NAÏVE BAYES MODELS

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GENERAL IDEA

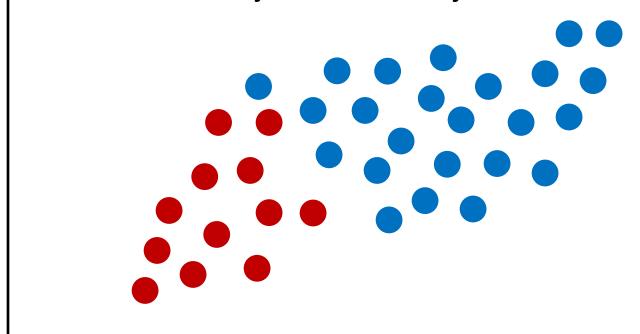
- When we need to classify variables there are two different sources of evidence:
 - 1. Similarity to each other based on certain metrics.
 - 2. Past decisions on classifications of observations like it.

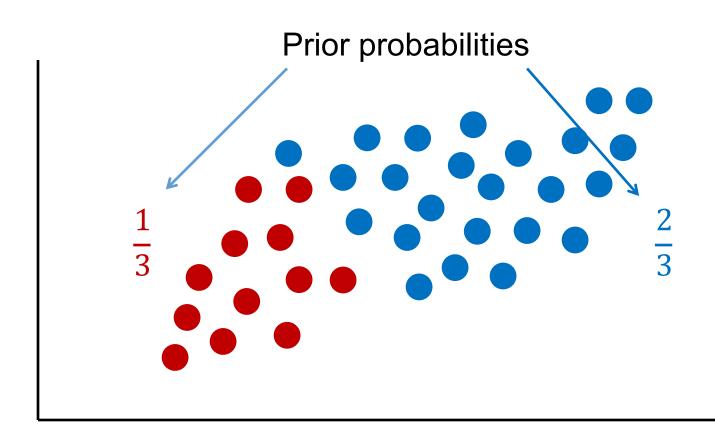
- When we need to classify variables there are two different sources of evidence:
 - 1. Similarity to each other based on certain metrics.
 - 2. Past decisions on classifications of observations like it.

1

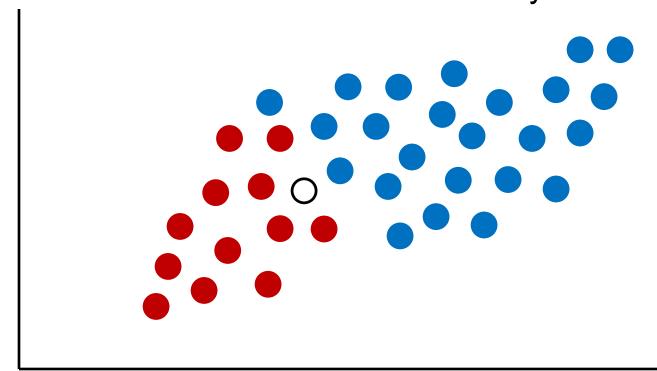
Bayesian approach, not frequentist.

Want to classify new observations based on currently observed objects.

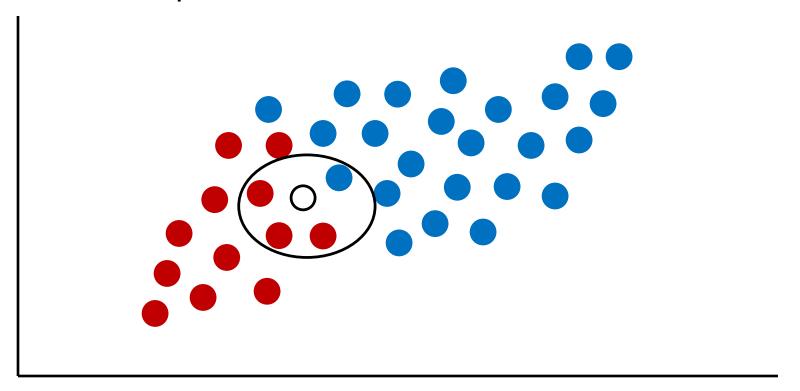




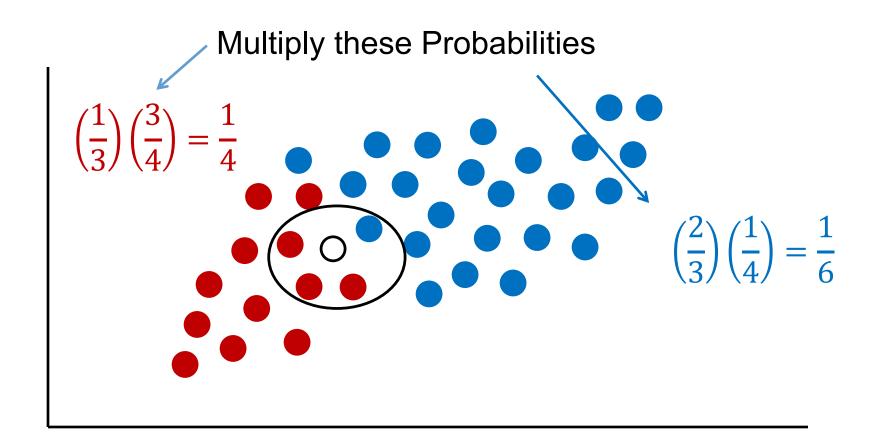
New observation to classify.

