# Carlos A. Carrasquillo Torres

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#### **Education**

Georgia Institute of Technology | GPA: 3.9 / 4.0 Aug 2021 – Present

■ PhD, Robotics Expected Summer 2026

Master of Science, Computer Science, Machine Learning Specialization

May 2025

Master of Science, Aerospace Engineering
 May 2025

**University of Florida** | GPA: 3.7 / 4.0 **Aug 2017 – May 2021** 

Bachelor of Science, Mechanical Engineering, Magna Cum Laude Honors
 Bachelor of Science, Computer Engineering, Magna Cum Laude Honors
 May 2021

# Research Experience

#### **Graduate Research Assistant**

Aug 2021 – Current

Institution: Georgia Institute of Technology, Institute for Robotics and Intelligent Machines

Location: Atlanta, GA

Lab: DART Lab and EPIC Lab

Advisors: Anirban Mazumdar, PhD, Aaron Young, PhD

#### **Dissertation Research:**

- Engineered exoskeleton orthoses and mechatronics.
- Conceptualized and validated exoskeleton controllers:
  - Obstacle avoidance and navigation in low-visibility conditions [J3]
  - o Impedance-based controllers for traditional exoskeleton control [J1]
  - o End-to-end biological torque exoskeleton controllers
  - o Uncertainty-aware exoskeleton torque controllers
- Used deep learning-based methods such as:
  - o TCNs for end-to-end exoskeleton biological moment estimators from exoskeleton data
  - O VO-VAEs to construct a human motion primitive library from biomechanical data
  - o CNNs for ground reaction force estimation from force-sensing insole data
  - O GANs for domain adaption between two distinct exoskeleton sensor datasets
  - o Transformers for full-body kinematics estimation from exoskeleton data
  - o Proximal Policy Optimization (PPO) to teach AI agents to avoid obstacles
- Led the development of (or made significant contributions to) the following pieces of software:
  - Virtual reality games to simulate unstructured and dynamic environments for obstacle avoidance
  - o Machine learning training package for human physiological state estimation
  - o Low-level sensor libraries for real-time exoskeleton control
  - o Exoskeleton control framework, graphical user interface, and command line tools
  - O Bio-feedback mechanisms for the Meta Quest 3S, including an avatar that estimate arm kinematics from hand location (using inverse kinematics) and lower limb kinematics from wearable sensor data
- Conducted human-subject experiments using:
  - Delsys electromyography
  - o Vicon motion capture
  - o COSMED and Parvo metabolics

### **Miscellaneous Research Projects:**

- *Microprocessor Knee (MPK) Recommendation Algorithm*: Developed an algorithm to identify the best commercial microprocessor knee for a transferoral amputees. This algorithm aims to assist clinicians in their evaluation in the absence of expensive laboratory equipment [J2].
- Bioreactor Control Box: An electronics box designed to interface with all of the necessary pumps and sensors in a closed-loop bioreactor. Control box designed to meet clean room specifications. Enclosure designed in Solidworks.
   PCB designed in Altium Designer.



### **Undergraduate Research Assistant**

Jan 2019 - Aug 2021

Institution: University of Florida, Department of Mechanical and Aerospace Engineering

Location: Gainesville, FL Lab: ADAMUS Lab

Advisor: Riccardo Bevilacqua, PhD

### **Bachelor's Thesis Work:**

- Developed embedded C++ avionics software for the D3 CubeSat, creating custom libraries to interface with the satellite's IMU, antenna, radio, and GPS on a BeagleBone Black microcomputer [C1, C2].
- Engineered a ground station application in Python to manage mission operations, including transmitting telecommands and receiving downlinked data from the satellite.

