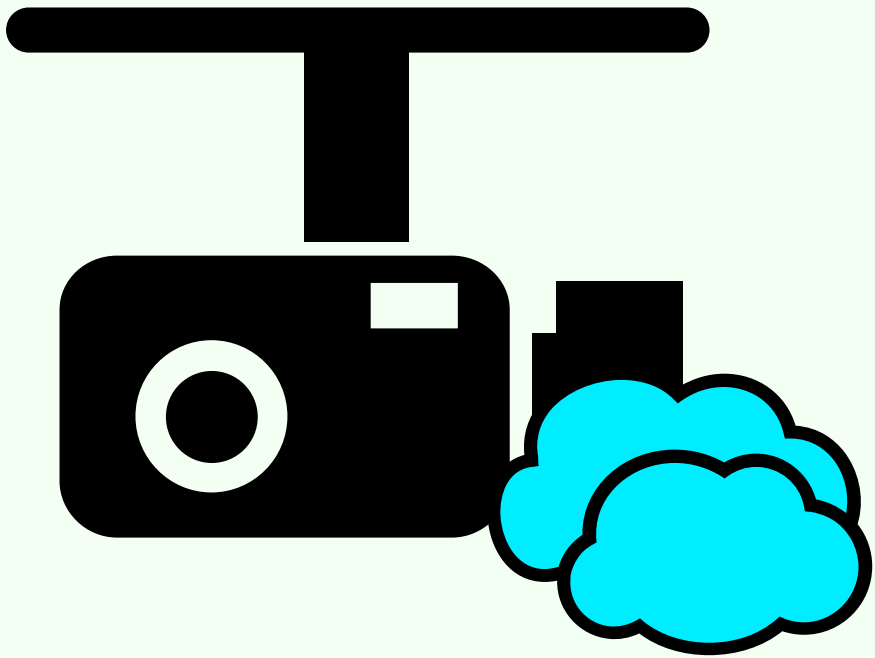


# POINT AT FRONT



Point the gimbal towards the front of the drone.

*The gimbal will attempt to always point towards the front.*