



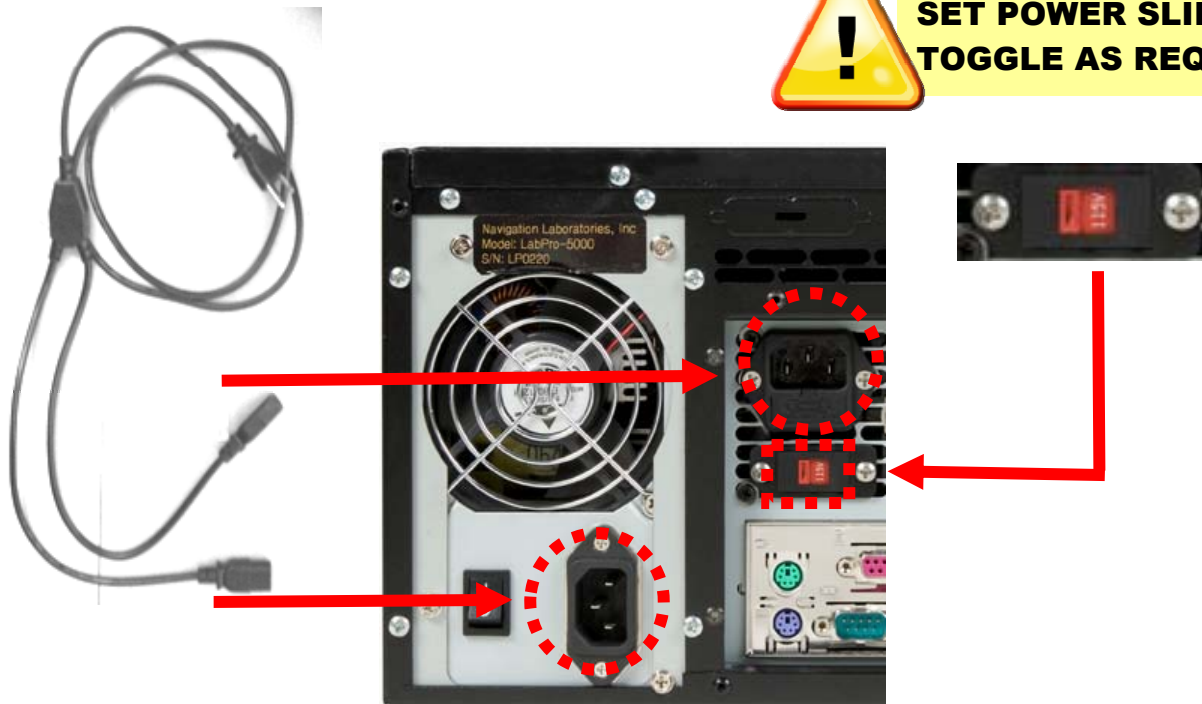
# SETTING UP THE LABPRO



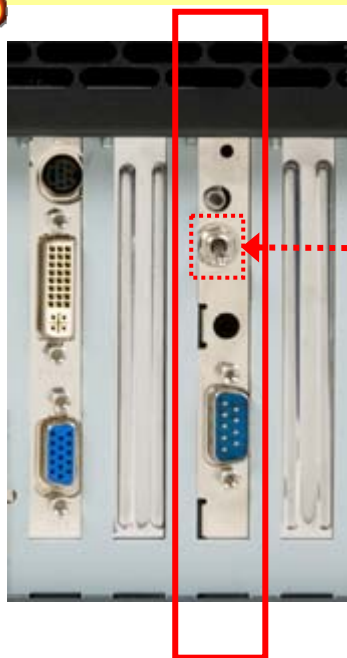
**TWO AC POWER CONNECTIONS  
[ USE THE SUPPLIED CORD ]**



**SET POWER SLIDE  
TOGGLE AS REQUIRED**



**IF MOUSE BEHAVES ERATIC DURING BOOT, LOCATE THIS  
TOGGLE AND PUSH SWITCH DOWN**



**FLIP UP TO ENABLE.  
FLIP DOWN TO DISABLE.**

(P.6) [[Tapestry\Documentation\Manuals\Using the Navlabs Reference Receiver.pdf](#)]

