

# Lever Arm Equations

$$\vec{L}^E = C_B^E \vec{L}^B$$

$$\dot{\vec{L}}^E = \dot{C}_B^E \vec{L}^B + C_B^E \dot{\vec{L}}^B$$

$\dot{C}_B^E = C_B^E (\boldsymbol{\omega}_{EB}^B X) \rightarrow \dot{C}_B^E = (\boldsymbol{\omega}_{EB}^E \times) C_B^E$

$$\dot{\vec{L}}^E = (\boldsymbol{\omega}_{EB}^E \times) (C_B^E L^B) = (\boldsymbol{\omega}_{EB}^E \times L^E)$$

$$\dot{\vec{L}}^E = (\boldsymbol{\omega}_{EB}^E \times L^E)$$

$$\ddot{\vec{L}}^E = (\dot{\boldsymbol{\omega}}_{EB}^E \times L^E) + (\boldsymbol{\omega}_{EB}^E \times \dot{\vec{L}}^E)$$

$\dot{\boldsymbol{\omega}}_{EB}^E = \dot{\boldsymbol{\omega}}_{EP}^E + \dot{\boldsymbol{\omega}}_{PB}^E$  SMALL  $\sim a/Re$

*P = Platform frame (local level tangent frame) computed*

$$\ddot{\vec{L}}^E = \dot{\boldsymbol{\omega}}_{PB}^E \times L^E + \boldsymbol{\omega}_{EB}^E \times (\boldsymbol{\omega}_{EB}^E \times L^E)$$

$$\vec{A} \times \vec{B} \times \vec{C} = \vec{B}(\vec{A} \bullet \vec{C}) - \vec{C}(\vec{A} \bullet \vec{B})$$

$$\omega \times \omega \times L = \omega(\omega \bullet L) - L(\omega \bullet \omega) = \vec{\boldsymbol{\omega}}_{EB}^E (\boldsymbol{\omega}_{EB}^E \bullet L^E) - \boldsymbol{\omega}_{EB}^E \cdot L^E$$

$$\ddot{\vec{L}}^E = \dot{\boldsymbol{\omega}}_{PB}^E \times L^E + \vec{\boldsymbol{\omega}}_{EB}^E (\boldsymbol{\omega}_{EB}^E \bullet L^E) - (\boldsymbol{\omega}_{EB}^E)^2 L^E$$

$$\ddot{\vec{L}}^E = \vec{\boldsymbol{\omega}}_{PB}^E \times L^E + \vec{\boldsymbol{\omega}}_{EB}^E (\boldsymbol{\omega}_{EB}^E \bullet L^E) - (\boldsymbol{\omega}_{EB}^E)^2 L^E$$