#### **Publications**

- [J4] K. L. Scherpereel, M. C. Gombolay, M. K. Shepherd, C. A. Carrasquillo, O. T. Inan, A. J. Young. "Deep Domain Adaptation Eliminates Costly Data Required for Task-Agnostic Wearable Robotic Control". Science Robotics. 2025. (Submitted)
- [J3] C. Carrasquillo, A. Bajpai, D. Iyengar, K. Collins, A. Mazumdar, A. Young. "Enhancing Human Navigation Ability Using Force-Feedback from a Lower-Limb Exoskeleton". IEEE Transactions on Haptics. 2025.
- [J2] C. Carrasquillo, S. Zhou, W. L. Childers, A. Young, K. Herrin. "A Clinical Decision-Making Algorithm for the Personalized Prescription of Microprocessor-Controlled Prosthetic Knees: An Evidence-Based Approach based on a Randomized Trial". Prosthetics and Orthotics International. 2025.
- [J1] A. Bajpai, C. Carrasquillo, J. Carlson, J. Park, D. Iyengar, K. Herrin, A. Young, A. Mazumdar. "Design and Validation of a Versatile High Torque Quasi-Direct Drive Hip Exoskeleton". IEEE Transactions on Mechatronics. 2023.
- [C2] C. Carrasquillo. "A Versatile and Open-Source Radio Framework for the D3 CubeSat Mission". Small Satellite Conference. 2021. Student Competition Best Paper Honorable Mention.
- [C1] S. Buckner, C. Carrasquillo, M. Elosegui, R. Bevilacqua. "A Novel Approach to CubeSat Flight Software Development Using Robot Operating System (ROS)". Small Satellite Conference. 2020. Poster Presentation.

### **Presentations**

- [P5] K. Herrin, C. Carrasquillo, S. Zhou, W. L. Childers, A. Young. "A Clinical Decision Equation for the Personalized Prescription of Prosthetic Microprocessor Knees". The American Orthotic and Prosthetic Association. September 2024.
- [P4] C. Carrasquillo, K. Herrin, S. Zhou, W. L. Childers, A. Young. "Toward data driven prescription personalization of microprocessor prosthetic knees". Military Health System Research Symposium. August 2024.
- [P3] C. Carrasquillo, "Towards Functional Exoskeleton Control". The National Defense Science and Engineering Graduate Fellowship Conference. July 2024.
- [P2] C. Carrasquillo, "Enhancing Human Navigation Ability Using Active Wearable Exoskeletons". Sloan UCEM Conference. April 2024.
- [P1] C. Carrasquillo, A. Bajpai, D. Iyengar, K. Collins, A. Mazumdar, A. Young. "Enhancing Human Navigation Ability Using an Active Wearable Exoskeleton". American Society of Biomechanics. August 2023.



# **Intern—Computer Science / Mechanical Engineering**

May 2021 - May 2022

Company: Raytheon Intelligence & Space

Location: Dallas, TX

Supervisors: Chris Bender, Malia Kawamura

- Developed a MERN stack web application to help engineers find components on printed circuit boards by search and mouseover.
- Designed 5 Splunk dashboards and developed 10 process programs for production-grade machinery.
- Engineered a VBA-based desktop application to automate the logging and tracking of material testing data, replacing a manual process.

### **Teaching Experience**

# **Mentor**—Vertically Integrated Projects (VIP)

Aug 2021 – Current

Institution: Georgia Institute of Technology, Institute for Robotics, and Intelligent Machines

Location: Atlanta, GA

Professor: Aaron Young, PhD

Team: Robotic Human Augmentation

Led and mentored a team of 16 undergraduate students performing research in the following areas:

- Designing exoskeleton hardware, including orthosis and mechatronics
- Creating exoskeleton controllers, from traditional impedance control to more recent, deep learning-based strategies
- Conducting human-subject experiments
- Performing biomechanical analysis, including Vicon processing, OpenSim, and data-driven strategies
- Developing virtual reality games for demonstration and experimentation
- Developing energetically optimal path planning algorithms for human navigation

### Senior Teaching Assistant—Design and Manufacturing Lab

May 2019 - May 2021

Institution: University of Florida Dept. of Mechanical and Aerospace Engineering

Location: Gainesville, FL Professor: Mike Braddock

- Instructed over 30 students (in groups of 4-5 each semester) on design for manufacturing (DFM) principles, conducting design reviews and providing feedback on CAD models and technical drawings.
- Trained and certified students on shop equipment, including lathes, mills, welders, waterjets, and CNC machines.
- Managed and supervised a university machine shop, assisting researchers and design teams with part fabrication.
- Held quarterly seminars on advanced manual machining methods.
- Provided mentorship and instruction incoming teaching assistants to prepare them to lead their own sections.