## FRONT PANEL CONFIGURATION

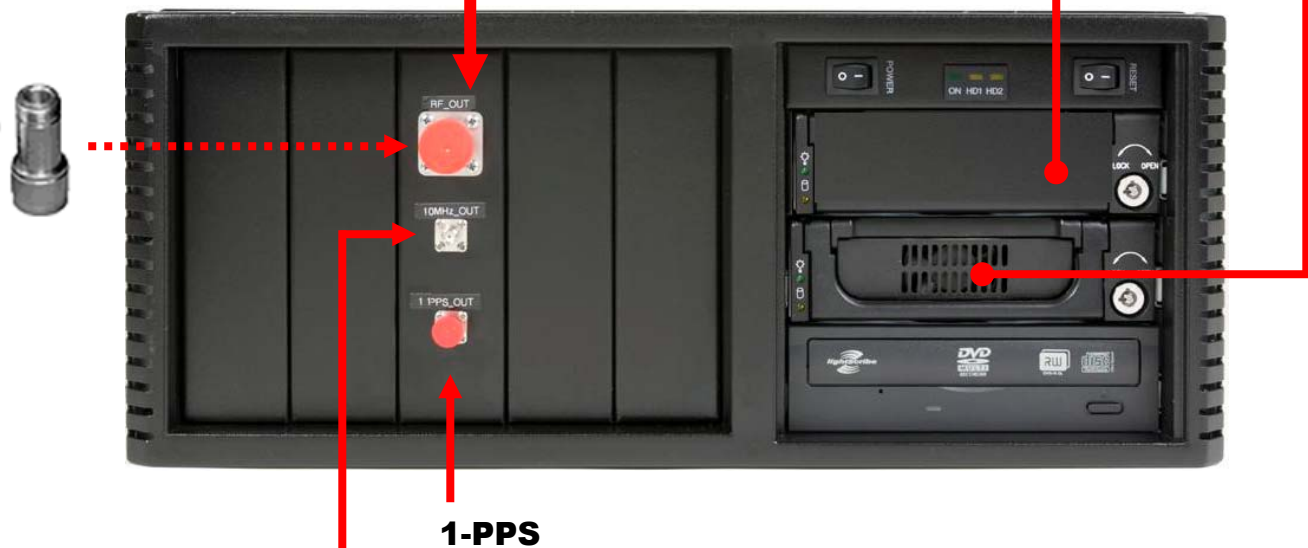
## REMOVABLE HARD DISK

## [ WINDOWS TAPESTRY INSTALLED ]

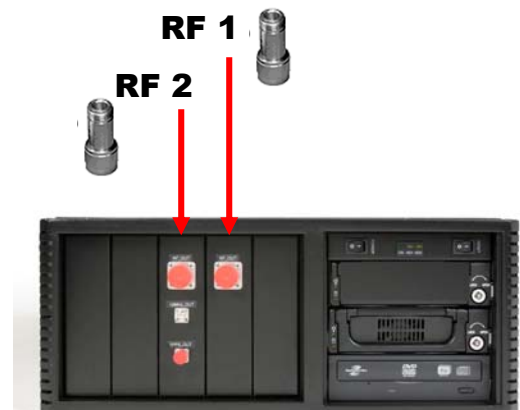
## RF OUTPUT [ N=TYPE ]

