ITS Toolbox:

A Matlab toolbox for the practical computation of Information Dynamics

Version 2.1 – January 2019

Luca Faes

Dept. of Engineering, University of Palermo, Italy

www.lucafaes.net

Luca.faes@unipa.it

INTRODUCTION

• Network of dynamic processes

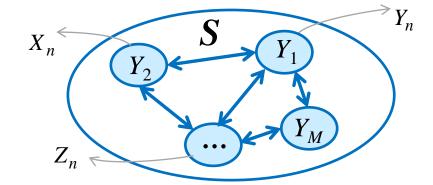
Observed dynamical system S



M dynamic processes $Y_1, Y_2, ..., Y_M$



Measured time series: $Y_{1,n}, Y_{2,n}, ..., Y_{M,n}$



• Realization:
$$N \times M$$
 data matrix $Y = \begin{bmatrix} Y_{1,1} & \cdots & Y_{M,1} \\ \vdots & \ddots & \vdots \\ Y_{1,N} & \cdots & Y_{M,N} \end{bmatrix}$

- Estimation of Information Dynamics:
 - (A) Definition of Measures: univariate, bivariate, multivariate Can be expressed in terms of **conditional entropies**
 - (B) Approximation of the past history of the processes Embedding procedures: **uniform**, **non-uniform**
 - (C) Computation of conditional entropy
 Entropy estimators: Linear (Gaussian), Binning, Kernel, Nearest Neighbors

UNIVARIATE SYSTEM ANALYSIS

TARGET SYSTEM:
$$\mathbf{Y}_j$$
 Time series: Y_n
$$\mathbf{y}_{-th} \text{ column of the data matrix}$$

$$Y = \begin{bmatrix} \cdots & Y_1 & \cdots \\ \vdots & \vdots & \vdots \\ \cdots & Y_N & \cdots \end{bmatrix}$$

• Information generated by Y_j : **Entropy**

$$H_Y = H(Y_n) = -\sum p(y_n) \log p(y_n)$$



• Information Storage in Y_j : *Mutual Information*

$$S_Y = I(Y_n; Y_n^-) = H(Y_n) - H(Y_n | Y_n^-)$$



✓ New Information: *Conditional Entropy*

$$N_Y = H(Y_n \mid Y_n^-)$$



$$S_Y \qquad H_Y = S_Y + N_Y$$

BIVARIATE SYSTEM ANALYSIS

TARGET SYSTEM: Y_j Time series: Y_n j-th column of the data matrix

DRIVER SYSTEM: Y_i Time series: X_n

i-th column of the data matrix

$$Y = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \dots & X_N & \dots & Y_N & \dots \end{bmatrix}$$

• Information Transfer from X to Y:

Conditional Mutual Information

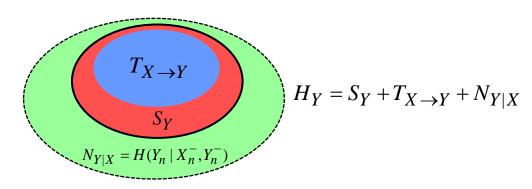
$$T_{X \to Y} = I(Y_n; X_n^- | Y_n^-) = H(Y_n | Y_n^-) - H(Y_n | X_n^-, Y_n^-)$$

functions for **Transfer Entropy**:

its_BTElin.m
its_BTEbin.m
its_BTEker.m
its_BTEknn.m

✓ New Information: *Conditional Entropy*

$$N_{Y|X} = H(Y_n | X_n^-, Y_n^-)$$



MULTIVARIATE SYSTEM ANALYSIS

TARGET SYSTEM: Y_i

 \longrightarrow Time series: Y_n

j-th column of the data matrix

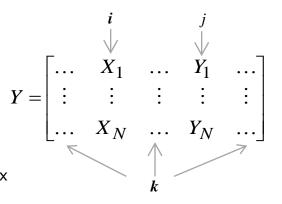
DRIVER SYSTEM: Y_i Time series: X_n

i-th column of the data matrix

OTHER SYSTEMS: $Y \setminus \{Y_i, Y_i\}$ Time series: Z_n



k-th columns of the data matrix



Joint Information Transfer from X,Z to Y :

$$T_{XZ \to Y} = I(Y_n; X_n^-, Z_n^- \mid Y_n^-) = H(Y_n \mid Y_n^-) - H(Y_n \mid X_n^-, Y_n^-, Z_n^-)$$



