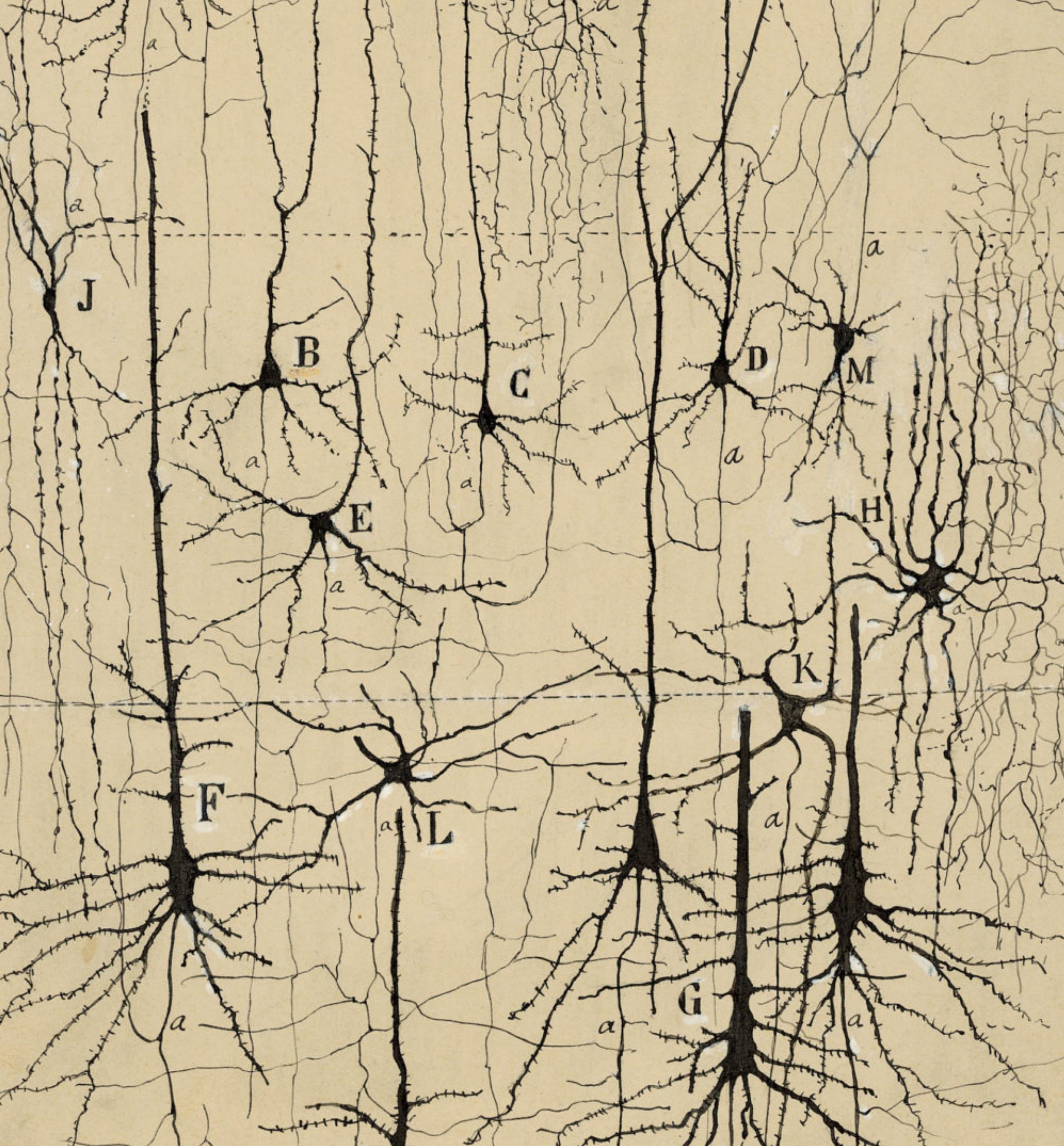




# Propagation-of-Chaos in Shallow NNs beyond Logarithmic time

Margalit Glasgow  
Denny Wu  
Joan Bruna



# Joint Work with



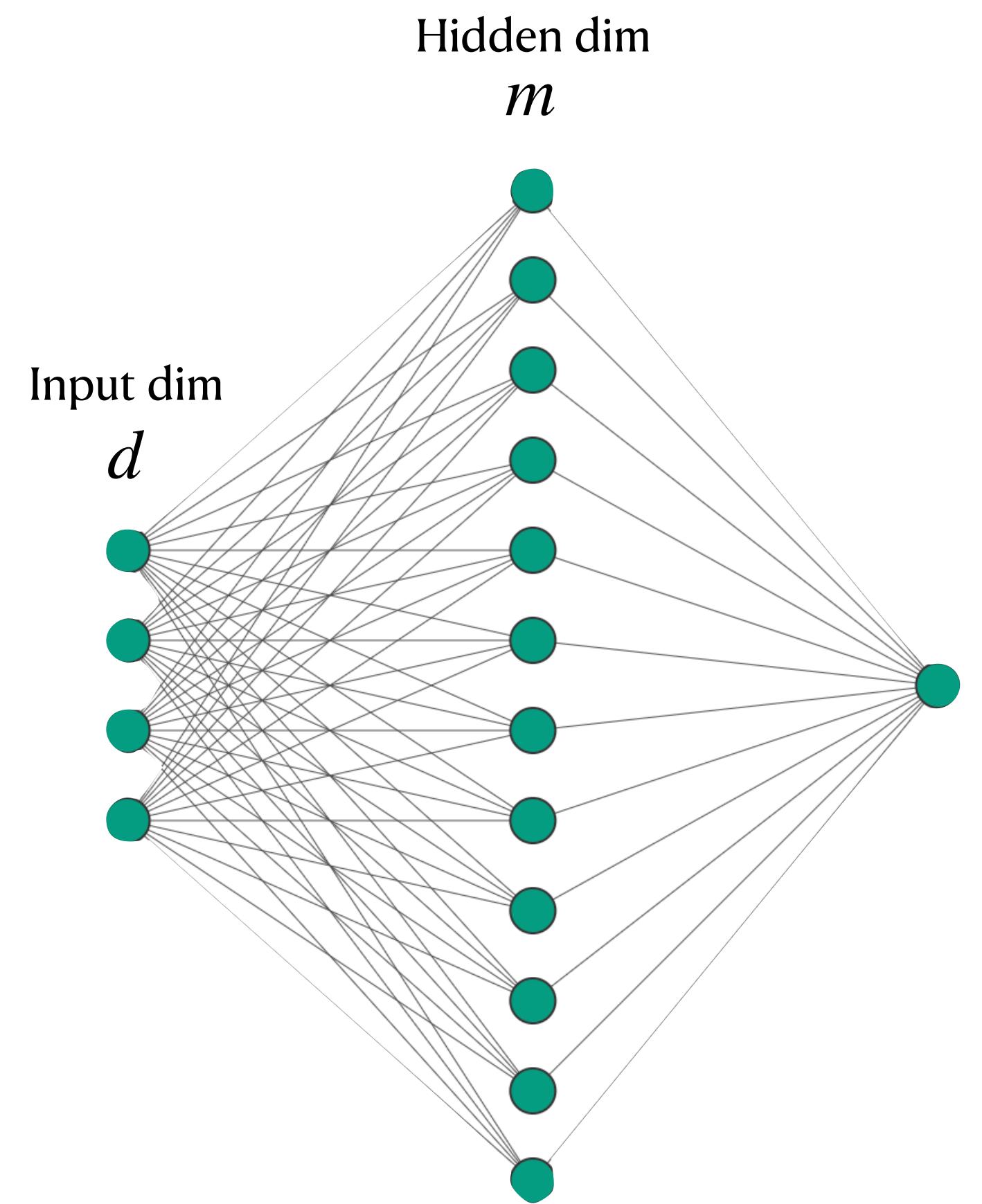
Margalit Glasgow  
(MIT)



Denny Wu  
(NYU/Flatiron)

# Overparametrized Shallow Nets

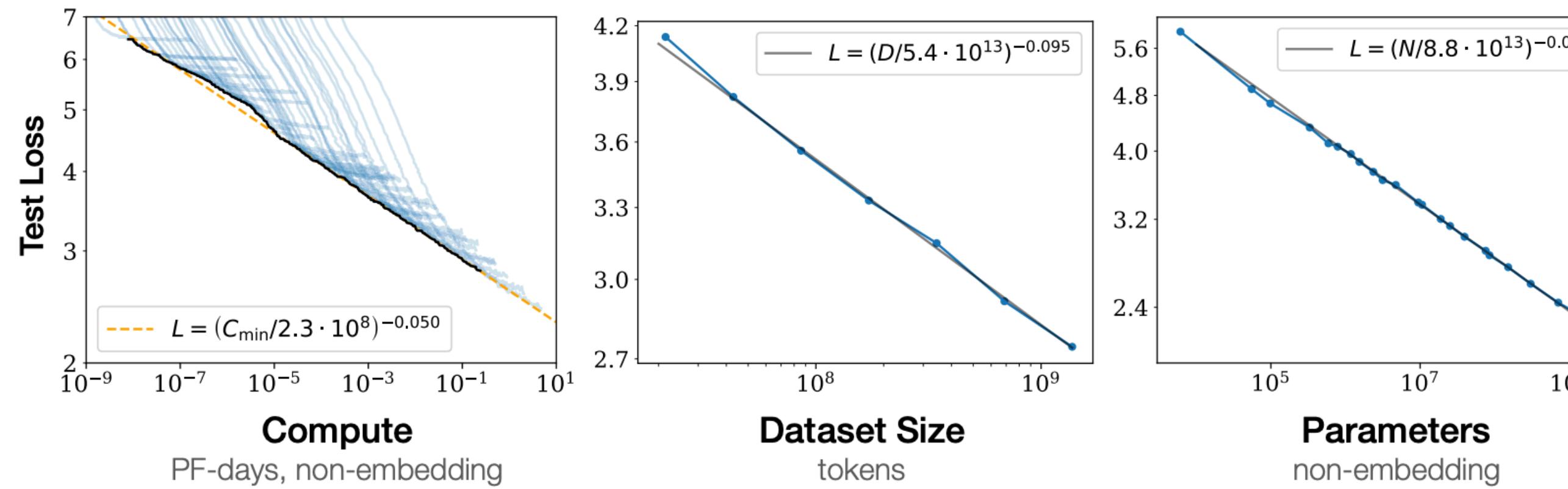
- Simplest non-linear model enabling feature learning.
- Approximation and statistical advantage over linear methods [Barron'90s, Bach'17].



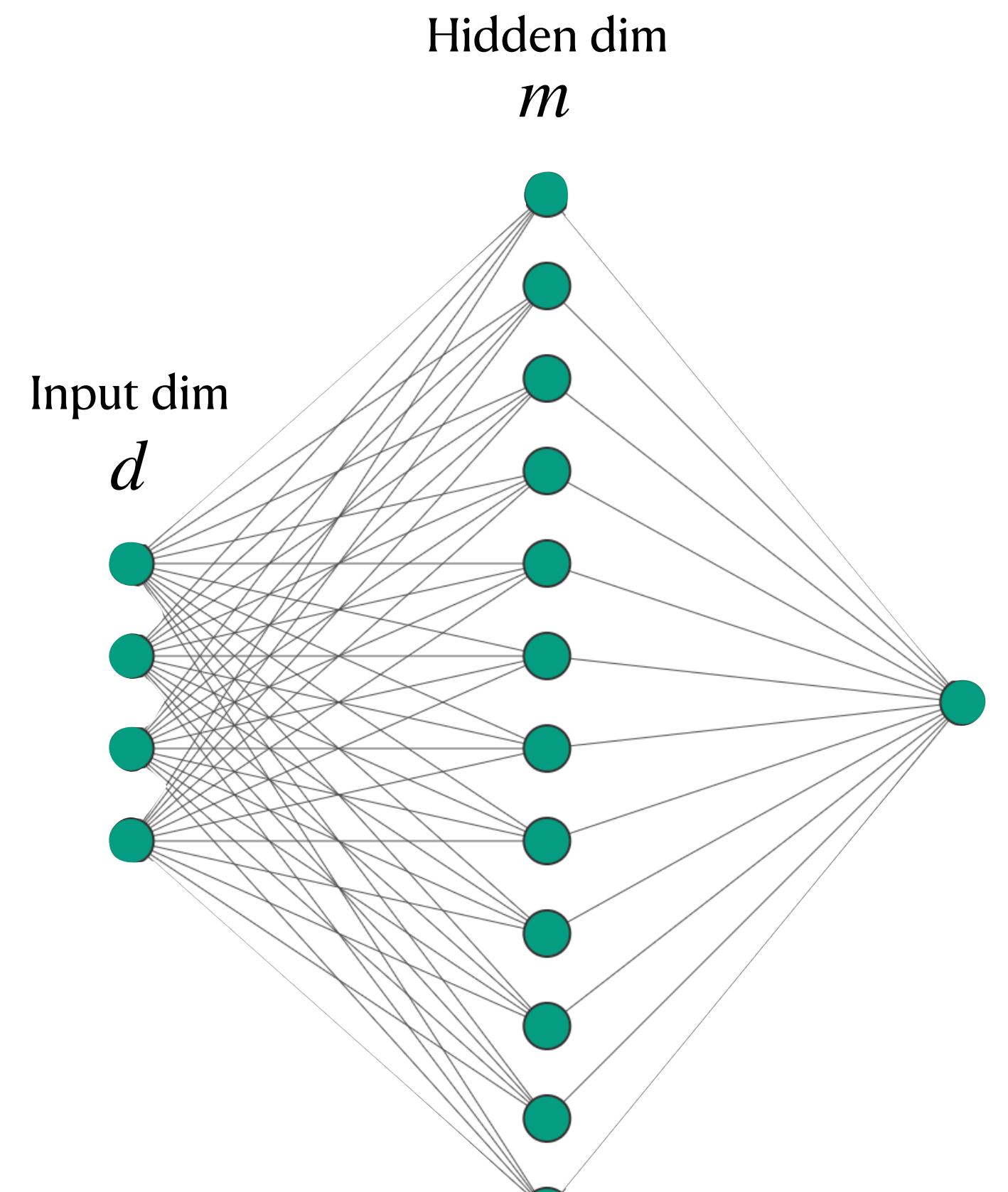
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- Approximation and statistical advantage over linear methods [Barron'90s, Bach'17].
- *Folklore*: Wide NNs provide best learning tradeoffs in practice [Neyshabour et al, Yang, Hanin, Bartlett, many more]



[Kaplan et al]



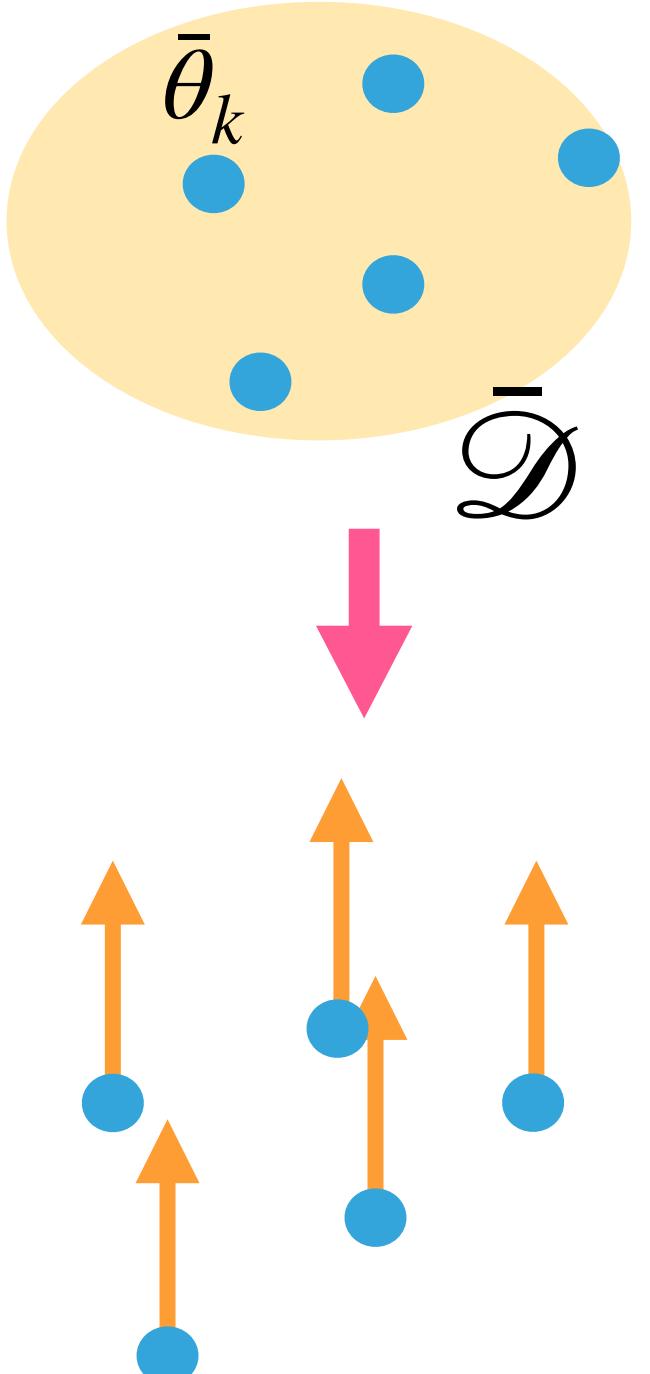
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# Eulerian view of Shallow NNs

[Bach, Rosset et al. Chizat et al., Nitanda et al, Mei et al, Rotskoff&EVE, Kurkova et al]

- Rewrite model  $f(x) = \frac{1}{m} \sum_{j=1}^m \rho(x, \bar{\theta}_j) = \int_{\mathcal{D}} \rho(x, \bar{\theta}) d\nu^{(m)}(\bar{\theta}) := f_\nu(x)$

Squared-loss: System of **interacting** particles



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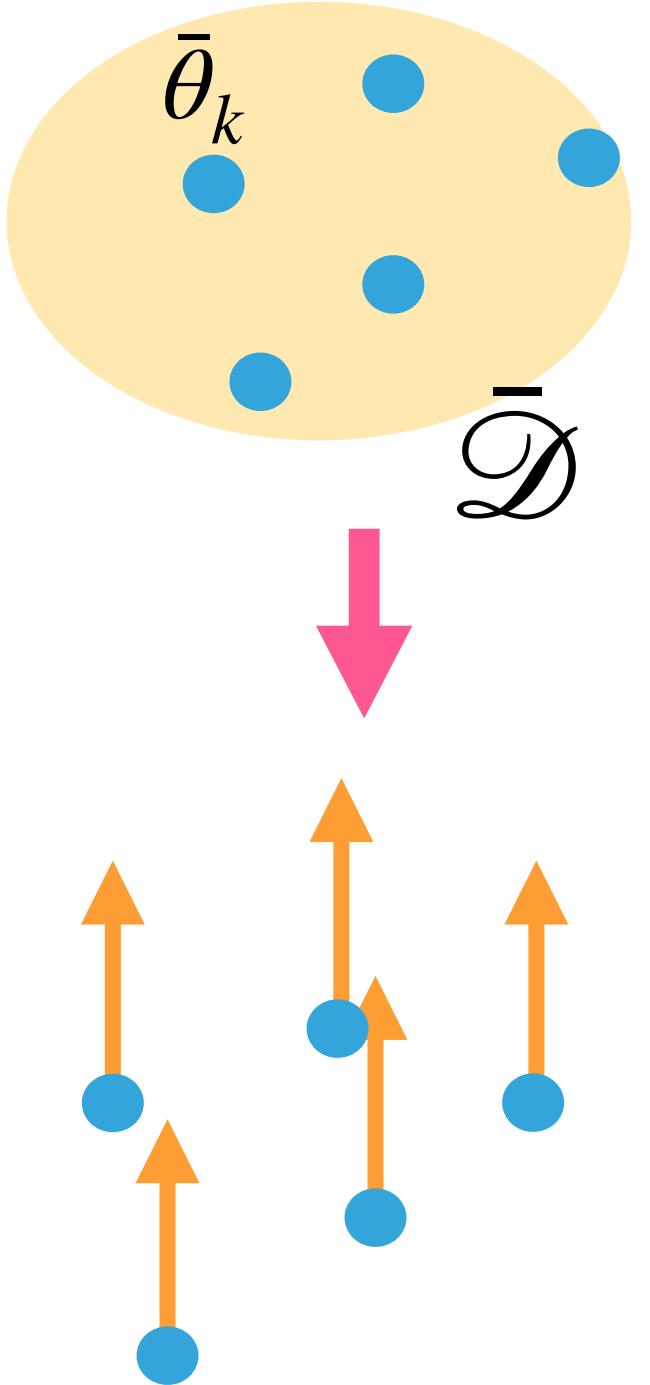
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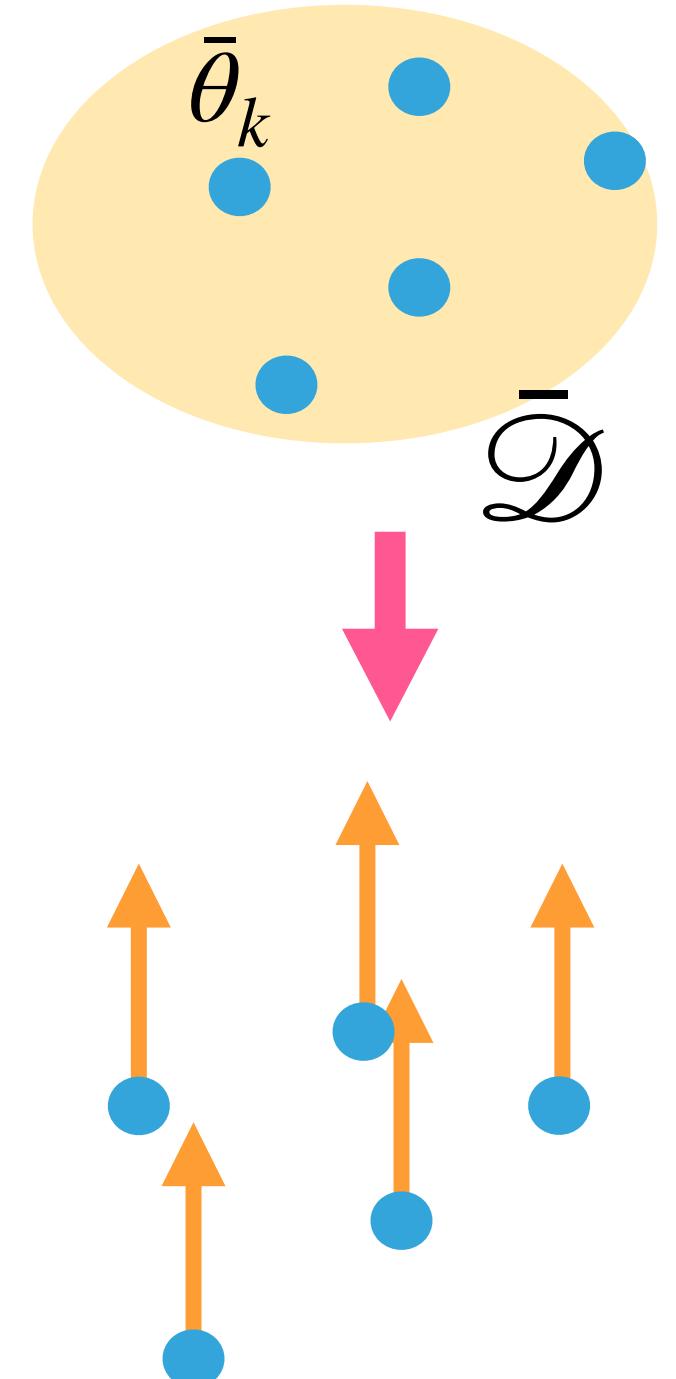
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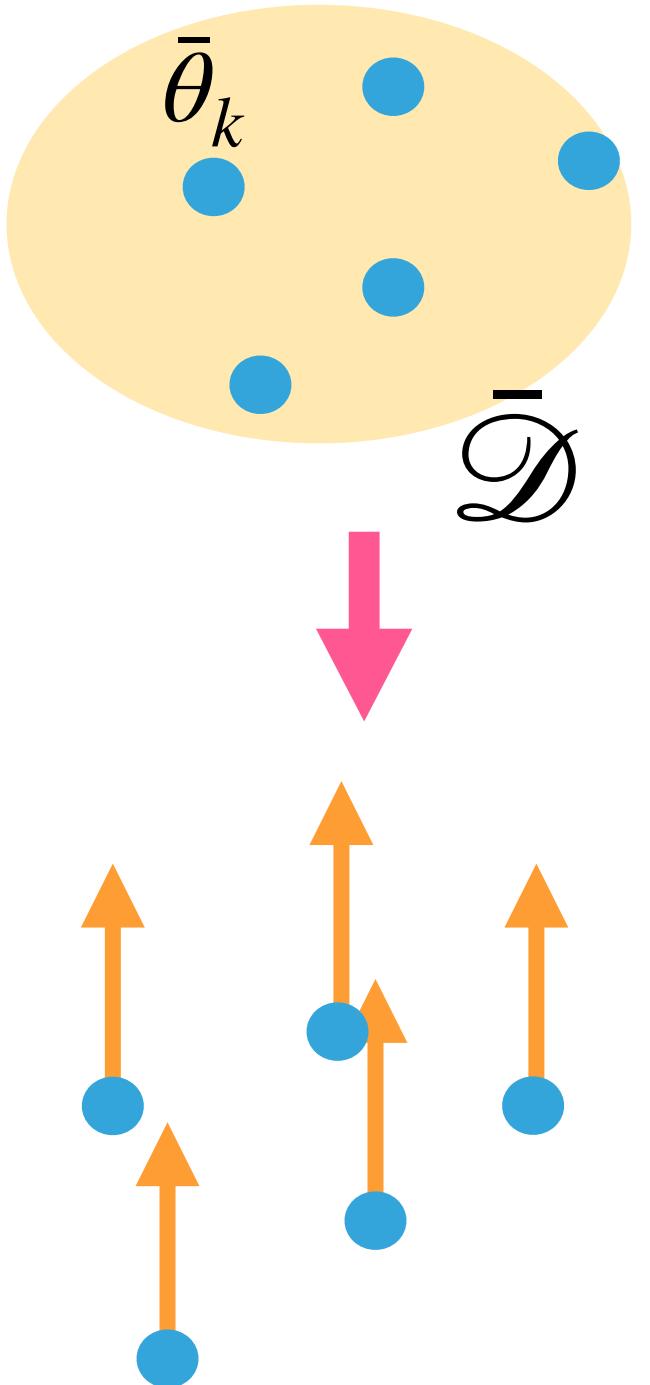
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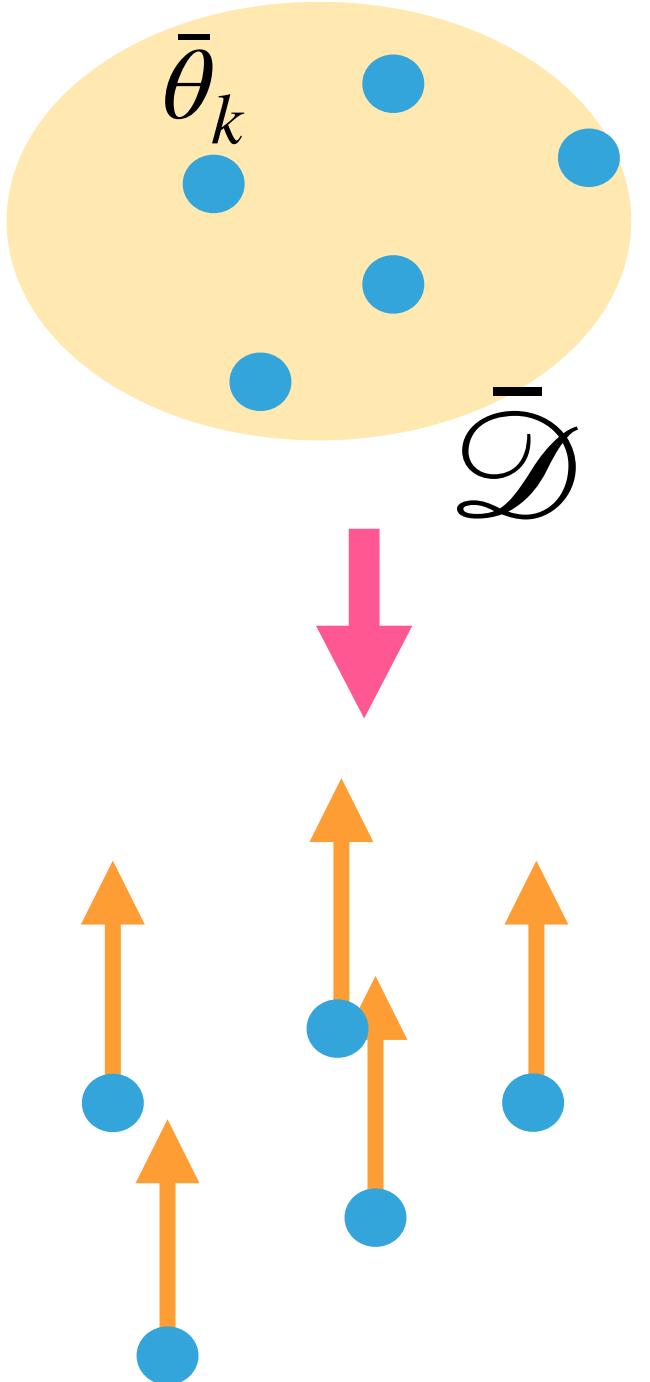
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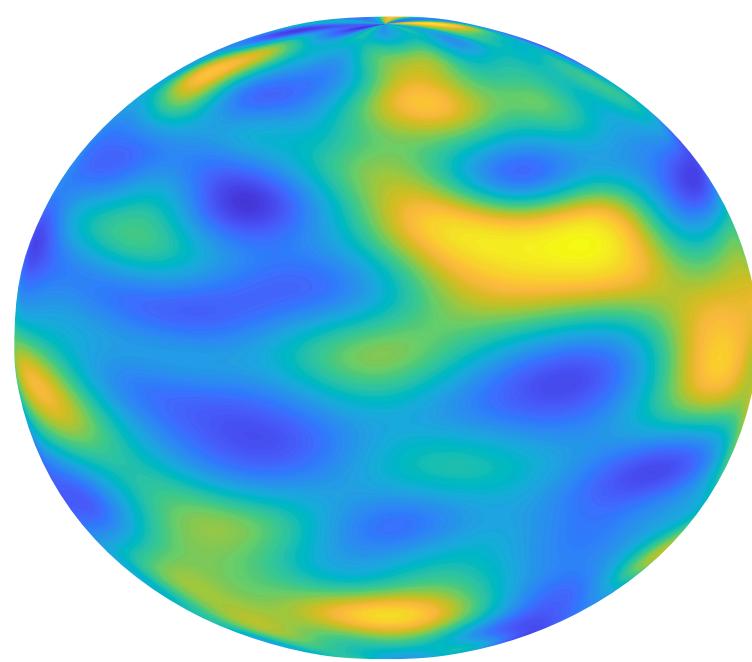


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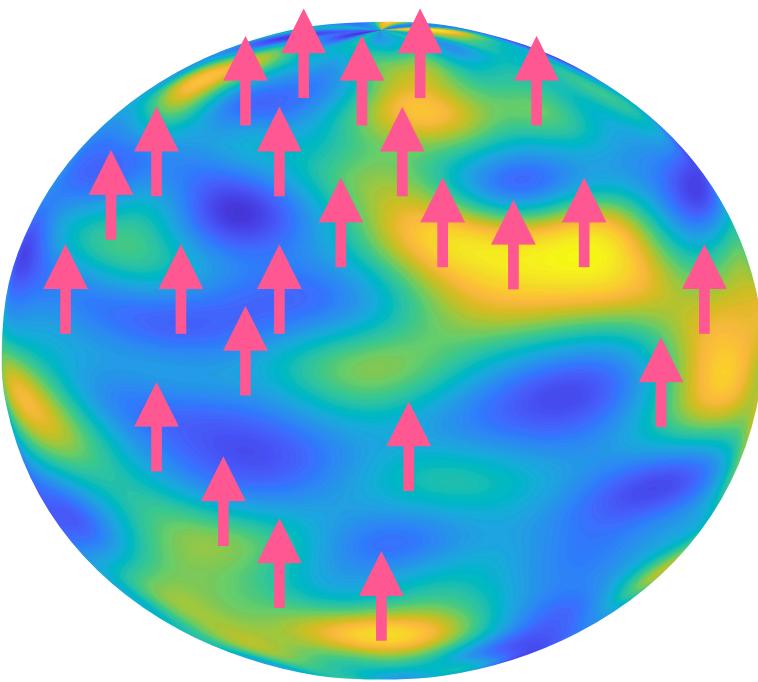
Towards quantitative (non-asymptotic) guarantees?

