Exerice 1

On sait que la symétrie orthogonal est égal a
$$s = 2p - Id$$

$$p(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) = \frac{\left\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix} | \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix} \right\rangle}{\| \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix}\|} \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix} = \begin{pmatrix} \cos \alpha * \cos \alpha \\ \cos \alpha * \sin \alpha \end{pmatrix}$$

$$p(\begin{pmatrix} 0 \\ 1 \end{pmatrix}) = \frac{\left\langle \begin{pmatrix} 0 \\ 1 \end{pmatrix} | \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix} | \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix} \right\rangle}{\| \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix}\|} \begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix} = \begin{pmatrix} \sin \alpha * \cos \alpha \\ \sin \alpha * \sin \alpha \end{pmatrix}$$

$$P = \begin{pmatrix} \cos^2 \alpha & \cos \alpha \sin \alpha \\ \cos \alpha \sin \alpha & \sin^2 \alpha \end{pmatrix}$$

$$S = 2P - I_2 = 2 \begin{pmatrix} \cos^2 \alpha & \cos \alpha \sin \alpha \\ \cos \alpha \sin \alpha & \sin^2 \alpha \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2\cos^2 \alpha & \cos \alpha \sin \alpha \\ 2\cos \alpha \sin \alpha & \sin^2 \alpha \end{pmatrix}$$

$$= \begin{pmatrix} \cos(2\alpha) & \sin(2\alpha) \\ \sin(2\alpha) & -\cos(2\alpha) \end{pmatrix} \begin{pmatrix} \cos(2\beta) & \sin(2\beta) \\ \sin(2\alpha) & -\cos(2\alpha) \end{pmatrix}$$

$$2) S_{\alpha}S_{\beta} = \begin{pmatrix} \cos(2\alpha) & \sin(2\alpha) \\ \sin(2\alpha) & -\cos(2\alpha) \end{pmatrix} \begin{pmatrix} \cos(2\beta) & \sin(2\beta) \\ \sin(2\beta) & -\cos(2\beta) \end{pmatrix}$$

$$S = 2P - I_2 = 2 \begin{pmatrix} \cos^2 \alpha & \cos \alpha \sin \alpha \\ \cos \alpha \sin \alpha & \sin^2 \alpha \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2\cos^2 \alpha - 1 & 2\cos \alpha \sin \alpha \\ 2\cos \alpha \sin \alpha & 2\sin^2 \alpha - 1 \end{pmatrix}$$

$$= \begin{pmatrix} \cos(2\alpha) & \sin(2\alpha) \\ \sin(2\alpha) & -\cos(2\alpha) \end{pmatrix}$$

$$2) S_{\alpha}S_{\beta} = \begin{pmatrix} \cos(2\alpha) & \sin(2\alpha) \\ \sin(2\alpha) & -\cos(2\alpha) \end{pmatrix} \begin{pmatrix} \cos(2\beta) & \sin(2\beta) \\ \sin(2\beta) & -\cos(2\beta) \end{pmatrix}$$

$$= \begin{pmatrix} \cos(2\alpha)\cos(2\beta) + \sin(2\alpha)\sin(2\beta) & \cos(2\alpha)\sin(2\beta) - \sin(2\alpha)\cos(2\beta) \\ \sin(2\alpha)\cos(2\beta) - \cos(2\alpha)\sin(2\beta) & \sin(2\alpha)\sin(2\beta) + \cos(2\alpha)\cos(2\beta) \end{pmatrix}$$

$$= \begin{pmatrix} \cos(2\alpha - 2\beta) & -\sin(2\alpha - 2\beta) \\ \sin(2\alpha - 2\beta) & \cos(2\alpha - 2\beta) \end{pmatrix}$$
Matrice de rotation d'angle $2(\alpha - \beta) = R_{2(\alpha - \beta)}$

 $S_{\beta}S_{\alpha}$ = Matrice de rotation d'angle $2(\beta - \alpha) = R_{2(\beta - \alpha)}$

- 3) Soit un angle θ on prend $\alpha=\frac{1}{2}\theta$ et $\beta=0$ on a bien que $2(\alpha-\beta)=\theta$ Donc la rotation d'angle θ peut être écris comme $R_{\theta}=S_{\frac{\theta}{2}}S_0$
- 4) Non le groupe O(P) n'est pas commutatif car $S_0S_{\frac{\pi}{4}}=R_{\frac{\pi}{2}}\neq R_{-\frac{\pi}{2}}=S_{\frac{\pi}{4}}S_0$