## **Minimal covers**



## Let's recap



- so far, we discussed why it may be necessary to decompose a relational schema R, on which a set of functional dependencies F is defined, in relation to the violation of 3NF (that causes different types of anomalies) and efficiency
- we said that, whatever reason we have for decomposing the schema, the decomposition must satisfy three basic requirements:
  - each sub-schema must be 3NF
  - the decomposition must preserve the functional dependencies in F
  - it must be possible to reconstruct every legal instance of the original schema through the natural join of the instances of the decomposition

## Let's recap



- we showed how to verify that a given decomposition (we don't care how it was produced) satisfies all the conditions, in particular we talked about how to verify:
  - if the decomposition preserves the functional dependencies in F
  - whether it is possible to reconstruct every legal instance of the original schema through the natural join of the instances of the decomposition

#### What's next?



- we now address the problem of how to obtain a "good" decomposition
- first of all: is it always possible to get it?
- the answer is YES: it is always possible, given a schema R on which a set of functional dependencies F is defined, to decompose it so as to obtain that:
  - each sub-schema is in 3NF
  - the decomposition preserves the functional dependencies in F
  - we can reconstruct any legal instance of the original schema through the natural join of instances of the decomposition
- we will present an algorithm that achieves this goal

#### **Note**



- the decomposition that is obtained from the algorithm is not the only possible one satisfying the 3 requirements
- the same algorithm, depending on its input can provide different and yet correct result
- there is not just one decomposition, but there are several possible ones
- so, we cannot use the algorithm to check if a given decomposition is "good", by comparing it with the one provided by the algorithm, as they could be both "good", but different

## **Before continuing...**



- we introduce the concept of "minimal cover" of a set of functional dependencies F
- a minimal cover of F will be the input to the decomposition algorithm
- given a set of functional dependencies F, there can exist <u>several equivalent minimal covers</u> (i.e., having the same closure as F)
- this is exactly why the decomposition algorithm can produce different correct results

#### **Definition**



Let *F* be a set of functional dependencies.

A **minimal cover** of *F* is a set of functional dependencies G, equivalent to *F*, such that:

- for each functional dependency in G, the dependent is a singleton (i.e., each dependent is non-redundant)
- for each dependency X→A in G, there not exists X'⊂X such that G≡G-{X→A}∪{X'→A} (i.e., each determinant is non-redundant)
- there not exists any X→A in G, such that G≡G-{X→A}
  (i.e., each dependency is non-redundant)

#### **Comments**



- for each functional dependency in G, the dependent is a singleton (i.e., each dependent is non-redundant)
  - that is always possible, thanks to the decomposition rule
- for each dependency X→A in G, it does not exists a X'⊂X such that G≡G-{X→A}∪{X'→A} (i.e., each determinant is non-redundant)
  - it is not possible to functionally determine A (in G or in G<sup>+</sup>) by a
    subset of X
- it does not exist any X→A in G, such that G≡G-{X→A}
  (i.e., each dependency is non-redundant)
  - it is not possible to functionally determine A (in G or in G<sup>+</sup>)
    through other dependencies

#### How it is calculated



For each set of functional dependencies *F* there always exists a minimal cover **equivalent to** *F* that can be obtained in **polynomial** time in three steps:

- 1. using the decomposition rule, the dependents are reduced to singletons
- 2. every functional dependency  $A_1A_2...A_{i-1}A_1A_1A_{i+1}...A_n \to \mathbf{A}$  in F such that  $F \equiv F \{A_1A_2...A_{i-1}A_iA_{i+1}...A_n \to \mathbf{A}\} \cup \{A_1A_2...A_{i-1}A_{i+1}...A_n \to \mathbf{A}\}$  is replaced by  $A_1A_2...A_{i-1}A_{i+1}...A_n \to \mathbf{A}$ ; if the latter **already belongs to** F the original dependency is **simply deleted**; the process is repeated **recursively** on  $A_1A_2...A_{i-1}A_{i+1}...A_n \to \mathbf{A}$ ; the process ends when **no** functional dependency can be further **reduced**
- 3. every functional dependency  $X \rightarrow A$  in F such that  $F \equiv F \{X \rightarrow A\}$  is **removed** from F, as it is redundant

## **Equivalence check**



 steps 2 and 3 require to verify the equivalence between two sets of functional dependencies

