

# Inference from heterogeneous pairwise data

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## Pairwise inference model

- ▶ Latent variables  $(x_1, \dots, x_N) \in \mathcal{X}^N$ .
- ▶ Observations through **memoryless channel**  $P$  with input alphabet  $\mathcal{X} \times \mathcal{X}$

$$Y_{ij} \stackrel{\text{ind}}{\sim} P(\cdot \mid x_i, x_j), \quad i, j = 1, \dots, N$$

## Spin glasses



### Sherrington-Kirkpatrick model (with planted signal)

$$Y_{ij} \sim \mathcal{N}\left(\sqrt{\frac{\lambda}{N}}x_ix_j, 1\right), \quad \lambda \geq 0, \quad x_i \in \{\pm 1\}$$

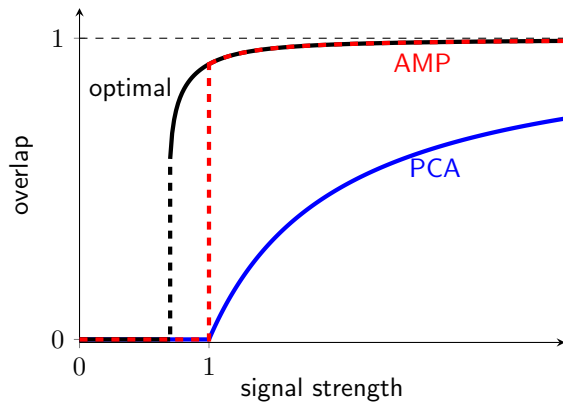
### Stochastic block model

$$Y_{ij} \sim \text{Bern}(Q_{x_i, x_j}), \quad Q \in [0, 1]^{K \times K}, \quad x_i \in \{1, \dots, K\}$$

### Spiked covariance model

$$Y_{ij} \sim \mathcal{N}\left(\sqrt{\frac{\lambda}{N}}\langle u_i, v_j \rangle, 1\right), \quad \lambda \geq 0, \quad u_i, v_j \in \mathbb{R}^r$$

## Statistical & computational limits



## Why mutual information?

$$I(\mathbf{X}; \mathbf{Y}) = D(P_{XY} \parallel P_X \otimes P_Y) = \int dP_{XY} \log \frac{dP_{XY}}{d(P_X \otimes P_Y)}$$

I-MMSE relationship: If  $\mathbf{X} \in \mathbb{R}^{N \times d}$  then

$$\left. \frac{d}{dt} I(\mathbf{X}; \mathbf{Y}, \sqrt{t}\mathbf{X} + \mathbf{Z}) \right|_{t=0} = \mathbb{E}[\|\mathbf{X} - \mathbb{E}[\mathbf{X} | \mathbf{Y}]\|_F^2]$$

where  $\mathbf{Z} \in \mathbb{R}^{N \times d} \perp\!\!\!\perp (\mathbf{X}, \mathbf{Y})$  has IID standard Gaussian entries.

Hence, formula for asymptotic mutual information (with side information) gives formula for asymptotic minimum mean square error almost everywhere\*.

\* Limit is not differentiable at phase transitions

# Channel universality

Classical scaling (fixed  $p$  large  $n$ ) Local asymptotic normality & Fisher information

$$\log \frac{dP_{n,\theta+\epsilon_n u}}{dP_{n,\theta}} \xrightarrow[n \rightarrow \infty]{d} \log \frac{dQ_u}{dQ_0}, \quad \underbrace{Q_u = \mathcal{N}(I_\theta u, I_\theta)}_{\text{Gaussian model}}$$

High-dimensional scaling Korada-Montanari 2011, Deshpande-Abbe-Montanari 2015  
Krzakala-Xu-Zdeborová 2016, Lesieur-Krzakala-Zdeborová 2017, R.-Mayya-Volfovsky 2019  
Guionnet-Ko-Krzakala-Zdeborová 2023

Compare free energy / mutual information for prior distribution  $\pi$  on  $\theta$

$$\left| \mathbb{E}_{P_\theta} \log \int \frac{dP_{n,\theta+r_n u}}{dP_{n,\theta}} \pi(du) - \mathbb{E}_{Q_0} \log \int \frac{dQ_u}{dQ_0} \pi(du) \right| = o(n)$$

- Gaussian comparison holds for dense SBM but not for sparse SBM

# Model for Today's talk

- ▶ Assume  $\mathcal{X}$  is (or can be embedded into) a subset of  $\mathbb{R}^d$ . ( $d$  is fixed)
- ▶  $\mathbf{X} = (x_1, \dots, x_N)^\top$  is  $N \times d$  matrix with IID rows & finite fourth moments.