### **Teaching Assistant—Dynamics and Control Systems Design Lab**

**Aug 2020 – Dec 2020** 

Institution: University of Florida Dept. of Mechanical and Aerospace Engineering

Location: Gainesville, FL

Professor: Prabir Barooah, PhD, Shannon Ridgeway, PhD

- Lectured to students on applying classical control theory to real-world systems, guiding them through system identification, PID controller implementation on microcontrollers, and computer vision algorithm development.
- Instructed students on using LabVIEW for the design and control of actuated closed-loop systems.



# Teaching Assistant—Thermal Sciences Design and Lab

Aug 2020 - Dec 2020

Institution: University of Florida Dept. of Mechanical and Aerospace Engineering

Location: Gainesville, FL Professor: John Abbitt, PhD

- Lectured and instructed students on the thermodynamics and operating principles of internal combustion engines.
- Guided student teams in designing mathematical models for internal combustion engines for the class final project through brainstorming and design review sessions.
- Prepared students for exams by conducting comprehensive in-class review sessions.

### **Teaching Assistant—Numerical Methods**

May 2019 - Aug 2020

Institution: University of Florida Dept. of Mechanical and Aerospace Engineering

Location: Gainesville, FL

Professor: Jonathan Brooks, PhD, Georges Akiki, PhD

- Lectured on topics including iterative algorithms, linear algebra, numerical derivatives and integrals, Fourier analysis, polynomial regression, and splines.
- Created homework solutions, including answer keys, example software solutions, and grading rubrics.
- Prepared and presented in-class exam reviews.

## Fellowships and Awards

•	Grad REACH Scholar	Aug 2024 – Current
-	Pathbreakers Fellow (formerly University Center of Exemplary Mentoring)	Aug 2023 – Current
-	National Defense Science and Engineering Graduate (NDSEG) Fellow	Aug 2022 – Aug 2025
-	Florida Academic Scholars Award	Aug 2017 – May 2021
•	SwampHacks VI Infinite Energy's Best Hack Award	Jan 2020

#### **Extracurriculars**

•	PADI Advanced Open Water Diver	July 2023 – Current
•	Student Pilot @ Skybound Aviation (90+ hours)	July 2023 – Current
•	Georgia Tech Marching Band/Drumline: Snare Drum	July 2023 – May 2024

### Skills

- Design & Manufacturing: SolidWorks (CAD, FEA), Fusion 360 (CAD/CAM), Machine Shop Equipment (Lathes, Mills, CNC, Welding), Rapid Prototyping
- Programming: Python (NumPy, Pandas, OpenCV, PyTorch, TensorFlow, ROS, OpenMDAO), C/C++, JavaScript, MATLAB, Simulink, VBA, VHDL
- Certifications: Amateur Radio Technician (2019, KN4ZUC), SOLIDWORKS Associate (2020), Student Pilot (90+ hours),
   PADI Open Water Diver
- Languages: English and Spanish



National Biomechanics Day Organizer

2025 Georgia Tech Robotics Summer Scholars (GTRSS) Summer Camp Organizer
 2025 IEEE International Conference on Robotics and Automation Volunteer
 2024 Georgia Tech Robotics Summer Scholars (GTRSS) Summer Camp Organizer
 2023 Georgia Tech Robotics Summer Scholars (GTRSS) Summer Camp Organizer
 Elementary School Science Fair Judge
 Atlanta Science Festival Volunteer
 American Controls Conference Volunteer
 Jan 2025 – Jul 2025
 Jan 2024 – Jul 2024
 Jan 2023 – Jul 2023
 Mar 2023
 Jun 2023
 Jun 2022

Feb 2022 - Apr 2022