# Quantitative Guarantees

- **Remark:** Not possible in all generality: existence of computational lower bounds under restricted algorithmic classes (SQ, LDP) [Goel et al, Diakonikolas et al.], or cryptographic assumptions [Song et al, Chen et al., Vardi et al. ].



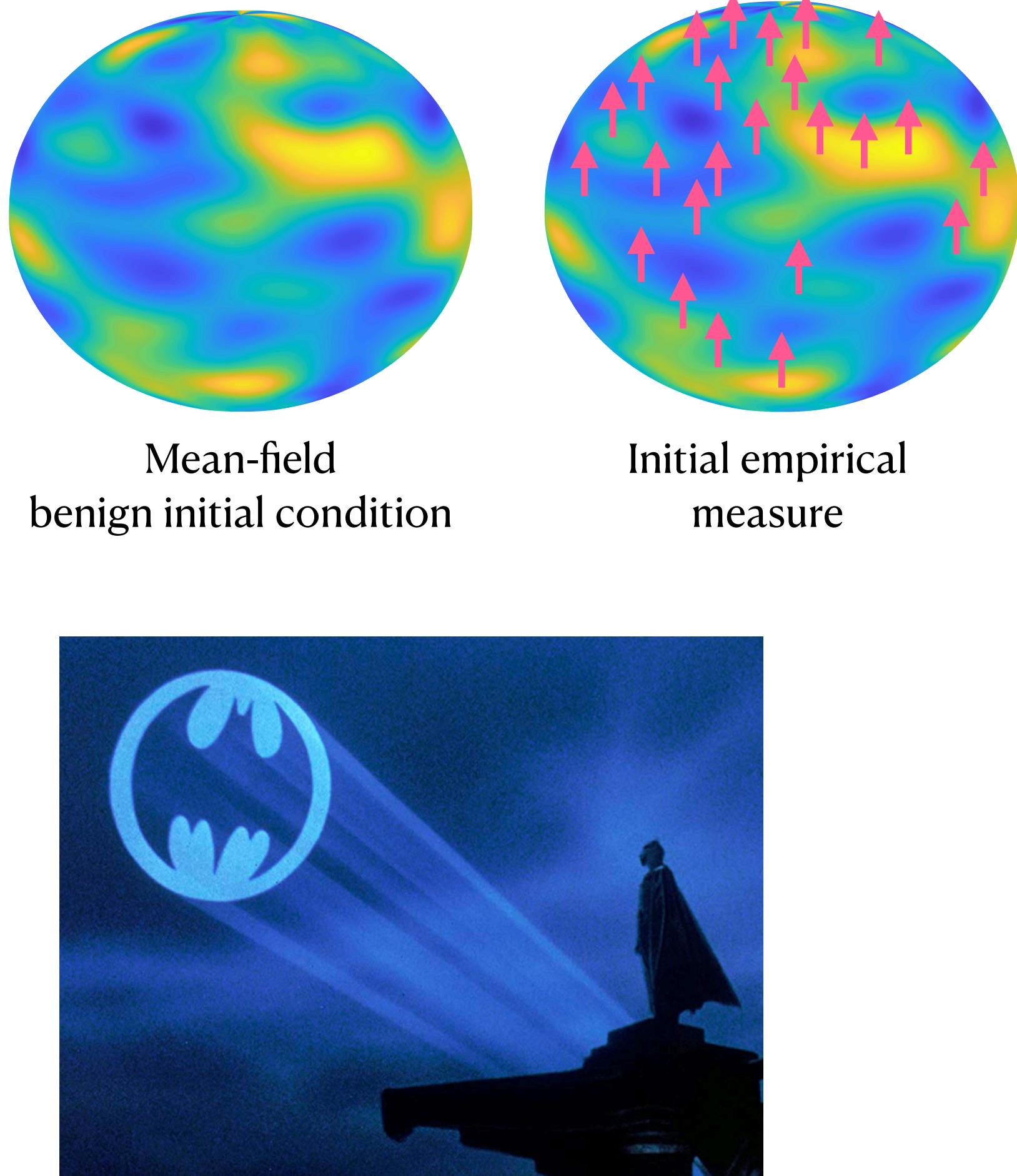
Mean-field  
benign initial condition



Initial empirical  
measure

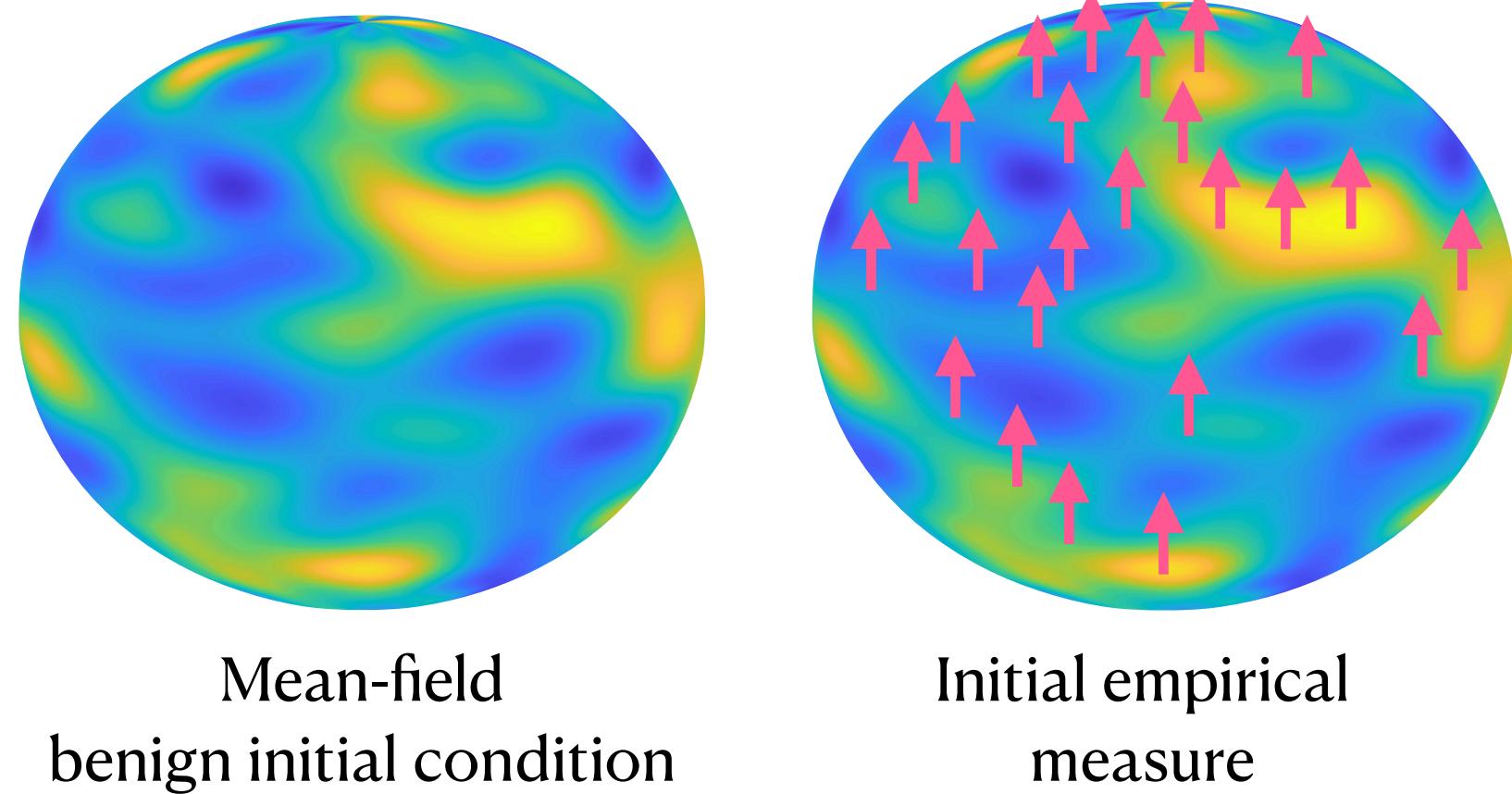
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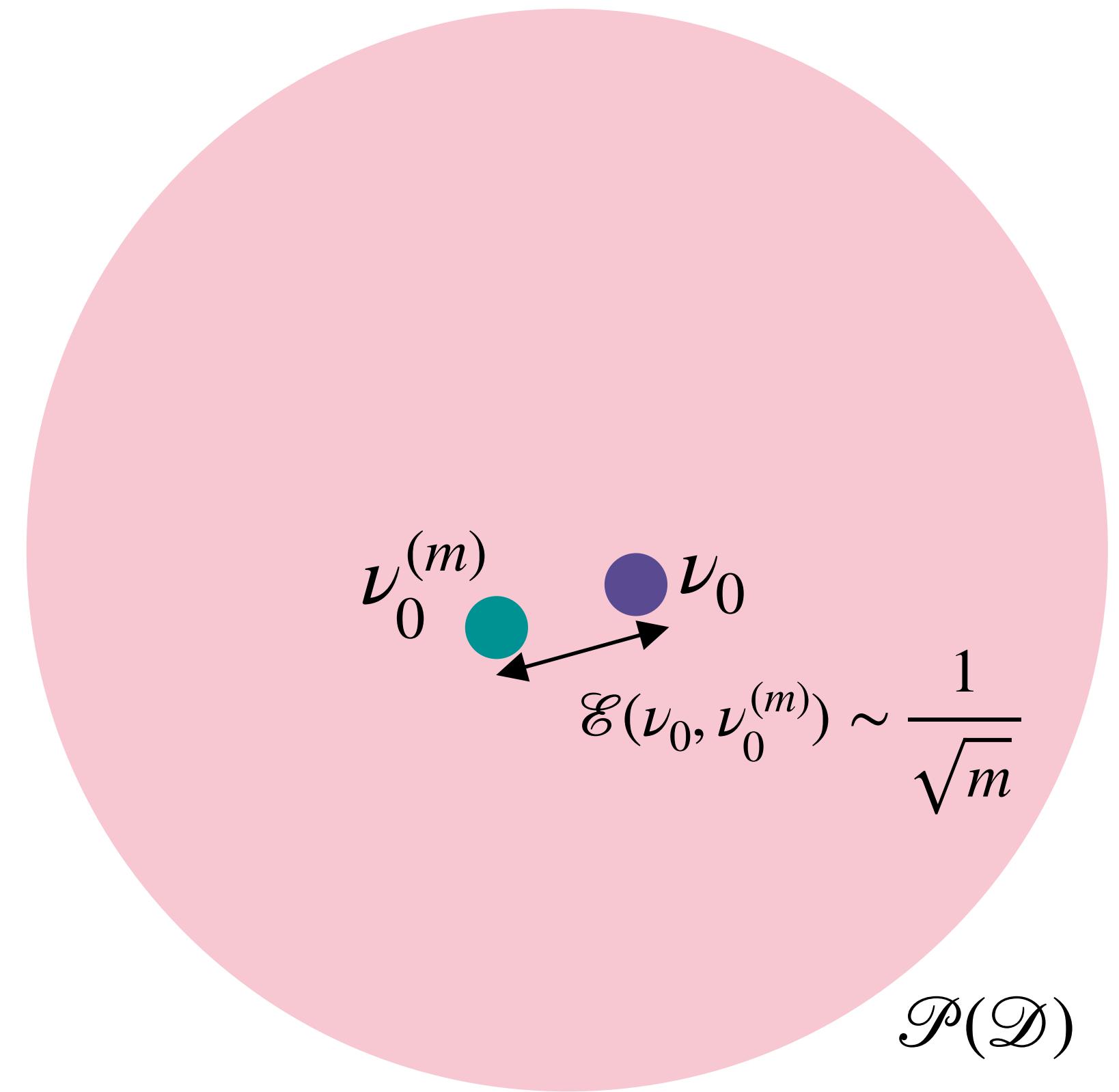


How about GD/GF on vanilla shallow NN?

# Finite-width Fluctuations

- **Static picture:** Monte-Carlo Approximation

$$\theta_1, \dots, \theta_m \sim_{iid} \nu, f_{\nu^{(m)}}(x) = \frac{1}{m} \sum_{j \leq m} \rho(\theta_j, x) \text{ satisfies}$$
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# Finite-width Fluctuations

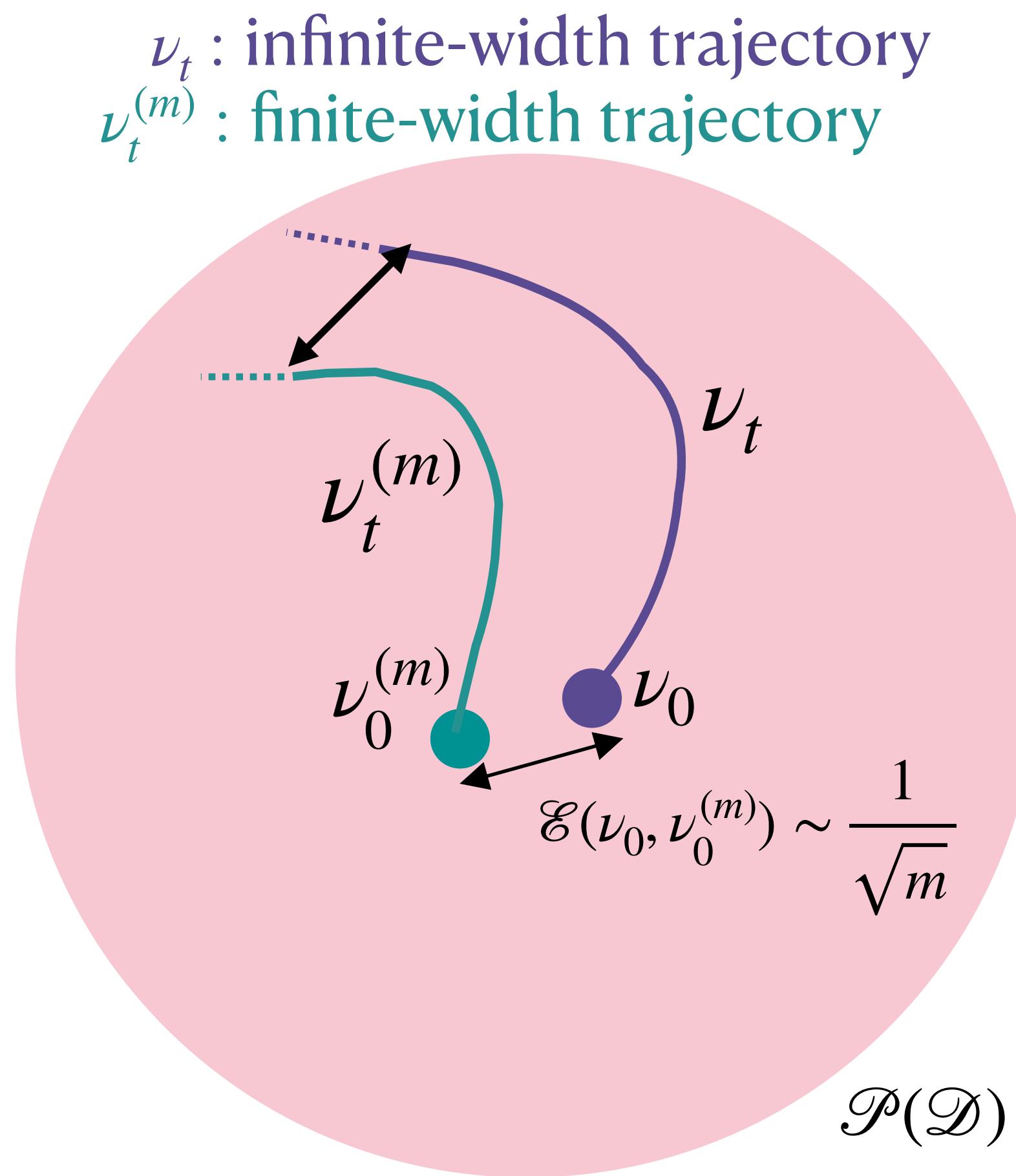
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- **Dynamic picture**, aka *Propagation-of-Chaos*  
[Kac,Sznitman]:

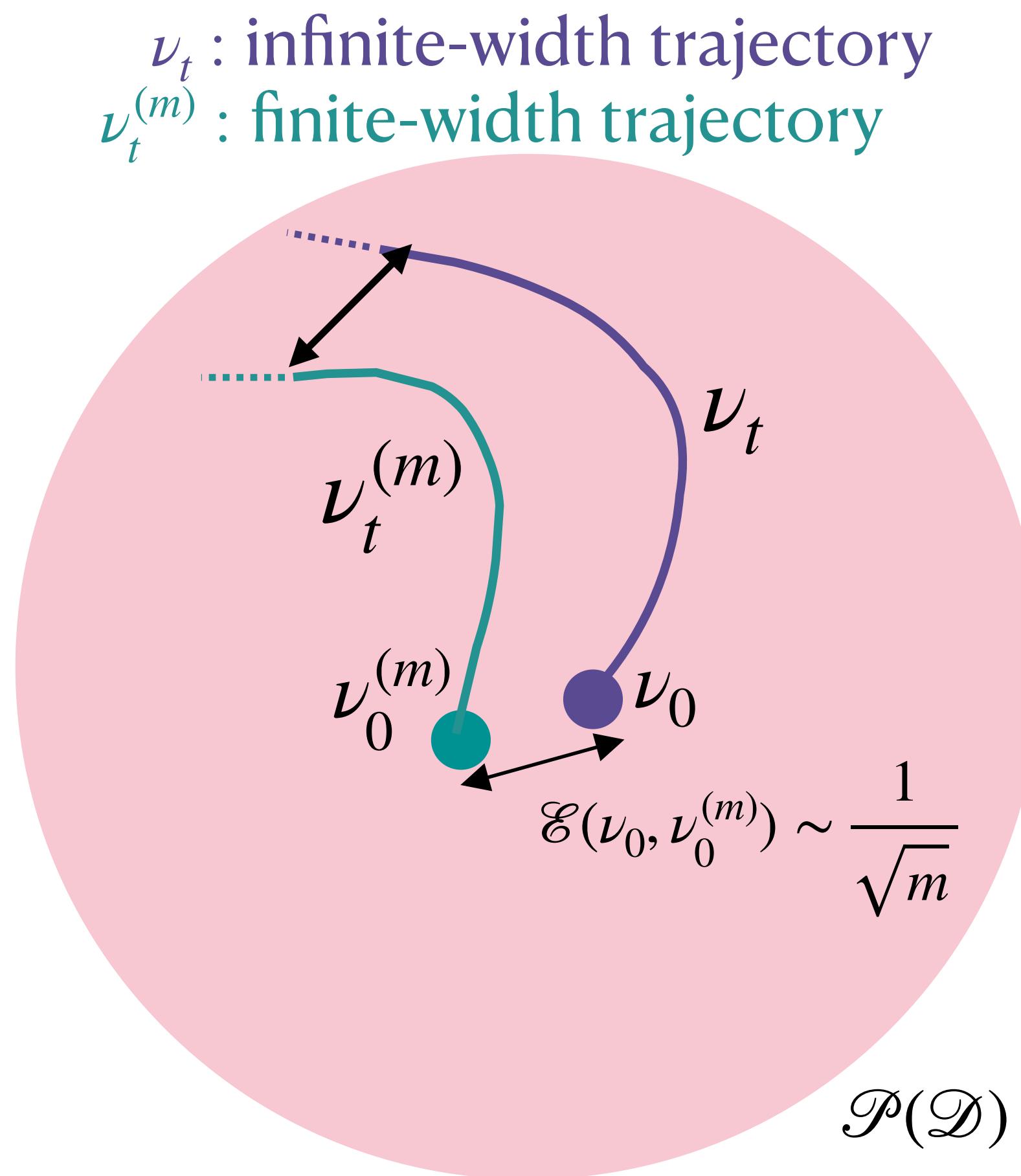
Does error remain at scale  $1/\sqrt{m}$ ? Expand? Contract?

For how long?



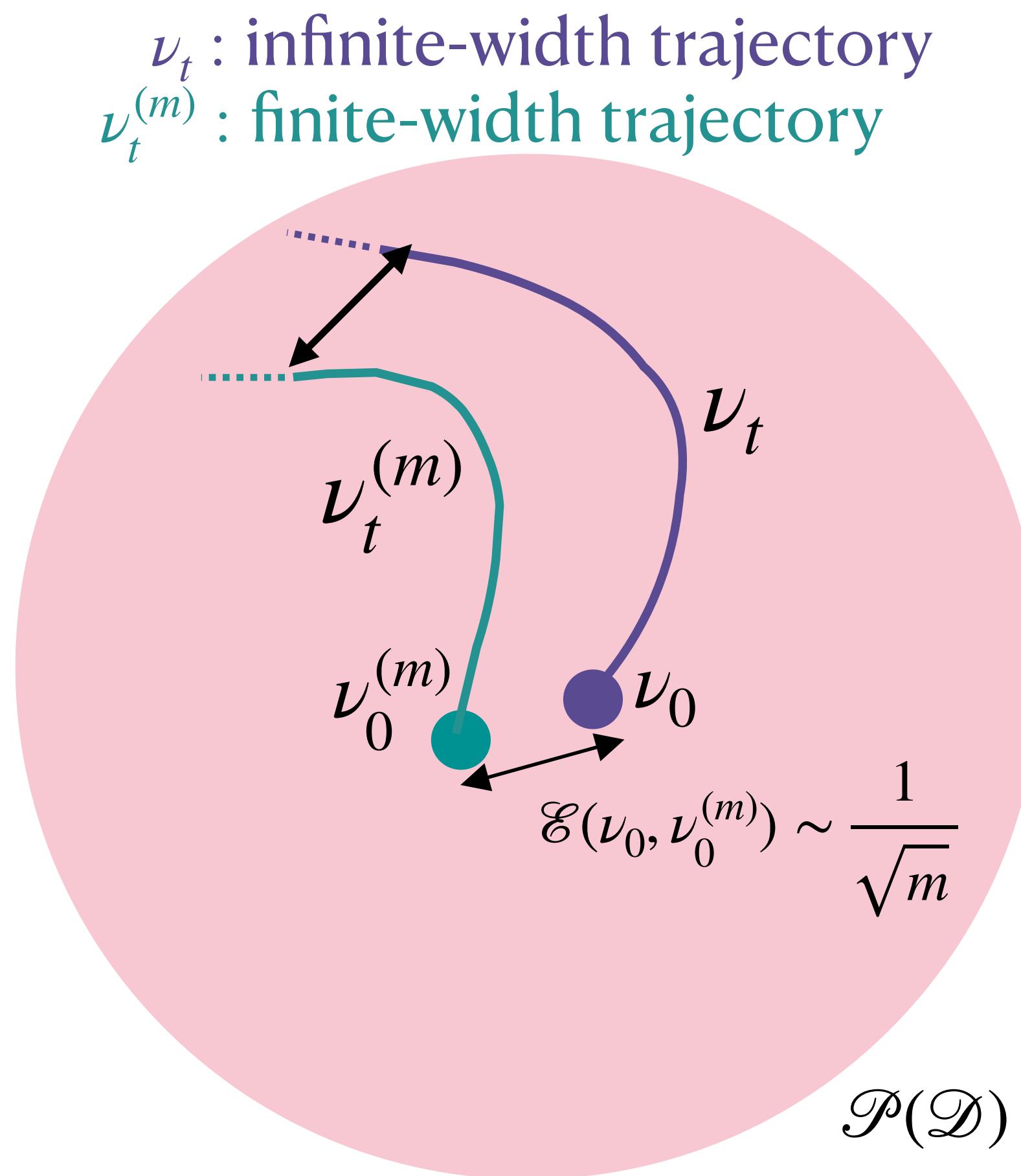
# Finite-width Fluctuations

- **Goal:** For time horizon  $T$  s.t. mean-field dynamics converge, establish polynomial PoC:  
$$\mathcal{E}(\nu_T, \nu_T^{(m)}) \lesssim \frac{\text{poly}(d, T)}{\sqrt{m}}, \text{ thus } \mathcal{L}(\nu_T^{(m)}) \lesssim \frac{\text{poly}(d, T)}{\sqrt{m}}.$$
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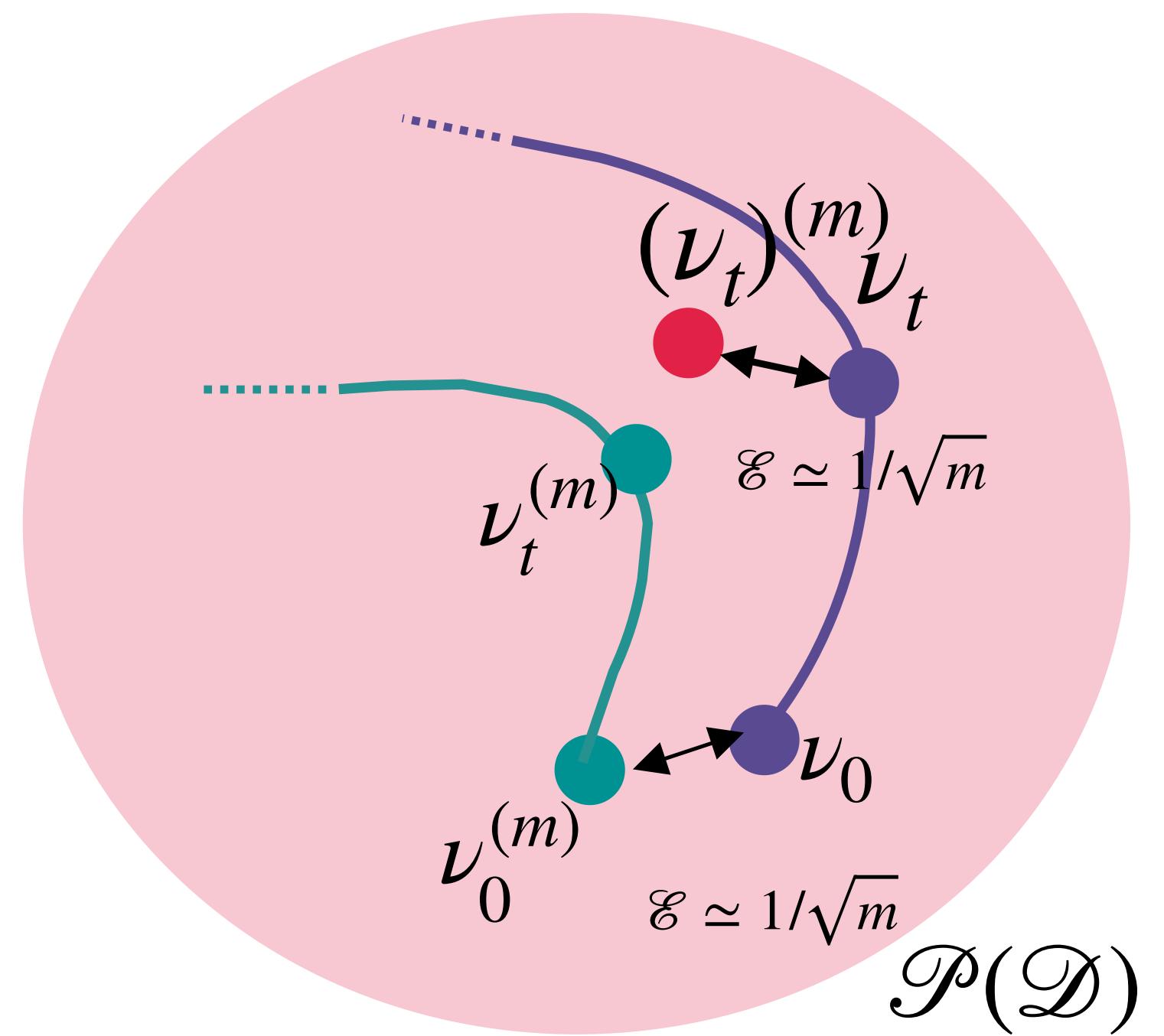


What assumptions to enable such polynomial control?