Family of channels  $(P_N)_{N \in \mathbb{N}}$ . Approximate by **linear Gaussian model**

$$P_N(\cdot \mid x_i, x_j) \approx \mathcal{N}\left(\sqrt{\frac{1}{N}} B^\top (x_i \otimes x_j), \mathbf{I}_L\right), \quad B \in \mathbb{R}^{d^2 \times L}$$

- ▶ Includes bounded degree polynomials in Gaussian noise via lifting

$$f(\theta_i, \theta_j) = b^\top (x_i \otimes x_j), \quad x_i = (1, \theta_i, \theta_i^2, \dots, \theta_i^{d-1})^\top$$

- ▶ Includes groupwise heteroskedasticity via augmentation

$$x_i = \underbrace{(0, \dots, \theta_i, \dots, 0)^\top}_{\text{position indexed by group}}$$



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## Entropy / free energy with IID prior

- ▶ Rows of  $\mathbf{X} \in \mathbb{R}^{n \times d}$  are IID copies of  $X_0 \in \mathbb{R}^d$  with finite fourth moments.

$$D(\mathbf{Y} \parallel \mathbf{Z}) = \underbrace{\mathbb{E} \left[ \log \int e^{\langle \mathbf{x}^{\otimes 2} B, \mathbf{Y} \rangle - \frac{1}{2} \|\mathbf{x}^{\otimes 2} B\|_F^2} P_0^{\otimes N}(d\mathbf{x}) \right]}_{\text{original problem is } N \times d}, \quad \mathbf{Y} = \mathbf{X}^{\otimes 2} B + \mathbf{Z}$$

- ▶ Entropy function  $\mathcal{D}: \mathbb{S}_+^d \rightarrow [0, \infty)$  defined by

$$\begin{aligned} \mathcal{D}(R) &:= D(R^{1/2} X_0 + Z_0 \parallel Z_0), \\ &= \underbrace{\mathbb{E} \left[ \log \int e^{\langle x, R X_0 + Z_0 \rangle - \frac{1}{2} x^\top R x} P_0(dx) \right]}_{\text{easy problem is } d \times 1}, \quad X_0 \perp\!\!\!\perp Z_0 \sim \mathcal{N}(0, I_d) \end{aligned}$$

# Symmetric spiked matrix model

$$\mathbf{Y} = \sqrt{\frac{\lambda}{N}} \mathbf{X} \mathbf{X}^\top + \mathbf{G} \sim \text{GOE}$$

$$\frac{1}{N} D(\mathbf{Y} \parallel \mathbf{G}) \xrightarrow{N \rightarrow \infty} \max_{Q \in \mathbb{S}_+^d} \left\{ \mathcal{D}(Q) - \frac{1}{4\lambda} \text{tr}(Q^2) \right\}$$

- ▶ Rank-one: [Deshpande et al. 2015](#), [Krzakala-Xu 2016](#), [Barbier et al. 2016](#)
- ▶ finite rank: [Lelarge, Miolane 2017](#)

## Asymmetric spiked matrix model

The diagram illustrates the asymmetric spiked matrix model equation. On the left is a gray square representing the matrix  $\mathbf{Y}$ . To its right is an equals sign followed by a square root term  $\sqrt{\frac{\lambda}{N}}$ . This is followed by a blue vertical rectangle representing the matrix  $\mathbf{U}$ , then a blue horizontal rectangle representing the matrix  $\mathbf{V}^\top$ . To the right of these is a plus sign, followed by a blue square representing the matrix  $\mathbf{Z}$ . Above the  $\mathbf{Z}$  square is the text  $\stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$ .

