

# ESCON

## Feature Comparison Chart

The ESCON servo controllers are small-sized, powerful 4-quadrant PWM servo controller for the highly efficient control of permanent magnet-activated DC motors.

The featured operating modes – speed control (closed loop), speed control (open loop), and current control – meet the highest requirements. The ESCON servo controllers are designed being commanded by an analog set value and features extensive analog and digital I/O functionality and are being configured via USB interface using the graphical user interface «ESCON Studio» for Windows PCs.

**Legend:** (✓)\* = only in use with DC Tacho or Encoder / nnnnnn = order number / \*\* = details refer to the pin header allocation



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Feature	ESCON Module 24/2 (466023)	ESCON 36/2 DC (403112)	ESCON 36/3 EC (414533)	ESCON Module 50/4 EC-S (446925)	ESCON 50/5 (409510)	ESCON Module 50/5 (438725)	ESCON 70/10 (422969)
Product image							
<b>Motors</b>							
DC motors up to	48 W / 144 W	72 W / 144 W	—	—	250 W / 750 W	250 W / 750 W	700 W / 2'100 W
EC motors up to	48 W / 144 W	—	97 W / 324 W	200 W / 600 W	250 W / 750 W	250 W / 750 W	700 W / 2'100 W
<b>Sensors</b>							
Digital Incremental Encoder (2 channel with or without Line Driver)	✓	✓	—	—	✓	✓	✓
DC Tacho	✓	✓	—	—	✓	✓	✓
Without sensor (DC motors)	✓	✓	—	—	✓	✓	✓
Without sensor (EC motors, sensor-less)	—	—	—	✓	—	—	—
Digital Hall Sensors (EC motors)	✓	—	✓	—	✓	✓	✓
<b>Electrical Data</b>							
Nominal operating voltage +V <sub>cc</sub>	10...24 VDC	10...36 VDC	10...36 VDC	10...50 VDC	10...50 VDC	10...50 VDC	10...70 VDC
Max. output voltage	0.98 x +V <sub>cc</sub>	0.98 x +V <sub>cc</sub>	0.98 x +V <sub>cc</sub>	0.96 x +V <sub>cc</sub>	0.98 x +V <sub>cc</sub>	0.98 x +V <sub>cc</sub>	0.95 x +V <sub>cc</sub>
Max. output current	6 A (<4 s)	4 A (<60 s)	9 A (<4 s)	12 A (<30 s)	15 A (<20 s)	15 A (<20 s)	30 A (<20 s)
Continuous output current	2 A	2 A	2.7 A	4 A	5 A	5 A	10 A

# maxon motor

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Pulse Width Modulation frequency	53.6 kHz						
Sampling rate PI current controller	53.6 kHz	53.6 kHz	53.6 kHz	—	53.6 kHz	53.6 kHz	53.6 kHz
Sampling rate PI speed controller	5.36 kHz						
Max. efficiency	92%	95%	95%	97%	95%	98%	98%
Max. speed (DC)	limited by max. permissible speed (motor) and max. out- put voltage (controller)	limited by max. permissible speed (motor) and max. out- put voltage (controller)	—	—	limited by max. permissible speed (motor) and max. out- put voltage (controller)	limited by max. permissible speed (motor) and max. out- put voltage (controller)	limited by max. permissible speed (motor) and max. out- put voltage (controller)
Max. speed (EC; 1 pole pair)	150'000 rpm	—	150'000 rpm	120'000 rpm	150'000 rpm	150'000 rpm	150'000 rpm
Built-in motor choke	—	300 µH; 2 A	3 x 47 µH; 2.7 A	—	3 x 30 µH; 5 A	—	3 x 15 µH; 10 A
Inputs / Outputs							
Hall sensor signals	H1, H2, H3	—	H1, H2, H3	—	H1, H2, H3	H1, H2, H3	H1, H2, H3
Encoder signals	A, A\, B, B\	A, A\, B, B\	—	—	A, A\, B, B\	A, A\, B, B\	A, A\, B, B\
Max. encoder input frequency differen- tial (single-ended)	1 MHz (100 kHz)	1 MHz (100 kHz)	—	—	1 MHz (100 kHz)	1 MHz (100 kHz)	1 MHz (100 kHz)
Back-EMF signals	—	—	—	BEMF-W1, BEMF-W2, BEMF-W3	—	—	—
Potentiometers	—	1	1	1	2	1	2
Digital inputs	2						
Digital inputs/outputs	2						
Analog inputs	2						
Resolution	12-bit						
Range	-10...+10 V						
Circuit	differential						
Analog outputs	2						
Resolution	12-bit						
Range	-4...+4 V						
Auxiliary voltage output	+5 VDC (IL ≤10 mA)	+5 VDC (IL ≤40 mA)	+5 VDC (IL ≤80 mA)	+5 VDC (IL ≤110 mA)	+5 VDC (IL ≤10 mA)	+5 VDC (IL ≤10 mA)	+5 VDC (IL ≤10 mA)
Hall sensor supply voltage	+5 VDC (IL ≤30 mA)	—	+5 VDC (IL ≤30 mA)	—	+5 VDC (IL ≤30 mA)	+5 VDC (IL ≤30 mA)	+5 VDC (IL ≤30 mA)
Encoder supply voltage	+5 VDC (IL ≤70 mA)	+5 VDC (IL ≤70 mA)	—	—	+5 VDC (IL ≤70 mA)	+5 VDC (IL ≤70 mA)	+5 VDC (IL ≤70 mA)
Status Indicators	Operation: green LED / Error: red LED						