# Coupling Dynamics

$\partial_t \nu_t = \operatorname{div} (\nabla U(\theta; \nu_t) \nu_t)$  ,  $U(\cdot, \nu)$  : instantaneous potential.

- Given  $\nu_t$ , its empirical measure  $(\nu_t)^{(m)}$  satisfies  
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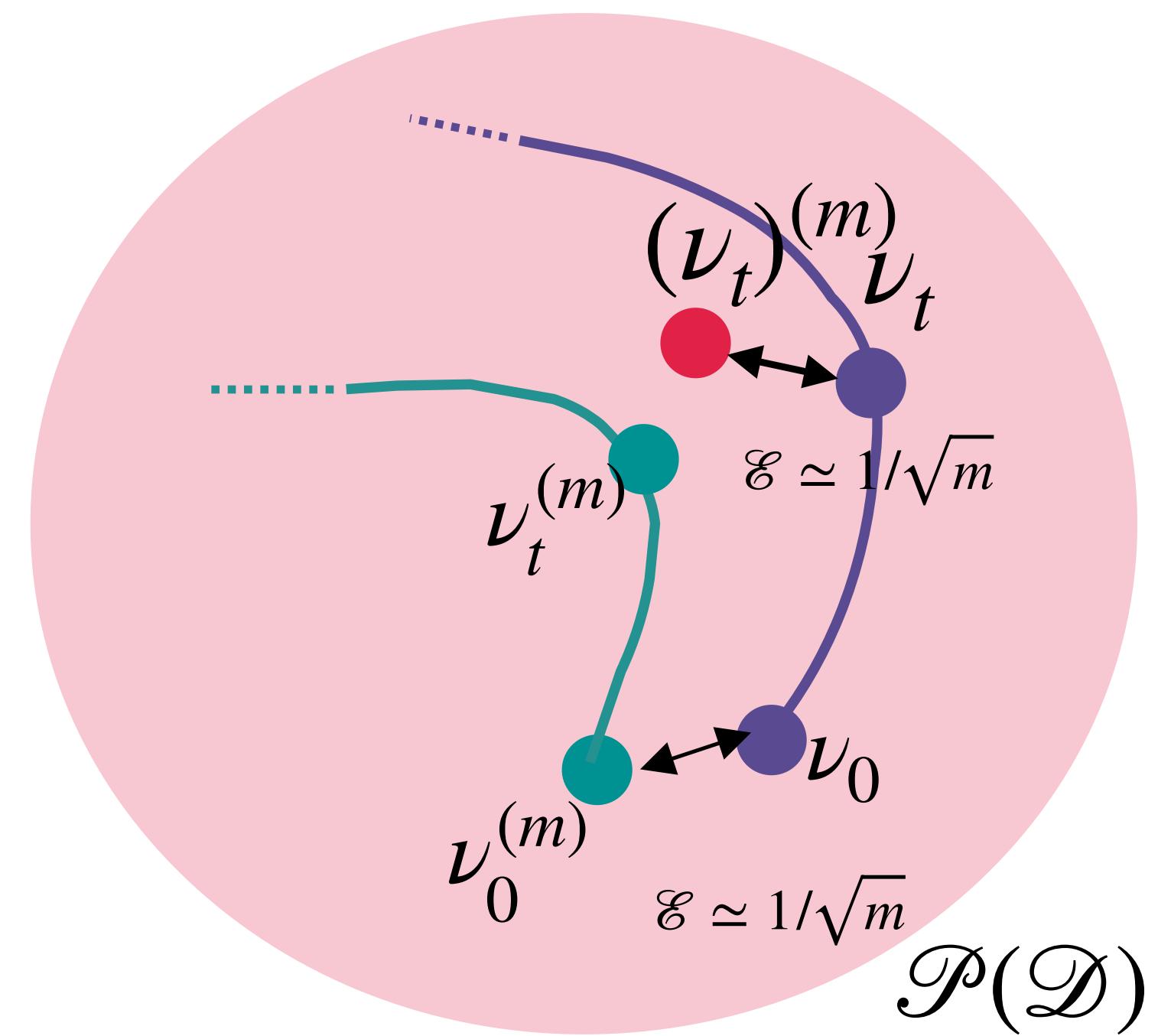


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$\nu_t^{(m)}$  : sample, then evolve  
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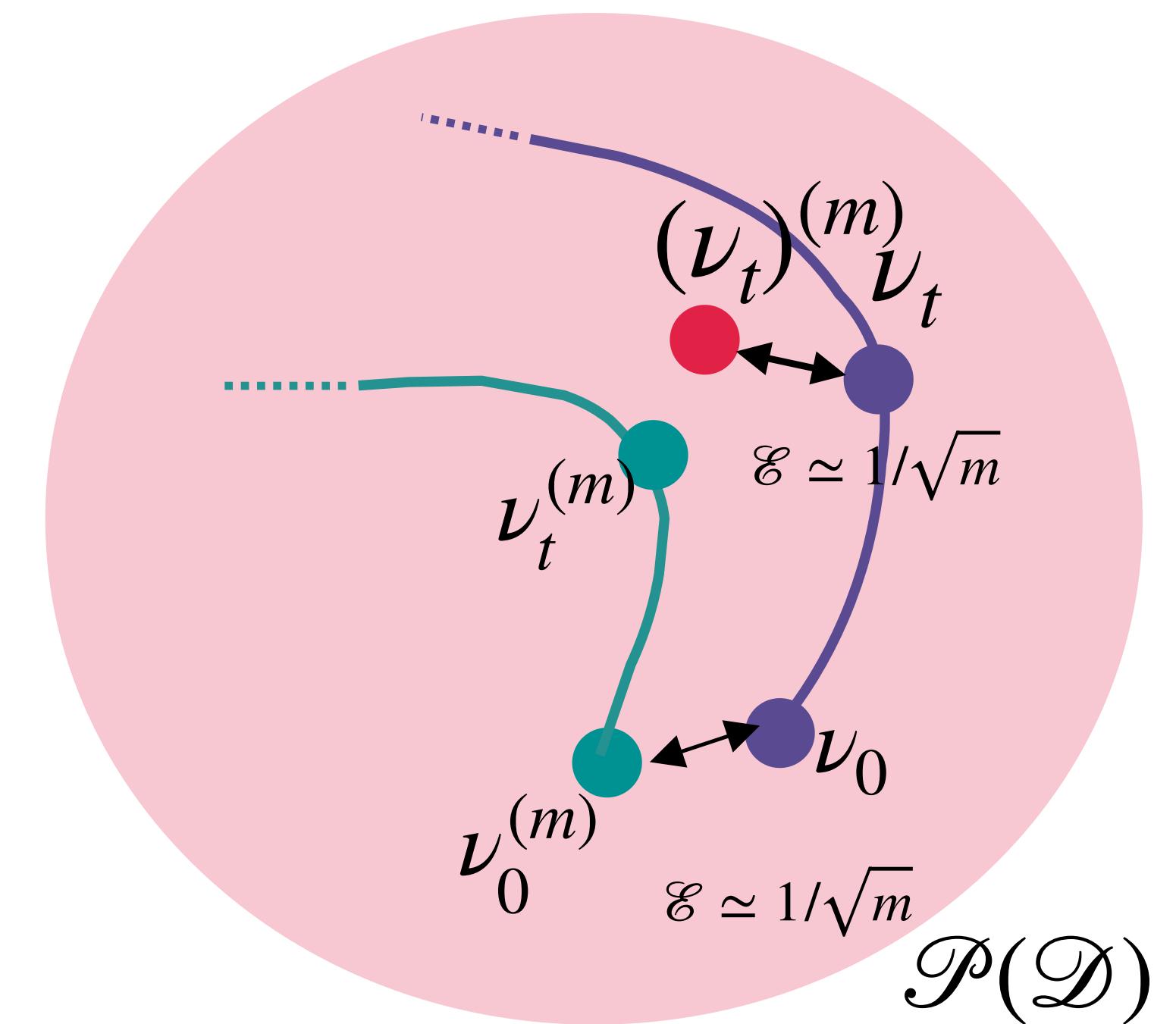
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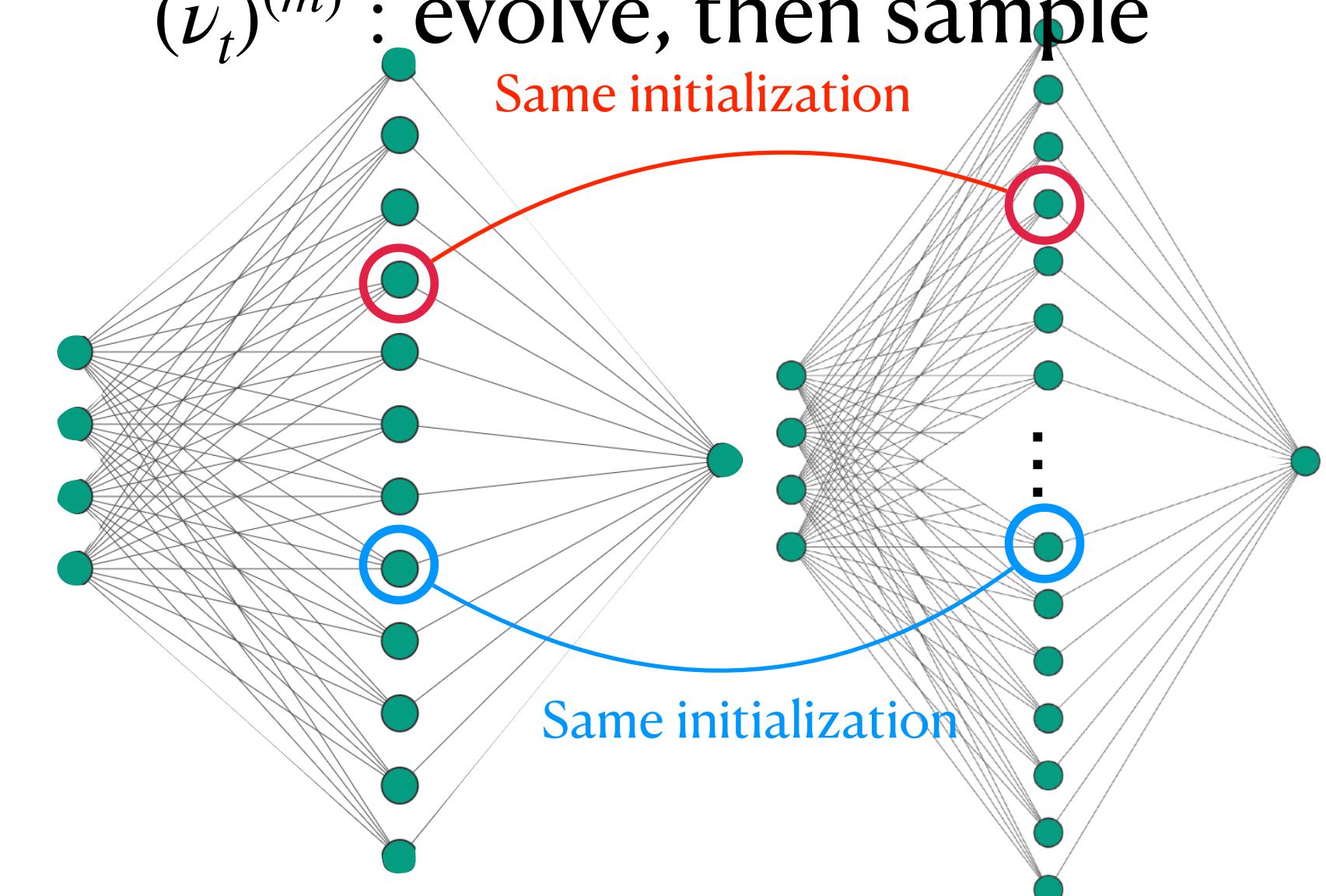
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Finite-Net evolution:  $\dot{\theta}_j = -\nabla U(\theta_j(t); \nu_t^{(m)}), \boxed{\theta_j(0) = \bar{\theta}_j(0)}$



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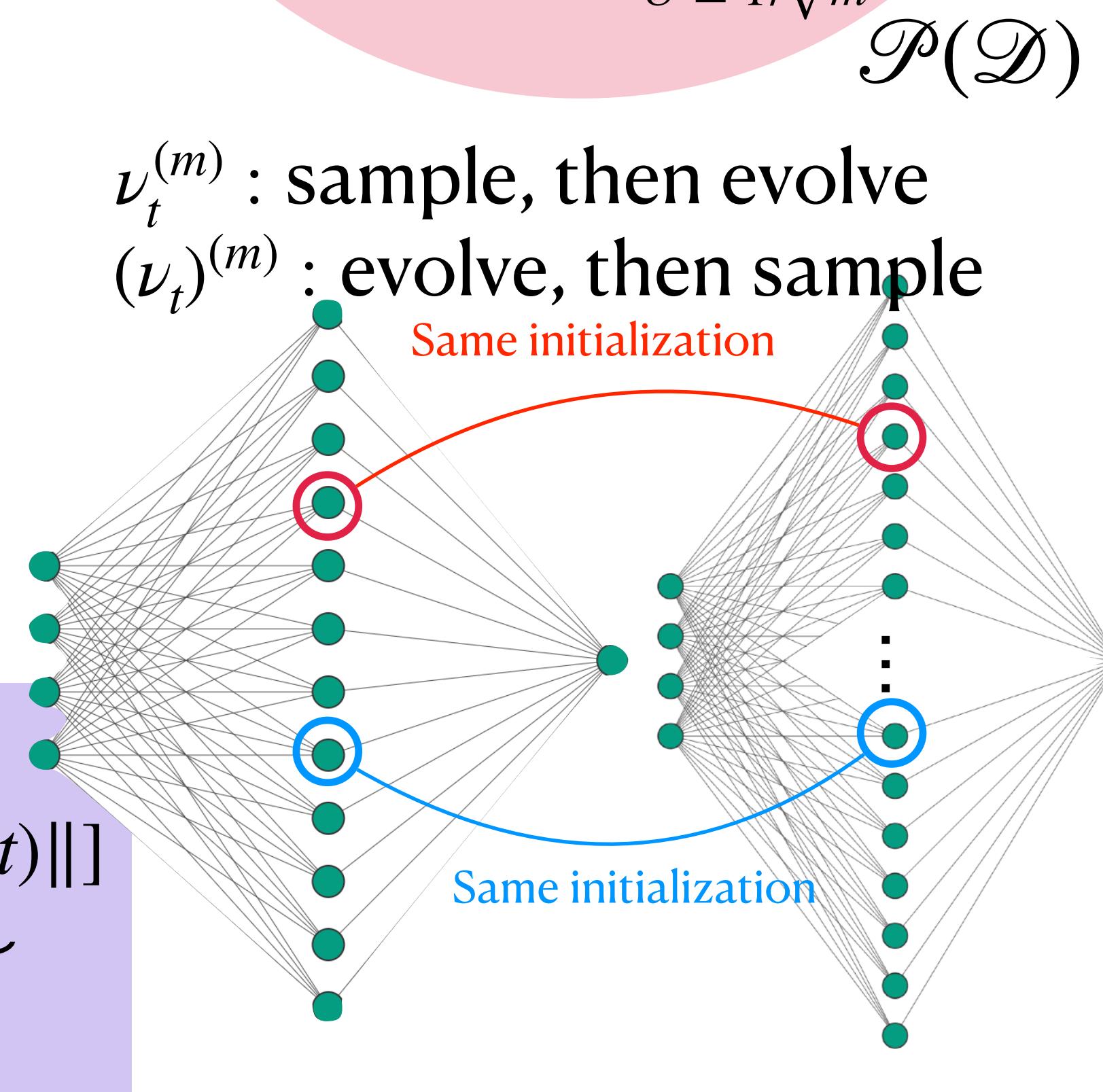
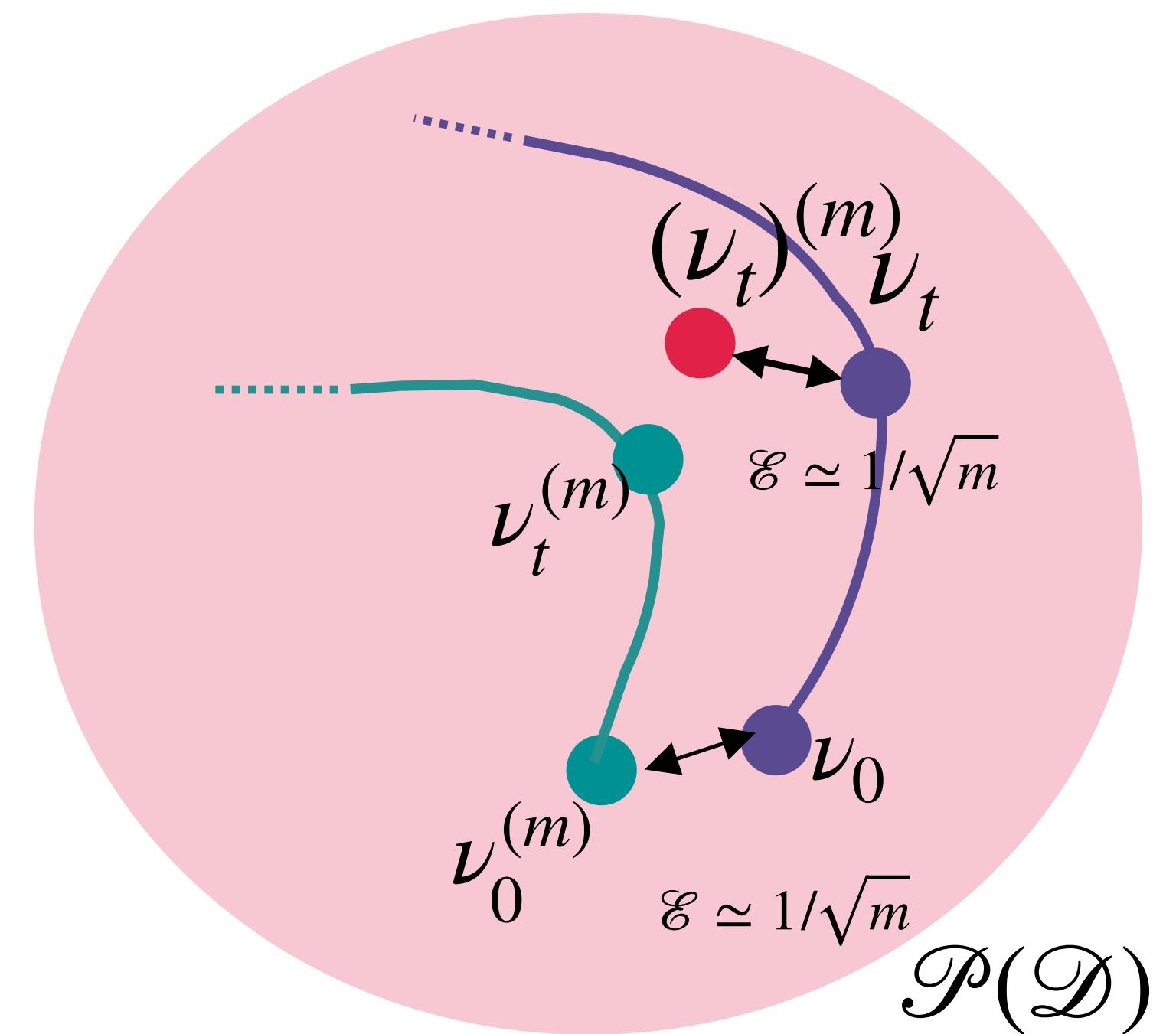
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- Proposition:** under mild regularity, we have

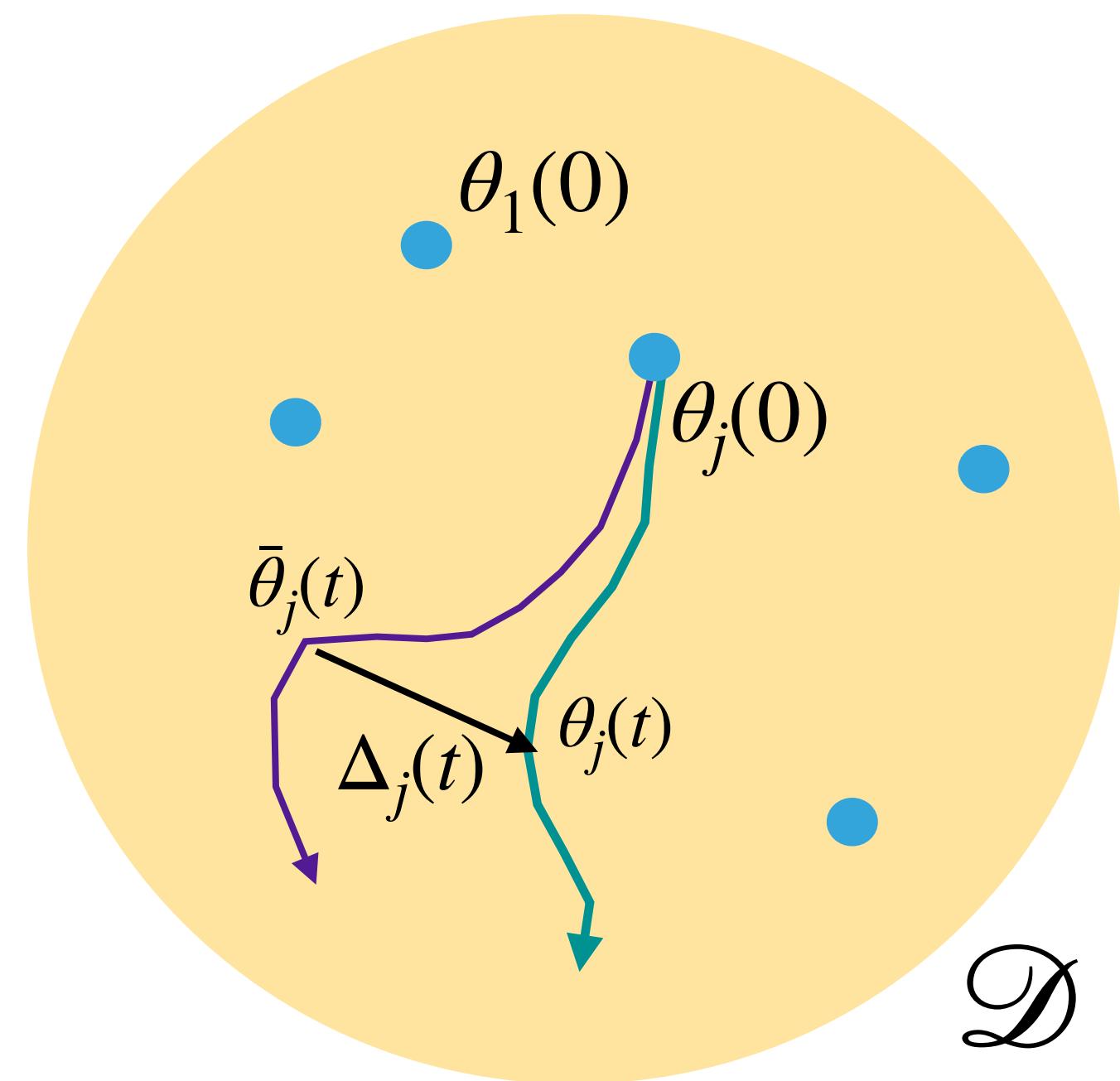
$$\mathcal{E}(\nu_t^{(m)}, \nu_t) \lesssim O(1/\sqrt{m}) + W_1(\nu_t^{(m)}, (\nu_t)^{(m)}) \leq O(1/\sqrt{m}) + \underbrace{\mathbb{E}_j[\|\theta_j(t) - \bar{\theta}_j(t)\|]}_{\Delta_j(t)}$$



# Coupling Dynamics and Gronwall

$\Delta_j(t) = \theta_j(t) - \bar{\theta}_j(t)$  : Coupling errors.