Joint Transfer Entropy:

its BTElin.m

its BTEbin.m its BTEker.m

its BTEknn.m

Conditional Information Transfer from X to Y given Z:

$$T_{X \to Y|Z} = I(Y_n; X_n^- | Y_n^-, Z_n^-) = H(Y_n | Y_n^-, Z_n^-) - H(Y_n | X_n^-, Y_n^-, Z_n^-)$$



Partial Transfer Entropy:

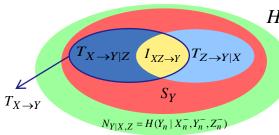
its PTElin.m

its PTEbin.m

its PTEker.m

its PTEknn.m

 \checkmark New Information: $N_{Y|X} = H(Y_n \mid X_n^-, Y_n^-, Z_n^-)$



$$H_Y = S_Y + T_{XZ \to Y} + N_{Y|X,Z}$$

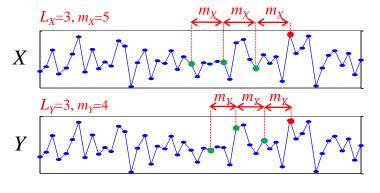
$$T_{XZ \to Y} = T_{X \to Y|Z} + T_{Z \to Y|X} + I_{XZ \to Y}$$
$$= T_{X \to Y} + T_{Z \to Y} - I_{XZ \to Y}$$

$$I_{XZ \to Y} = T_{X \to Y} - T_{X \to Y|Z}$$

ESTIMATION: APPROXIMATION OF THE SYSTEM PAST

• Uniform embedding (UE):

Covers the past of each system with predetermined lagged components, uniformly spaced in time



$$X_n^- \approx [X_{n-m_X} \dots X_{n-L_X m_X}]$$

 $Y_n^- \approx [Y_{n-m_Y} \dots Y_{n-L_Y m_Y}]$

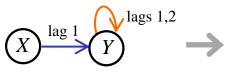
L = embedding dimension m = embedding lag

Example: L=3,
$$m=1$$
 \longrightarrow $V_n = [X_{n-1}, X_{n-2}, X_{n-3}, Y_{n-1}, Y_{n-2}, Y_{n-3}]$

• Non-Uniform embedding (NUE):

Approximates the system past through a sequential procedure that selects progressively the lagged components according to a criterion for maximum relevance and minimum redundancy

Example:



$$V_n = [X_{n-1}, Y_{n-1}, Y_{n-2}]$$
 $X_n Y_n$

ESTIMATION: COMPUTATION OF CONDITIONAL ENTROPY

Functions for embedding (common to all estimators):

its_SetLag.m Sets the indices for embedding

its_buildvectors.m Given the embedding indices, forms the observation matrix B

Example: M=2 time series

Uniform embedding with L=2, m=1

 $V_n = [X_{n-1}, X_{n-2}, Y_{n-1}, Y_{n-2}]$

Data matrix

Embedding indices

Observation matrix

$$\begin{bmatrix} X_1 & Y_1 \\ \vdots & \vdots \\ X_N & Y_N \end{bmatrix} \quad \Longrightarrow \quad$$

$$Vi = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 2 & 1 \\ 2 & 2 \end{bmatrix} \quad \Longrightarrow \quad$$

$$\begin{bmatrix} X_1 & Y_1 \\ \vdots & \vdots \\ X_N & Y_N \end{bmatrix} \longrightarrow Vi = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 2 & 1 \\ 2 & 2 \end{bmatrix} \longrightarrow B = \begin{bmatrix} Y_3 & X_2 & X_1 & Y_2 & Y_1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ Y_n & X_{n-1} & X_{n-2} & Y_{n-1} & Y_{n-2} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ Y_N & X_{N-1} & X_{N-2} & Y_{N-1} & Y_{N-2} \end{bmatrix}$$

Functions for computing conditional entropy (estimator-specific):