## **Equivalence check**



- let us recall some definitions and results:
  - F ≡ G if and only if F<sup>+</sup> = G<sup>+</sup>, i.e., if and only if F<sup>+</sup> ⊆ G <sup>+</sup>
    and G<sup>+</sup> ⊆ F <sup>+</sup>
  - if  $F \subseteq G$ , trivially  $F \subseteq G^+$
  - ∘ if  $F \subseteq G^+$  then, for the lemma, that  $F^+ \subseteq G^+$
- to check whether  $F \subseteq G^+$ , for each  $X \to Y \in F$  we check whether  $X \to Y \in G^+$ , i.e., whether  $Y \subseteq (X)^+_G$ , i.e., whether Y is in the closure of X, with respect to the set of functional dependencies G (i.e., we can use the algorithm for computing  $X^+_F$ )
- important: we are still dealing with the schema R, not yet decomposed

## **Equivalence check**



- we analyze steps 2 and 3 separately
- we deal with two particular cases of the problem of equivalence between sets of dependencies

# Step 2



- in step 2, whenever we want to check the redundancy of an attribute in the determinant of a dependency, we call F the set that contains the original dependency A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i</sub>A<sub>i+1</sub>...A<sub>n</sub> → A and G the set that contains the dependency A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i+1</sub>...A<sub>n</sub> → A
- so, the two sets differ by exactly one dependency, while the remaining ones are equal; so, they trivially belong to the closure of both sets
- then, we just have to check that both:
  - $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \to A \in G^+$
  - $A_1A_2...A_{i-1}A_{i+1}...A_n \to A \in F^+$

# Step 2



- because of the way the closure algorithm works, we can conclude that it is not necessary to check if
  - $A_1 A_2 ... A_{i-1} A_i A_{i+1} ... A_n \rightarrow A \in G^+$ , that is, if  $A \in (A_1 A_2 ... A_{i-1} A_i A_{i+1} ... A_n)_G^+$
- in fact, the algorithm initializes Z to a set that is larger than the one present to the left of the dependency of  $A_1A_2...A_{i-1}A_{i+1}...A_n \rightarrow A \in G$ , i.e.:  $Z = A_1A_2...A_{i-1}A_iA_{i+1}...A_n$
- consequently, because of the assignment S := { A | Y → V ∈ G, A ∈ V ∧ Y ⊆ Z }, and in particular of the condition Y ⊆ Z, we would immediately insert A in S, because of the presence in G of the dependency A₁A₂...A₁...An → A
- the theoretical justification for this is in the Armstrong's axioms of reflexivity and transitivity:
- as  $A_1A_2...A_{i-1}A_{i+1}...A_n \subseteq A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ , by reflexivity we have that  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \to A_1A_2...A_{i-1}A_{i+1}...A_n$  and, since  $A_1A_2...A_{i-1}A_{i+1}...A_n \to A \in G$ , by **transitivity** we obtain that  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \to A$

# **Example**



given  $F = \{AB \rightarrow C, A \rightarrow D, D \rightarrow C\}$ to know if we can eliminate B in AB  $\rightarrow$  C we have to check:

- 1.if  $A \rightarrow C \in \mathbf{F}^+$ 
  - we compute A<sup>+</sup><sub>F</sub> and we check if it contains C
- 2.if AB  $\rightarrow$  C  $\in$  **G**<sup>+</sup> with G = {A  $\rightarrow$  C, A  $\rightarrow$  D, D  $\rightarrow$  C}
  - we compute AB<sup>+</sup><sub>G</sub> and we check if it contains C
  - •point 2 is trivial, as if we compute (AB)<sup>+</sup><sub>G</sub> we immediately add C to S and Z, thanks to the dependency A → C

# Step 2



- we still need to check whether A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i+1</sub>...A<sub>n</sub> → **A** ∈ F<sup>+</sup>
- we use the algorithm to check if:

• 
$$A \in (A_1 A_2 ... A_{i-1} A_{i+1} ... A_n)_F^+$$

- in this case we could be trying to add a constraint that is **not in** the schema definition
- there could be the special case in which the dependency
   A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i+1</sub>...A<sub>n</sub> → A is already in F, so it is also in F<sup>+</sup>; in such a case, we can directly eliminate the original dependency (for example, if F contains both AB → C and A → C then AB → C can be eliminated)
- in any other case, if we prove the equivalence of F and G, we can take G as the new reference set for continuing the reduction (i.e., the new F is G)

## **Step 2: observation**



- in checking other dependencies, it is unnecessary to recompute the closures of groups of attributes for which such a calculation was already performed
- for example, given X, since (X)<sup>+</sup><sub>F</sub> = { A | X → A ∈ F<sup>+</sup>}, and since the direction of the check (if A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i+1</sub>...A<sub>n</sub> → A ∈ F<sup>+</sup>...) implies the computation of closures on a set of dependencies that is either the initial F or a set G that was already showed to be equivalent to F (so F<sup>+</sup> = G<sup>+</sup>), then if X → A ∈ F<sup>+</sup> then X → A ∈ G<sup>+</sup>, i.e., X<sup>+</sup><sub>F</sub> = X<sup>+</sup><sub>G</sub>