$$\mathbf{Y} = \sqrt{\frac{\lambda}{N}} \mathbf{U} \mathbf{V}^\top + \mathbf{Z} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$$

$$\frac{1}{N} D(\mathbf{Y} \parallel \mathbf{Z}) \xrightarrow{N \rightarrow \infty} \max_{Q_1 \in \mathbb{S}_+^d} \min_{Q_2 \in \mathbb{S}_+^d} \left\{ \mathcal{D}_1(Q_2) + \mathcal{D}_2(Q_1) - \frac{1}{2\lambda} \text{tr}(Q_1 Q_2) \right\}$$

- ▶ Rank-one: [Barbier et al. 2017](#)
- ▶ finite rank: [Miolane 2017](#)

# Spiked matrix model with coupling matrix

$$\mathbf{Y} = \sqrt{\frac{1}{N}} \mathbf{X} \mathbf{B} \mathbf{X}^T + \mathbf{Z}$$

- ▶ Deterministic coupling matrix  $B \in \mathbb{R}^{d \times d}$
- ▶ Stochastic block model with general interactions [R.-Mayya-Volvosky 2019](#)

Includes previous models as special cases:

- ▶ Symmetric spiked model  $\iff B$  is positive (or negative) semidefinite
- ▶ Asymmetric spiked model  $\iff$  augmentation + asymmetric  $B$

# Multiview spiked matrix model

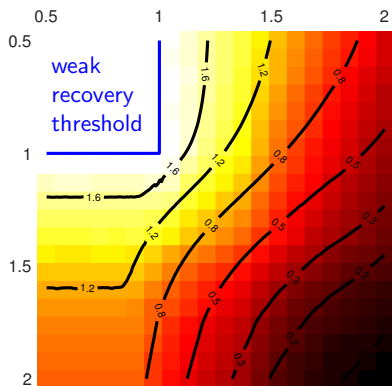
The diagram illustrates the Multiview spiked matrix model equation for  $\ell = 1, \dots, L$ . It shows a gray square matrix  $Y_\ell$  on the left, followed by an equals sign and a scalar factor  $\sqrt{\frac{1}{N}}$ . This is followed by a product of three matrices: a tall light blue rectangle  $X$ , a small gray square  $B_\ell$ , and a wide light blue rectangle  $X^T$ . To the right of this product is a plus sign and a light blue square matrix  $Z_\ell$ . The entire equation is labeled with  $\ell = 1, \dots, L$  on the far right.

$$Y_\ell = \sqrt{\frac{1}{N}} X B_\ell X^T + Z_\ell \quad \ell = 1, \dots, L$$

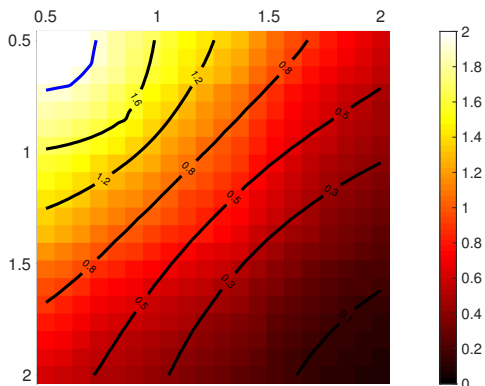
- ▶ Applied to community detection with [correlated networks](#) by [Mayya-R. 2019](#) who proved **lower bound** on the asymptotic free energy.
- ▶ Matching **upper bound** by [Barbier-R. 2020](#) under [structural assumption](#)

$$\sum_{\ell=1}^L \{ (B_\ell \otimes B_\ell) + (B_\ell \otimes B_\ell)^\top \} \succeq 0.$$

## Community detection with correlated networks [Mayya-R. 2019]



one network ( $L = 1$ )



two networks ( $L = 2$ )

Asymptotic MMSE (contour lines) vs. empirical MSE of BP (heat map). Networks have  $N = 10^5$  nodes, 3 communities, and average degree 30. Axes are eigenvalues of first coupling matrix.

Assumption on the coupling matrices in [Barbier-R. 2020] is restrictive

$$\sum_{\ell=1}^L \{(B_{\ell} \otimes B_{\ell}) + (B_{\ell} \otimes B_{\ell})^{\top}\} \succeq 0.$$

- ▶ Cannot apply to asymmetric model or directed networks
- ▶ Formula for asymptotic MMSE is incorrect if assumption is violated.

Is there a universal formula that holds for arbitrary coupling matrices?