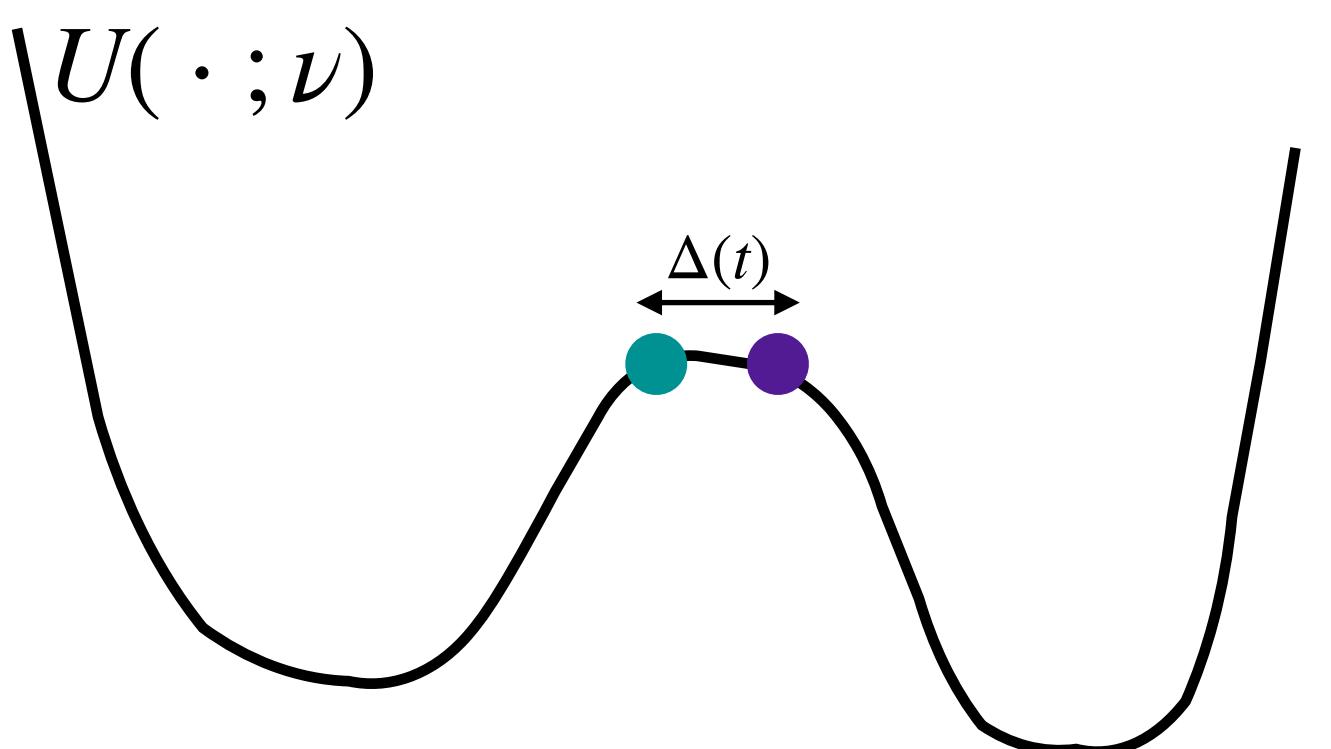
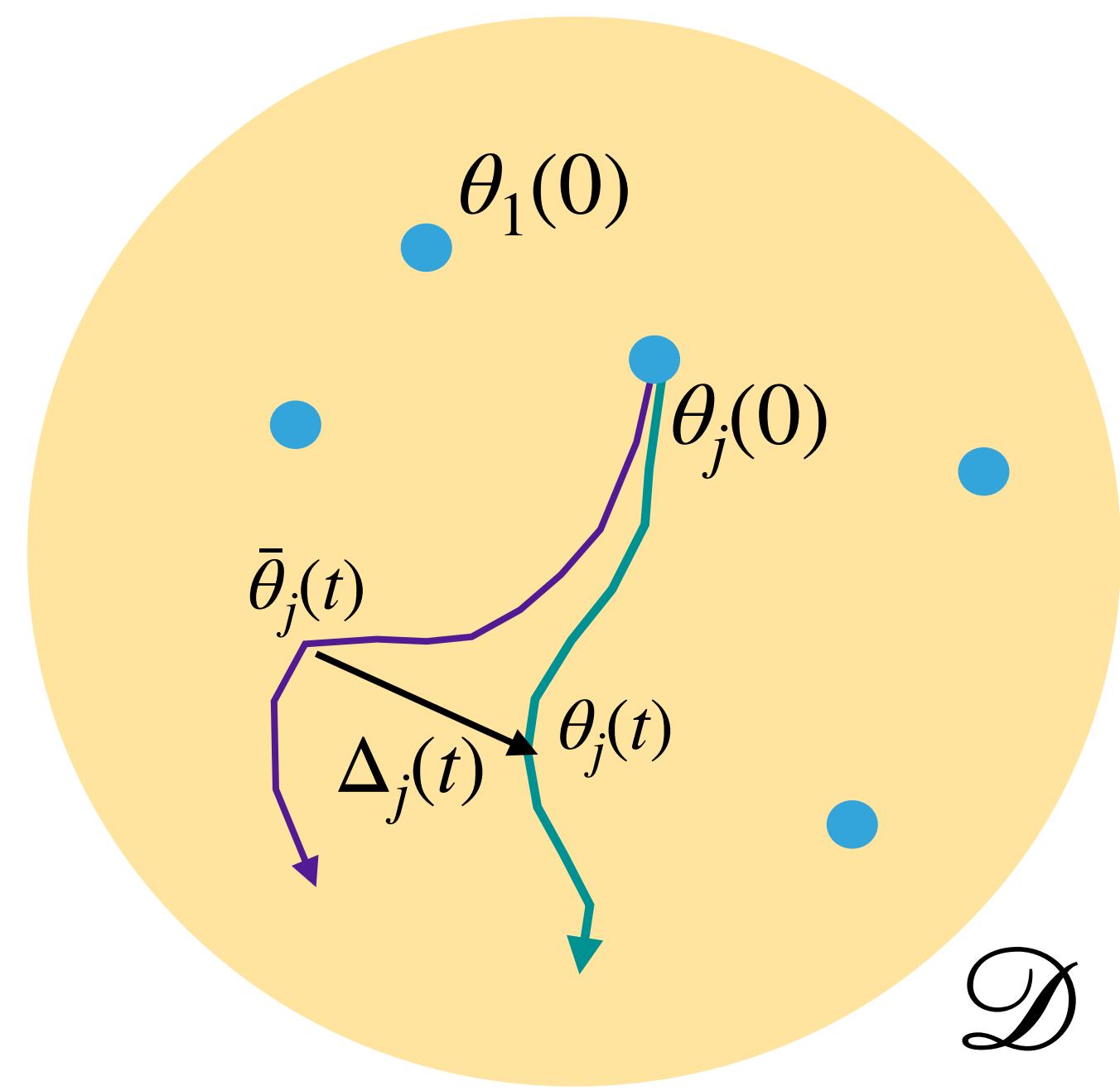
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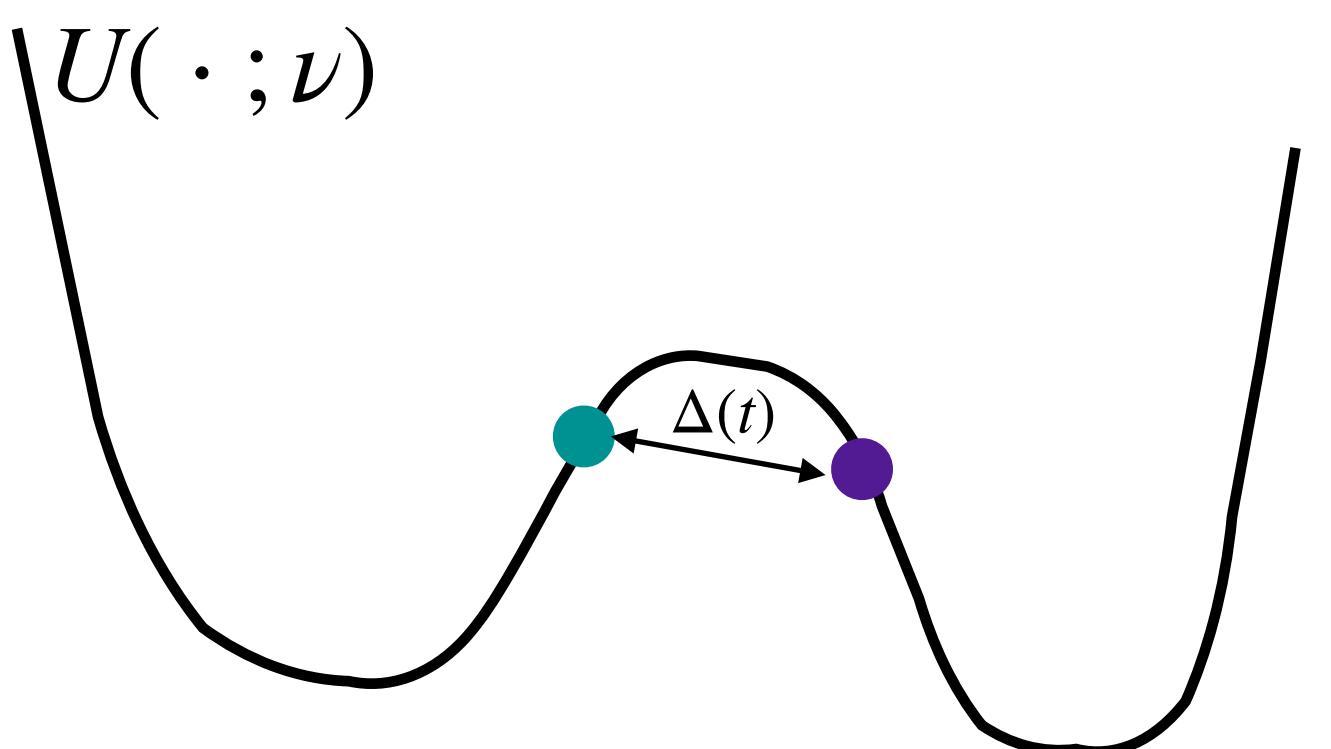
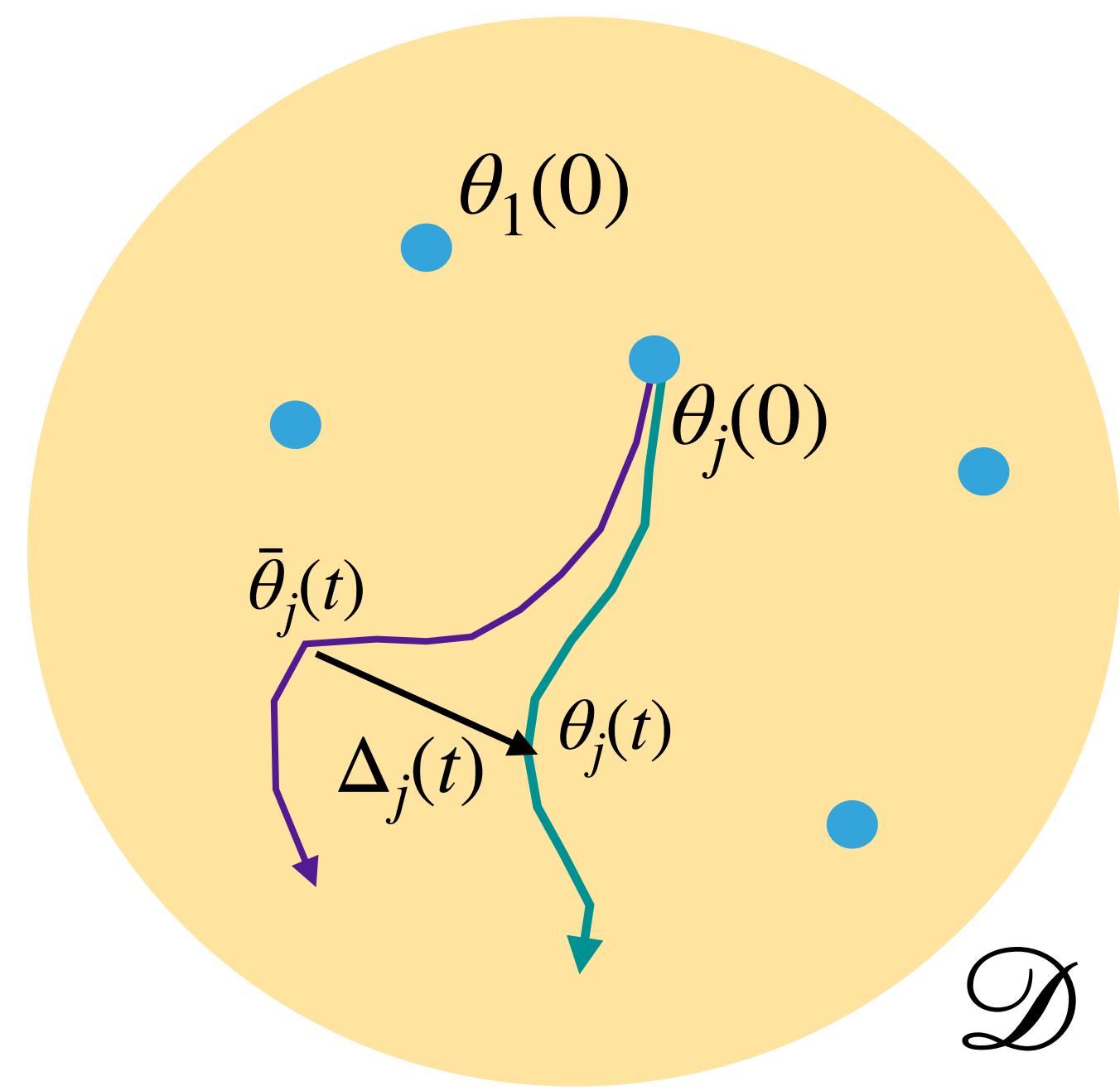
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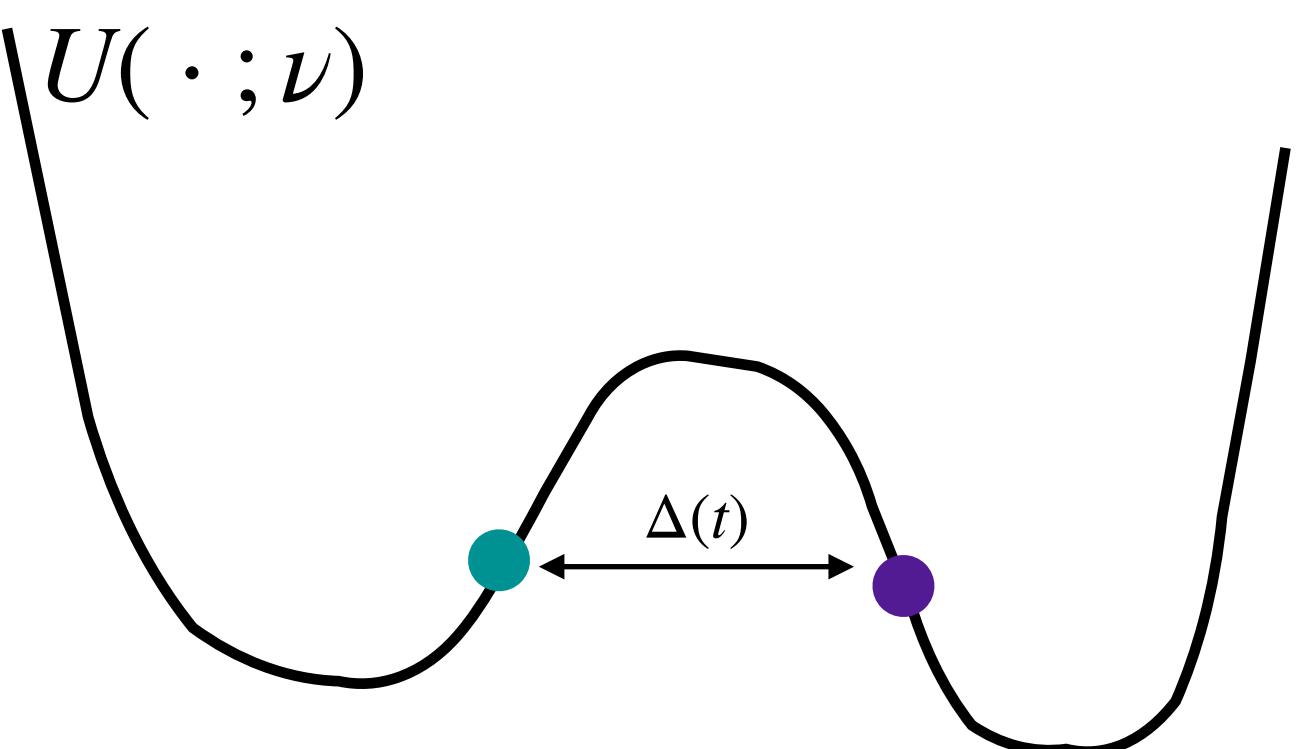
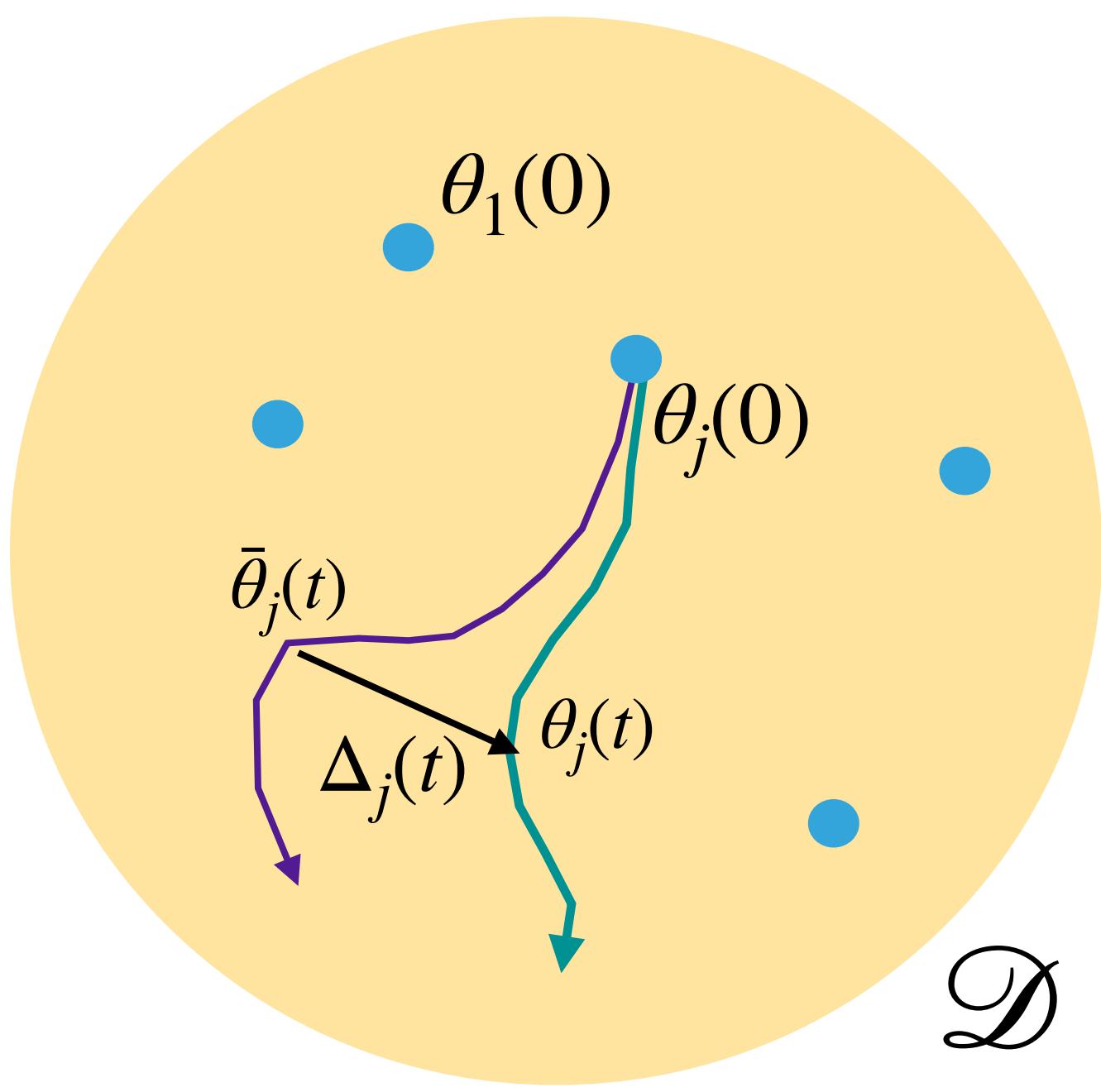
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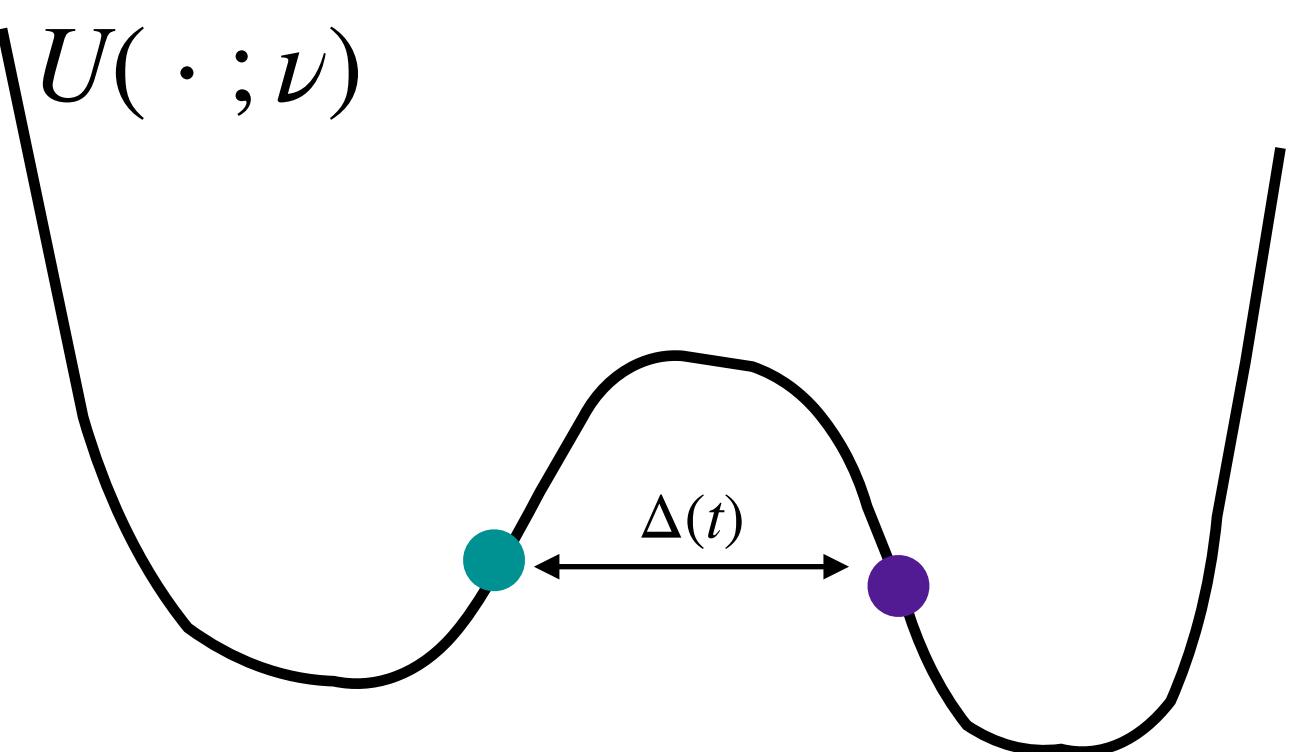
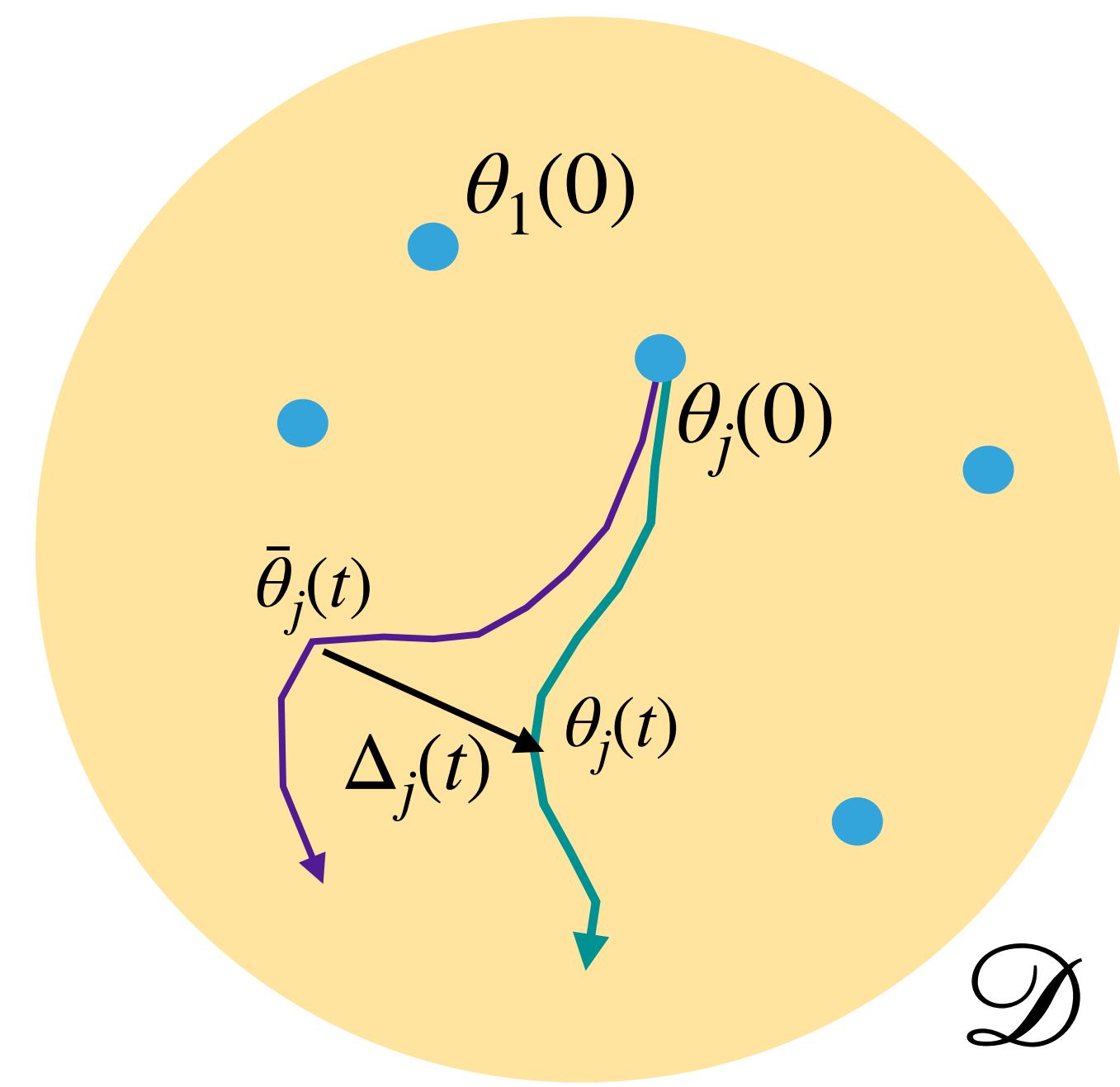
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• Leveraging uniform Lipschitz smoothness:

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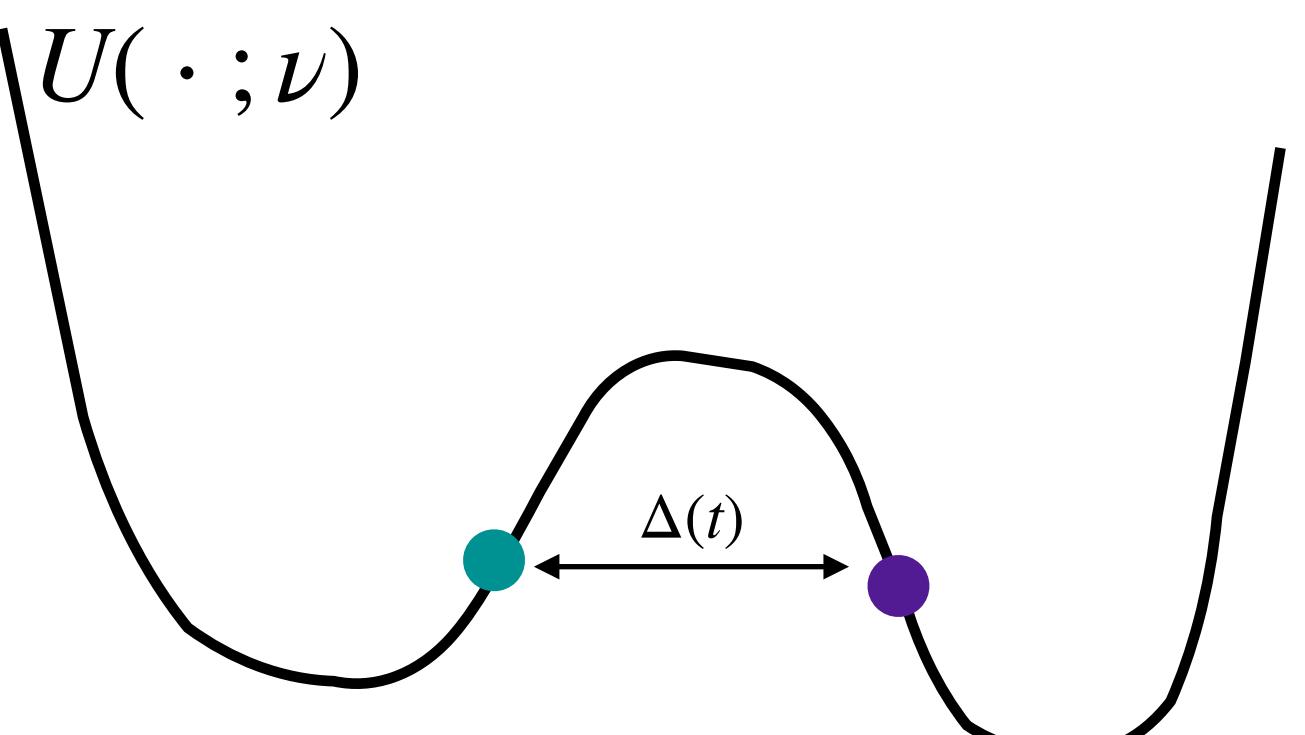
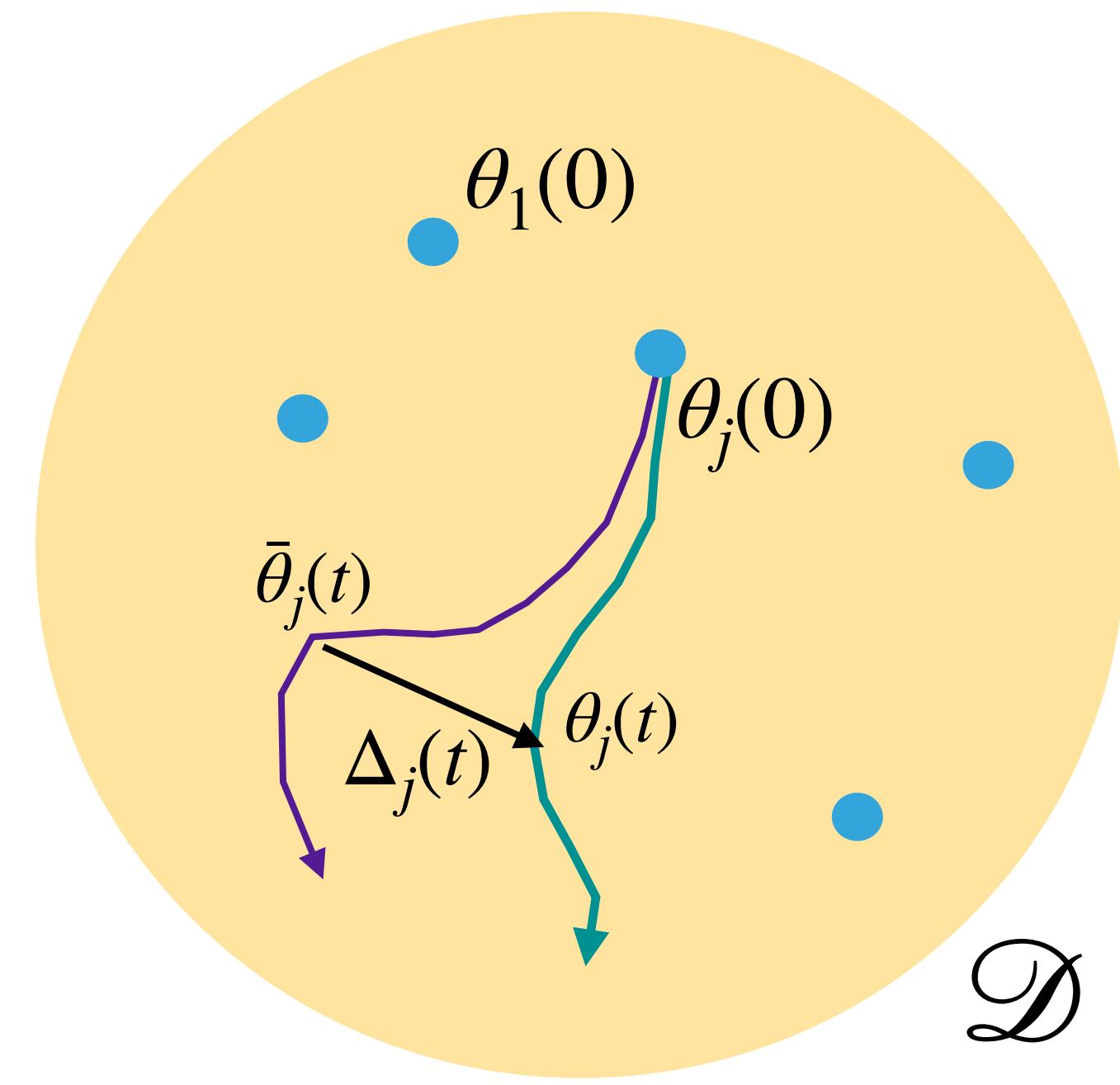


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- PoC via Gronwall's inequality:  $\mathcal{E}(\nu_t^{(m)}, \nu_t) \lesssim \frac{\exp(Lt)}{\sqrt{m}}$ .
  - Exploited in [Mei et al, Misiakiewicz et al, Mahankali et al] for **short** time-horizons, e.g  $T = O(1)$  or  $T = O(\log d)$ . Morally  $\text{IE} \leq 2$  ‘type’ problems.