• Linear	<pre>its_CElin.m its_CElinVAR.m</pre>	Conditional Entropy from the Observation Matrix Conditional Entropy from the VAR parameters (Uniform Embedding)
• Binning	<pre>its_CEbin.m its_NUEbin.m</pre>	Conditional Entropy from the Observation Matrix Conditional Entropy from the Observation Matrix, Non-Uniform Embedding
· Kernel	<pre>its_CEker.m its_NUEker.m</pre>	Conditional Entropy from the Observation Matrix, Non-Uniform Embedding
Nearest neighbor	<pre>its_CEknn.m its_CMIknn.m its_NUEknn.m</pre>	Conditional Entropy from the Observation Matrix Conditional Mutual Information from the Observation Matrix Conditional Mutual Information from the Observation Matrix, Non-Uniform Embedding

ESTIMATORS: LINEAR-MODEL BASED ESTIMATOR

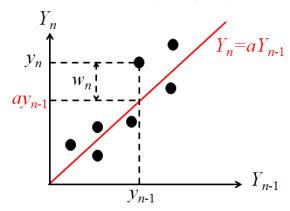
• Computation based on linear prediction models

Exploits the analytic relation between (conditional) entropy and (prediction error) variance valid for Gaussian processes, and performs linear regression to find the prediction error variance

$$Y_n = a_1 Y_{n-1} + \dots + a_L Y_{n-L} + W_n$$

$$S_Y = \frac{1}{2} \ln \frac{\sigma(Y_n)}{\sigma(Y_n \mid Y_n^L)} = \frac{1}{2} \ln \frac{\sigma_Y^2}{\sigma_W^2}$$

• Example: L=1 $Y_n^L \cong Y_n^1 = Y_{n-1}$



- The estimator uses Uniform Embedding \longrightarrow $X_n^- \cong X_n^L = [X_{n-1} \dots X_{n-L}], \ Y_n^- \cong Y_n^L = [Y_{n-1} \dots Y_{n-L}]$
- **Analysis parameters:** Regression order: L (either imposed or selected with optimization criteria)

Main functions:

• its_Elin.m System Information, univariate system

• its_SElin.m Information Storage, univariate system

• its_BTElin.m Information Transfer, bivariate system

• its_PTElin.m Conditional Information Transfer, multivariate system



its_SetLag.m
its_buildvectors.m
its_CElin.m
its_CElinVAR.m

Other functions:

• its_LinReg_Ftest.m Statistical significance of Information Dynamics, based on Fisher F-test

• its_FindOrderLin.m Selection of regression order, based on Akaike or Bayesian information criteria

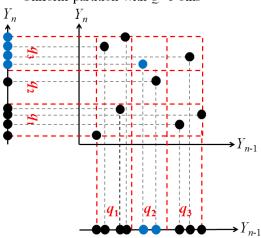
ESTIMATORS: MODEL-FREE ESTIMATOR BASED ON BINNING

• Computation based on time series quantization

Discretize the values of each variable using quantization levels, then estimate the probability as the relative frequency of visitation of the hypercubes in the multidimensional space spanned by the variables

• Example: L=1 $Y_n^L \cong Y_n^1 = Y_{n-1}$

Uniform partition with Q=5 bins



- · Non-Uniform Embedding is recommended to limit dimensionality
- **Analysis parameters:** Number of quantization levels: *c*Embedding parameters: *L*, *m* (for non-uniform embedding, also parameters for procedure termination)

Main functions:

its_Ebin.m
 its_SEbin.m
 its_BTEbin.m
 Information Storage, univariate system
 Information Transfer, bivariate system

• its_PTEbin.m Conditional Information Transfer, multivariate system



its_SetLag.m
its_buildvectors.m
its_CEbin.m
its_NUEbin.m

Other functions:

• its_quantization.m Uniform quantization of the time series

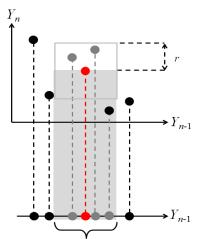
ESTIMATORS: MODEL-FREE ESTIMATOR BASED ON KERNELS

Computation based on kernel density estimation

Approximate the probability density at each data point by using kernel functions to weight the distance from the reference point to any other point in the time series;