# Matrix tensor product model

$$\mathbf{Y} = \frac{1}{\sqrt{N}}(\mathbf{X} \otimes \mathbf{X})\mathbf{B} + \mathbf{Z}$$

- ▶  $\mathbf{X} \otimes \mathbf{X}$  is  $N^2 \times d^2$  Kronecker product
- ▶  $\mathbf{B}$  is  $d^2 \times L$  coupling matrix
- ▶ Equivalent to multiview model with matrices  $B_1, \dots, B_L$  via

$$\mathbf{B} = [\text{vec}(B_1) \quad \dots \quad \text{vec}(B_L)]$$

**Theorem [R. 2020]** For any coupling matrix  $\mathbf{B}$ ,

$$\frac{1}{N}D(\mathbf{Y} \parallel \mathbf{Z}) \xrightarrow{N \rightarrow \infty} \max_{Q \in \mathbb{S}_+^d} \inf_{R \in \mathbb{S}_+^d} \left\{ \mathcal{D}(R) + \frac{1}{2} \text{tr}(\mathbf{B}\mathbf{B}^\top (Q \otimes Q)) - \frac{1}{2} \text{tr}(RQ) \right\}$$

Bound on convergence rate is  $O(d^4 N^{-1/5})$ .

## Relation with previous work

- Structural assumption in [Barbier, R. 2020] is equivalent to **convexity** of

$$Q \mapsto \text{tr}(BB^\top(Q \otimes Q))$$

- If convexity holds, then max-min formula reduces to simplified max formula

$$\begin{aligned} \max_{Q \in \mathbb{S}_+^d} \inf_{R \in \mathbb{S}_+^d} \left\{ \mathcal{D}(R) + \frac{1}{2} \text{tr}(BB^\top(Q \otimes Q)) - \frac{1}{2} \text{tr}(RQ) \right\} \\ = \max_{Q \in \mathbb{S}_+^d} \left\{ \mathcal{D}(T(Q)) - \frac{1}{2} \text{tr}(BB^\top(Q \otimes Q)) \right\} \end{aligned}$$

where  $T: \mathbb{S}^d \rightarrow \mathbb{S}^d$  is self-adjoint linear operator defined by  $B$ .

## Why this formula?

Augmented model: Given  $(R, S) \in \mathbb{S}^d \times \mathbb{S}^{d^2}$  define

$$\mathbf{Y} = \begin{cases} \frac{1}{\sqrt{N}} \mathbf{X}^{\otimes 2} S^{1/2} + \mathbf{Z}, & \text{MTP model} \\ \mathbf{X} R^{1/2} + \mathbf{Z}' & \text{linear Gaussian model} \end{cases}$$

$$\mathcal{D}_N(R, S) := \frac{1}{N} D(\mathbf{Y} \parallel \text{IID Gaussian})$$

Overlap concentration implies matching of derivatives

$$2\nabla_S \mathcal{D}_N = \mathbb{E}\left[\left(\frac{1}{N} \mathbf{X}^\top \tilde{\mathbf{X}}\right)^{\otimes 2}\right] \approx \left(\mathbb{E}\left[\frac{1}{N} \mathbf{X}^\top \tilde{\mathbf{X}}\right]\right)^{\otimes 2} = (2\nabla_R \mathcal{D}_N)^{\otimes 2}$$

## Heuristic derivation (assuming overlap concentration)

$$\mathcal{D}_N^*(Q, S) := \sup_R \underbrace{\left\{ \frac{1}{2} \langle R, Q \rangle - \mathcal{D}_N(R, S) \right\}}_{\text{convex conjugate in 1st arg.}}$$

$$\nabla_S \mathcal{D}_N^*(Q, S) = -\nabla_S \mathcal{D}(R^*(Q), S) \stackrel{\text{overlap conc.}}{\approx} -2(\nabla_R \mathcal{D}(R^*(Q), S))^{\otimes 2} = -\frac{1}{2} Q^{\otimes 2}$$

$$\mathcal{D}_N^*(Q, S) \approx \mathcal{D}_N^*(Q, 0) - \frac{1}{2} \langle S, Q^{\otimes 2} \rangle \quad (\star)$$

$$\begin{aligned} \underbrace{\mathcal{D}_N(0, S)}_{\text{original problem}} &= \sup_Q \underbrace{\{ \langle 0, Q \rangle - \mathcal{D}^*(Q, S) \}}_{\text{biconjugate in 1st arg.}} \stackrel{(\star)}{\approx} \sup_Q \left\{ \langle 0, Q \rangle - \mathcal{D}^*(Q, 0) + \frac{1}{2} \langle S, Q^{\otimes 2} \rangle \right\} \\ &= \sup_Q \inf_R \left\{ \mathcal{D}(R) + \frac{1}{2} \langle S, Q^{\otimes 2} \rangle - \langle R, Q \rangle \right\} \end{aligned}$$