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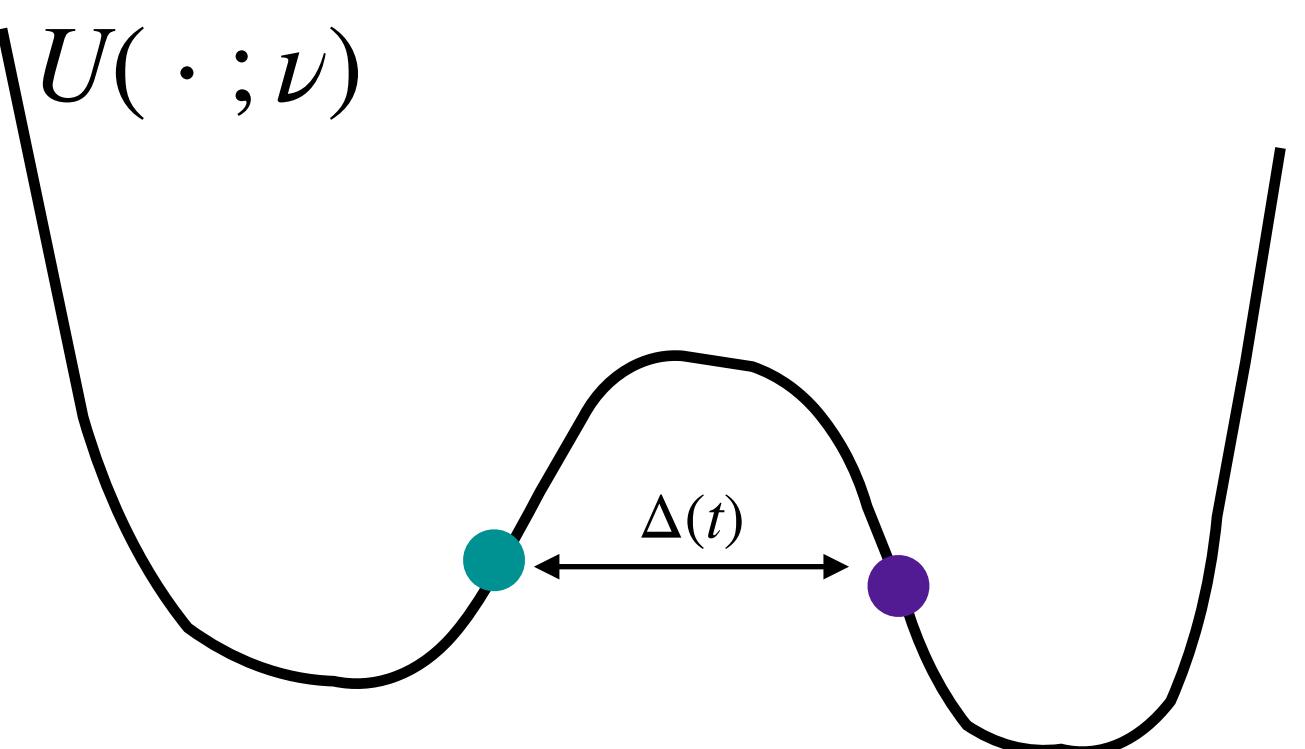
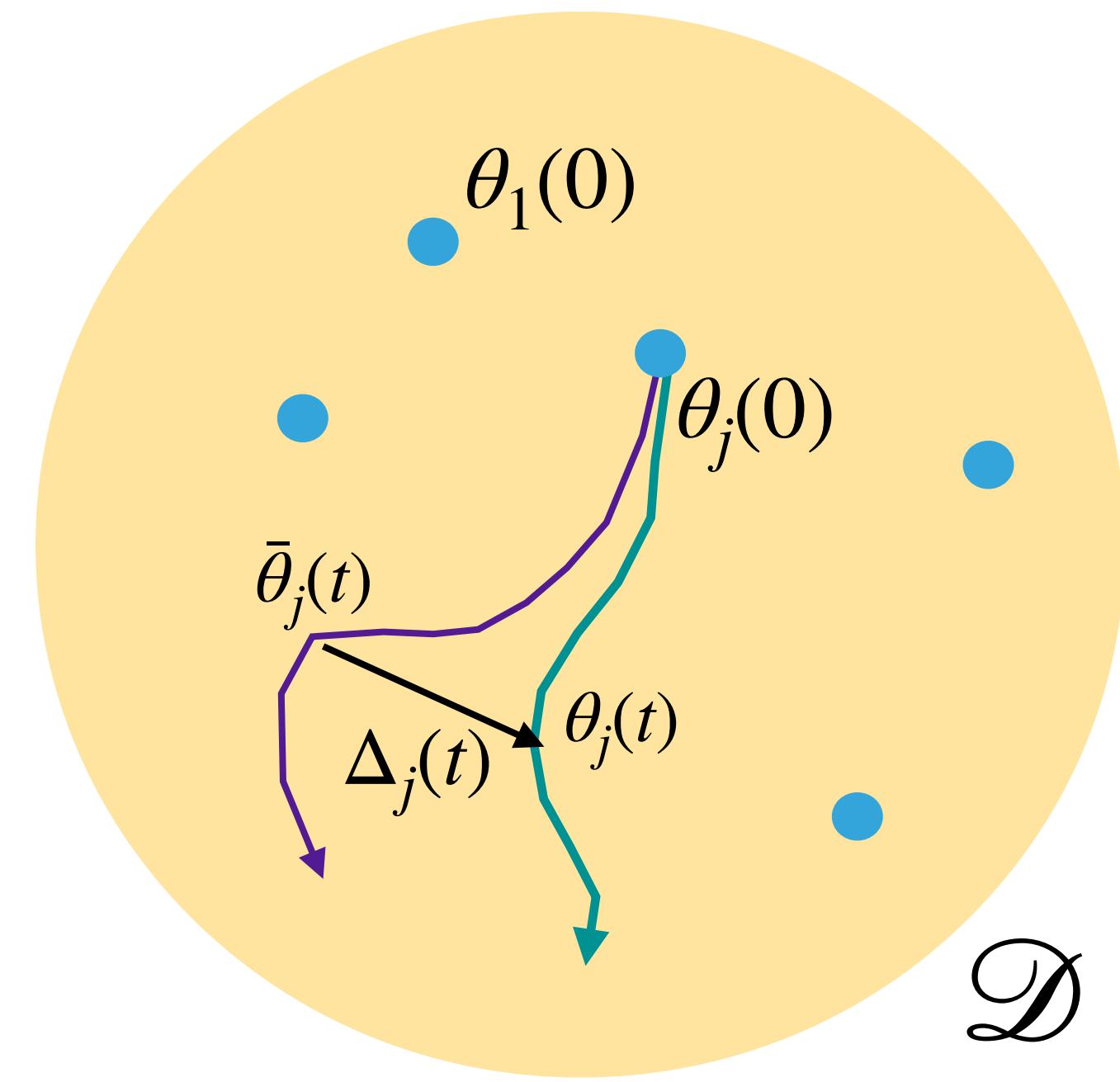
- Leveraging uniform Lipschitz smoothness:

$$\begin{aligned} \frac{d}{dt} \mathbb{E}_j \|\Delta_j(t)\| &\leq L_\theta \mathbb{E}_j \|\Delta_j(t)\| + L_\nu W_1(\nu_t^{(m)}, (\nu_t)^{(m)}) + O(1/\sqrt{m}) \\ &\leq (L_\theta \vee L_\nu) \mathbb{E}_j \|\Delta_j(t)\| + O(1/\sqrt{m}). \end{aligned}$$

- PoC via Gronwall's inequality:  $\mathcal{E}(\nu_t^{(m)}, \nu_t) \lesssim \frac{\exp(Lt)}{\sqrt{m}}$ .

- Exploited in [Mei et al, Misiakiewicz et al, Mahankali et al] for **short** time-horizons, e.g  $T = O(1)$  or  $T = O(\log d)$ . Morally  $\text{IE} \leq 2$  ‘type’ problems.

Excludes many situations of interest!



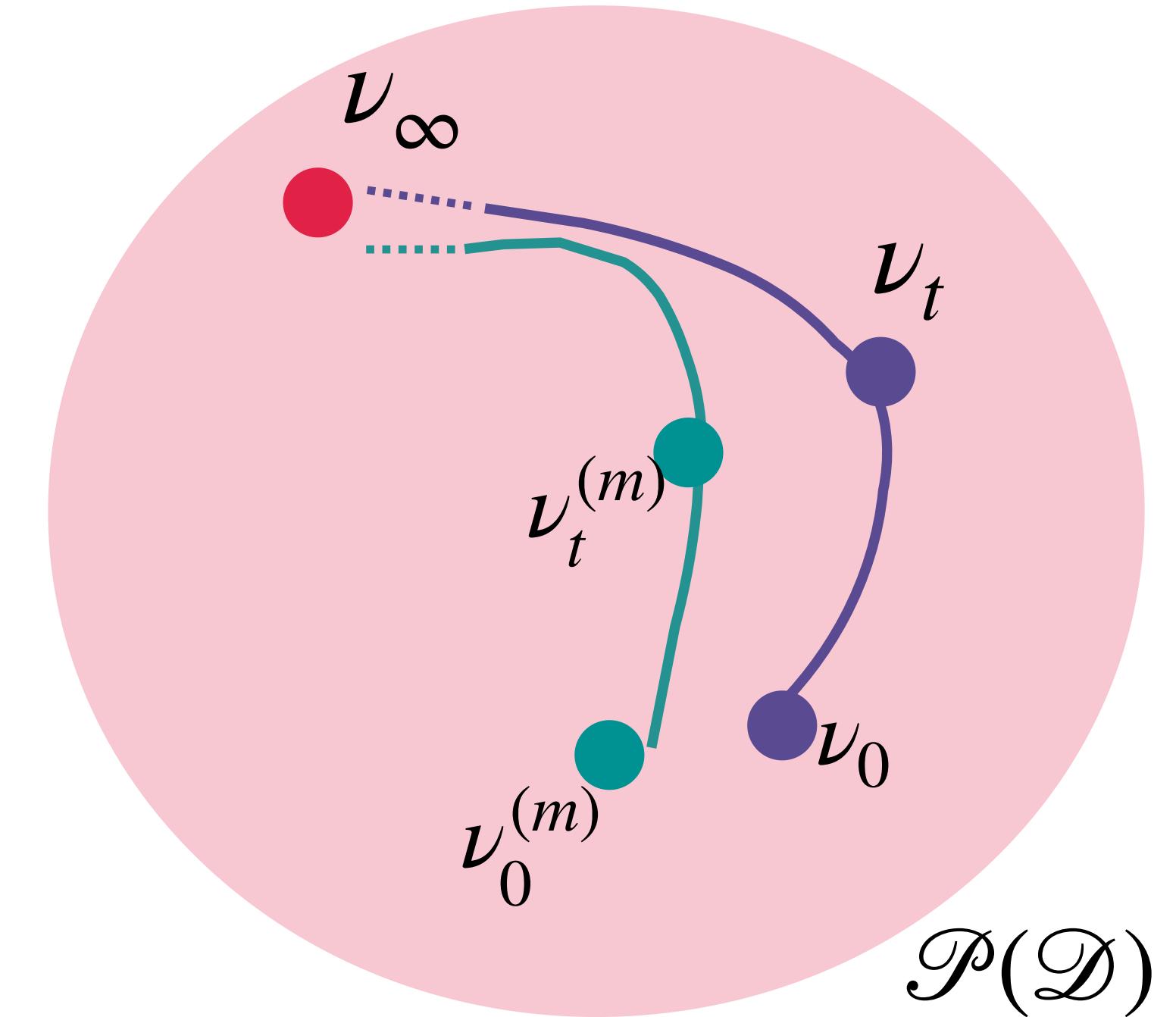
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# PoC via Mean-Field Langevin Contraction

[Chizat et al., Suzuki et al., Nitanda]

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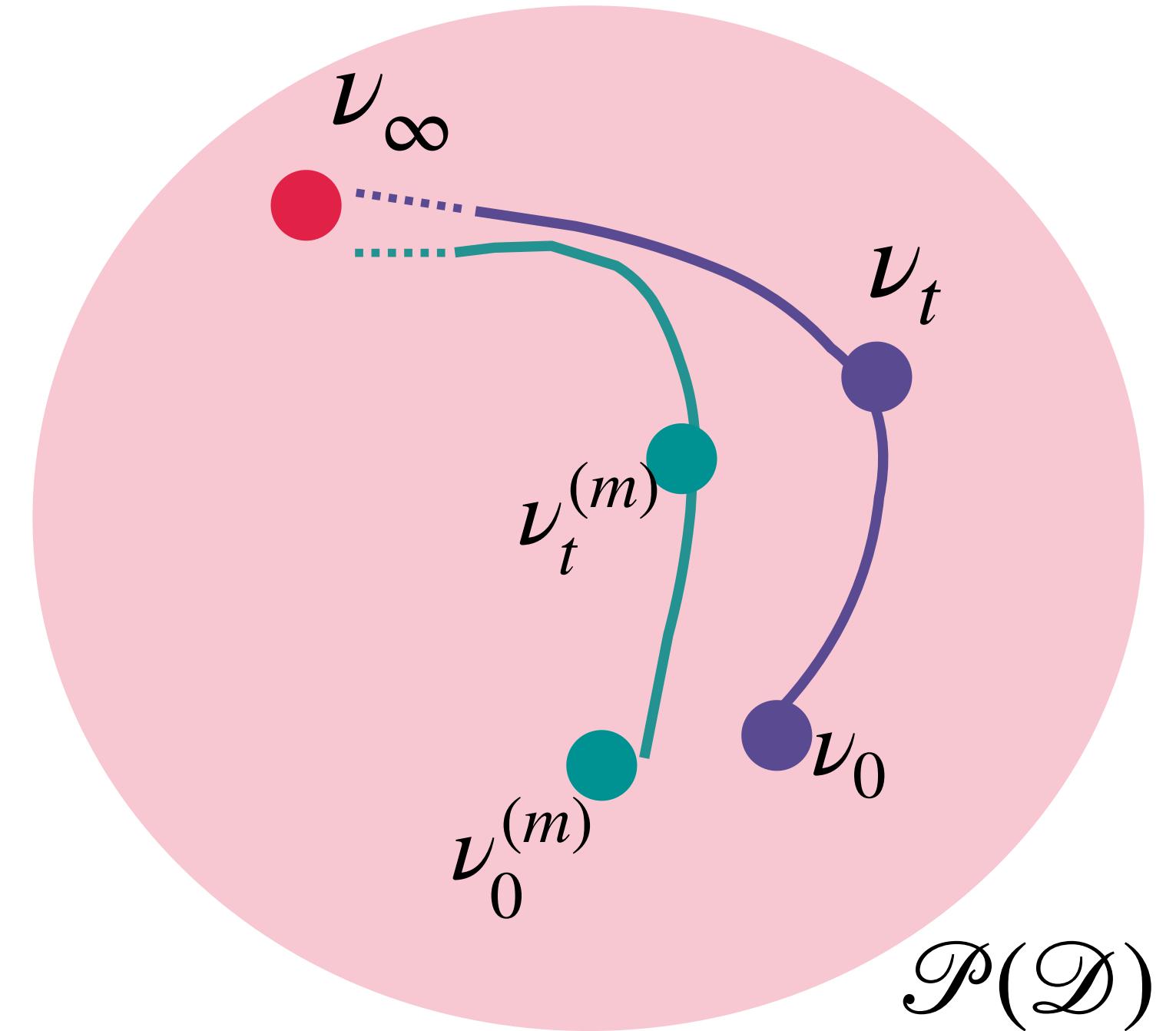
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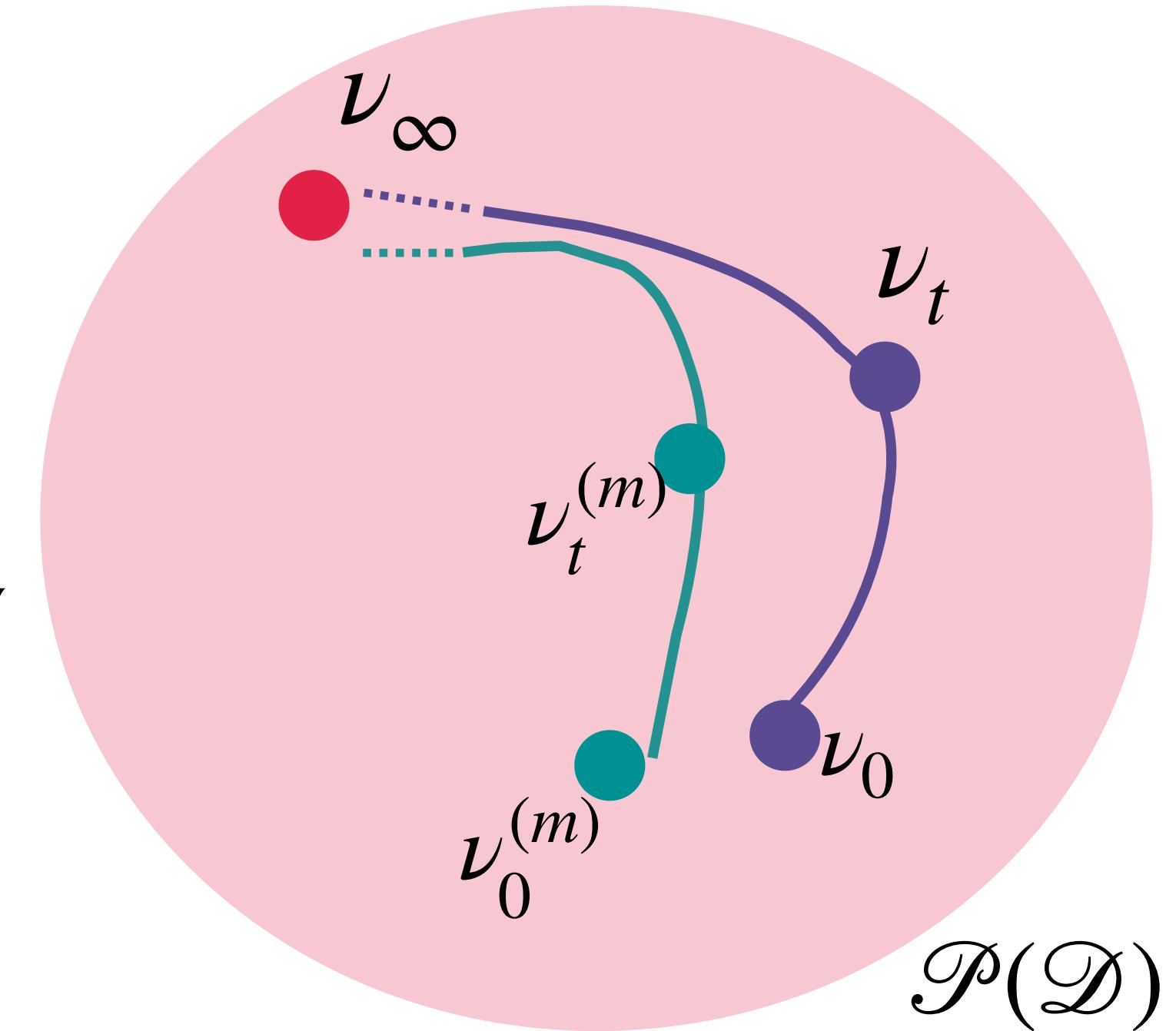


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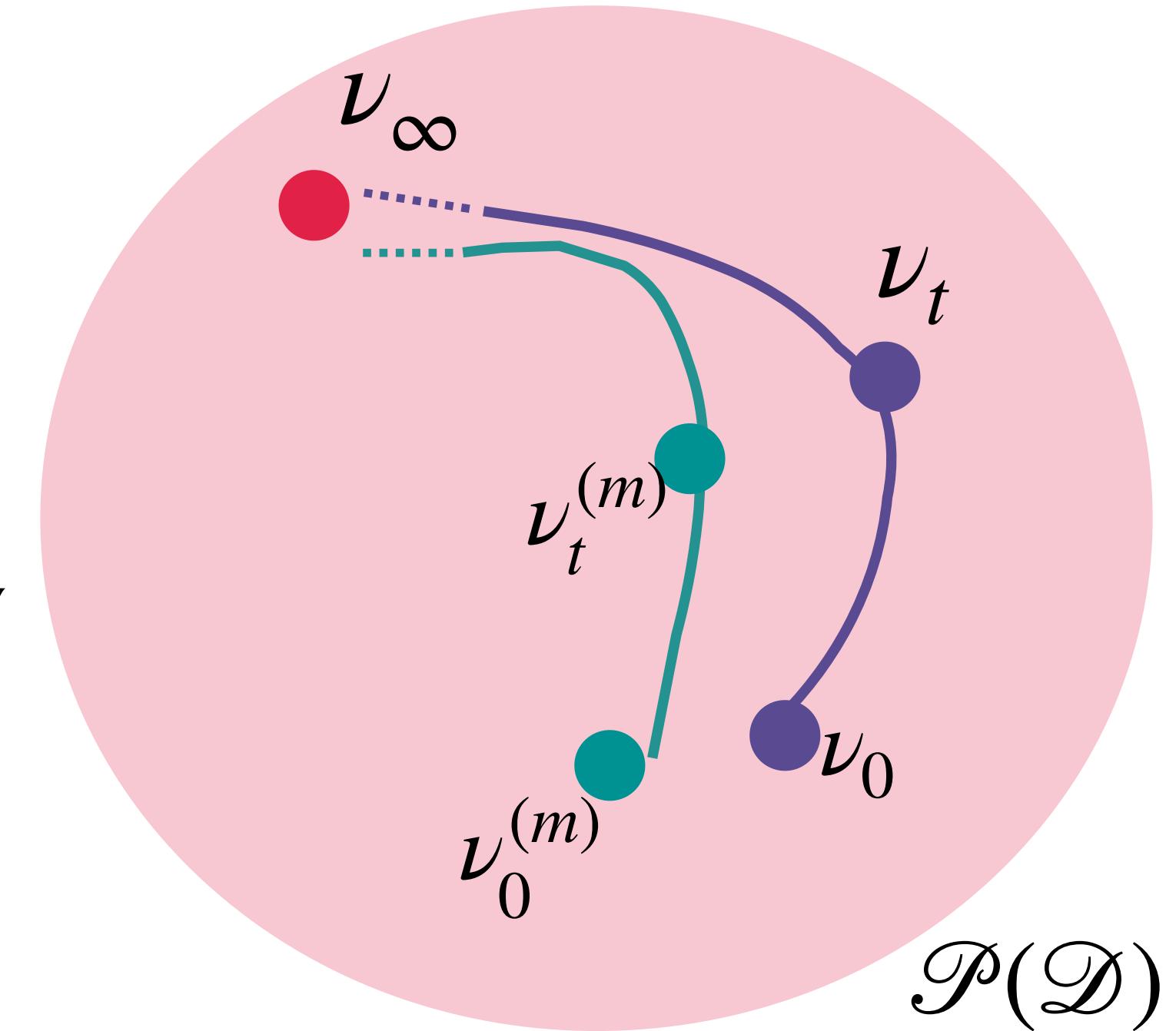


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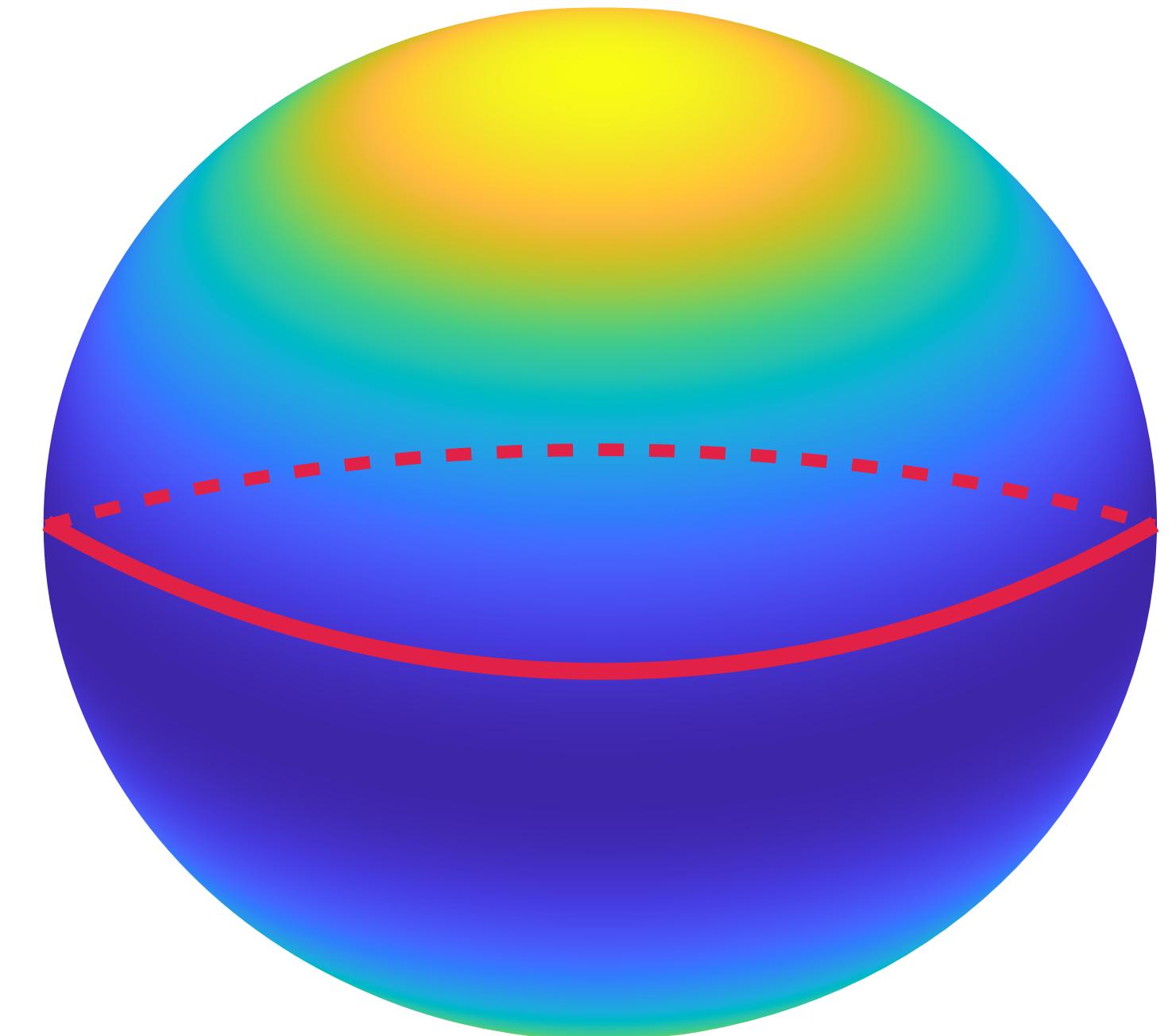
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Log-concavity is ‘artificial’ – noiseless alternative?

# Setup from now on

- Shallow NN architecture with unit-norm 1st-layer weights and fixed 2nd-layer weights:  $f(x) = \frac{1}{m} \sum_{j \leq m} \rho(\theta_j \cdot x)$ ,  $\theta_j \in \mathbb{S}^{d-1}$ .
- Planted setting:  $y = f_{\nu^*}(x)$  for some  $\nu^* \in \mathcal{P}(\mathbb{S}^{d-1})$ .
- Training by Spherical Gradient Flow:  
$$\frac{d}{dt} \theta_j = (I - \theta_j \theta_j^\top) \nabla_{\theta_j} \mathbb{E}_x [ |f(x) - f_{\nu^*}(x)|^2 ]$$

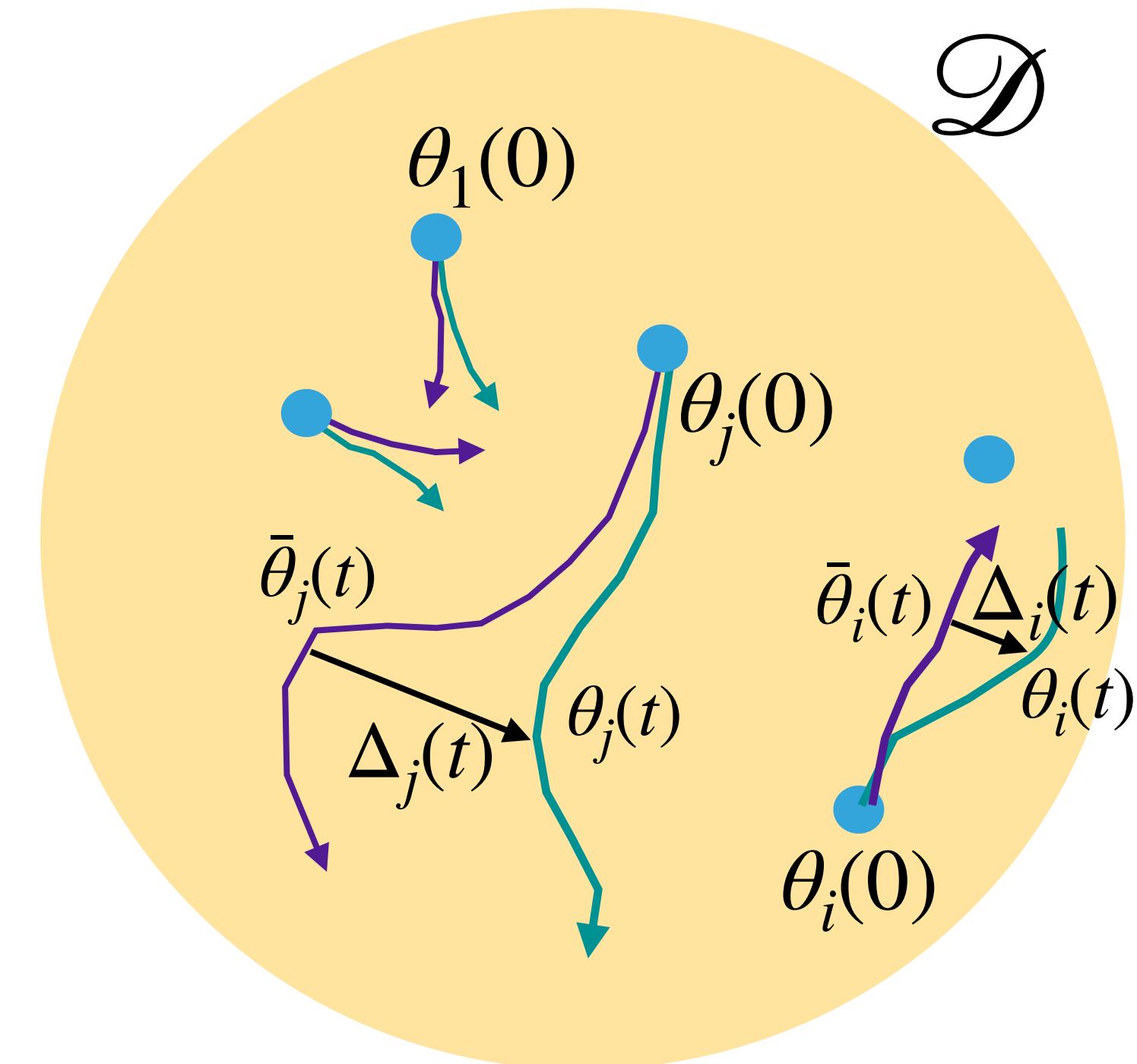


# Dissecting the Coupling Dynamics

- In regression, instantaneous potential writes

$$U(\theta; \rho) = -F(\theta) + \int K(\theta, \theta') d\rho(\theta'), \text{ with}$$