If the Heaviside kernel with parameter r is used, the method counts the relative number of points having distance less than r from the reference point, then averages across all points

• Example: L=1 $Y_n^L \cong Y_n^1 = Y_{n-1}$



Range search with fixed threshold, r

Non-Uniform Embedding is recommended to limit dimensionality

• **Analysis parameters:** Threshold distance: r (usually a fraction of the SD of the time series)

Embedding parameters: *L*, *m* (for non-uniform embedding, also parameters for procedure termination)

Main functions:

its_Eker.m
 its_SEker.m
 its_BTker.m
 its_PTEker.m
 System Information, univariate system
 Information Storage, univariate system
 Information Transfer, bivariate system
 Conditional Information Transfer, multivariate system



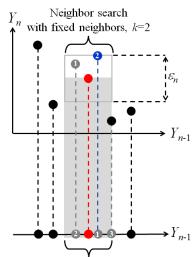
its_SetLag.m
its_buildvectors.m
its_CEker.m
its_NUEker.m

ESTIMATORS: MODEL-FREE ESTIMATOR BASED ON NEAREST NEIGHBORS

• Computation based on nearest neighbor statistics

Study the probability distribution for the distance between an observation and its k-th neighbor

 Compensation of the estimation bias in a sum of entropies by looking for neighbors in the higher dimensional spaces, and counting within ranges in the lower dimensional spaces • Example: L=1 $Y_n^L \cong Y_n^1 = Y_{n-1}$



Range search with fixed distance, ε_n

- Non-Uniform Embedding is recommended to limit dimensionality
- **Analysis parameters:** Number of neighbors: *k*

Embedding parameters: L, m (for non-uniform embedding, also parameters for procedure termination)

Main functions:

its_Eknn.mits_SEknn.mSystem Information, univariate systemInformation Storage, univariate system

• its_BTEknn.m Information Transfer, bivariate system

• its_PTEknn.m Conditional Information Transfer, multivariate system



its_SetLag.m
its_buildvectors.m
its_CMIknn.m
its_NUEknn.m

Other functions:

nn_prepare, nn_search, range_search

functions for neighbor search and range search

COMPUTATION OF INFORMATION DYNAMICS

General procedure for the computation of Information Dynamics

Load data matrix

(normalize time series)



Set indices of time series

Univariate: index of Y
Bivariate: indices of X,Y
Multivariate: indices of X,Y,Z



Compute Entropy Hy Elin, Ebin, Eker, Eknn



Compute Information Dynamics:

a) Set embedding Indices

Uniform Embedding: SetLag

Non-Uniform Embedding:

SetLag + NUEbin

SetLag + NUEker

SetLag + NUEknn



- b) Compute the desired measure
 - Univariate analysis: Information storage S_Y SElin, Sebin, Seker, SEknn
 - Bivariate analysis: Information Transfer $T_{X \to Y}$ BTElin, BTEbin, BTEker, BTEknn
 - Multivariate analysis: Conditional Information Transfer $T_{X \to Y|Z}$ PTElin, PTEbin, PTEker, PTEknn

REFERENCES

Theory and generalities about estimation

• L Faes, A Porta, 'Conditional entropy-based evaluation of information dynamics in physiological systems', in *Directed Information Measures in Neuroscience*, R Vicente, M Wibral, J Lizier (eds), Springer-Verlag; **2014**, pp. 61-86

Theory and linear-model based estimation

- L Faes, A Porta, G Nollo, 'Information decomposition in bivariate systems: theory and application to cardiorespiratory dynamics', *Entropy*, special issue on "Entropy and Cardiac Physics", **2015**, 17:277-303.
- L Faes, A Porta, G Nollo, M Javorka, 'Information decomposition in multivariate systems: definitions, implementation and application to cardiovascular networks', Entropy, special issue on Multivariate entropy measures and their applications, **2017**, 19(1), 5.

Comparison of Entropy measures and estimators

• W Xiong, L Faes, P Ch Ivanov, 'Entropy measures, entropy estimators and their performance in quantifying complex dynamics: effects of artifacts, nonstationarity and long-range correlations', Phys. Rev. E, **2017**; 95:062114 (37 pages).