# Main ideas in proof

- ▶ Start with adaptive interpolation method [Barbier-Macris 2018]
- ▶ Lack of convexity complicates specification of adaptive path
- ▶ Rely heavily on order-preserving properties of overlap in Gaussian noise.
- ▶ Introduce continuous time variance inequality linking free energy and overlap.

## Higher order tensor products?

$$\mathbf{Y} = \frac{1}{\sqrt{N^{p-1}}} \mathbf{X}^{\otimes p} B + \mathbf{Z}$$

Applying result for  $p = 2$  [recursively](#) suggests following formula

$$\frac{1}{N} D(\mathbf{Y} \parallel \mathbf{Z}) \xrightarrow{N \rightarrow \infty} \max_{Q \in \mathbb{S}_+^d} \min_{R \in \mathbb{S}_+^d} \left\{ \mathcal{D}_0(R) + \frac{1}{2} \langle BB^\top, Q^{\otimes p} \rangle - \frac{1}{2} \langle R, Q \rangle \right\}$$

This formula proved via Hamilton–Jacobi equations by [Chen-Mourrat-Xia 2021](#)

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Pairwise observations through channel  $P$  with input alphabet  $\mathcal{X} \times \mathcal{X}$

$$Y_{ij} \stackrel{\text{ind}}{\sim} P(\cdot \mid x_i, x_j), \quad i, j = 1, \dots, N$$

- ▶ What if there are different types of variables?
- ▶ What if the observations depend on the variable type?



# Groupwise spiked matrix model

- ▶ Latent variables partitioned in  $K$  groups.
- ▶ Obtain pairwise observations for each group

$$\mathbf{Y}_{k\ell} = \sqrt{\frac{\lambda_{k\ell}}{N}} \mathbf{X}_k \mathbf{X}_\ell^\top + \mathbf{Z}_{k\ell}, \quad k, \ell = 1, \dots, K$$

where  $\mathbf{X}_k$  is  $n_k \times 1$  vector of variables in  $k$ -th group.

**Theorem** [Behne-R. 2022] If  $n_k/N \rightarrow \beta_k > 0$  and  $k$ -th group IID  $P_k$ ,

$$\frac{1}{N} D(\mathbf{Y} \parallel \mathbf{Z}) \xrightarrow{N \rightarrow \infty} \max_{q \succeq 0} \inf_{r \succeq 0} \left\{ \sum_{k=1}^K \mathcal{D}_k(r_k) + \frac{1}{2} \sum_{k,\ell=1}^K \lambda_{k\ell} q_k q_\ell - \frac{1}{2} r^\top q \right\}$$

- ▶ Related recent work by Guionnet-Ko-Krzakala-Zdeborová

## Special cases depend on which interactions are observed

$$\Lambda = \begin{pmatrix} \lambda_{11} & \dots & \lambda_{1K} \\ \vdots & & \vdots \\ \lambda_{K1} & \dots & \lambda_{KK} \end{pmatrix}$$

- ▶ One nonzero (diagonal)  $\implies$  symmetric spiked matrix model
- ▶ One nonzero (off-diagonal)  $\implies$  asymmetric spiked matrix model
- ▶ Off-diagonal row  $\implies$  generalized spiked covariance model [Bai-Yao 2012]
- ▶ Two nonzeros (one diagonal, one off-diagonal)  $\implies$  Gaussian version of the contextual stochastic block model (SBM) [Deshpande-Montanari-Mossel-Sen 2018]
- ▶ Family of doubly stochastic Toeplitz matrices  $\implies$  Proof technique called spatial coupling. Used to study spiked Wigner model [Barbier et al. 2018]
- ▶ Tri-diagonal matrix  $\implies$  Used to analyze free energy in deep Boltzmann machine with  $K$  layers [Alberici et al. 2021]