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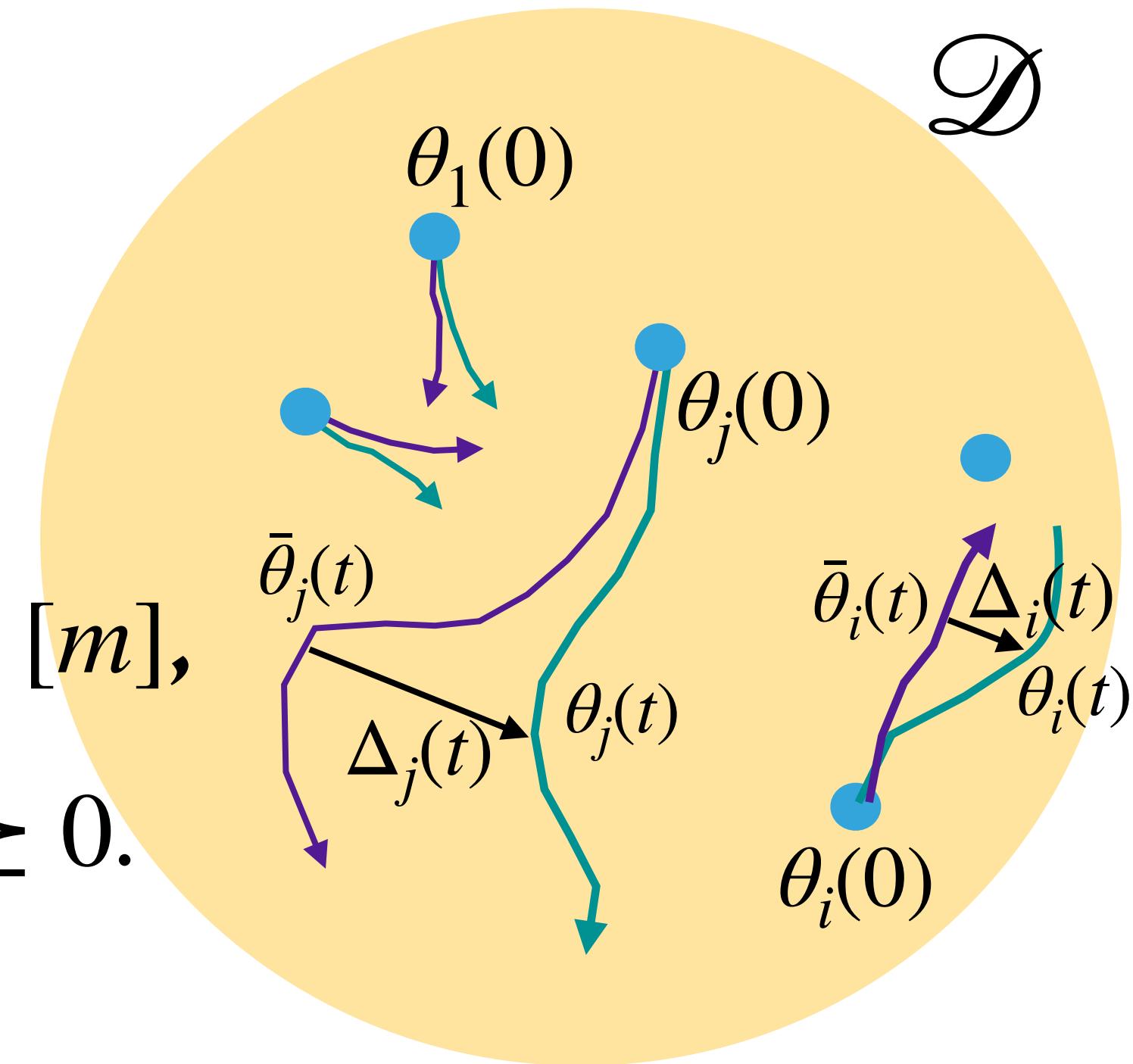
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$\nabla, \nabla^2$  : Spherical Gradient/ Hessian

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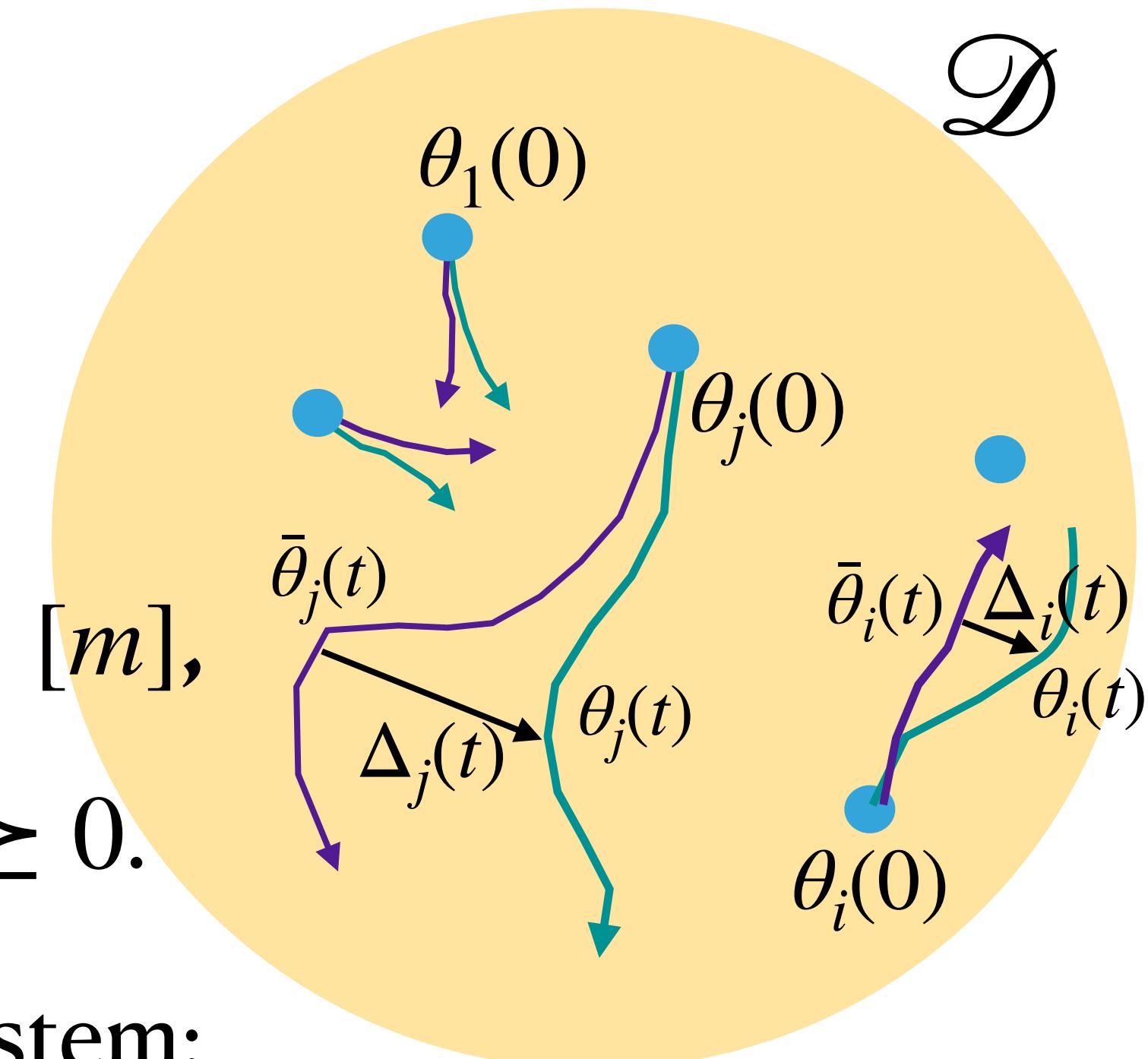
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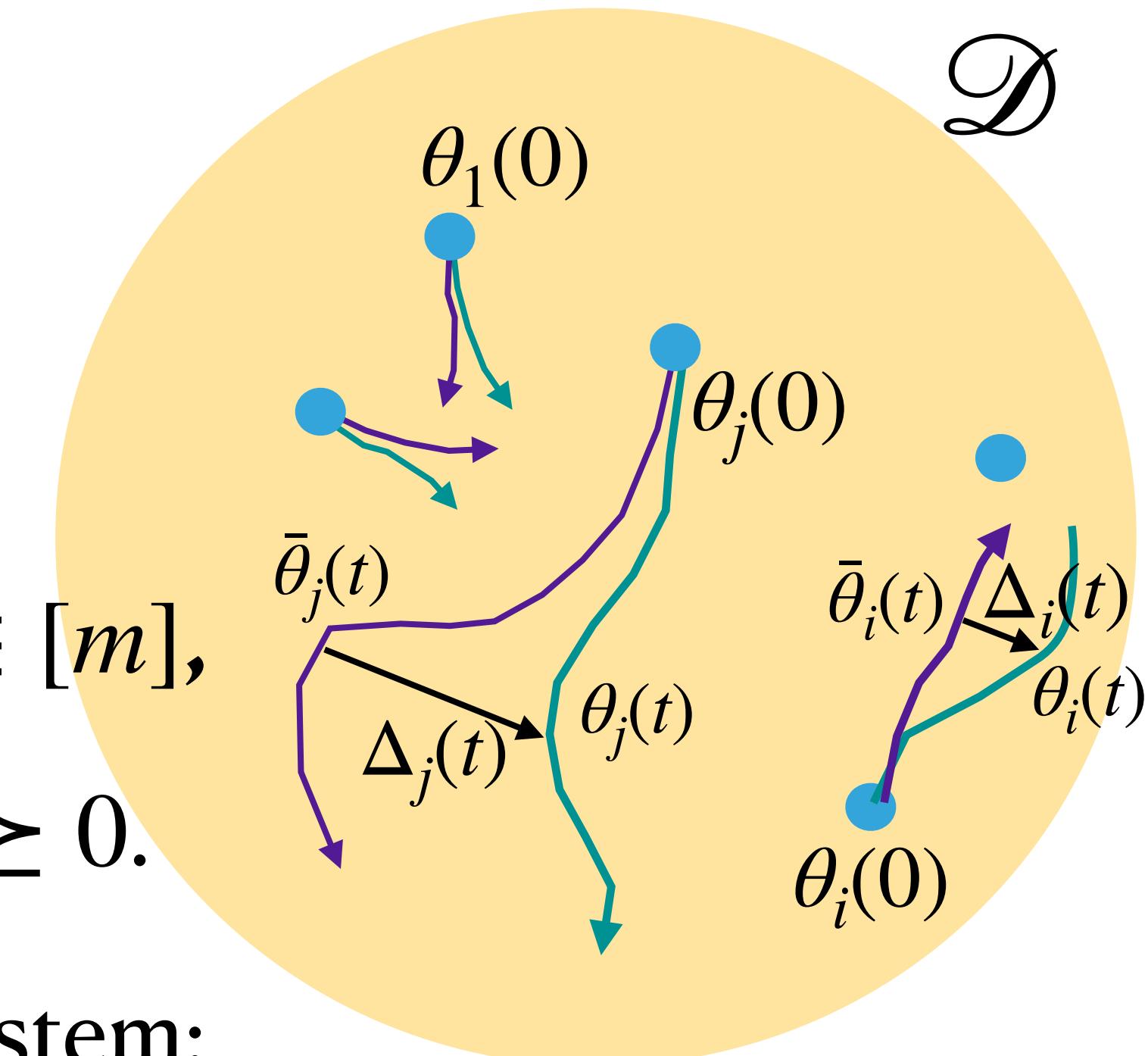
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“External field”

Interaction term

Source term

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# Dissecting the Coupling Dynamics

$$\frac{d}{dt} \Delta_i(t) - D_i(t) \Delta_i(t) = -\mathbb{E}_j[H_{i,j} \Delta_j(t)] + O(\|\Delta_i\|^2) + O(1/\sqrt{m}) := -\mathbb{E}_j[H_{i,j} \Delta_j(t)] + \epsilon_i(t)$$

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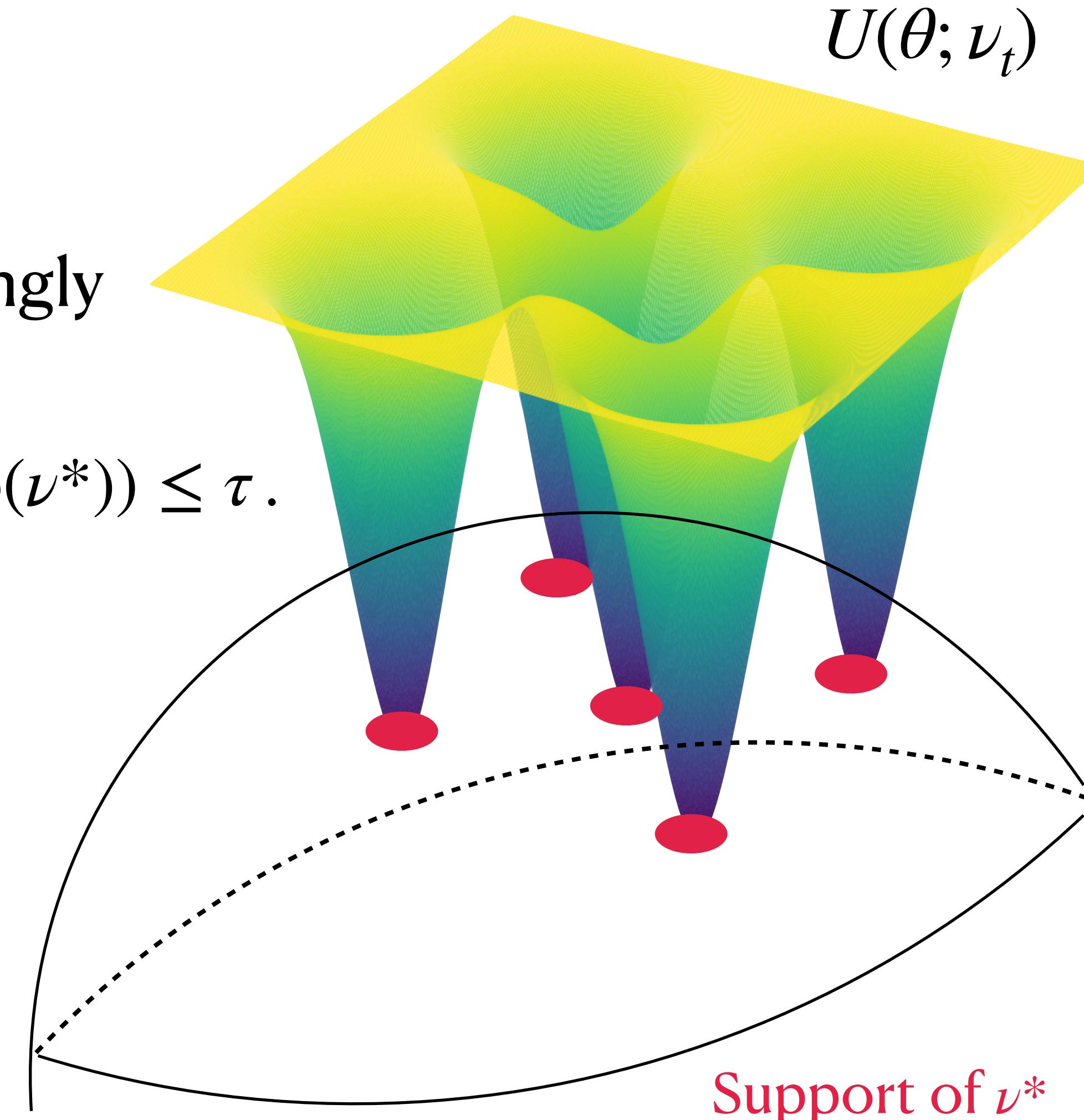
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Key ingredients to control growth?

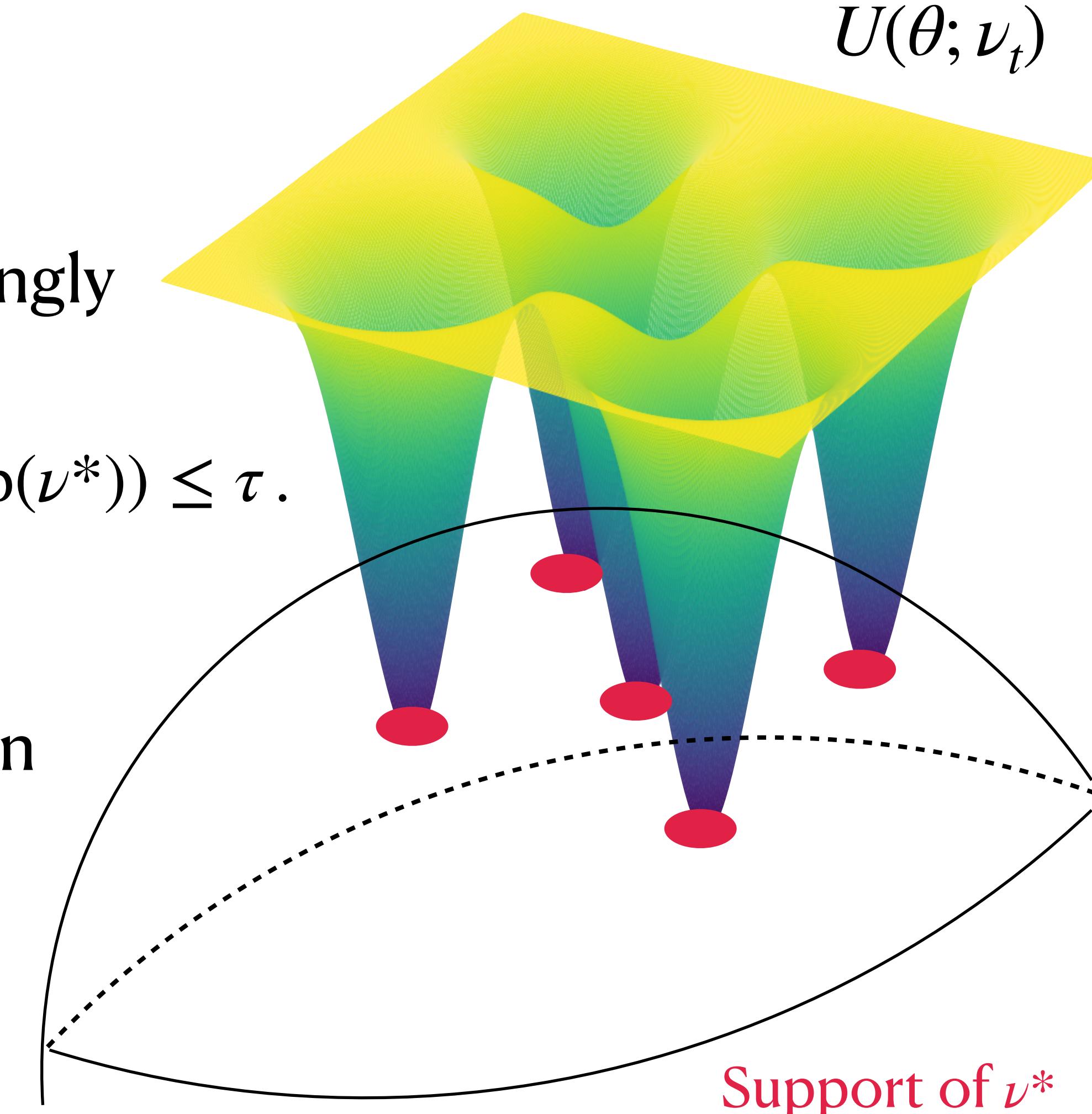
# Ingredient 1: Local Strong Convexity

- Let  $\xi_t(\theta)$  M-F flow map starting at  $\theta$ :  $\bar{\theta}_i(t) = \xi_t(\theta_i)$ .
- Instantaneous potentials  $U(\xi_t(\theta); \nu_t)$  are locally strongly convex in a neighborhood of  $\text{supp}(\nu^*)$ :  
$$\exists \tau > 0; \nabla_\theta^2 U(\xi_t(\theta); \nu_t) \geq C\sqrt{\mathcal{L}(\nu_t)} \mathsf{P}_\theta^\mathbb{S} \text{ for } \text{dist}(\xi_t(\theta), \text{supp}(\nu^*)) \leq \tau.$$



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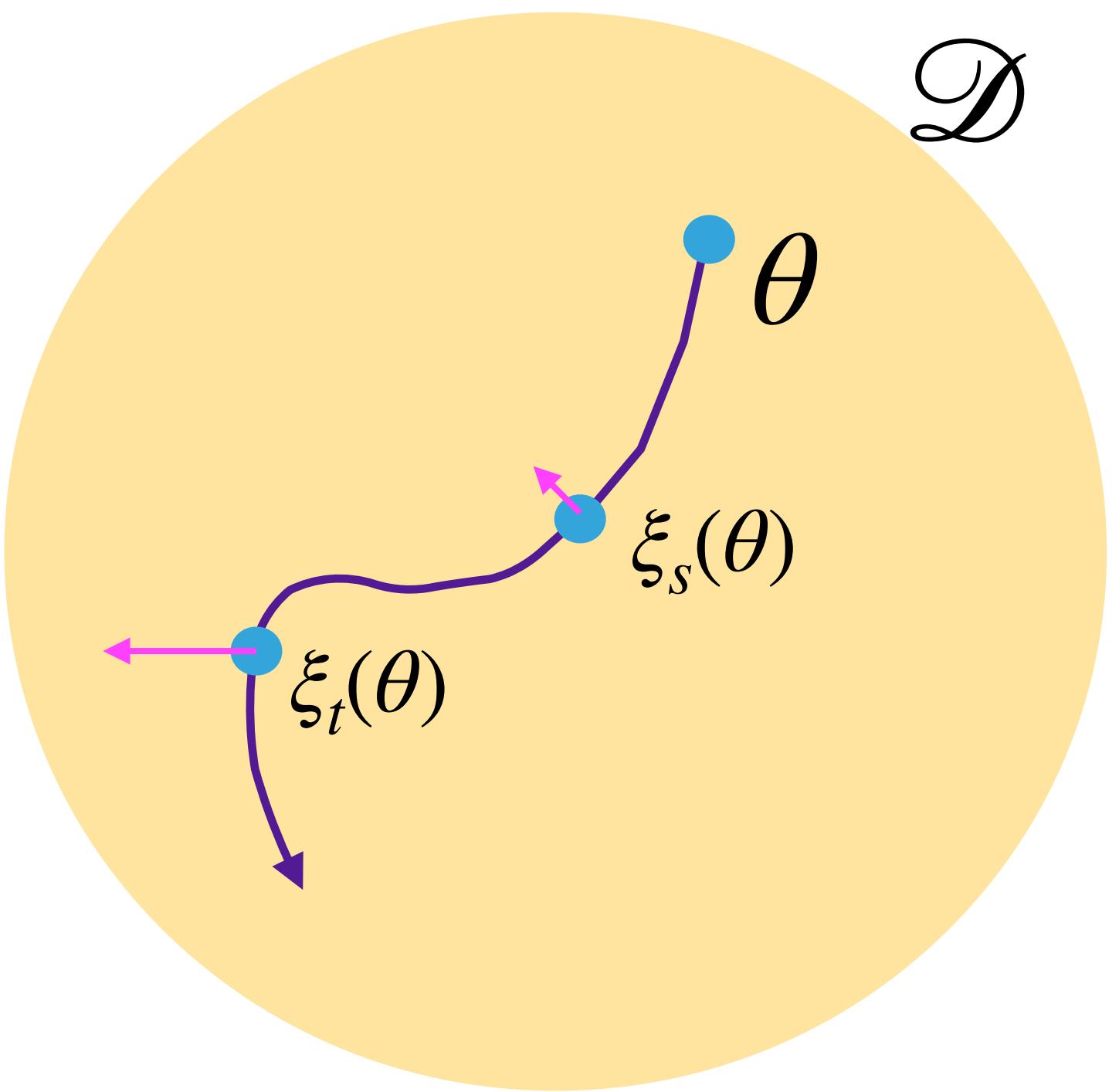
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- Implies that  $\nu^*$  is atomic in current formulation.
- Also exploited in [Chizat'19] [Chen et al.'20] to obtain uniform-in-time, asymptotic (in  $m$ ), PoC.



# Ingredient 2: Stability

- Local stability matrix now defined for any initial condition:

$$J_\theta(t, s) := \exp \left( \int_s^t \nabla^2 U(\xi_u(\theta); \nu_u) du \right).$$



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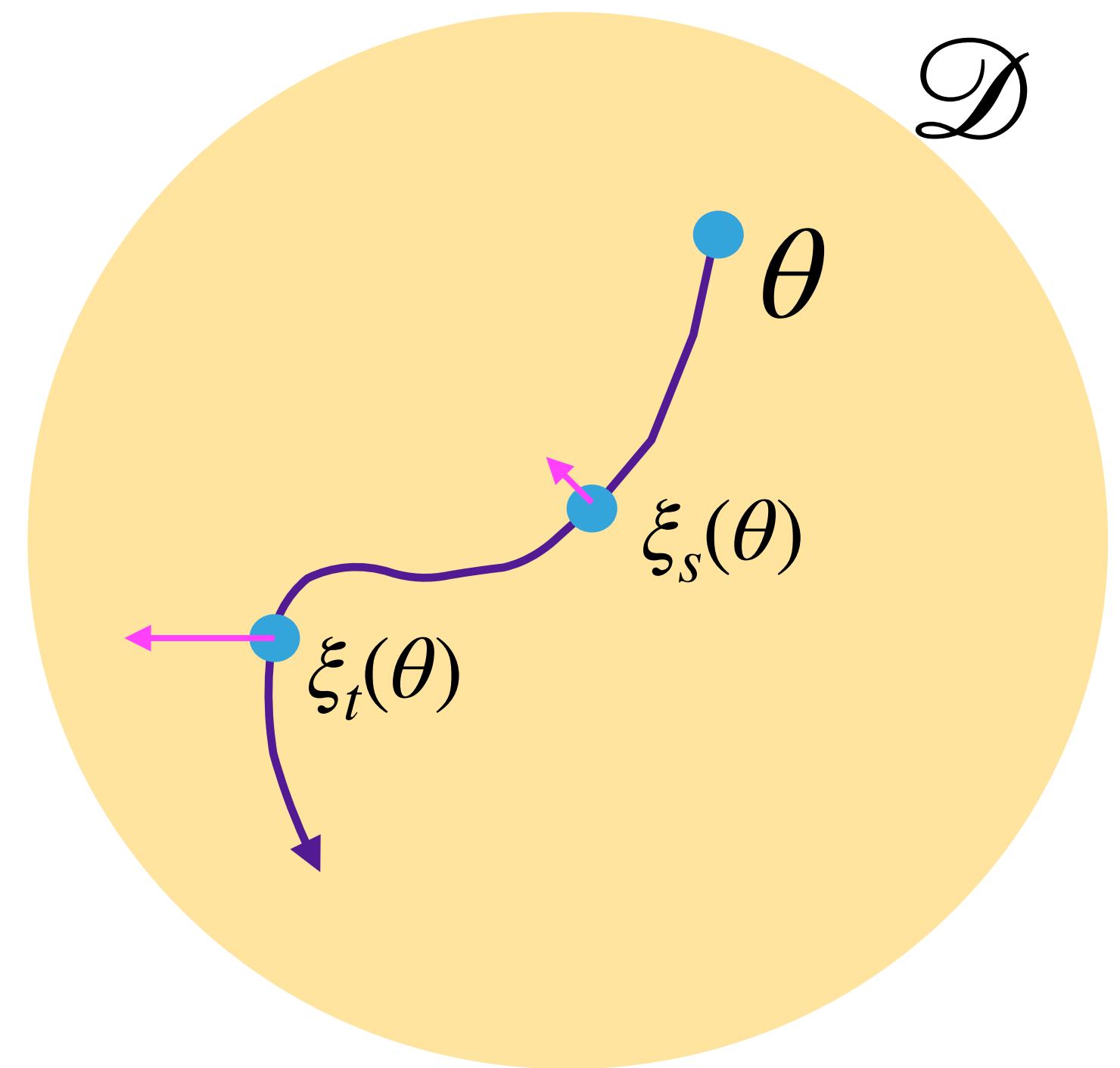
- For a desired convergence time  $T$ , we assume:

1. *Uniform* Stability:  $\sup_{s \leq t \leq T, \theta} \|J_\theta(t, s)\| = \text{poly}(d, T)$ ,

2. *Average* Stability far from convergence:

$$\sup_{s \leq t \leq T, \theta'} \mathbb{E}_\theta [\|J_\theta(t, s) H_{\theta, \theta'}(s)\| \cdot \mathbf{1}(\text{dist}(\xi_t(\theta), \text{supp}(\nu^*)) > \tau)] \lesssim \text{poly}(\tau^{-1})/T$$

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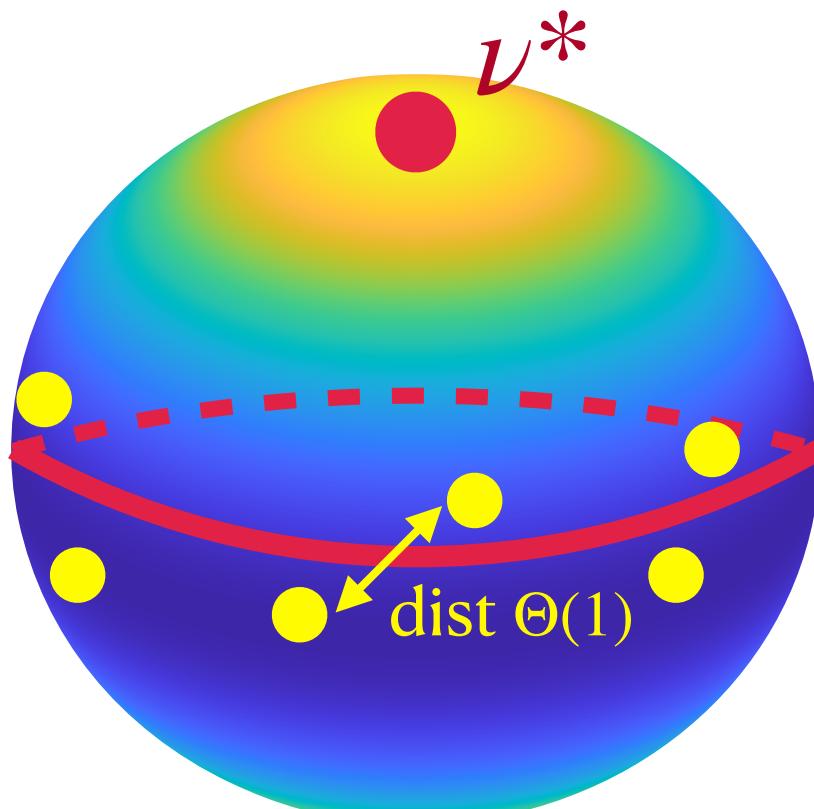
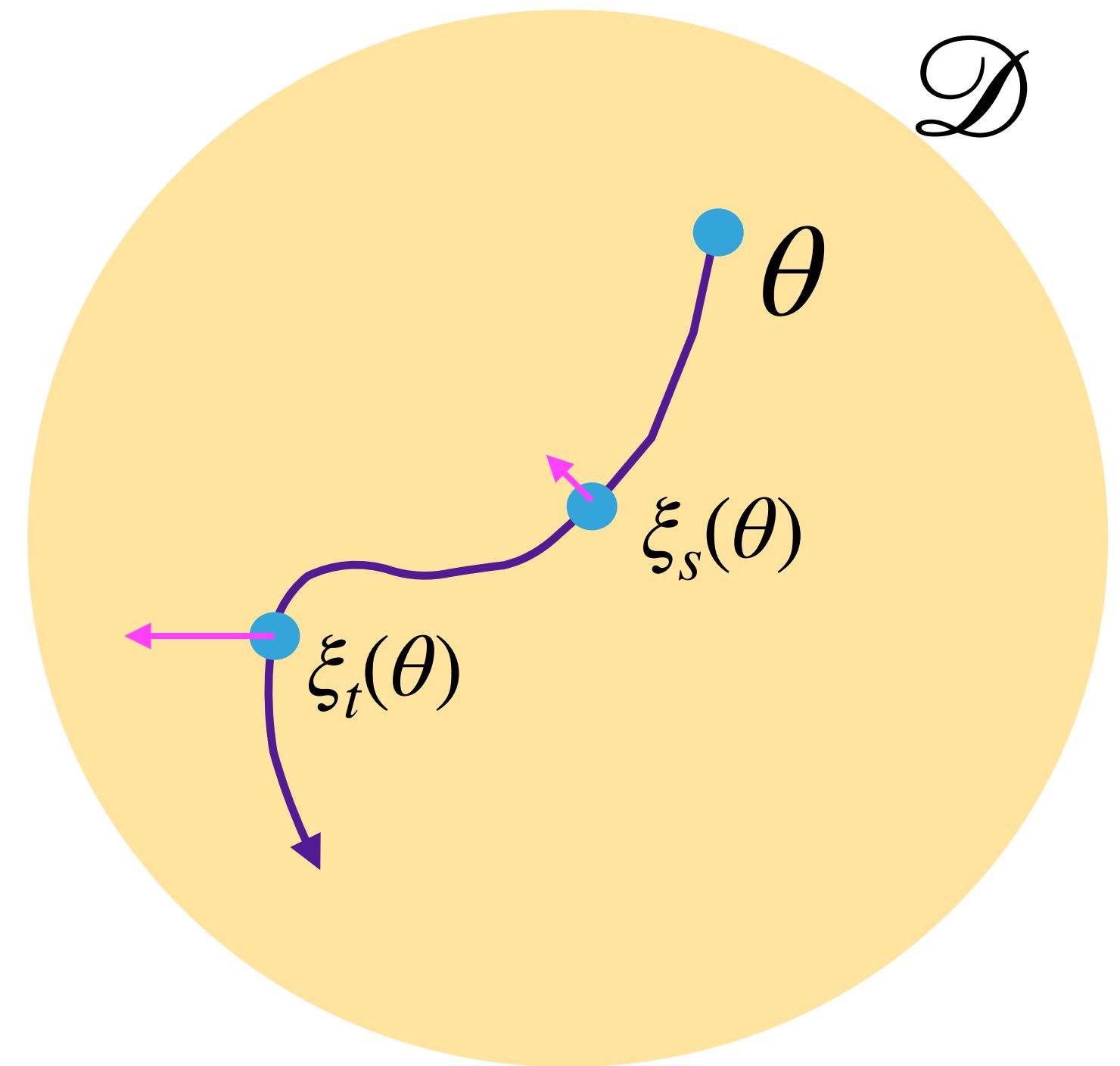
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“Self-concordance” property:  
sharpness  $\|D_\theta(t)\| \lesssim \|\nabla U(\theta_t, \nu_t)\|$

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Neurons ‘dispersed’ before converging



# Main Result

- Under local strong convexity and stability, we have quantitative PoC:
- **Theorem** [GWB'25], informal: Assume **LSC** and **Stability** over horizon  $T$ , plus technical regularity assumptions. Then whp  $\mathcal{E}(\nu_T, \nu_T^{(m)}) \lesssim \frac{\text{poly}(d, T)}{\sqrt{m}}$ .

