Finding Ben Nevis

Optimization on Great Britain height map

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What's been done so far?

- 1. The pip package nevis
- 2. A benchmark framework for comparing algorithms running on nevis

The objective function

```
import nevis
nevis.download_os_terrain_50() # Download the data when first run
f = nevis.linear_interpolant()
\# z = f(x, y)
# (x, y) is given in metres, z is the altitude of the point
# In case we need the gradient (which is not continuous)...
f_grad = nevis.linear_interpolant(grad=True)
\# z, (gx, gy) = f_grad(x, y)
# the domain of f is [0, x_max] \times [0, y_max]
x_max, y_max = nevis.dimensions()
```

Our task is to maximize f over its domain, and we know the global maximum point is Ben Nevis with height 1345m.

Plotting methods

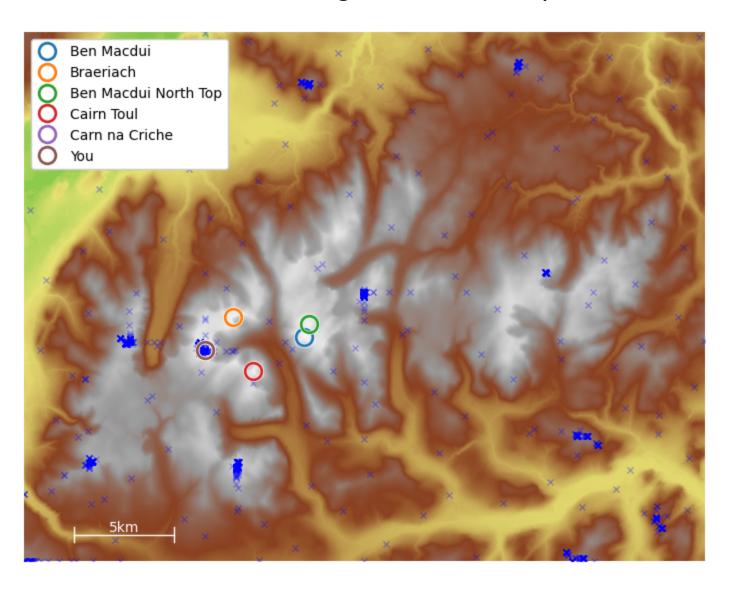
https://github.com/CardiacModelling/BenNevis/blob/main/examples/viewing-gb.ipynb

Subproblem: Cairngorms Mountains

- a region that contains the 2nd to the 6th highest hills of GB
- a simpler problem for global optimizors

Subproblem: Cairngorms Mountains

A run of SHGO on this region that ends up at Carn na Criche, the 6th highest hill of GB