Nearest neighbor estimation and non-uniform embedding

• L Faes, D Kugiumtzis, A Montalto, G Nollo, D Marinazzo, 'Estimating the decomposition of predictive information in multivariate systems', *Phys. Rev. E* **2015**; 91:032904 (16 pages)

· Binning estimation and non-uniform embedding

- L Faes, D Marinazzo, A Montalto, G Nollo, 'Lag-specific transfer entropy as a tool to assess cardiovascular and cardiorespiratory information transfer', IEEE Trans Biomed Eng **2014**; 61(10):2556-2568.
- L Faes, G Nollo, A Porta: 'Non-uniform multivariate embedding to assess the information transfer in cardiovascular and cardiorespiratory variability series', Comput Biol Med **2012**; 42:290-297.
- L Faes, G Nollo, A Porta: 'Information-based detection of nonlinear Granger causality in multivariate processes via a nonuniform embedding technique', Phys Rev E; **2011**; 83(5 Pt 1):051112.

Implementation for Transfer Entropy

• A Montalto, L Faes, D. Marinazzo, 'MuTE: a MATLAB toolbox to compare established and novel estimators of the multivariate transfer entropy', PLOS ONE **2014**; 9(10):e109462 (13 pages).

Applications

- L Faes, D Marinazzo, F Jurysta, G Nollo, 'Linear and nonlinear analysis of brain-heart and brain-brain interactions during sleep', Phys. Meas. 2015; 36:683-698.
- L Faes, G Nollo, F Jurysta, D Marinazzo, 'Information dynamics of brain-heart physiological networks during sleep', New J Phys **2014**; 16:105005 (20 pages).
- L Faes, A Porta, G Rossato, A Adami, D Tonon, A Corica, G Nollo: 'Investigating the mechanisms of cardiovascular and cerebrovascular regulation in orthostatic syncope through an information decomposition strategy', Autonomic Neurosci **2013**; 178:76-82.
- L Faes, G Nollo, A Porta: 'Mechanisms of causal interaction between short-term heart period and arterial pressure oscillations during orthostatic challenge', J Appl Physiol **2013**;114:1657-1667.

EXAMPLES: SIMULATIONS 1-2

• Simulated VAR process: cardiorespiratory dynamics

$$X_n = a_1 X_{n-1} + a_2 X_{n-2} + U_n$$



 $a_1 a_2$ Respiratory oscillation (HF)

$$Y_n = b_1 Y_{n-1} + b_2 Y_{n-2} + C X_{n-2} + V_n$$



 b_1 , b_2 Slow cardiac oscillation (LF)

cardiorespiratory coupling

Transfer function poles:

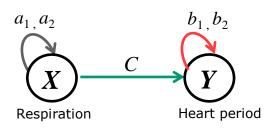
Parameters:

$$\rho_x$$
=0.9, f_x =0.3 Hz
 ρ_y =0.8, f_y =0.1 Hz

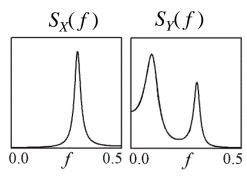


$$a_1$$
=-0.556, a_2 =-0.81 b_1 =1.294, b_2 =-0.64,

* Process Graph







- Simulation scripts:
 - Example_simu1_AR1.m Information Dynamics for X only
 - Example_simu2_AR2.m Information Dynamics for both X and Y (var simulations.m, var filter.m, var spectra.m)

EXAMPLES: SIMULATION 3

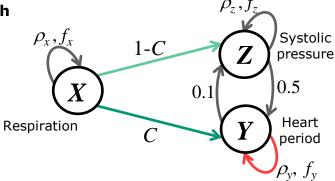
• Simulated VAR process: cardiovascular and cardiorespiratory dynamics

• Respiratory flow $X_n = 2r_x \cos(2\pi f_x) \cdot X_{n-1} - r_x^2 \cdot X_{n-2} + U_n$

• Heart period:
$$Y_n = 2r_y \cos(2\pi f_y) \cdot Y_{n-1} - r_y^2 \cdot Y_{n-2} + 0.5 \cdot Z_{n-1} + C \cdot X_{n-1} + V_n$$