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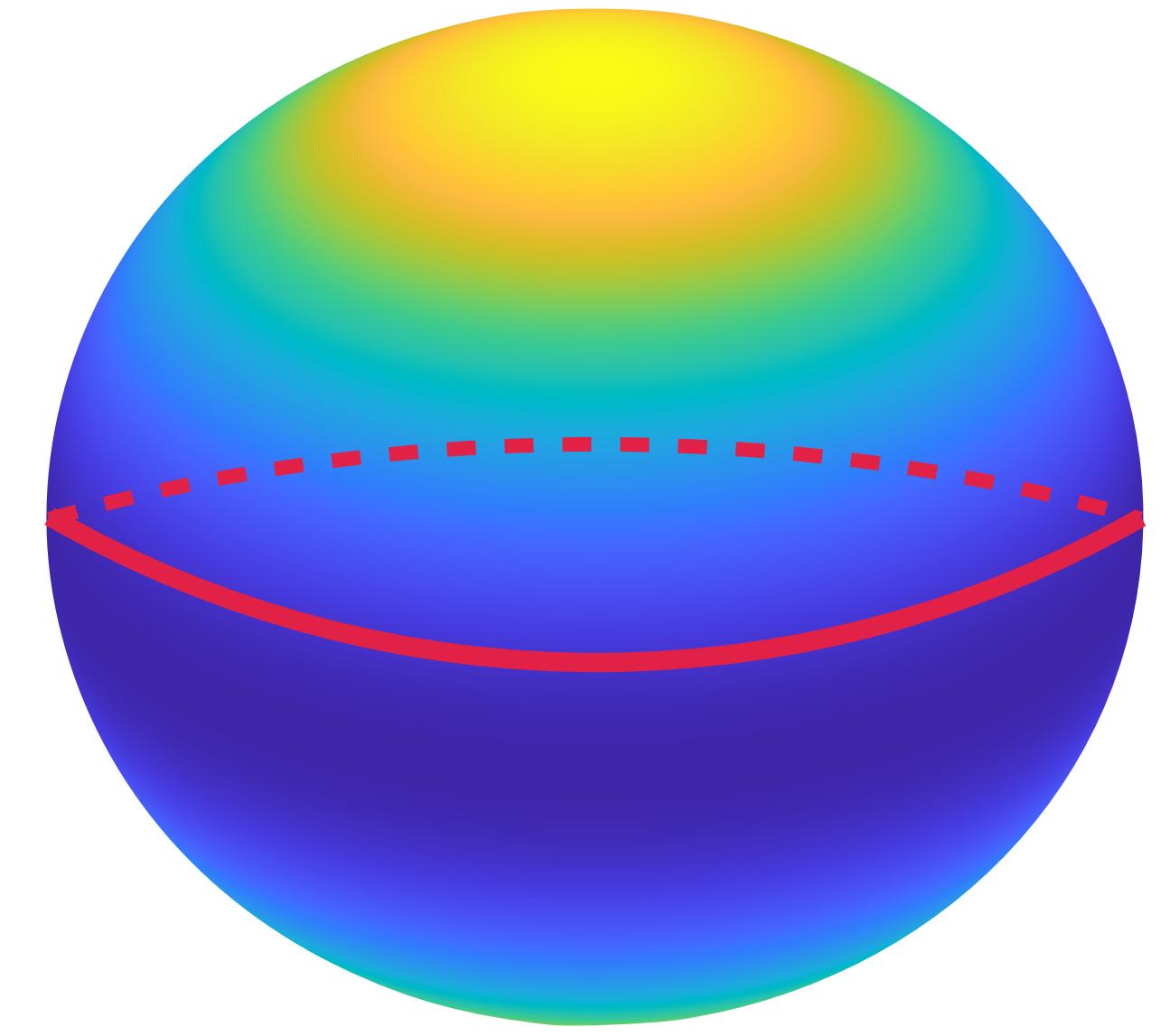
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When can we verify these assumptions?

# Application: Single-Index Models

- Well-specified, Gaussian setting:  $x \sim \mathcal{N}(0, I_d)$ ,  $y = \rho(\theta^* \cdot x) + w$ ,
- $\rho$  :even function with Information-Exponent  $k^* \geq 4$ .

• **Theorem** [GWB'25]: Let  $f_{\nu_t^{(m)}}(x) = \frac{1}{m} \sum_{j \leq m} \rho(\theta_j(t) \cdot x)$  trained with L2-loss on  $n$  iid samples for  $T = O(\delta^{-k^*+1} d^{k^*/2-1})$ . Then if  $m \gtrsim d^{13k^*}$ ,  $n \gtrsim d^{11k^*}$ , we have whp  $\|f_{\nu_T^{(m)}} - f^*\|^2 = O(\delta^2)$ .

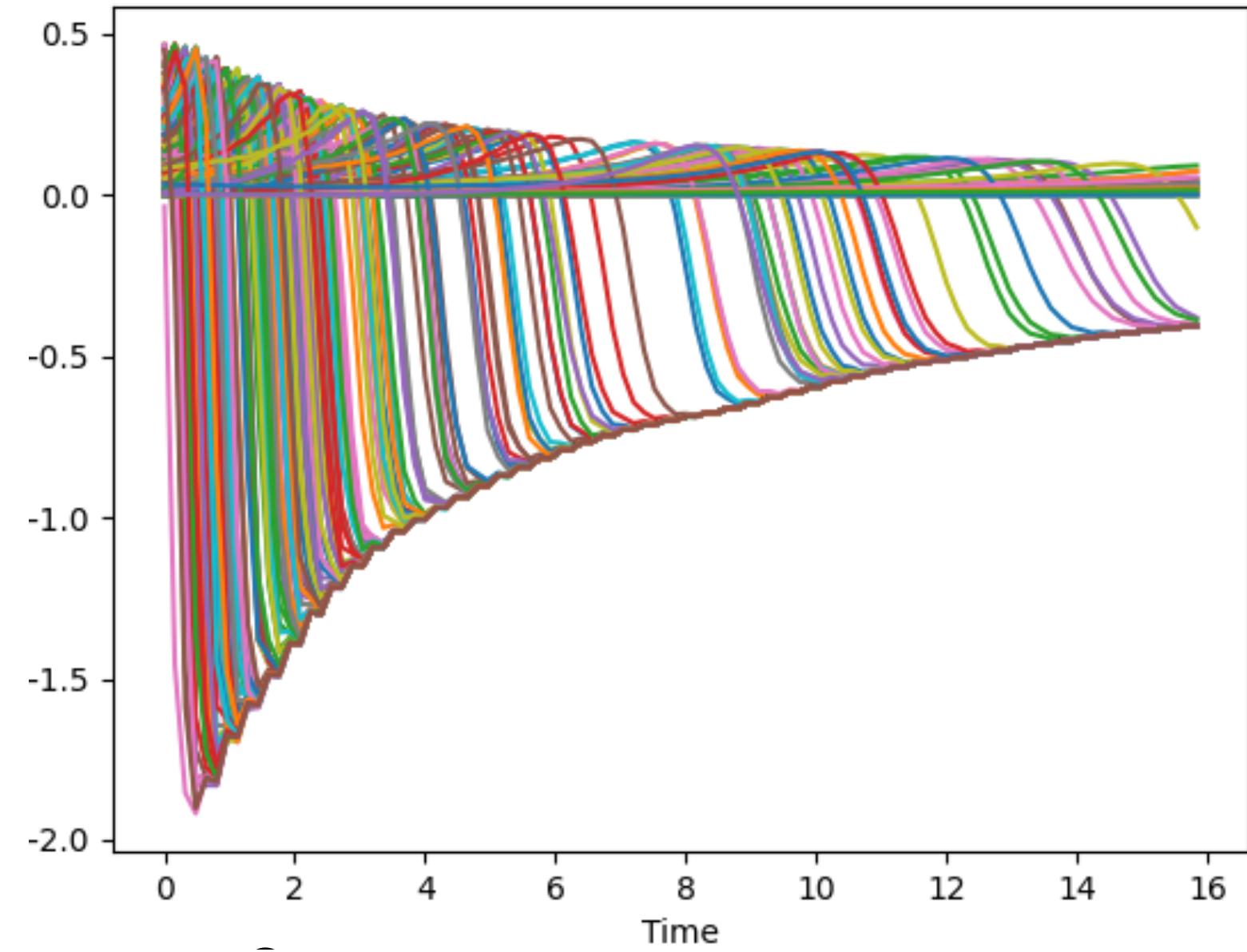
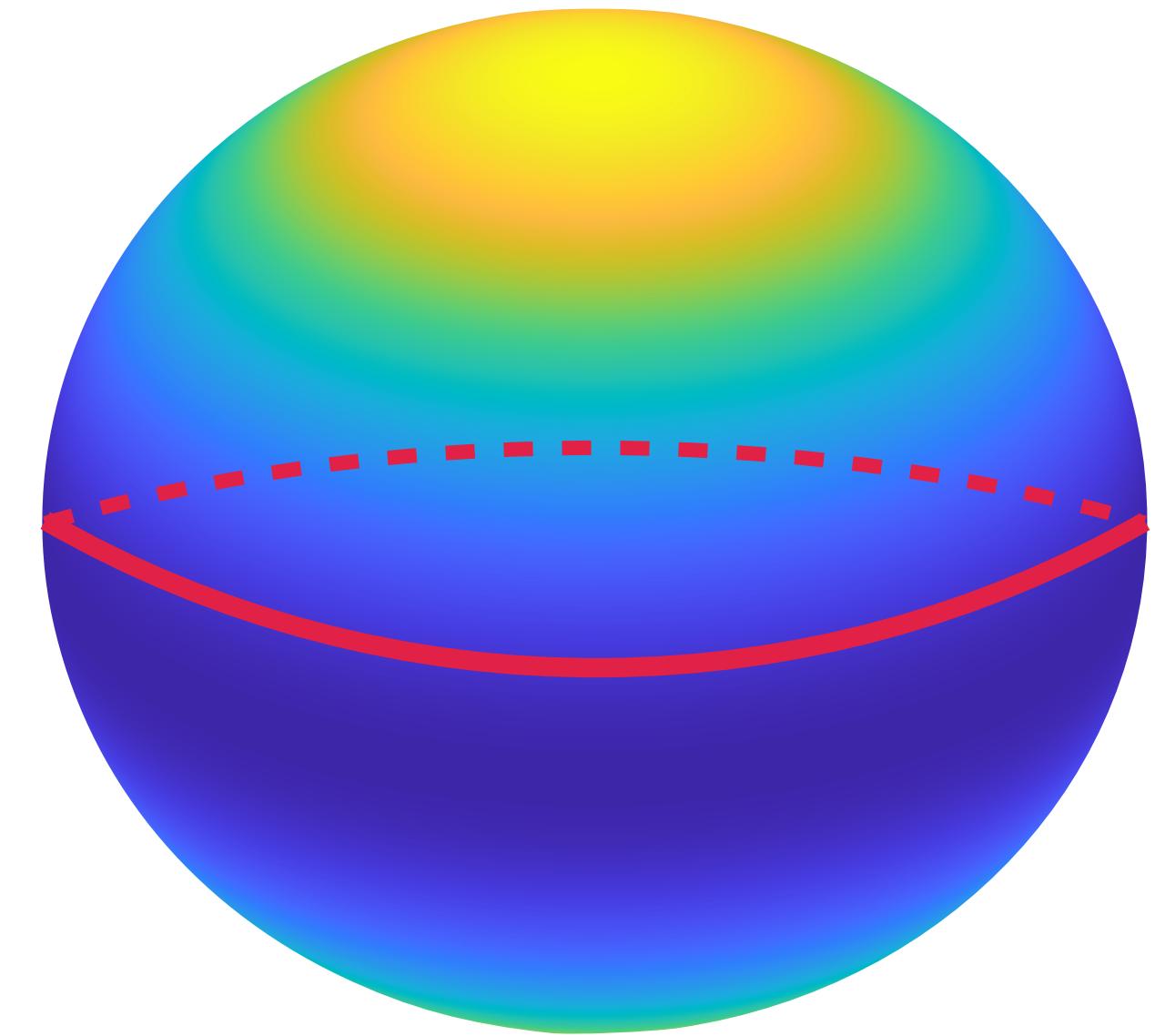


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- $k^* = 2$  violates current stability assumptions; covered in [Damian et al.'22], [Mahankali et al].
- Exploits *self-concordance* of SIM landscapes:  
$$\|\nabla^2 U(\theta)\| \simeq (\theta \cdot \theta^*)^{-1} \|\nabla U(\theta)\|.$$



# Proof Overview

$$\frac{d}{dt} \Delta_i(t) = D_i(t) \Delta_i(t) - \mathbb{E}_j[H_{i,j} \Delta_j(t)] + \epsilon_i(t).$$

Self-interaction: driven by local Hessian  $\nabla^2 U(\theta; \nu_t)$   
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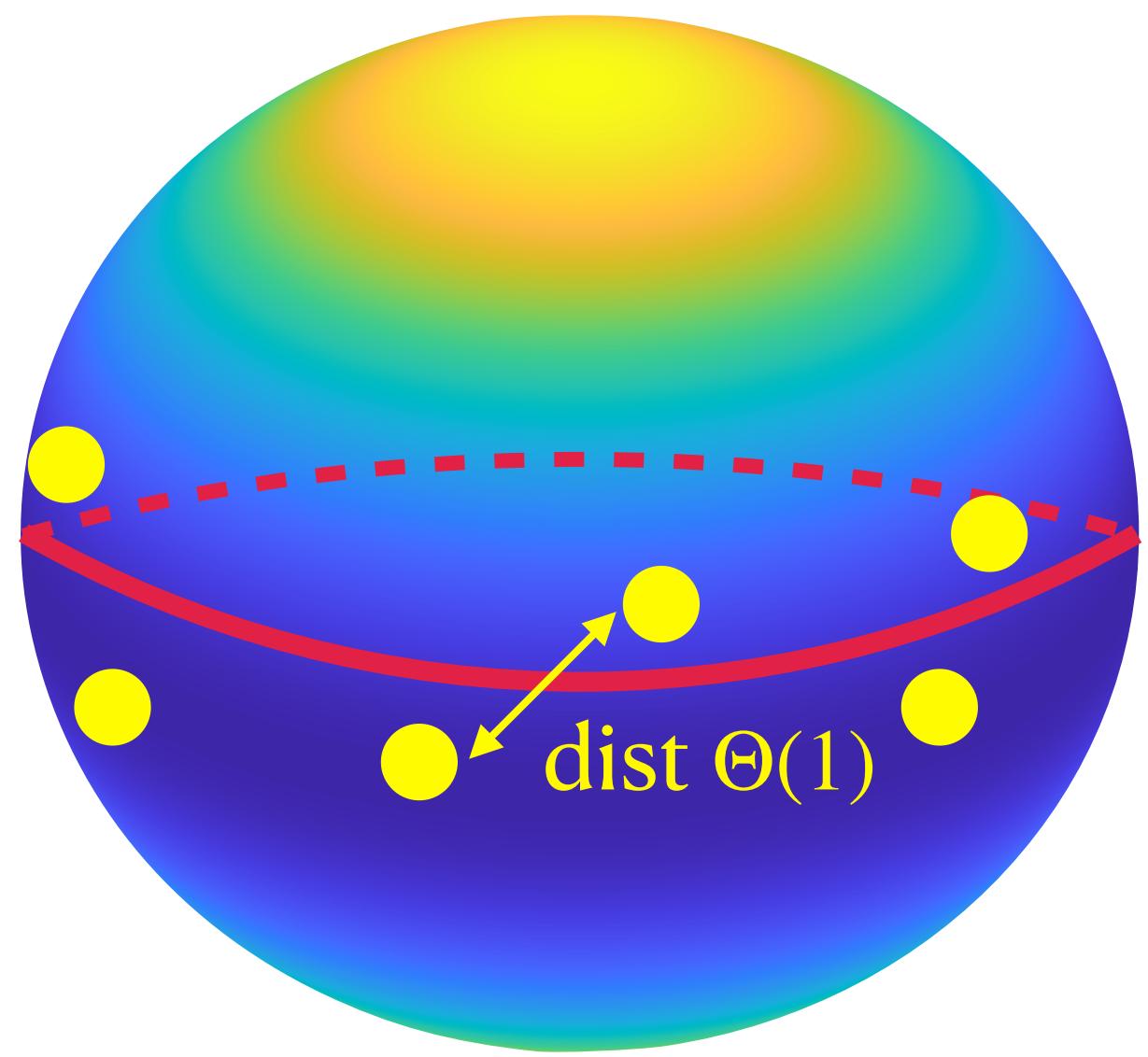
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- Near initialisation, dynamics are driven by local term  $D_i(t)$ , thanks to the average stability assumption (neurons are dispersed before converging).



# Proof Overview

$$\frac{d}{dt} \Delta_i(t) = D_i(t) \Delta_i(t) - \mathbb{E}_j [H_{i,j} \Delta_j(t)] + \epsilon_i(t).$$

Self-interaction: driven by local Hessian  $\nabla^2 U(\theta; \nu_t)$   
Interactions: driven by neuron repulsion kernel  $\nabla_\theta \nabla_{\theta'} K(\theta, \theta')$   
Source term: at Monte-Carlo scale  $O(1/\sqrt{m})$

- Near convergence, dynamics are driven by interaction terms  $H_{i,j}(t)$ :
- **Balanced Interaction Lemma:** If  $\mathbb{E}_i \|\Delta_i(s)\|_1$  is small, then interaction dynamics cannot increase it too much:

Let  $\frac{d}{dt} \Delta = -H\Delta$ , and consider eigendecomposition  $H(\infty) = \sum_{\lambda \in \Lambda} \lambda P_\lambda$ .

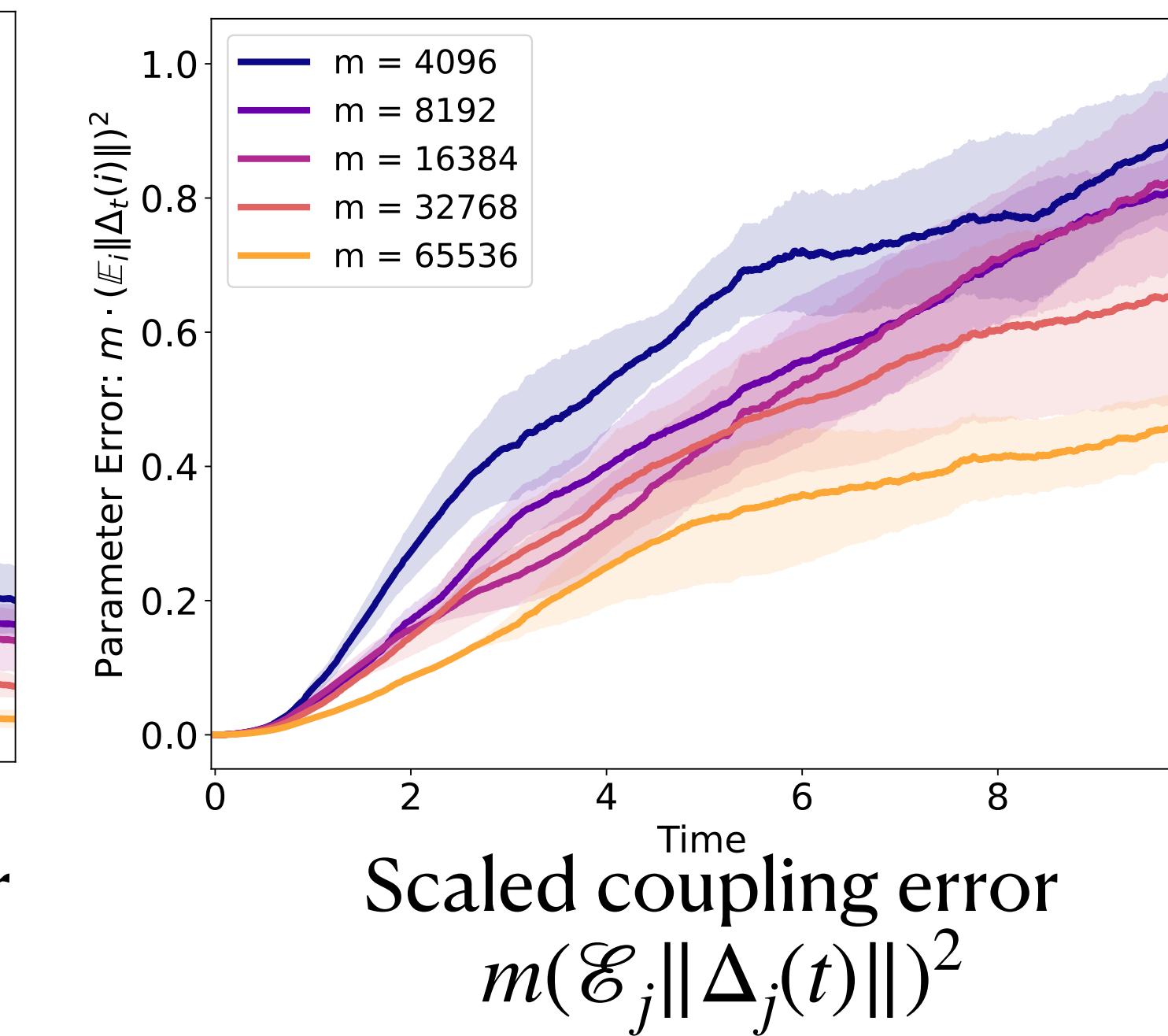
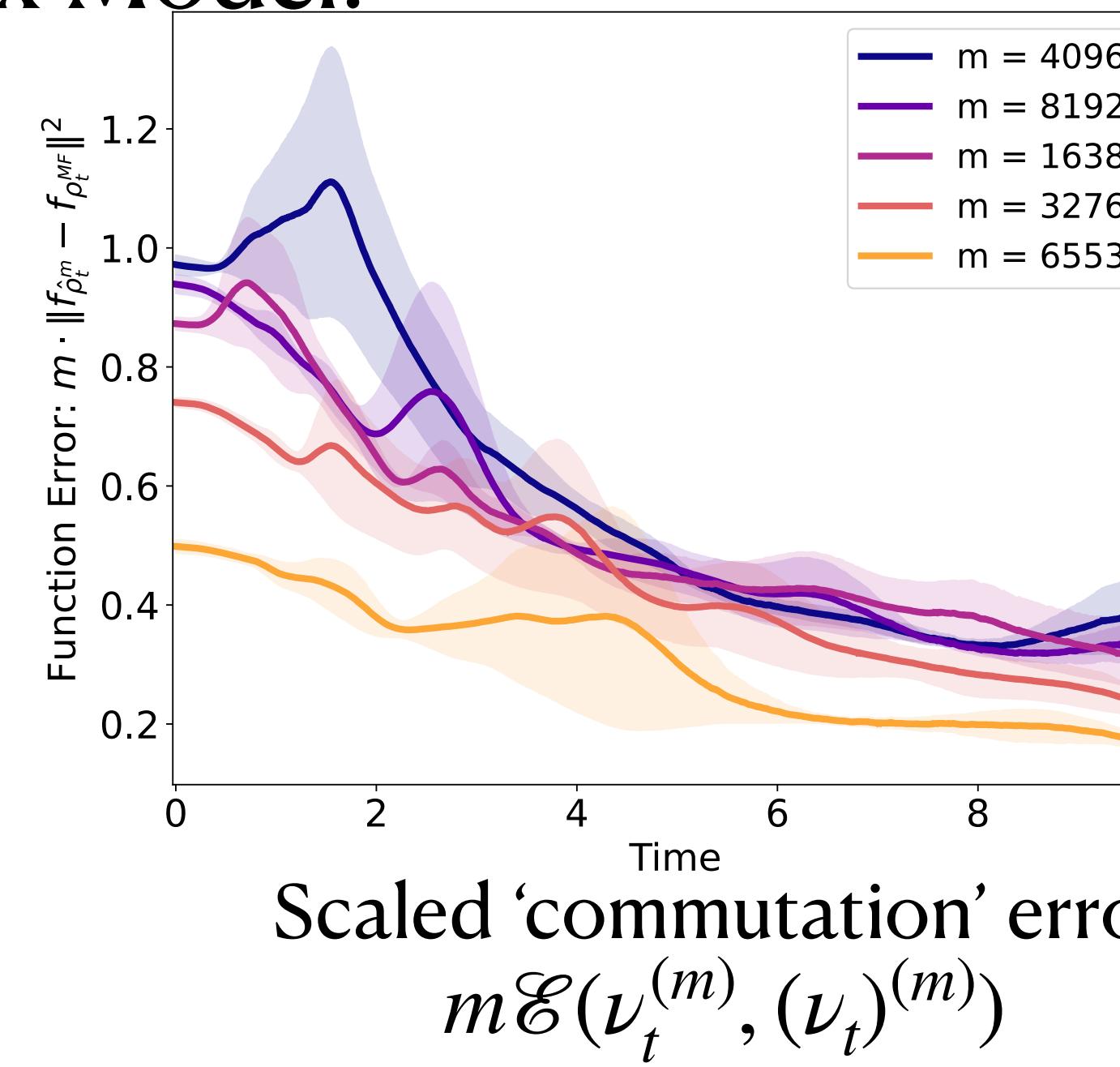
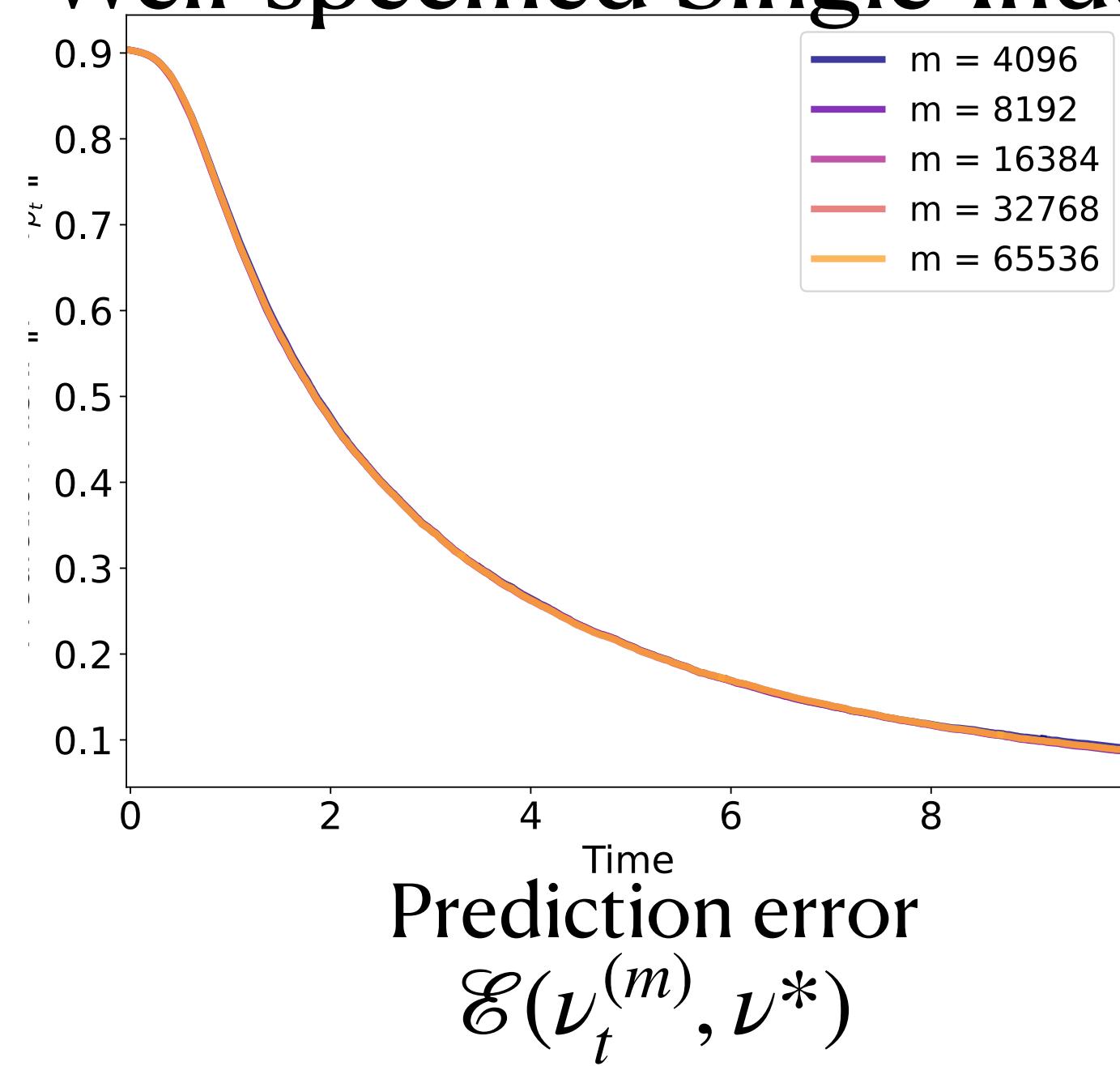
For  $t \geq s$ , we have  $\|\Delta(t)\|_1 \leq \|\Delta(s)\|_1 \sum_{\lambda} \|P_\lambda\|_\infty = \Theta(|\Lambda|) \|\Delta(s)\|_1$ .

