

# Carlos A. Carrasquillo Torres

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## Education

<b>Georgia Institute of Technology</b>   GPA: 3.9 / 4.0	<b>Aug 2021 – Present</b>
▪ PhD Candidate, <i>Robotics</i>	Expected Spring 2026
▪ Master of Science, <i>Computer Science</i> , Machine Learning Specialization	May 2025
▪ Master of Science, <i>Aerospace Engineering</i>	May 2025
<b>University of Florida</b>   GPA: 3.7 / 4.0	<b>Aug 2017 – May 2021</b>
▪ Bachelor of Science, <i>Mechanical Engineering</i> , Magna Cum Laude Honors	May 2021
▪ Bachelor of Science, <i>Computer Engineering</i> , Magna Cum Laude Honors	May 2021

## Experience

<b>Graduate Research Fellow</b>   Georgia Institute of Technology, Institute for Robotics and Intelligent Machines	<b>Aug 2021 – Current</b>
<b>Advisors:</b> Anirban Mazumdar, PhD; Aaron Young, PhD	
▪ Designed and implemented real-time closed-loop control systems for highly non-linear, multi-DOF wearable robotic platforms for unstructured and dynamic activities while enforcing strict safety constraints.	
▪ Developed model-based and data-driven exoskeleton controllers, including impedance, adaptive, and end-to-end torque controllers, and validated on hardware in 200+ human-in-the-loop experiments.	
▪ Performed state estimation using extended Kalman filters to infer latent system states from noisy, partially observed sensor data.	
▪ Conducted trajectory planning for both human locomotion and 6-DOF aircraft models.	
▪ Deployed deep learning-based models (TCNs, VAEs, CNNs, Transformers, PPO) for state estimation into exoskeleton control stacks.	
▪ Designed and implemented mechatronic hardware, including custom PCBs, sensors, and actuators, and validated in hardware tests.	
▪ Built real-time exoskeleton software, including multiprocessing controller frameworks, communication packages, and GUIs.	
▪ Developed AR/VR games in Unity and conducted human-subject studies with real-time biofeedback using EMG and motion capture.	
<b>Software &amp; Mechanical Engineering Intern</b>   RTX	<b>May 2021 – Apr 2023</b>
▪ Developed a web application that streamlined component discovery on printed circuit boards for engineers.	
▪ Designed and deployed assembly line programs and dashboards to monitor and optimize production-grade machinery.	
▪ Automated a manual material testing process by building a desktop application, improving data logging and tracking efficiency.	
<b>Undergraduate Research Assistant</b>   University of Florida Dept. of Mechanical and Aerospace Engineering	<b>Jan 2019 – Aug 2021</b>
<b>Advisor:</b> Riccardo Bevilacqua, PhD	
▪ Developed embedded C++ avionics software for the D3 CubeSat, creating custom libraries to interface with the satellite's IMU, antenna, radio, and GPS on an Ubuntu microcomputer. Developed a Python-based ground station application to manage satellite communications.	
▪ Designed satellite circuit boards and CNC-machined parts for custom actuators.	
<b>Teaching Assistant</b>   University of Florida Dept. of Mechanical and Aerospace Engineering	<b>May 2019 – May 2021</b>
▪ <b>Design and Manufacturing Lab (6 semesters):</b> Taught >30 students on design for manufacturing principles and usage of shop equipment.	
▪ <b>Dynamics and Controls Lab (1 semester):</b> Lectured to >50 students on applying classical control theory to real-world systems.	
▪ <b>Thermal Systems and Design Lab (1 semester):</b> Guided student teams in designing models for internal combustion engines.	
▪ <b>Numerical Methods (2 semesters):</b> Lectured on iterative algorithms, linear algebra, Fourier analysis and held routine office hours.	

## Skills

- **Programming:** Python (NumPy, Pandas, OpenCV, PyTorch, TensorFlow, ROS/ROS2, OpenMDAO), C/C++, C# (Unity), High-Performance Computing (HPC), JavaScript (React.js, MongoDB, Express.js, Node.js), MATLAB, Simulink, VBA, VHDL
- **Design & Manufacturing:** Altium Designer (PCB), SolidWorks (CAD, FEA), Fusion 360 (CAD/CAM), Machine Shop Equipment (Lathes, Mills, CNC, Welding), Rapid Prototyping
- **Experimentation:** AR/VR, Electromyography, Metabolics (COSMED, Parvo), Motion Capture (Vicon), OpenSim
- **Miscellaneous Projects:** reinforcement learning-based aircraft landing autopilot, microprocessor knee recommendation algorithm, bioreactor pump controller, 12-degree-of-freedom quadruped robot, 3D bioprinter, desktop lathe, MIPS CPU, assortment of websites
- **Certifications:** Amateur Radio Technician (2019, KN4ZUC), SolidWorks Associate (2020), Private Pilot (100 hours)
- **Languages:** English and Spanish

## Fellowships and Awards

- Georgia Space Grant Consortium Fellow
- Grad REACH Scholar
- National Defense Science and Engineering Graduate (NDSEG) Fellow
- Pathbreakers Fellow (formerly University Center of Exemplary Mentoring)

**Aug 2025 - Current**

**Aug 2024 – Current**

**Aug 2022 – Aug 2025**

**Aug 2023 – May 2025**