# Implications for weighted PCA

- **Heteroskedastic spiked covariance model:** Samples from  $p$ -variate Gaussian with covariance

$$\Sigma = \sqrt{\frac{\lambda}{N}} \mathbf{x} \mathbf{x}^\top + \underbrace{\Sigma_0}_{\text{diagonal}}$$

- Overlap of **optimally weighted PCA** when diagonal entries of  $\Sigma_0$  are supported on a finite set  $\{\sigma_1^2, \dots, \sigma_L^2\}$ , [Hong et al. 2018](#)

$$\frac{\langle \mathbf{x}, \hat{\mathbf{x}} \rangle^2}{\|\mathbf{x}\|^2 \|\hat{\mathbf{x}}\|^2} \xrightarrow[n \rightarrow \infty]{\text{a.s.}} \text{largest real root of } R(z) := 1 - \sum_{\ell=1}^L \frac{\beta_\ell}{\sigma_\ell^2} \frac{1-z}{\sigma_\ell^2 + z}$$

**Theorem** [[Behne-R. 2022](#)]

The weighted PCA method of [Hong et al. 2018](#) is information-theoretically optimal for a spherical spike.

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Joint with with Riccardo Rossetti



# AMP for low-rank + IID Gaussian noise

$$\mathbf{Y} = \frac{1}{n} \mathbf{X} \mathbf{X}^\top + \frac{1}{\sqrt{n}} \text{GOE}$$

- ▶ Low-rank [Lesieur-Krzakala-Zdeborová 2017, Montanari-Venkataramanan 2021](#)
- ▶ Non-separable denoisers [Berthier-Montanari-Nguyen 2020](#)

Matrix-valued AMP with non-separable denoisers: [Gerbelot-Berthier 2021](#)

- ▶ Sequence of Lipschitz denoisers:  $f_t: \mathbb{R}^{N \times d} \rightarrow \mathbb{R}^{N \times d}$
- ▶ Initialize  $\mathbf{X}_0 \in \mathbb{R}^{N \times d}$  and iterate

$$\mathbf{M}_t = f_t(\mathbf{X}_t), \quad \mathbf{D}_t = \frac{1}{N} \sum_{i=1}^N \frac{\partial f_{ti}}{\partial \mathbf{x}_{ti}}(\mathbf{X}_t)$$

$$\mathbf{X}_{t+1} = \mathbf{Y} \mathbf{M}_t - \mathbf{M}_{t-1} \mathbf{D}_t$$

# State evolution with non-separable denoisers

**State Evolution:** Define  $\mathbf{X}_t^* \sim \mathcal{N}(\mathbf{X} K_t, \Sigma_t \otimes \mathbf{I}_N)$  recursively via

$$\begin{aligned} K_0 &= \frac{1}{n} \mathbb{E}[\mathbf{X}^\top f_0(\mathbf{X}_0)], & \Sigma_0 &= \frac{1}{n} \mathbb{E}[f_0(\mathbf{X}_0)^\top f_0(\mathbf{X}_0)] \\ K_{t+1} &= \frac{1}{n} \mathbb{E}[\mathbf{X}^\top f_t(\mathbf{X}_t^*)], & \Sigma_{t+1} &= \frac{1}{n} \mathbb{E}[f_t(\mathbf{X}_t^*)^\top f_t(\mathbf{X}_t^*)] \end{aligned}$$

**Theorem:** Gerbelot-Berthier 2021 Under regularity conditions, for all uniformly pseudo-Lipschitz  $\phi_N: \mathbb{R}^{N \times d} \rightarrow \mathbb{R}$

$$\left| \phi_N(\underbrace{\mathbf{X}, \mathbf{X}_0, \dots, \mathbf{X}_t}_{\text{amp iterations}}) - \mathbb{E} \phi_N(\underbrace{\mathbf{X}, \mathbf{X}_0^*, \dots, \mathbf{X}_t^*}_{\text{state evolution}}) \right| \xrightarrow[N \rightarrow \infty]{\text{pr}} 0$$

## AMP for MTP model

$$\mathbf{Y}_\ell = \frac{1}{n} \mathbf{X} B_\ell \mathbf{X}^\top + \frac{1}{\sqrt{n}} \mathbf{Z}_\ell, \quad \ell = 1, \dots, L$$

AMP for MTP: Rossetti-R.

