## Our output for desk1

compared\_pose\_pairs 564 pairs
translational\_error.rmse 0.044932 m
translational\_error.mean 0.035572 m
translational\_error.median 0.027440 m
translational\_error.std 0.027450 m
translational\_error.min 0.002648 m
translational\_error.max 0.147287 m
rotational\_error.rmse 3.045778 deg
rotational\_error.mean 2.811292 deg
rotational\_error.median 0.048801 deg
rotational\_error.std 1.171922 deg
rotational\_error.min 0.217012 deg
rotational\_error.max 6.989060 deg