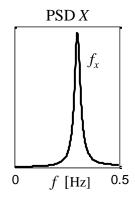
• Systolic pressure: $Z_n = 2r_z \cos(2\pi f_z) \cdot Z_{n-1} - r_z^2 \cdot Z_{n-2} + (1-C) \cdot X_{n-2} + 0.1 \cdot Y_{n-2} + W_n$

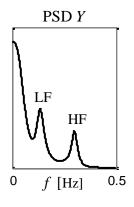
❖ Process Graph

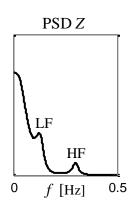


❖ Spectra *Parameters:*

$$\rho_x$$
=0.9, f_x =0.3 Hz (HF)
 ρ_y =0.8, f_y =0.1 Hz (LF)
 ρ_z =0.8, f_z =0.1 Hz (LF)
 C =0.5







- Simulation script:
 - Example_simu3_AR3.m (var_simulations.m, var_filter.m, var_spectra.m)

EXAMPLES: SIMULATION 4

• Order-two autoregressive process (AR2):

$$X_n = 2\rho\cos(2\pi f)X_{n-1} - \rho^2 X_{n-2} + U_n$$

The input white noise is colored with a 1-pole filter, where ρ and f are the pole modulus and frequency

This simulation compares the performance of linear, binning, kernel and nearest neighbor estimators in quantifying Entropy (information), Conditional Entropy (new information) and Self Entropy (information storage) for a simple linear autoregressive process

After choosing an estimator, results are displayed showing the theoretical values of the measures, and the distribution of the estimated values over several replications of the process, as a function of the parameter ρ determining the dynamical complexity of the process.

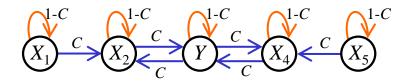
- Simulation script:
 - Example_simu4_cmpEst.m(var_filter.m)

EXAMPLES: SIMULATION 5

Simulated Coupled Nonlinear Henon systems:

$$\begin{split} X_{i,n} &= 1.4 - X_{i,n-1}^2 + 0.3 X_{i,n-2} \quad , \quad i = 1, M \\ X_{i,n} &= 1.4 - \left[0.5 C(X_{i-1,n-1} + X_{i+1,n-1}) + (1-C) X_{i,n-1} \right]^2 + 0.3 X_{i,n-2} \quad , i = 2, ..., M-1 \end{split}$$

Process graph (M=5):



This simulation shows the necessity of using non-uniform embedding for quantifying the information transfer in non-linear systems composed by many subsystems where model-free estimators are more appropriate;

In the script, the nearest neighbor or kernel estimators are employed, and simulation parameters to test are the number of nodes, the coupling strength, and the data length

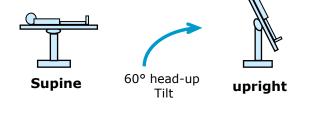
- Simulation script:
 - Example_simu5_UEvsNUE.m

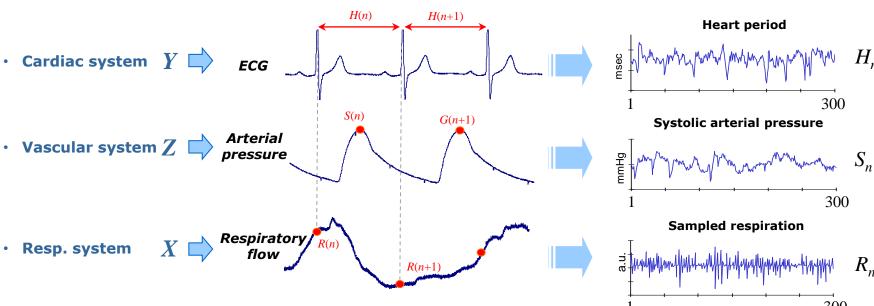
(sim_coupledhenonmaps2.m)

EXAMPLES: APPLICATION TO CARDIOVASCULAR VARIABILITY

• Experimental protocol:

- ✓ Young healthy subject
- ✓ Head-up tilt test





• Application scripts: **Example_RR.m** Univariate analysis of heart period, UE, all estimators