- ▶ Sequence of Lipschitz denoisers:  $f_t: \mathbb{R}^{n \times d} \rightarrow \mathbb{R}^{n \times d}$ ,
- ▶ Initialize  $\mathbf{X}_0 \in \mathbb{R}^{n \times d}$  and iterate

$$\mathbf{M}_t = f_t(\mathbf{X}_t) \quad \mathbf{D}_t = \frac{1}{n} \sum_{i=1}^n \frac{\partial f_{ti}}{\partial \mathbf{x}_{ti}}(\mathbf{X}_t)$$

$$\mathbf{X}_{t+1} = \sum_{\ell=1}^L \mathbf{Y}_\ell \mathbf{M}_t \mathbf{A}_{t\ell}^\top + \mathbf{Y}_\ell^\top \mathbf{M}_t \mathbf{A}_{t\ell} - \mathbf{M}_{t-1} (\mathbf{A}_{t\ell} \mathbf{D}_t \mathbf{A}_{t\ell}^\top + \mathbf{A}_{t\ell}^\top \mathbf{D}_t \mathbf{A}_{t\ell})$$

**Theorem:** Optimal reweighting  $\iff \mathbf{A}_{t\ell} = \mathbf{B}_\ell$  for all  $\ell, t$ .



# State evolution under optimal reweighting

**State Evolution:** Define  $\mathbf{X}_t^* \sim \mathcal{N}(\mathbf{X}K_t, \Sigma_t \otimes \mathbf{I}_n)$  recursively via

$$\begin{aligned} K_0 &= \frac{1}{n} \mathbf{X}^\top f_0(\mathbf{X}_0), & \Sigma_0 &= \frac{1}{n} f_0(\mathbf{X}_0^\top) f_0(\mathbf{X}_0) \\ K_{t+1} &= \mathbf{T}\left(\frac{1}{n} \mathbb{E}[\mathbf{X}^\top f_t(\mathbf{X}_t^*)]\right), & \Sigma_{t+1} &= \mathbf{T}\left(\frac{1}{n} \mathbb{E}[f_t(\mathbf{X}_t^*)^\top f_t(\mathbf{X}_t^*)]\right) \end{aligned}$$

$$\mathbf{T}(S) = \sum_{\ell} B_{\ell} S B_{\ell}^\top + B_{\ell}^\top S B_{\ell}$$

Linear operator  $\mathbf{T}: \mathbb{R}^{d \times d} \rightarrow \mathbb{R}^{d \times d}$  is **self-adjoint** and **completely positive**

**Theorem:** SE for Bayes-optimal AMP defined by  $\mathbb{S}_+^d$ -valued recursion

$$S_{t+1} = \mathbf{T}(2\nabla \mathcal{D}(S))$$

**Fixed-points**  $\iff$  **Stationary point of IT potential**

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- ▶ G. Reeves, Information-theoretic limits for the matrix tensor product, *IEEE Journal on Selected Areas in Information Theory*, 2020
- ▶ J. K. Behne and G. Reeves, Fundamental limits for rank-one matrix estimation with groupwise heteroskedasticity, *AISTATS*, 2023
- ▶ R. Rossetti and G. Reeves, Heteroskedastic Low-rank Matrix Factorization [Arxiv, 2023] [See poster this evening](#)

# Summary and future directions

## Pairwise inference model

$$Y_{ij} \stackrel{\text{ind}}{\sim} P_N(\cdot \mid x_i, x_j), \quad i, j = 1, \dots, N$$

## MTP model

$$P_N(\cdot \mid x_i, x_j) \approx \mathcal{N}\left(\sqrt{\frac{1}{N}} B^\top (x_i \otimes x_j), \mathbf{I}_L\right), \quad B \in \mathbb{R}^{d^2 \times L}$$

## Further directions

- ▶ Weak recovery / BBP phase transitions
- ▶ Non-Gaussian observations + channel universality
- ▶ Spectral methods
- ▶ Coupling matrices are unknown, mismatched estimation
- ▶ Extrinsic rank, higher-order interactions