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Connections								
J1	Power	Pin header (2.54 mm), 2 poles**	Pin header (2 mm), 2 poles	Pin header (2 mm), 2 poles	Pin header (2.54 mm), 4 poles**	Pluggable screw-type terminal block (3.5 mm), 2 poles	Pin header (2.54 mm), 4 poles**	Pluggable screw-type terminal block (5.0 mm), 2 poles
J2	Motor Motor / Hall sensors Motor / BEMF signals	Pin header (2.54 mm), 3 poles**	Pin header (2 mm), 3 poles	Mini module pin header, 8 poles	Pin header (2.54 mm), 9 poles**	Pluggable screw-type terminal block (3.5 mm), 4 poles	Pin header (2.54 mm), 6 poles**	Pluggable screw-type terminal block (5.0 mm), 4 poles
J2A	Motor Motor / Hall sensors	—	Spring-loaded contacts, 2 poles	Spring-loaded contacts, 8 poles	—	—	—	—
J3	Hall sensors	Pin header (2.54 mm), 5 poles**	—	—	—	Pluggable screw-type terminal block (3.5 mm), 5 poles	Pin header (2.54 mm), 5 poles**	Pluggable screw-type terminal block (3.5 mm), 5 poles
J4	Encoder	Pin header (2.54 mm), 4 poles**	Pin header (2.54 mm), 5 x 2 poles	—	—	Pin header (2.54 mm), 5 x 2 poles	Pin header (2.54 mm), 4 poles**	Pin header (2.54 mm), 5 x 2 poles
J4A	Encoder	—	Pin header (1.27 mm), 5 x 2 poles	—	—	—	—	—
J5	Digital I/O	Pin header (2.54 mm), 5 poles**	Pin header (2 mm), 6 poles	Pin header (2 mm), 6 poles	Pin header (2.54 mm), 5 poles**	Pluggable screw-type terminal block (3.5 mm), 6 poles	Pin header (2.54 mm), 5 poles**	Pluggable screw-type terminal block (3.5 mm), 6 poles
J6	Analog I/O	Pin header (2.54 mm), 6 poles**	Pin header (2 mm), 7 poles	Pin header (2 mm), 7 poles	Pin header (2.54 mm), 6 poles**	Pluggable screw-type terminal block (3.5 mm), 7 poles	Pin header (2.54 mm), 6 poles**	Pluggable screw-type terminal block (3.5 mm), 7 poles
J7	USB	USB Type micro B female						
Mechanical Data								
Weight (approximate)		7 g	30 g	36 g	11 g	204 g	12 g	259 g
Dimensions (L x W x H)		35.6 x 26.7 x 12.7 mm	55 x 40 x 16.1 mm	55 x 40 x 19.8 mm	43.2 x 31.8 x 12.7 mm	115 x 75.5 x 24 mm	43.2 x 31.8 x 12.7 mm	125 x 78.5 x 27 mm
Mounting		Pluggable (female headers RM 2.54 mm)	M2.5 screws	M2.5 screws	Pluggable (female headers RM 2.54 mm)	M4 screws	Pluggable (female headers RM 2.54 mm)	M4 screws