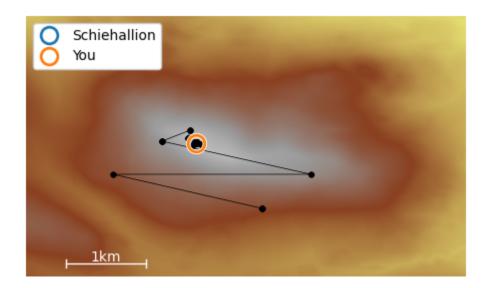


Subproblem: Schiehallion

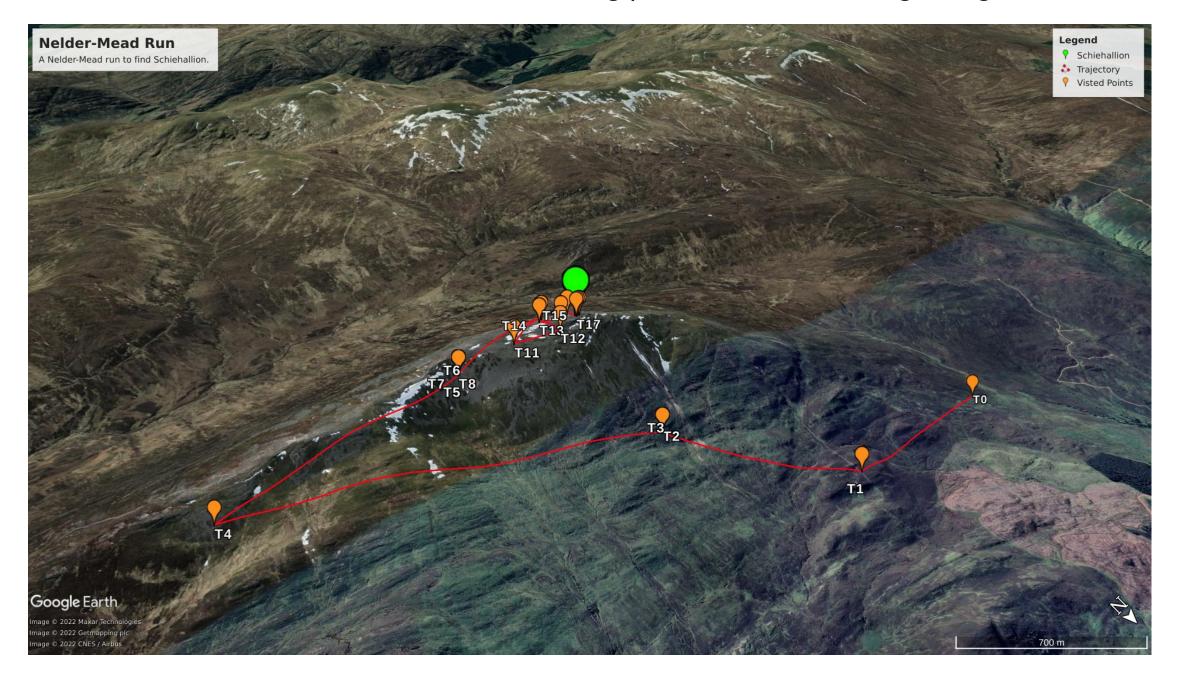
- isolated from other hills & almost symmetric in shape
- can be used to test local optimisors

Subproblem: Schiehallion

A run of Nelder-Mead that successfully finds Schiehallion



Another successful run with a different starting point, visualized using Google Earth



More examples

- Fitting with CMA-ES using PINTS
 - Global optimization on the whole map
- Fitting with Nelder-Mead using SciPy
 - Derivative-free local optimization on Schiehallion
- Fitting with Method of Moving Asymptotes NLopt
 - Gradient-based local optimization on Schiehallion

Benchmark framework

List of algorithms to be considered (not exhaustive)

- Grid Search and Random Search (brutal force)
 - can be used with local optimizers
- CMA-ES [1]
- DIRECT and DIRECT-L Method [2]
- SHGO (simplicial homology global optimization) [3]
 - used with local optimizers
- Simulated Annealing and Dual Annealing [4]
 - can be used with local optimizers
- Local optimizers
 - BFGS
 - Nelder-Mead

Benchmark framework

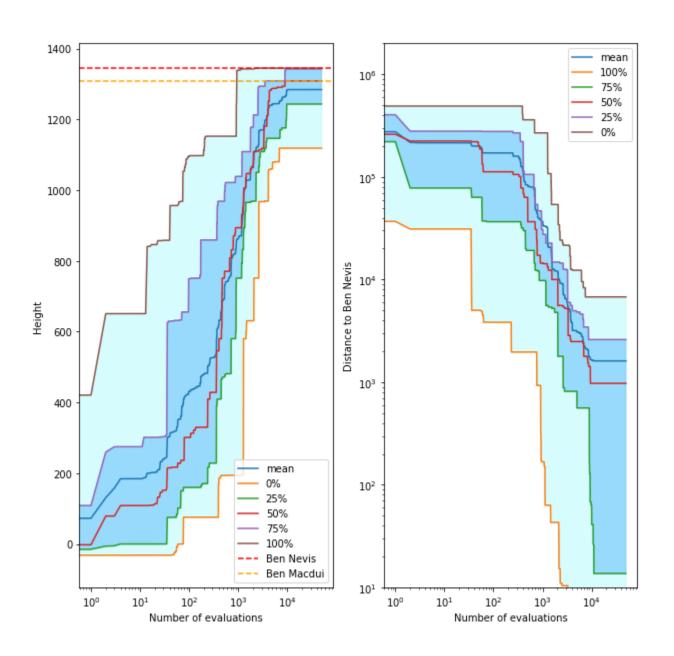
- Problem: which algorithm works the best on finding Ben Nevis?
- In other words, reaching somewhere sufficiently close to Ben Nevis (or somewhere sufficiently high) within a low number of function evaluations
- Two important pre-defined variables
 - $\circ T_{
 m max}$ maximum number of function evaluations allowed for each algorithm
 - \circ f_s only an algorithm run that reaches somewhere higher than this value can be classified as successful
- Two separate objectives
 - \circ a high successful rate r_s : the ratio between the number of successful runs and all runs
 - \circ a low average number of function evaluations for each successful run $ar{T}_s$