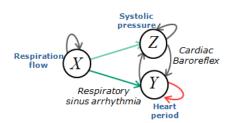
Example_Cardio_lin.m Linear, full analysis, order selection

Example_Cardio_bin.m Binning, full analysis

Example_Cardio_ker.m Kernel, full analysis

Example_Cardio_knn.m Nearest neighbors, full analysis

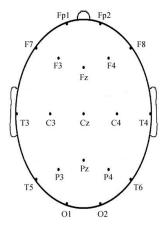
• Data: supine.prn upright.prn



EXAMPLES: APPLICATION TO EEG

• Experimental protocol:

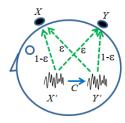
- ✓ Young healthy subject
- ✓ Acquisition of EEG signals with eyes closed in the relaxed awake state
- ✓ Acquisition: international 10-20 system (128 Hz)
- ✓ Pre-processing: bandpass filter (0.3-40 Hz)
 - selection of 8 sec window



Information transfer in the presence of volume conduction

Implementation of a compensation for instantaneous causality effects in the computation of BTE and PTE

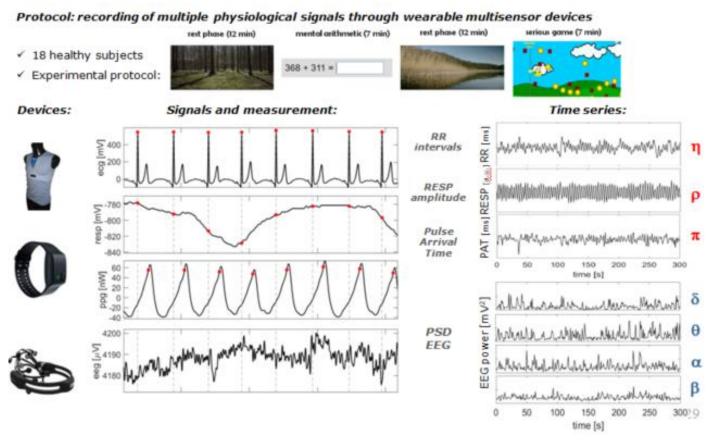
L Faes, G Nollo, A Porta: 'Compensated transfer entropy as a tool for reliably estimating information transfer in physiological time series', Entropy; special issue on "Transfer Entropy", 2013; 15(1):198-219.



- Application script: Example_EEG.m
- Data: EEG_EyesClosed.mat
- Additional functions: Non-uniform embedding with initial embedding vector passed as input
 - •its_NUEknn_Vstart.m
 - •its BTEknn 0.m
 - •its_PTEknn_0.m^{Small} modification to allow conditioning to lag-zero terms
 - (AR_filter.m) Autoregressive high-pass (de-trending) filter

EXAMPLES: APPLICATION TO BRAIN-BODY INTERACTIONS

Experimental protocol and time series:



- Data: BrainBodyStress.mat
- Application scripts: Example_BrainBodyStress_1.m

Maps of mutual information between body and brain, and of the information transfer along the two directions

Example_BrainBodyStress_2.m

Computation of information storage, information transfer (total+conditional) for a given scalp location

New functions – added in 2019 (v.2.1)

- In the computation of the bivariate TE, the driver process can be multivariate (index i passed as a vector), but the target process must be univariate (index j is scalar). To overcome this limitation, the following functions are added to the toolbox:
 - its_MIknn_V.m Extension to multivariate target process of the computation of
 - its CMIknn V.m mutual information and conditional mutual information, and of the
 - its NUEknn V.m non-uniform embedding procedure (nearest neighbor estimator)
 - its_CEknn_V.m Extension to multivariate target process of the Conditional Entropy for the nearest neighbor estimator
 - its BTElin V.m Extension to multivariate target process of the bivariate Transfer Entropy for the linear estimator
 - its_BTEknn_V.m Extension to multivariate target process of the bivariate Transfer Entropy for the nearest neighbor estimator
 - its_JBTEknn_VS.m For the nearest neighbor estimator, computes the joint transfer entropy from two (possibly multivariate) source processes to a scalar target process, and computes also the terms of its decomposition (individual and conditional transfer entropies from one source to target) through distance projection.