## Step 2: observation



- if  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$  → **A** ∈ F but **there is no** Y → A ∈ F with Y ≠  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ , or {subset1 of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ } → {subset2 of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ } ∈ F<sup>+</sup>, then it would be **useless to** try to remove attributes to the left of the dependency, since the way the closure is defined, and the way the algorithm works, we won't be able to insert A into any closure, other than the one generated by the dependency  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$  → **A** ( there are no subsets of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$  that determine A, nor combinations  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$  → Y ^ Y → A that allow us to apply transitivity, nor {subset1 of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ } → {subset2 of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ } ∈ F<sup>+</sup>, which would still allow A to be included in the closure of {subset1 of  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ }); however, the second condition is not evident, so... better check!
- if  $A_1A_2...A_n \rightarrow A \in F$  and  $Y \rightarrow A \in F$  with  $Y \subseteq A_1A_2...A_n$ , we eliminate  $A_1A_2...A_n \rightarrow A$  without checking anything; in fact, in the equivalence check for replacing  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \rightarrow A$  with  $A_1A_2...A_{i-1}A_{i+1}...A_n \rightarrow A$ , provided that  $Y \subseteq A_1A_2...A_{i-1}A_{i+1}...A_n$ , it will always be  $A \in S$ , thanks to the dependency  $Y \rightarrow A$

# Step 3



- assume that we denote by F the set that contains the dependency X
   → A, and by G the set in which this dependency has been
  eliminated
- again, the two sets differ by only one dependency; indeed, it can be verified that G ⊆ F, so we already know that G<sup>+</sup> ⊆ F<sup>+</sup>
- so, it remains to be checked that it is F<sup>+</sup>⊆ G<sup>+</sup>, i.e., F⊆ G<sup>+</sup>
- it is enough to check whether X → A ∈ G<sup>+</sup>, that is, whether A ∈ X<sup>+</sup><sub>G</sub>

## **Step 3: observation**



- in this case, however, the closures of groups of attributes must be recalculated, because the direction of verification leads to the computation of closures with respect to a set of dependencies that was not shown to be equivalent to F
- we also note that if X → A ∈ F, but there is no Y → A ∈ F with Y ≠ X, then there is no point in trying to eliminate X → A, since by eliminating this dependency we would no longer be able to determine A

### To sum up...



#### step 2:

- if F isthe set that contains the original dependency
   A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i</sub>A<sub>i+1</sub>...A<sub>n</sub> → A and G is the set that contains instead the dependency A<sub>1</sub>A<sub>2</sub>...A<sub>i-1</sub>A<sub>i+1</sub>...A<sub>n</sub> → A, to check if F ≡ G it is enough to check:
  - if  $A_1A_2...A_{i-1}A_{i+1}...A_n \to A \in F^+$  (so, if  $A \in (A_1A_2...A_{i-1}A_{i+1}...A_n)_F^+$ )
- if  $A_1A_2...A_{i-1}A_{i+1}...A_n \rightarrow A \in F^+$ , then we eliminate the dependency  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \rightarrow A$
- if  $A_1A_2...A_n \rightarrow A \in F$  and  $Y \rightarrow A \in F$  with  $Y \subseteq A_1A_2...A_n$ , then we eliminate the dependency  $A_1A_2...A_n \rightarrow A$
- if  $A_1A_2...A_{i-1}A_iA_{i+1}...A_n \rightarrow A \in F$  but **there is no**  $Y \rightarrow A \in F$  with  $Y \neq A_1A_2...A_{i-1}A_iA_{i+1}...A_n$ , then there is no point in trying to remove attributes in the determinant
- it is not necessary to recalculate the transitive closures of attributes or groups of attributes

### To sum up...



#### step 3:

- F is the set that contains the original dependency X → A and G is the set that does not contain it
- to verify if F ≡ G it is enough to verify if X → A ∈ G<sup>+</sup> (i.e., A ∈ X<sup>+</sup><sub>G</sub>)
- if X → A ∈ F but there is no Y → A ∈ F with Y ≠ X, then it is useless to try to eliminate X → A
- transitive closures of attributes or attribute groups must be recalculated

### To sum up...



- there may be multiple minimal covers for a given set of functional dependencies.
- using the algorithm, one can always find at least one minimal cover for any set F
- it may also be the case that F is already in minimal form, and so there is no reduction to be made