

亚历克上 - M202161029

Numerical Exam

PART A

Final exam	
亚历克上 - M202161029	
2021 - 2022 - Exam	
PART A	
1) Bisection	
Advantages	disadvantages
<ul style="list-style-type: none">- Brackets the root much quicker since it discharges 50% of the current interval.- Example: if the interval is between 0-1 it takes 6-7 junctions evaluation to estimate the root to within 0,1 accuracy.- The root evaluation with 6-7 junctions estimation is within 0,625 to 0,031 accuracy	<ul style="list-style-type: none">- Difficult to find complex roots of pynomials.- Can be not easily rooted by singularities in the junctions.- Doesn't work work when the junction has a tangent to the x-axis.
Fixed Point Iteration	
<ul style="list-style-type: none">→ Global optimum→ Pareto ranking→ Converges→ Formula: $x_{n+1} = F(x_n)$Examples → Jacobi iterations and Gauss-Seidel.	<ul style="list-style-type: none">→ not enough numbers covered.

Advantages	Newton's Methods	Disadvantages
<ul style="list-style-type: none"> - Can identify repeated roots - It converges quicker - Can find complex roots assuming we start at x_1 - Doesn't get fooled by singularity 		<ul style="list-style-type: none"> - Can delay to find the root. - Only works if we have a function representation of $f(x)$. - Root is not granted. - Hard to find the root for example $f(x) = \tan^{-1}(x)$ - Can oscillate around the point due to change of sign.

2) Interpolation refers to estimation of unknown values.

Polynomial Approximation refers to an approximation of a curve with a polynomial.

Examples of Interpolation and polynomial approximation

- (i) Taylor's polynomial which illustrates that for a given function $f(x)$ and a point x_0 , we approximate $f(x)$ by the Taylor's polynomial $P_n(x)$.
- (ii) Neville's method which illustrates that we don't know which choice is better since true $f(x)$ is unknown, but we can compute all elements and see the trend.

→ the data is arranged closer to the interpolated point.

- The formula is:-
$$P(x) = (x - x_i) \frac{P_{0,i}, \dots, j+1, \dots, k(x) - P_{0,i-1}, i-1, i+1, \dots, k(x)}{x_i - x_j}$$

Lagrange interpolating polynomial

Advantages

- Its more efficient when interpolating several functions on the same set of points

Disadvantages

- The formula length of interpolation is large.
- Its too tedious as the approximation increases.

Newtonian interpolating polynomial.

Advantages

- Fast convergence
- The length of interpolation formula is small.
- No need to recompute as more interpolation points are added.

disadvantages.

- convergence is not guaranteed
- division by zero can occur
- root jumping might take place
- Inflection point issue might occur

3) ~~Jacobi~~

Gauss Elimination method

Advantages

- An augmented matrix is ~~in~~ form from the linear systems.
- Operation $a_{ij} \times b_i \rightarrow L_i$
 $a_i E_i + \lambda E_j \rightarrow b_i$
- It can solve more than 2 linear equations simultaneously.
- The procedure is $O(n^3)$.
- Useful for solving large problems

disadvantages

- The method require more operations
- Prone to false results.
-

Pivot strategies

→ Its Gaussian with partial pivoting.

The formula is

$$a_{rk} = \max_{1 \leq i \leq n} |a_{ik}^{(k)}|$$

→ only converge for gradually dominant matrix.

The formula is

$$|a_{ii}| > \sum_{j \neq i} |a_{ij}|$$

4) Numerical differentiation refers to the process of finding the numerical value of a derivative of a given function at a given point.

• good example is Taylor series or Lagrange interpolation.

Taylor's series expansion is defined as:-

$$f(x_i) = f(x_0) + \Delta x \left. \frac{d}{dx} \right|_{x=x_0} + \frac{(\Delta x)^2}{2!} \left. \frac{d^2}{dx^2} \right|_{x=x_0} + \dots \quad \Delta x = x_i - x_0$$

$$\Rightarrow f(x_i) = f(x_0) + (x_i - x_0) f'(x_0) + \frac{(x_i - x_0)^2}{2!} f''(x_0) + \frac{(x_i - x_0)^3}{3!} f'''(x_0) + \dots$$

Numerical Integration refers to the approximation of a definite integration by a weighted sum of function values at discretized points within the interval of integration.

