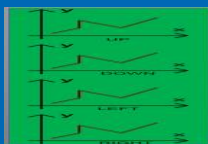
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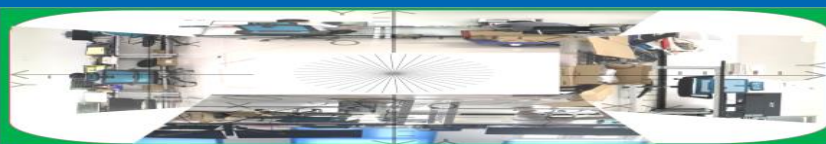
Software Diagram

Software Architecture

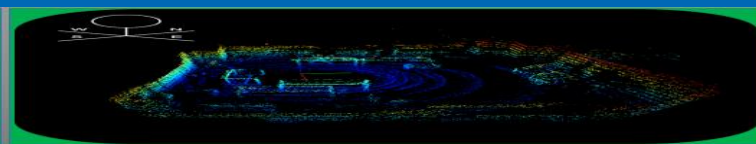
App



Latency Indicator



Camera data / stitched image



LiDAR data / depth map

ROS

Modified Robot OS

Config

Time Sync

Data Capture

Lidar
ROS Node

Camera ROS
Node

IMU
ROS Node

Odom
ROS Node

Joystick
ROS Node

Sensor
Fusion
Driver

Sensor Fusion Driver

V4L2

CAN

UART

RS485

Eth

GPIO

System Setting

Extract Timestamp

Data Depacking

FPGA/ Kernel
Driver

FPGA Kernel Driver

Interface

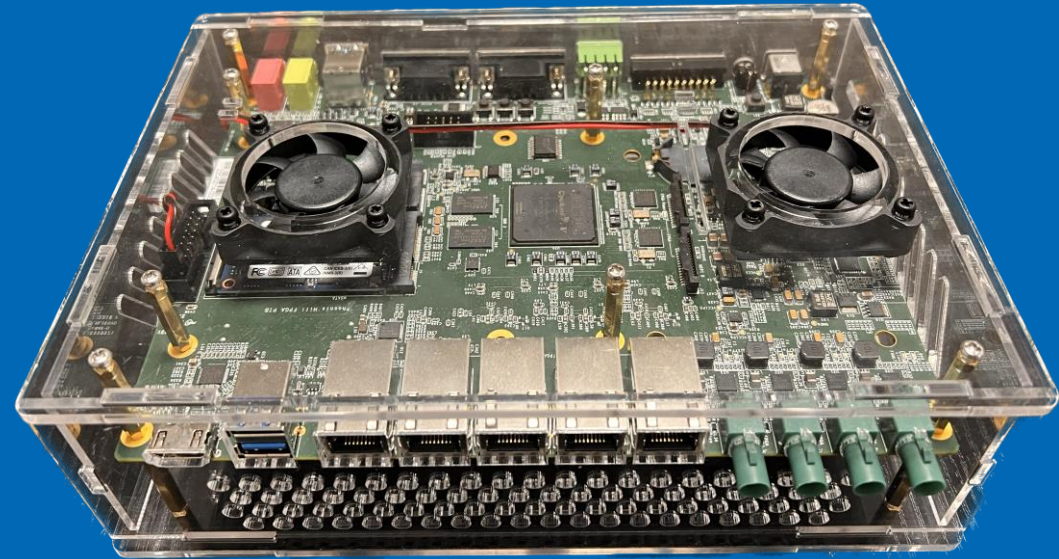
Sync Adjust

Data capture

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More are coming



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