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Environmental Conditions							
Temperature – Operation	–30...+60 °C	–30...+45 °C	–30...+45 °C	–30...+45 °C	–30...+45 °C	–30...+45 °C	–30...+45 °C
Temperature – Extended range	+60...+80 °C; Derating: –0.1 A/°C	+45...+81 °C; Derating: –0.056 A/°C	+45...+78 °C; Derating: –0.082 A/°C	+45...+65 °C; Derating: –0.2 A/°C	+45...+85 °C; Derating: –0.111 A/°C	+45...+75 °C; Derating: –0.167 A/°C	+45...+82 °C; Derating: –0.270 A/°C
Temperature – Storage	–40...+85 °C						
Altitude – Operation	0...6'000 m MSL	0...6'000 m MSL	0...6'000 m MSL	0...6'000 m MSL	0...10'000 m MSL	0...6'000 m MSL	0...10'000 m MSL
Altitude – Extended range (Derating: see Hardware Reference)	6'000...10'000 m MSL	6'000...10'000 m MSL	6'000...10'000 m MSL	6'000...10'000 m MSL	—	6'000...10'000 m MSL	—
Humidity (condensation not permitted)	5...90%						
Functionality							
Operating Mode							
Current controller (torque control)	✓	✓	✓	—	✓	✓	✓
Speed controller (closed loop)	✓	✓	✓	✓	✓	✓	✓
with encoder feedback	✓	✓	—	—	✓	✓	✓
with DC Tacho feedback	✓	✓	—	—	✓	✓	✓
with Hall sensor feedback	✓	—	✓	—	✓	✓	✓
with BEMF feedback	—	—	—	✓	—	—	—
Speed controller (open loop)	✓	✓	✓	✓	✓	✓	✓
with static IxR Compensation	✓	✓	✓	✓	✓	✓	✓
with adaptive IxR Compensation	✓	(✓)*	✓	✓	✓	✓	✓
Set Value							
Analog set value	✓						
PWM set value	✓						
RC Servo set value	✓						
Fixed set value	✓						
2 fixed set values	✓						

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<b>Digital I/O Functionality</b>							
Enable				✓			
Enable CW				✓			
Enable CCW				✓			
Enable CW + CCW				✓			
Enable + Direction				✓			
Stop				✓			
Ready				✓			
Speed Comparator				✓			
Current Comparator				✓			
Commutation frequency	✓	—	✓	✓	✓	✓	✓
<b>Monitoring Outputs</b>							
Monitor Current				✓			
Monitor Speed				✓			
<b>Analog Settings</b>							
Set value				✓			
Current limit				✓			
Offset adjust set value				✓			
Speed ramp				✓			
Current gain (using potentiometer)	—	✓	✓	—	✓	✓	✓
Speed gain (using potentiometer)	—	✓	✓	✓	✓	✓	✓
IxR Factor (using potentiometer)	—	✓	✓	✓	✓	✓	✓
<b>Protection</b>							
Overcurrent				✓			
Current limiter (adjustable)				✓			
Thermal overload				✓			
Undervoltage				✓			
Overvoltage				✓			
Voltage transients				✓			
Short-circuit of motor winding				✓			

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<b>Software</b>							
Installation Program	ESCON Setup						
Graphical User Interface	ESCON Studio						
Startup Wizard	✓						
Regulation Tuning	✓						
Diagnostics	✓						
Firmware Update	✓						
Controller Monitor	✓						
Parameters	✓						
Data Recording	✓						
Online Help	✓						
Language	German, English, French, Italian, Spanish, Japanese, Chinese						
Operating System	Windows 10, 8, 7, XP SP3						
Communication interface	USB 2.0 / USB 3.0 (full speed)						

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Accessories (not included in delivery)								
418719	Adapter BLACK FPC11poles	—	—	✓	—	—	—	—
418723	Adapter BLUE FPC8poles	—	—	✓	—	—	—	—
418721	Adapter GREEN FPC8poles	—	—	✓	—	—	—	—
403962	DC Motor Cable	—	✓	—	—	—	—	—
275934	Encoder Cable	—	✓	—	—	✓	—	✓
404404	ESCON 36/2 DC Connector Set	—	✓	—	—	—	—	—
425255	ESCON 36/3 EC Connector Set	—	—	✓	—	—	—	—
486400	ESCON Module 24/2 Motherboard	✓	—	—	—	—	—	—
438779	ESCON Module Motherboard	—	—	—	—	—	✓	—
450237	ESCON Module Motherboard Sensorless	—	—	—	✓	—	—	—
409286	ESCON USB Stick	✓	✓	✓	✓	✓	✓	✓
403965	I/O Cable 6core (Digital I/Os)	—	✓	✓	—	—	—	—
403964	I/O Cable 7core (Analog I/Os)	—	✓	✓	—	—	—	—
403957	Power Cable	—	✓	✓	—	—	—	—
403968	USB Type A - micro B Cable	✓	✓	✓	✓	✓	✓	✓

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