The formula is:-

$$\int_a^b f(x) dx \approx \sum_{i=0}^N w_i f(x_i)$$

Composite Trapezoidal rule	Composite Simpson's rule
<ul style="list-style-type: none"> → Evaluates the area under the curves by dividing the total area into smaller trapezoids rather than using rectangles. → Works by approximating the region under the graph of a function as a trapezoid. → takes the average of the left and the right sum. → No accurate value when underlying function is smooth. → gives approximation value by:- $\Delta x = \frac{(b-a)}{n}$ where a $a = x_0 < x_1 < x_2 \dots < x_n = b$ 	<ul style="list-style-type: none"> → uses fundamental theorems of Calculus. → Used to evaluate definite integrals integral. → Uses the quadratic approximation instead instead of linear approximation. → Provides accurate values when the underlying function is smooth. → gives approximation value by:- $\Delta x = \frac{b-a}{n}$ where $x_i = a + i\Delta x$

PART B

PART B

1a) Bisection method $\rightarrow P_3 \rightarrow f(x) = \sqrt{x} - \cos x = 0$

\therefore We know that there is at least one root.

$$f(x) = \sqrt{x} - \cos x$$

$$f(0) = \sqrt{0} - \cos(0) \quad ; \quad f(1) = \sqrt{1} - \cos(1)$$

$$f(0) = -1 \quad ; \quad f(1) = 0,459697$$

$$P_1 = \frac{x_1 + x_0}{2} = \frac{0+1}{2} = \frac{1}{2}$$

$$f(x) = \sqrt{x} - \cos x$$

$$f(0,5) = \sqrt{0,5} - \cos(0,5)$$

$$f(0,5) \Rightarrow \underline{\underline{-0,17}}$$

Since $f(0)$ and $f(0,5) < 0$ new root is $[P_1, x_1] \Rightarrow [0,5; 1]$

$$P_2 = \frac{1 + 0,5}{2} = \frac{1,5}{2} = 0,75$$

$$f(0,75) = \sqrt{0,75} - \cos(0,75)$$

$$\Rightarrow \underline{\underline{0,13}}$$

Since P_1 and $P_2 < 0$ new root is $[P_1, x_1] \Rightarrow [0,5; 0,75]$

$$P_3 = \frac{0,5 + 0,75}{2} = \underline{\underline{0,625}}$$

b) $f(x) = x^2 - 6 = 0$ Find p_2 with $p_0 = -1$

$$f(x) = x^2 - 6 \quad \therefore p_0 = -1$$

$$f'(x) = 2x$$

$$f'(p_0) = 2(-1) = -2$$

$$-2 \neq 0$$

↓
applicable.

$$p_n = p_{n-1} - \frac{f(p_{n-1})}{f'(p_{n-1})}$$

$$p_1 = -1 - \frac{(-1)^2 - 6}{2(-1)} \Rightarrow -1 - \frac{+5}{-2} = -3,5$$

$$p_2 = -3,5 - \frac{(-3,5)^2 - 6}{2(-3,5)} \Rightarrow -4,392857143$$

$$\underline{\underline{p_2 = -4,39286}}$$

2)

x	$f(x)$
1.3	0.5234
1.6	0.4554
1.9	0.4554

$$x_2 = 1.3, x_3 = 1.6, x_4 = 1.9$$

$$\text{degree I} = p_1(x) = L_0(x)f(x_0) + L_1(x)f(x_1) + \dots$$

$$p_1(x) = \frac{x-x_3}{x_2-x_3} f(x_2) + \frac{x-x_2}{x_3-x_2} f(x_3)$$

$$\Rightarrow \frac{x-1.6}{1.3-1.6} (0.5234) + \frac{x-1.3}{1.6-1.3} (0.4554)$$

$$\Rightarrow -0.548946x + 1.33376$$

$$\text{Since } x=1.5, p_1(1.5) \Rightarrow -0.549(1.5) + 1.33376$$

$$\Rightarrow 0.5103$$

$$\text{degree II} \quad x_2 = 1.3, x_3 = 1.6, x_4 = 1.9$$

$$p_2(x) \Rightarrow \frac{(x-x_3)(x-x_4)}{(x_2-x_3)(x_2-x_4)} f(x_2) + \frac{(x-x_2)(x-x_4)}{(x_3-x_2)(x_3-x_4)} f(x_3) + \frac{(x-x_2)(x-x_3)}{(x_4-x_2)(x_4-x_3)} f(x_4)$$

