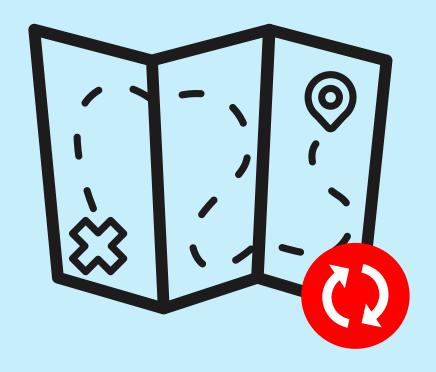
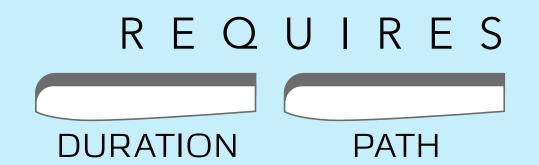


## PACE





Pace back and forth on a path. The drone will wait at each waypoint (on the path) for a specified <u>time interval</u>.

The drone will repeatedly travel the path.