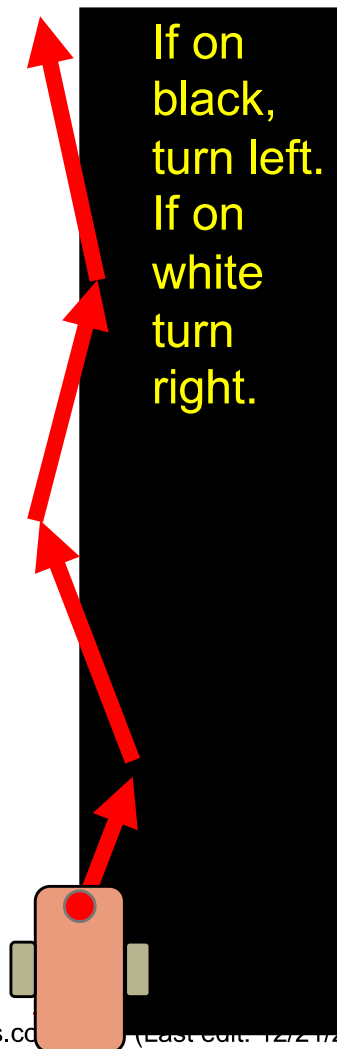


# ROBOT LINE FOLLOWING HAPPENS ON THE EDGES

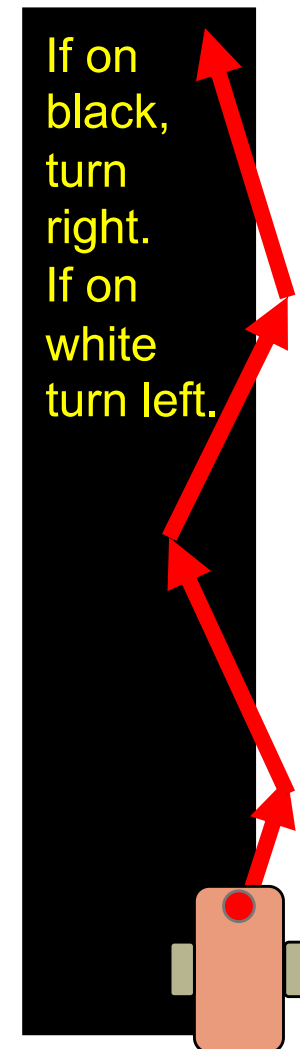
Left side line following

Right side line following



The robot has to  
choose which  
way to turn when  
the color sensor  
sees a different  
color.

The answer  
depends on what  
side of the line  
you are following!



# STARTING THE ROBOT ON THE CORRECT SIDE