**MAX OUTPUT - PAD  $\approx$  - 65 dBm**  
**MAX OUTPUT + PAD  $\approx$  -100 dBm**

## 2<sup>nd</sup> DISK CADDY SATA-3



**10 MHz INPUT/OUTPUT\*\***  
[ \*\* OPTIONAL FOR LABPRO 1000/2000 ]

**RF 1****RF 2**

**USE SUPPLIED MONITOR**  
**1920 x 1200 REQUIRED**



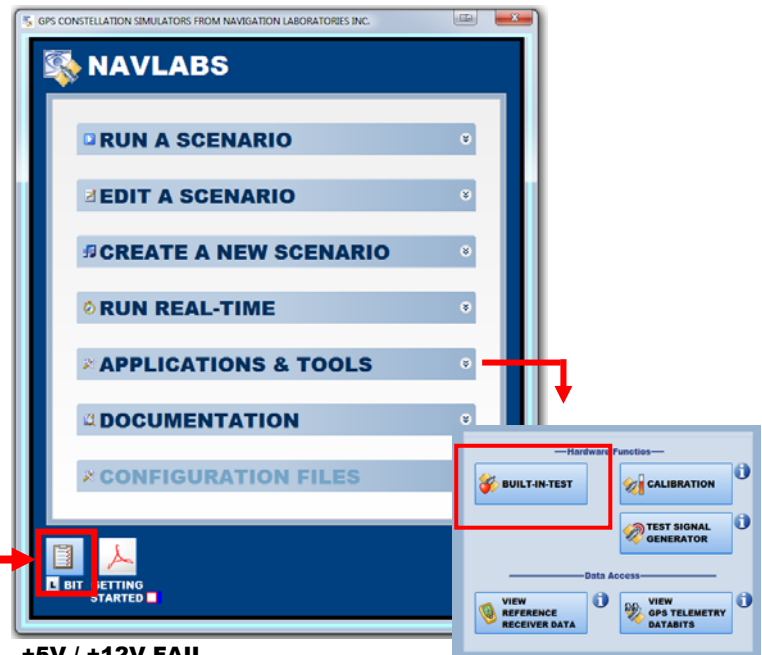
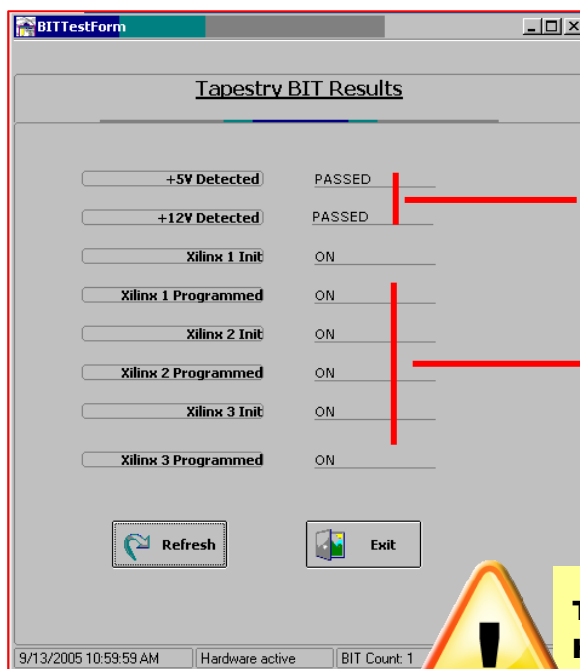
## DUAL RF OUTPUT CONFIGURATION

# VERIFYING THE SETUP

- CONNECT COMPONENTS AND POWER UP THE CHASSIS.
- TAPESTRY WILL BOOT AUTOMATICALLY [ SHORTCUT ]
- RUN BIT



## BUILT IN TEST [ BIT ]



? +5V / +12V FAIL  
BOTH AC PLUGS ATTACHED?

? OFF  
GETTING STARTED !



THE FIRST TIME BIT IS RUN, THE DIGITAL  
HARDWARE IS FLASHED. EXPECT A SHORT DELAY  
BEFORE THE RESULTS SCREEN UPDATES.



# CALIBRATION CERTIFICATE

**DATE** \_\_\_\_\_

**LABPRO MODEL**                      **1000**                      **2000**                      **3000**                      **4000**                      **5000**

**MFIO**                                      **1**      **2**                      **AUTO** \_\_\_\_\_ **IMU** \_\_\_\_\_

**SERIAL #**                                      **NLC** \_\_\_\_\_

**RF1 CALIBRATION**                      **L1** \_\_\_\_\_                      **L2** \_\_\_\_\_                      **L5** \_\_\_\_\_

**RF2 CALIBRATION**                      **L1** \_\_\_\_\_                      **L2** \_\_\_\_\_                      **L5** \_\_\_\_\_

**RF3 CALIBRATION**                      **L1** \_\_\_\_\_                      **L2** \_\_\_\_\_                      **L5** \_\_\_\_\_

**RF4 CALIBRATION**                      **L1** \_\_\_\_\_                      **L2** \_\_\_\_\_                      **L5** \_\_\_\_\_

**1-PPS** \_\_\_\_\_

**10 MHZ** \_\_\_\_\_

**REFERENCE RECEIVER**                      **GPSC** [9600]      [19200]                      **SIRF** [57600]

**OTHER** \_\_\_\_\_