Performance measures

- They all somehow combines the two separate objectives
 - \circ "success performance" $ar{T}_s/r_s$ [8]
 - \circ penalized average runtime, which is the average number of function evaluations with the failed runs considered as $kT_{\rm max}$, where k is by convention taken as 2 and 10, and thus we have PAR2 and PAR10
 - \circ dominated hypervolume $r_s(T_{
 m max}-ar{T}_s)$ [9]
 - is correlated to PAR according to [9]
 - \circ expected running time $ar{T}_s + (1-r_s)/r_s T_{
 m max}$ [10]
- ERT seems to be the most appropriate one so far

Performance plots

- Convergence plot: maximum height reached at a certain number of function evaluations [7]
 - data are aggregated (i.e. 0, 25, 50, 75, 100 percentiles and mean and std)
 across multiple runs
 - variant: the percentage of runs that are reach certain heights (e.g. 1000, 1100, 1200, 1300) at a certain number of function evaluations (to-do)



Hyper-parameter tuning

- Some algorithms might have one or more hyper-parameters, e.g. population size for CMA-ES and initial temperature for simulated annealing
- Finding an appropriate set of hyper-parameters is another optimization problem
 - o the goal is to optimize a chosen performance measure, e.g. ERT
- We currently use Random Search for this purpose
 - RS is proved to have equal or better performance for manual or grid search (because often only a small number of hyper-parameters affect the performance) [5]
 - will try Bayesian optimization (said to outperform RS in more complex situations) [6]

Benchmark framework

• An algorithm contains

- o a function that takes hyper-parameters and returns an optimization result
- a hyper-parameter space (the range of values they can take)
- multiple algorithm instances (or one if there is no hyper-parameter)

• An algorithm instance contains

- an algorithm
- a particular set of hyper-parameter
- multiple run results (or one if it is a deterministic algorithm)

• A run result contains

- the found optimization point and value
- a list of all visited points
- a message that explains why the run was terminated

Benchmark framework

A run result can

- be classified as successful or failed
- be visualized using 2D plots or Google Earth
- be saved and loaded

• An algorithm instance can

- run and obtain multiple results
- calculate its performance measure using (the classification of) its run results
- plot its converge graph using its run results

• An algorithm can

 tune its hyper-parameters by generating random algorithm instances and picking the one with the best performance measure

Work flow

```
def run_dual_annealing(**kwargs):
   # ...
    ret = dual_annealing(
        wrapper,
        bounds=[(0, x_max), (0, y_max)],
        maxfun=MAX_FES,
        **kwargs
    return Result(
        ret.x,
        -ret.fun,
        points,
        ret.message,
algo = Algorithm(
    name='Dual Annealing',
    func=run_dual_annealing,
    param_space={
        'maxiter': [1500, 2000, 2500],
        'initial_temp': np.linspace(2e4, 4e4, 1000),
        'restart_temp_ratio': np.logspace(-5, -3, 100),
    },
```

Work flow

```
algo.tune_params(
    measure='ert',
    mode='min'
)
algo_instance = algo.best_instance
print(algo_instance.success_measures())
algo_instance.plot_convergence_graph()
plt.show()
```

taken from here

Summary

- The pip package nevis
 - an objective function which mimics GB terrain using Ordnance Survey data and linear interpolation
 - methods to visualize optimization processes, including plotting global or partial 2D maps and and exporting to Google Earth
 - pre-defined subproblems that are easier to solve or more suitable for testing local optimizors
 - examples of how to apply different optimization algorithms to this problem and visualize them

Summary

- A benchmark framework for comparing algorithms running on nevis
 - a process and several measures and plots to compare the performance of different algorithm instances
 - hyper-parameter tuning using random search
 - o a hierarchy of algorithms, algorithm instances, and run results

To-dos

- More performance plots for algorithm instances, especially plots for comparing different instances
- More algorithms to consider
- Bayesian optimization as a hyper-parameter tuning method
- Applying the benchmark framework to all proposed algorithms in a consistent way and finding out which one is doing the best
- Perhaps explaining the performance of the algorithms on our problem by examining their visualized optimization process

References

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The end

Thank you for listening:-)