## Carlos A. Carrasquillo Torres

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## **Education**

Georgia Institute of Technology | GPA: 3.9 / 4.0

■ PhD, Robotics

Grad REACH Scholar

o Pathbreakers Fellow (formerly University Center for Exemplary Mentoring)

NDSEG Fellow

Master of Science, Computer Science, Machine Learning Specialization

Master of Science, Aerospace Engineering

**University of Florida** | GPA: 3.7 / 4.0

Bachelor of Science, Mechanical Engineering, Magna Cum Laude Honors

Bachelor of Science, Computer Engineering, Magna Cum Laude Honors

Experience

Graduate Research Assistant | Georgia Institute of Technology, Institute for Robotics and Intelligent Machines Aug 2021 – Current Advisors: Anirban Mazumdar, PhD, Aaron Young, PhD

Developed exoskeleton hardware and optimal learning-based controllers for human navigation, mobility, and injury reduction.

Performed human-subject experiments using motion capture, EMG, and metabolics to validate exoskeleton hardware and controllers.

Intern | Raytheon Intelligence & Space

May 2021 - May 2022

Aug 2021 - Present

August 2024 - Current

August 2023 - Current

Aug 2017 - May 2021

 $August\ 2022-August\ 2025$ 

Expected Spring 2026

May 2025

May 2025

May 2021

May 2021

Developed a MERN stack web application to help engineers find components on printed circuit boards by search and mouseover.

Engineered a VBA-based desktop application to automate the logging and tracking of material testing data, replacing a manual process.

**Undergraduate Research Assistant** | University of Florida Dept. of Mechanical and Aerospace Engineering

\*\*Advisor: Riccardo Bevilacqua, PhD\*\*

Jan 2019 – Aug 2021

Developed embedded C++ avionics software for the D3 CubeSat, creating custom libraries to interface with the satellite's sensors [C1, C2].

Engineered a ground station application in Python to transmit telecommands and receiving downlinked data from the satellite.

Undergraduate Teaching Assistant | University of Florida Dept. of Mechanical and Aerospace Engineering May 2019 – May 2021

- Design and Manufacturing Lab (6 semesters): Taught >30 students on design for manufacturing principles and usage of shop equipment.
- Dynamics and Controls Lab (1 semester): Lectured to >50 students on applying classical control theory to real-world systems.
- Thermal Systems and Design Lab (1 semester): Guided student teams in designing mathematical models for internal combustion engines.
- Numerical Methods (2 semesters): Lectured on iterative algorithms, linear algebra, Fourier analysis and held routine office hours.

## **Select Publications**

- [J4] K. L. Scherpereel, M. C. Gombolay, M. K. Shepherd, C. A. Carrasquillo, O. T. Inan, A. J. Young. "Deep Domain Adaptation Eliminates Costly Data Required for Task-Agnostic Wearable Robotic Control". Science Robotics. 2025. (Submitted)
- [J3] C. Carrasquillo, A. Bajpai, D. Iyengar, K. Collins, A. Mazumdar, A. Young. "Enhancing Human Navigation Ability Using Force-Feedback from a Lower-Limb Exoskeleton". IEEE Transactions on Haptics. 2025.
- [J2] C. Carrasquillo, S. Zhou, W. L. Childers, A. Young, K. Herrin. "A Clinical Decision-Making Algorithm for the Personalized Prescription of Microprocessor-Controlled Prosthetic Knees: An Evidence-Based Approach based on a Randomized Trial". Prosthetics and Orthotics International. 2025.
- [J1] A. Bajpai, C. Carrasquillo, J. Carlson, J. Park, D. Iyengar, K. Herrin, A. Young, A. Mazumdar. "Design and Validation of a Versatile High Torque Quasi-Direct Drive Hip Exoskeleton". IEEE Transactions on Mechatronics. 2023.
- [C2] C. Carrasquillo. "A Versatile and Open-Source Radio Framework for the D3 CubeSat Mission". Small Satellite Conference. 2021. Student Competition Best Paper Honorable Mention.
- [C1] S. Buckner, C. Carrasquillo, M. Elosegui, R. Bevilacqua. "A Novel Approach to CubeSat Flight Software Development Using Robot Operating System (ROS)". Small Satellite Conference. 2020. Poster Presentation.

## Skills

- Design & Manufacturing: Altium Designer (PCB), SolidWorks (CAD, FEA), Fusion 360 (CAD/CAM), Machine Shop Equipment (Lathes, Mills, CNC, Welding), Rapid Prototyping
- Programming: Python (NumPy, Pandas, OpenCV, PyTorch, TensorFlow, ROS, OpenMDAO), C/C++, C# (Unity), JavaScript (React.js), MATLAB, Simulink, VBA, VHDL
- Experimentation: AR/VR, Electromyography, Metabolics (COSMED, Parvo), Motion Capture (Vicon), OpenSim
- Personal Projects: 12-DOF quadruped robot, 3D bioprinter, desktop lathe, MIPS CPU, 5+ websites
- Certifications: Amateur Radio Technician (KN4ZUC), SOLIDWORKS Associate (2020), Private Pilot (90+ hours)
- Languages: English and Spanish