$$\Rightarrow \frac{(x-1.6)(x-1.9)}{(1.3-1.6)(1.3-1.9)} (0.5234) + \frac{(x-1.3)(x-1.9)}{(1.6-1.3)(1.6-1.9)} (0.4554) + \frac{(x-1.3)(x-1.6)}{(1.9-1.3)(1.9-1.6)} (0.4554)$$

$$\text{Since } x=1.5, p_2(1.5) \Rightarrow \frac{(1.5-1.6)(1.5-1.9)}{(1.3-1.6)(1.3-1.9)} \cdot \dots \cdot 0.2818186$$

$$\Rightarrow \underline{\underline{0.51135}}$$

3)

$$\int_{-2}^2 e^x x^2 dx, n=4$$

The width of each subinterval is

$$\Delta x = h = \frac{b-a}{n} \Rightarrow \frac{2-(-2)}{4} = \frac{4}{4} = 1$$

$$T_4 = \frac{h}{2} [f(x_0) + 2f(x_1) + 2f(x_2) + 2f(x_3) + f(x_4)]$$

$$f(x_0) = f(-2) = e^{(-2)} (-2)^2 \Rightarrow 0,54134113$$

$$f(x_1) = f(-1) = e^{(-1)} (-1)^2 \Rightarrow 0,36787944$$

$$f(x_2) = f(0) = e^{(0)} (0)^2 \Rightarrow 0$$

$$f(x_3) = f(1) = e^{(1)} (1)^2 \Rightarrow 2,71828182$$

$$f(x_4) = f(2) = e^{(2)} (2)^2 \Rightarrow 29,55622439$$

$$T_4 \Rightarrow \frac{1}{2} [0,5413 + 2(0,36788) + 0 + 2(2,71828) + 29,556]$$

$$\Rightarrow \underline{\underline{18,13494402}}$$

4) Jacobi iteration & Gauss-Seidel

$$\begin{bmatrix} 10 & -1 & -1 \\ -1 & 10 & -2 \\ -2 & -1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6,2 \\ 8,5 \\ 3,2 \end{bmatrix}$$

$$10x_1 - x_2 - x_3 = 6,2$$

$$-x_1 + 10x_2 - 2x_3 = 8,5$$

$$-2x_1 - x_2 + 5x_3 = 3,2$$

$$x_1 = \frac{6,2 + x_2 + x_3}{10}$$

$$x_2 = \frac{8,5 + 2x_3 + x_1}{10}$$

$$x_3 = \frac{3,2 + 2x_1 + x_2}{5}$$

initial guess $(x_1, x_2, x_3) = (0, 0, 0)$

$$1^{st} \text{ iteration } x_1^{(1)} = \frac{6,2}{10}, x_2^{(1)} = \frac{8,5}{10}, x_3^{(1)} = \frac{3,2}{5}$$

$$II^{nd} \text{ iteration } x_1^{(2)} = 6,2, x_2^{(2)} = 0,2, x_3^{(2)} = 0,13$$

$$\therefore x_1 = \frac{1}{10} [6,2 + 0,2 + 0,13]$$

$$\Rightarrow \underline{\underline{0,653}}$$

5.

$$\begin{cases} y' = -5y + 5t^2 + 2t & 0 \leq t \leq 1 \\ y(0) = \frac{1}{3} \end{cases}$$

$h = 0,1$
 $n = 1 - 0 = 1$

$$y' = -5y + 5t^2 + 2t$$

t	y	y' = -5y + 5t^2 + 2t	new new y
0,0	1,061	1,00	1,00
0,1	1,10	1,20	1,22
0,2	1,22	1,42	1,36
0,3	1,38	1,66	1,53
0,4	1,53	1,93	0,3456
0,5	1,72	2,22	0,6654
0,6	1,94	2,54	0,47275
0,7	2,19	2,89	0,6321
0,8	2,48	3,29	0,783455
0,9	2,81	3,71	0,9803999
1,0	3,18		

⇒ 0,9803