- Exploited by designing appropriate potential function  $\Phi(t)$  that combines interaction at convergence  $H_\infty$  and surrogate quantity of interest  $\mathbb{E}_i \|\Delta_i(t)\|$ .

# Experiments

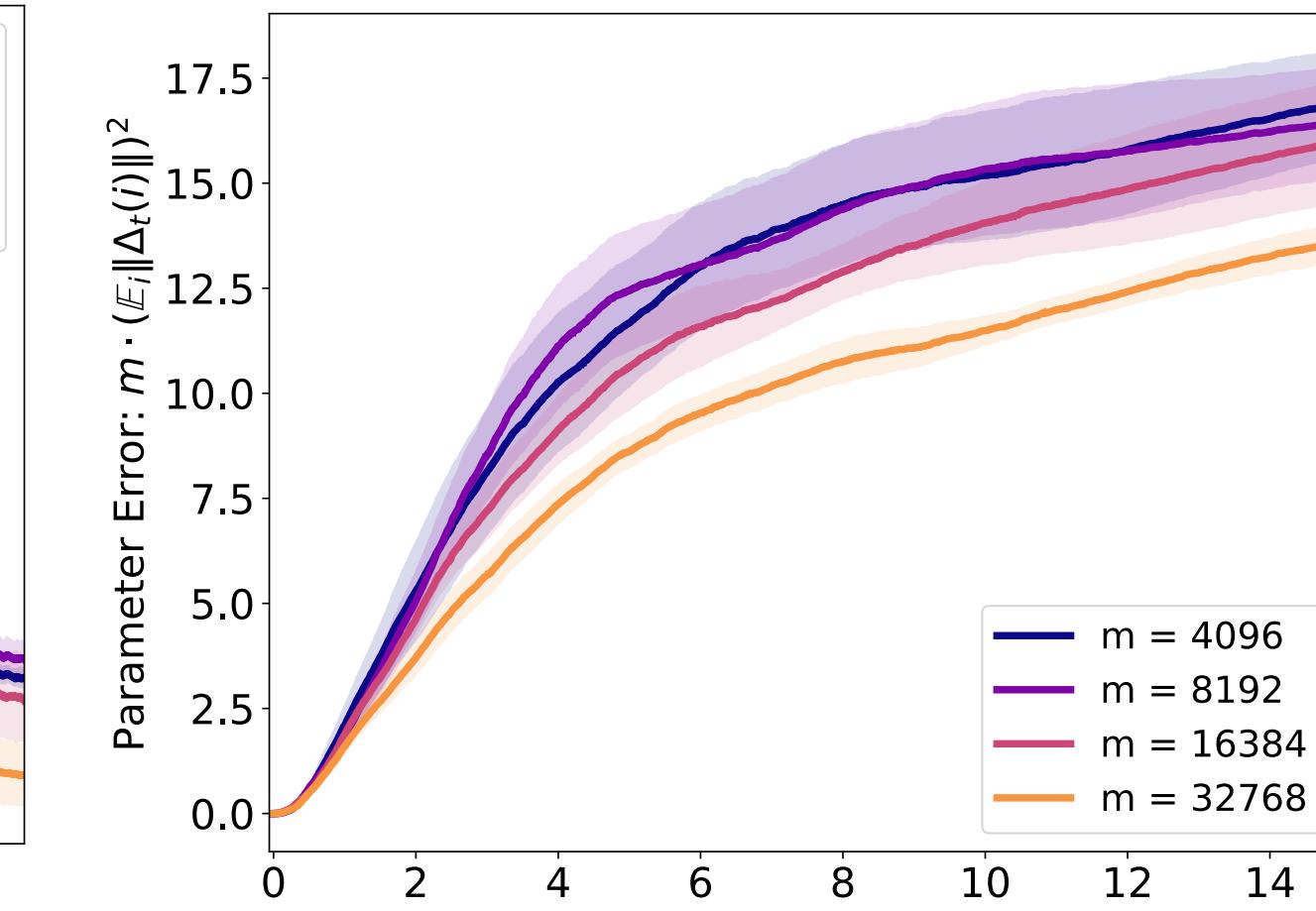
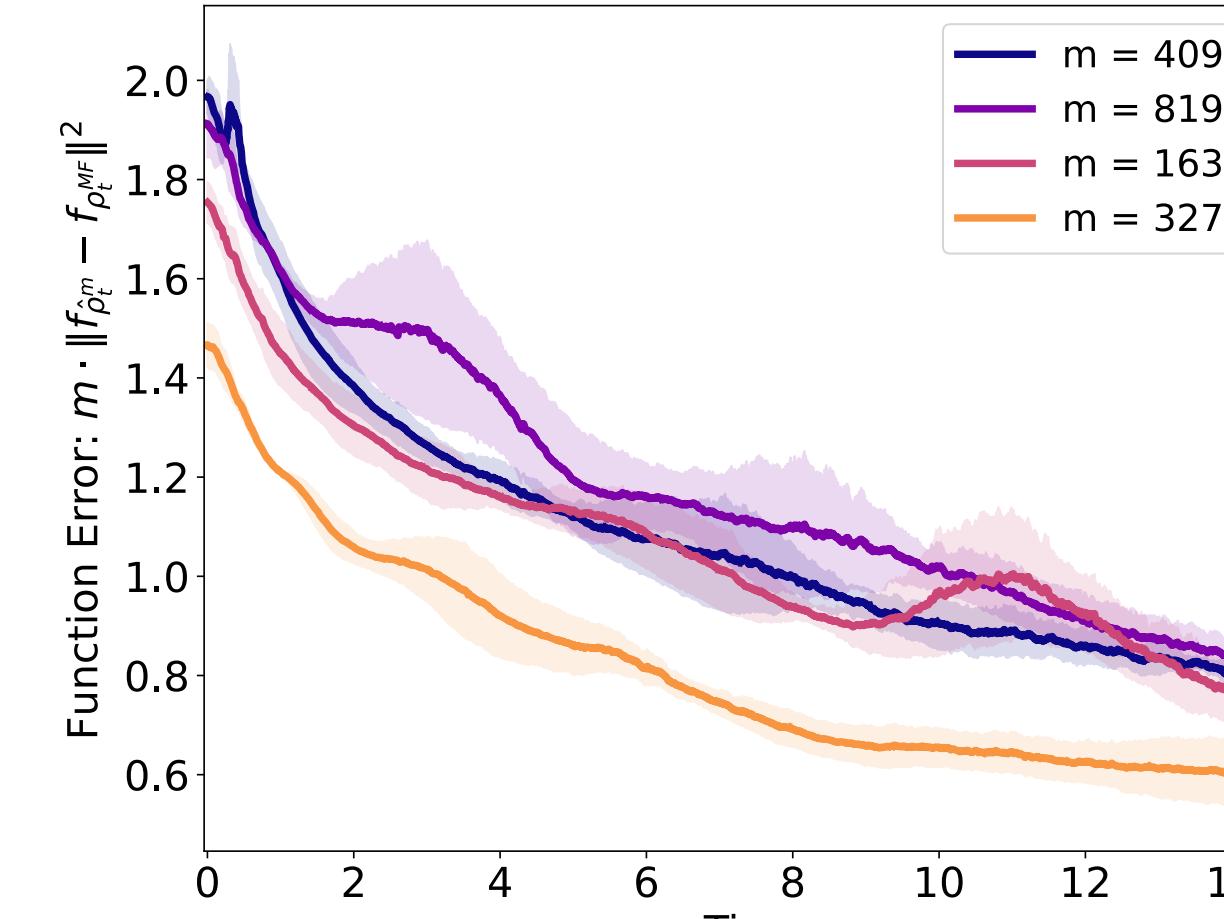
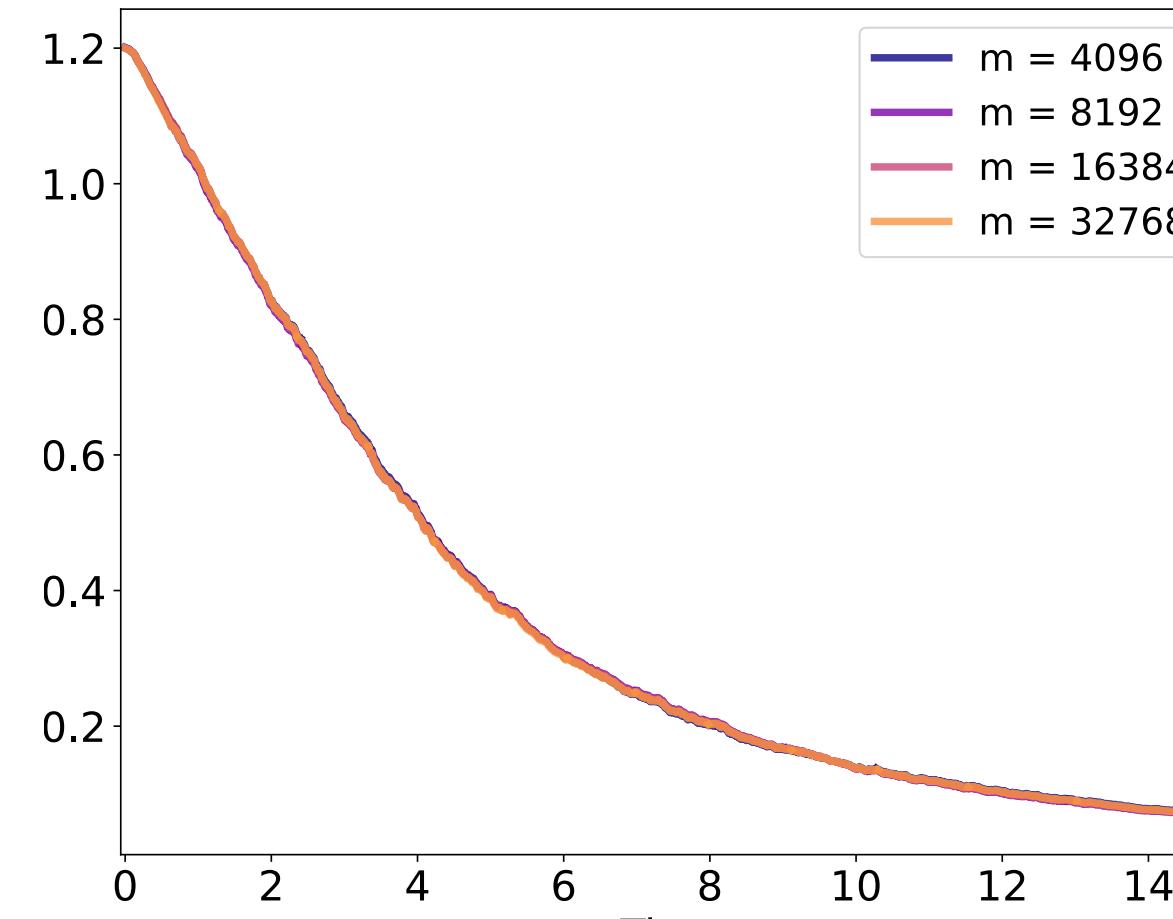
Name	Target Function	Activation/Network Design	LSC?	Symmetric?	$J_{\text{avg}}$ assm?
$\text{He}_4$	$\text{He}_4(x^\top e_1)$	$\sigma = \text{He}_4$	Yes	Yes	Yes
Circle	$\mathbb{E}_{w \sim \mathbb{S}^1} \text{He}_4(x^\top w)$	$\sigma = \text{He}_4$	No	Yes	Yes
Misspecified	$0.8\text{He}_4(x^\top e_1) + 0.6\text{He}_6(x^\top e_1)$	$\sigma = \text{He}_4 + \text{He}_6$	No	No	Yes
Random <sub>6,6</sub>	$\text{He}_4$ link, 6 random teachers in $\mathbb{R}^6$	$\sigma = \text{He}_4$	Yes	No	Yes?
Staircase	$0.25x_1 + 0.75\text{XOR}_4(x_{[4]})$	$\sigma = \text{SoftPlus}$ , 2nd layer $\pm 8$	Yes	No	No
XOR <sub>4</sub>	$\text{XOR}_4(x_{[4]})$	$\sigma = \text{SoftPlus}$ , 2nd layer $\pm 8$	Yes	No	?

- Well-specified Single-Index Model:

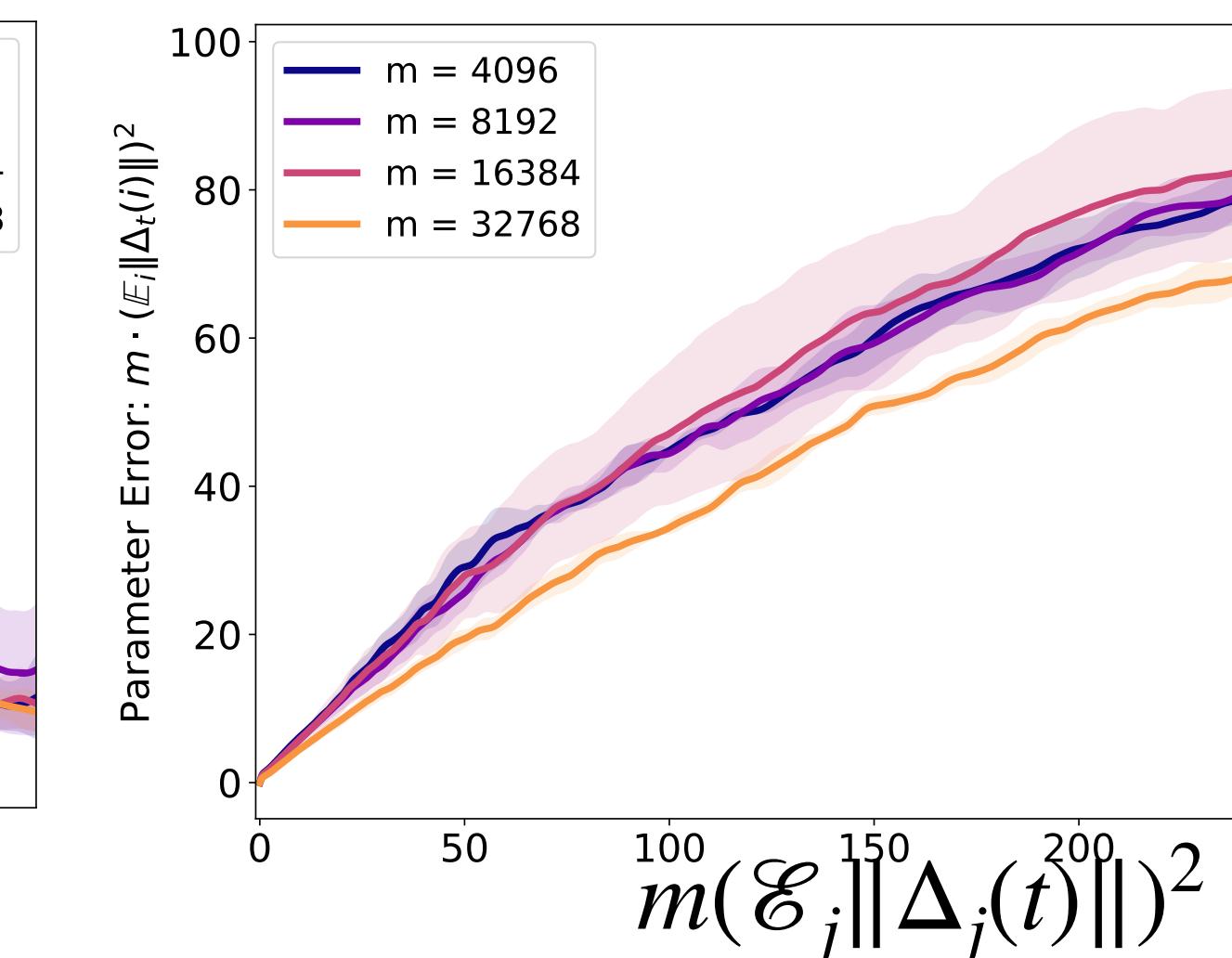
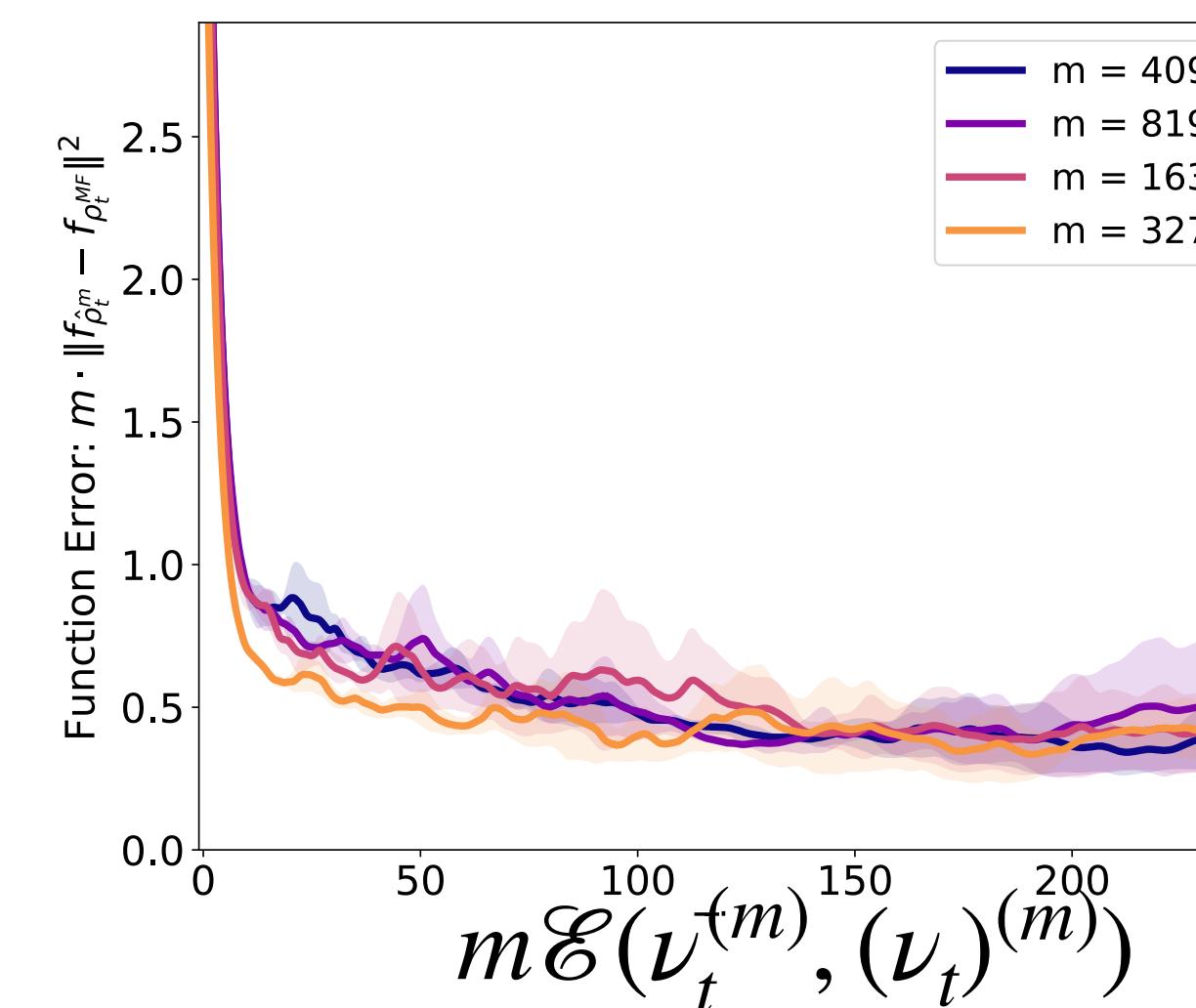
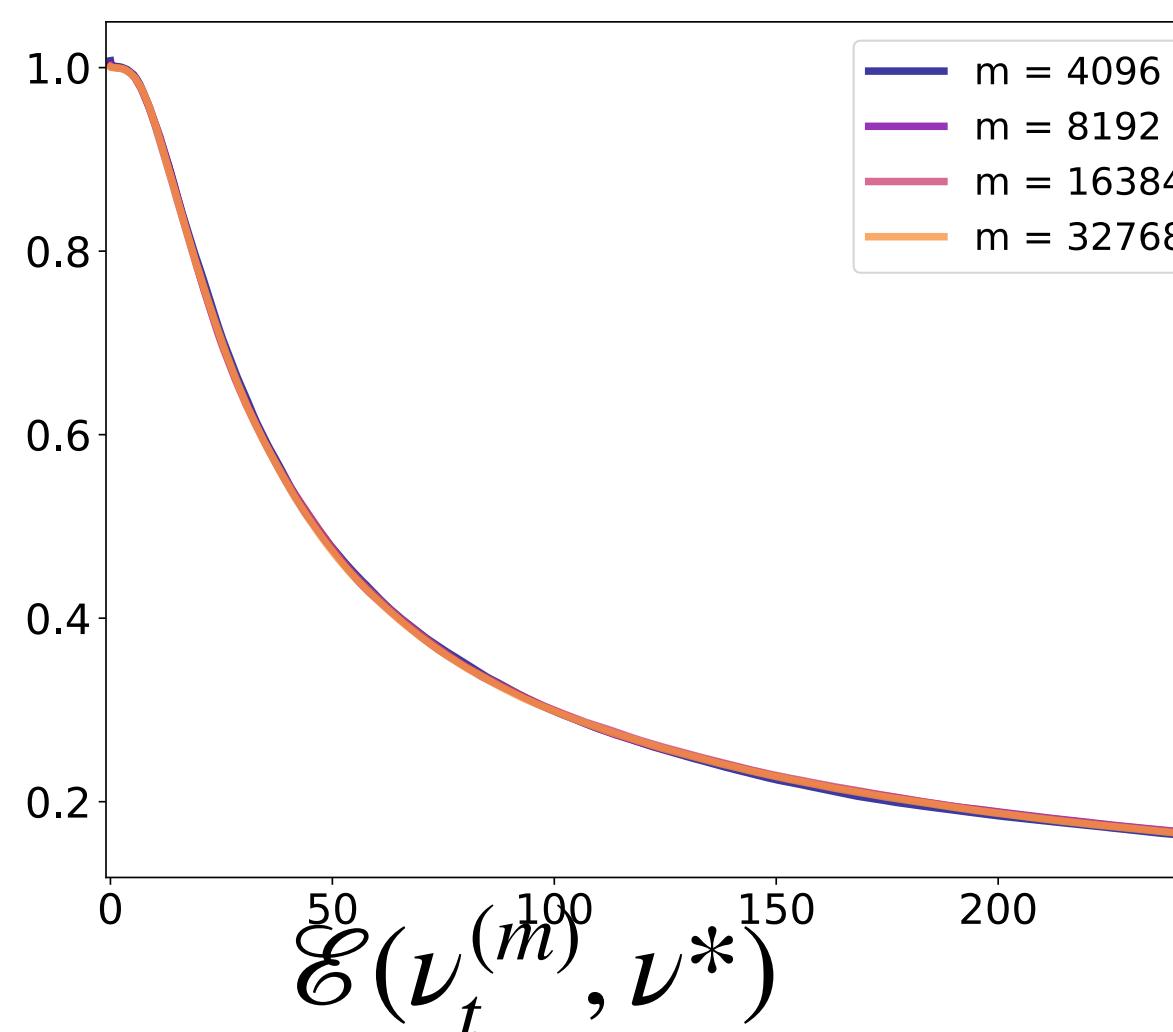


# Experiments

- Misspecified Single-Index Model:

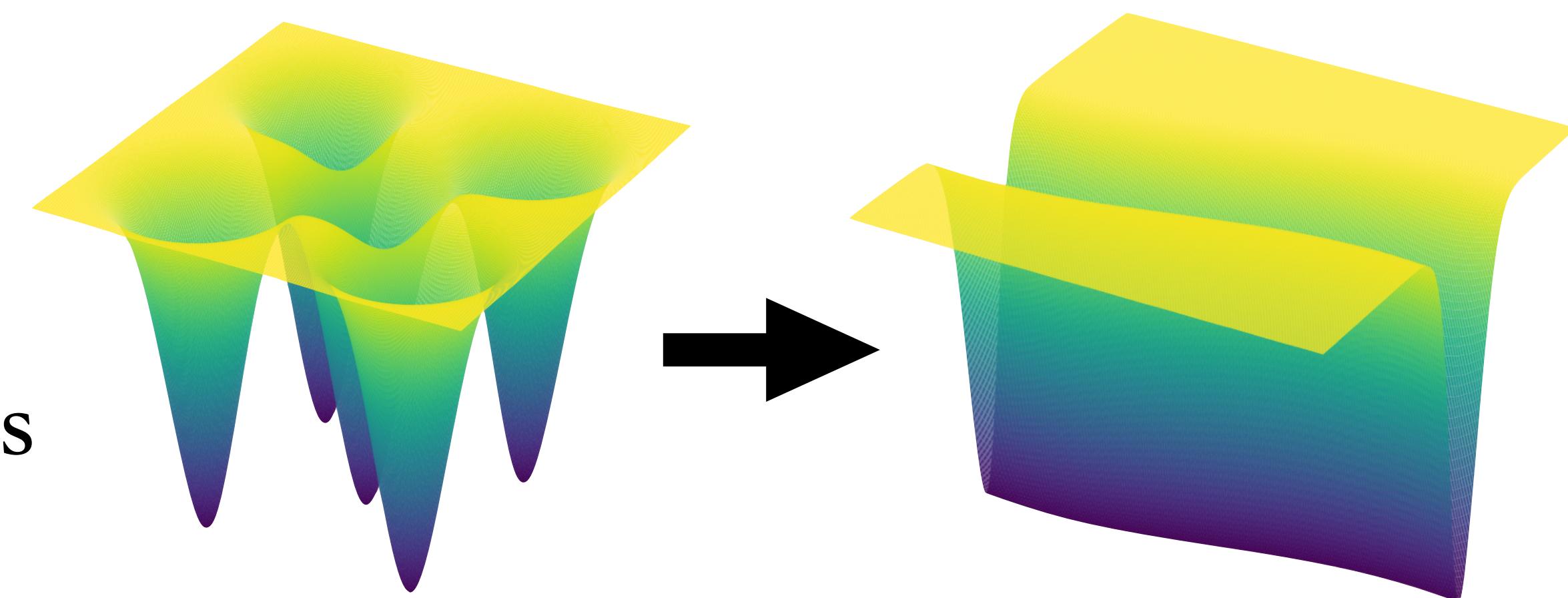


- 4-parity (misspecified Multi-index model):



# Next Steps / Questions

- Relaxing LSC to allow mis-specified problems
- Establishing stability properties beyond ‘self-concordant’ SIM-MIM-type problems? BBP-like?
- Effect of step-size: Links between sharpness and velocity related to central flow [[Cohen & Damian et al](#)]?
- Relationship with DMFT analysis of fluctuations [[Bordelon et al](#)]?
- Links between PoC and scaling laws, beyond linear models [[Paquette et al.](#)]?



# Thanks!

## References:

- Propagation-of-Chaos in Single-Hidden Layer Neural Networks beyond Logarithmic time, with Denny Wu and Margalit Glasgow, COLT 25.

