

$$\cos \phi = \frac{\sqrt{2}}{2}$$

$$0 \leq \phi < 2\pi$$

$$\phi = \frac{\pi}{4} \text{ rad}$$

$$\phi = \frac{7\pi}{4} \text{ rad.}$$

$$\vec{R} = \vec{F} + \vec{N} + m\vec{g} = \vec{F}$$

2a lei de Newton:  $F = -kx = ma$

$$a(x) = -\frac{k}{m}x = -\omega^2 x \Rightarrow \omega = \sqrt{\frac{k}{m}}.$$

$$x(t) = x_m \cos(\omega t + \phi). \quad \omega = \sqrt{\frac{k}{m}}.$$

$$x(t=0) = x_0 = x_m \Rightarrow \phi = 0$$

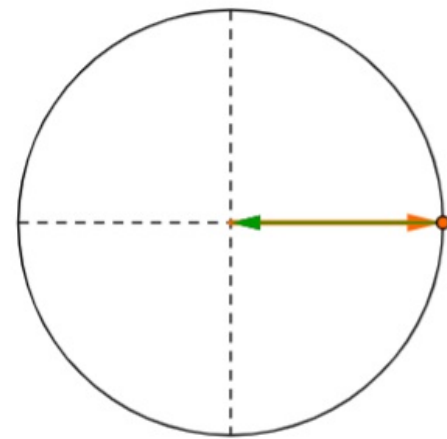
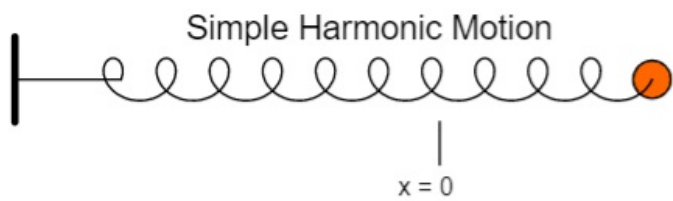
$$x_0 = x_m \cos \phi \Rightarrow \cos \phi = \frac{x_0}{x_m}$$

$$v(t) = -\omega x_m \sin(\omega t + \phi) \Rightarrow$$

$$v_0 = v(t=0) = -\omega x_m \sin \phi \Rightarrow \sin \phi = \frac{-v_0}{\omega x_m}$$

A constante de fase é determinada pelas condições iniciais do movimento.

A frequência angular não depende das condições iniciais.



Related Circular Motion

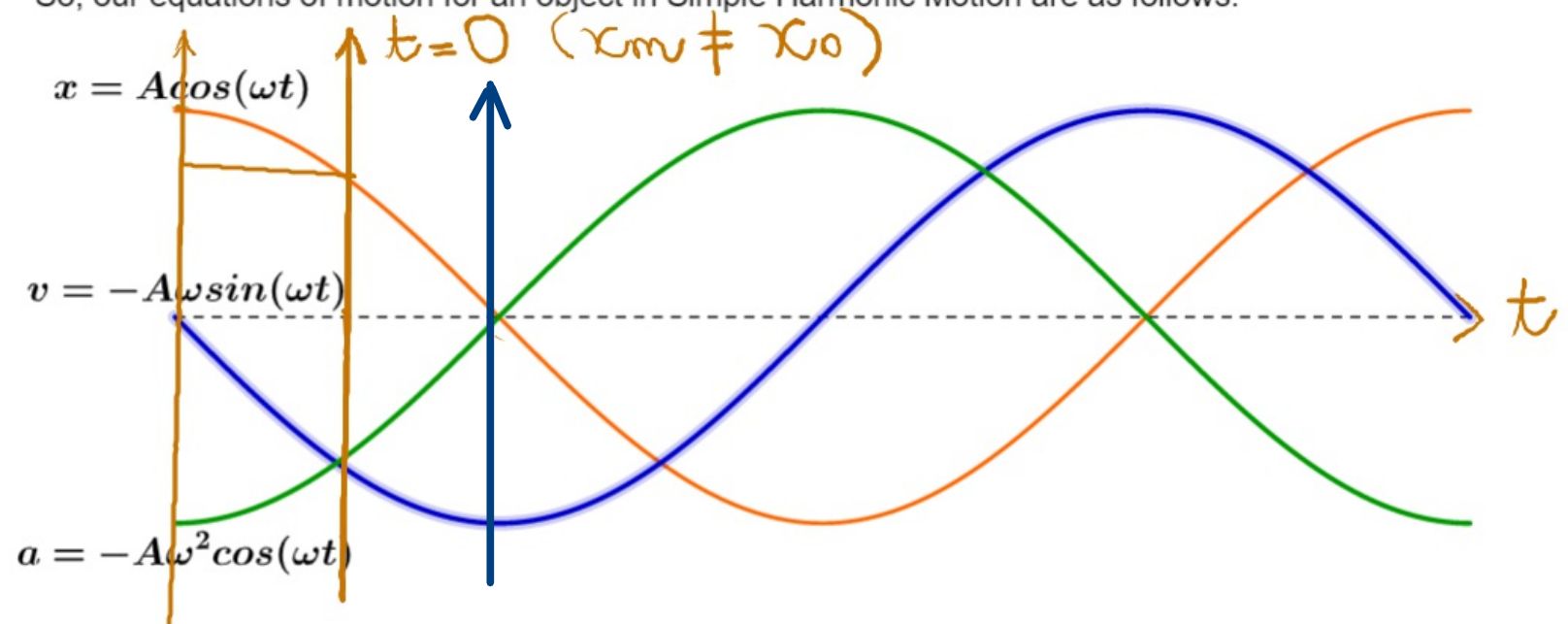
$\omega = 1$

$A = 1$

Run

Pause

So, our equations of motion for an object in Simple Harmonic Motion are as follows:



$$\cos \phi = \frac{x_0}{x_m}$$

$$\sin \phi = -\frac{v_0}{v_m}$$

$$\sin^2 \phi + \cos^2 \phi = 1 \Rightarrow \frac{x_0^2}{x_m^2} + \frac{v_0^2}{\omega^2 x_m^2} = 1.$$

$$x_m = \left( x_0^2 + \frac{v_0^2}{\omega^2} \right)^{1/2}$$

Se  $t=0$  é tal que:  $x_0 = \pm x_m$ ;  $v_0 = 0$

Se  $t=0$  é tal que:  $x_0 = 0$ ;  $v_0 = \pm v_m$

$$x_m = \left( \frac{v_m}{\omega} \right)$$

M-RUV: 
$$x(t) = x_0 + v_0 t + \frac{1}{2} a t^2$$

Condições iniciais:  $(x_0, v_0)$

Resultante:  $\vec{a} = \vec{R}/m$

Entradas:  $(x_0, v_0, F = -kx)$

↓  
caracterizar o MHS.

$$F = -kx = ma$$

$$a(x) = -\omega^2 x$$

$$\omega = \left( \frac{k}{m} \right)^{1/2}$$

$$x_m = \left( x_0^2 + \frac{v_0^2}{\omega^2} \right)^{1/2};$$

⇓  
 $x(t) = x_m \cos(\omega t + \phi).$

$$\cos \phi = \frac{x_0}{x_m}$$

$$\sin \phi = - \frac{v_0}{\omega x_m}$$