

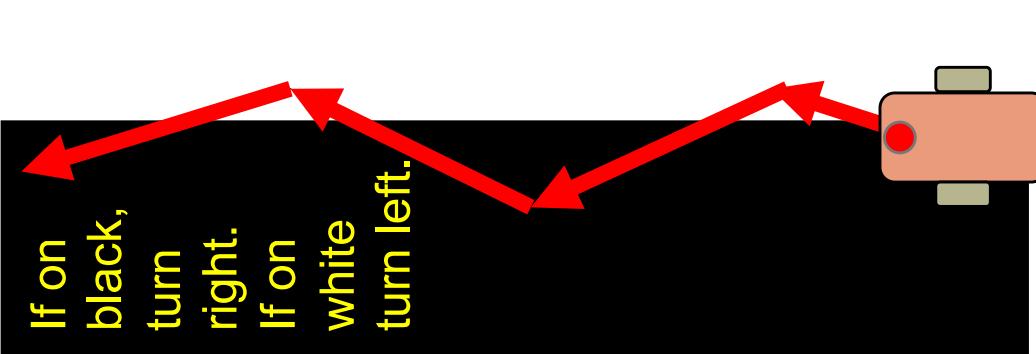
# ROBOT LINE FOLLOWING HAPPENS ON THE EDGES

Left side line following

If on black, turn left.  
If on white turn right.

The robot has to choose which way to turn when the color sensor sees a different color.

If on black, turn right.  
If on white turn left.



Right side line following

The answer depends on what side of the line you are following!

# STARTING THE ROBOT ON THE CORRECT SIDE