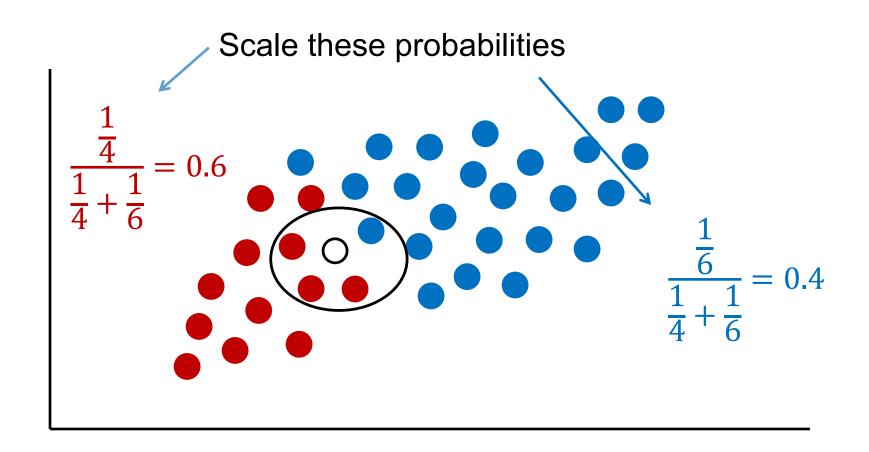


Take predefined closest number of observations.









Naïve Bayes Assumption

- One of the big assumptions of the Naïve Bayes Classification method is one of the hardest things to accept:
 - Predictor variables are independent in their effects on the classification.
- This is a rather "naïve" assumption.
- Assumption doesn't seem to bother posterior probabilities too greatly in case studies.



UNDERLYING MATH

Posterior Probabilities

 Posterior probability → Given values of variables for this observation, the predicted probability of success is...

P(*success*|*variable values*)

Prior probability >> Probability that an observation has those variable values.

Bayesian Classifiers

- Bayesian classifiers are based on Bayes' Theorem.
- Naïve Bayes Classifier assumes that the effect of the inputs are independent of one another.
- Bayes Theorem:

$$P(y_i|x_1, x_2, ..., x_p) = \frac{P(y_i) \times P(x_1, x_2, ..., x_p|y_i)}{P(x_1, x_2, ..., x_p)}$$

Bayesian Classifiers

- Bayesian classifiers are based on Bayes' Theorem.
- Naïve Bayes Classifier assumes that the effect of the inputs are independent of one another.
- Remember the probabilities behind independent events:

$$P(A \cap B) = P(A) \times P(B)$$

$$P(A \cap B|C) = P(A|C) \times P(B|C)$$

Bayesian Classifiers

- Bayesian classifiers are based on Bayes' Theorem.
- Naïve Bayes Classifier assumes that the effect of the inputs are independent of one another.
- Bayes Theorem:

$$P(y_i|x_1,x_2,...,x_p) = \frac{P(y_i)\times P(x_1|y_i)\times \cdots \times P(x_k|y_i)}{P(x_1)\times \cdots \times P(x_k)}$$

Color	Accident
Blue	Yes
Red	Yes
Blue	No
Blue	No
Red	Yes
Blue	Yes
Red	Yes
Blue	No
Red	Yes
Red	No
	Blue Red Blue Blue Red Blue Red Blue Red Red Blue

$$P(Y|M \&B) = \frac{P(Y) \times P(M|Y) \times P(B|Y)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{P(Y) \times P(M|Y) \times P(B|Y)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{P(Y) \times P(M|Y) \times \left(\frac{2}{6}\right)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{P(Y) \times \left(\frac{3}{6}\right) \times \left(\frac{2}{6}\right)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{P(Y) \times \left(\frac{3}{6}\right) \times \left(\frac{2}{6}\right)}{\left(\frac{3}{10}\right) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{P(Y) \times \left(\frac{3}{6}\right) \times \left(\frac{2}{6}\right)}{\left(\frac{3}{10}\right) \times \left(\frac{5}{10}\right)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y|M \&B) = \frac{\left(\frac{6}{10}\right) \times \left(\frac{3}{6}\right) \times \left(\frac{2}{6}\right)}{\left(\frac{3}{10}\right) \times \left(\frac{5}{10}\right)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(Y \mid M \& B) = \frac{\left(\frac{6}{10}\right) \times \left(\frac{3}{6}\right) \times \left(\frac{2}{6}\right)}{\left(\frac{3}{10}\right) \times \left(\frac{5}{10}\right)} = \frac{2}{3}$$

Color	Accident
Blue	Yes
Red	Yes
Blue	No
Blue	No
Red	Yes
Blue	Yes
Red	Yes
Blue	No
Red	Yes
Red	No
	Blue Red Blue Red Blue Red Blue Red Blue Red Red

$$P(N|M \&B) = \frac{P(N) \times P(M|N) \times P(B|N)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N|M \&B) = \frac{P(N) \times P(M|N) \times P(B|N)}{P(M) \times P(B)}$$

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{P(N) \times \left(\frac{0}{4}\right) \times P(B \mid N)}{P(M) \times P(B)} = 0$$



Problems of Zero Probability

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{P(N) \times \left(\frac{0}{4}\right) \times P(B \mid N)}{P(M) \times P(B)} = 0$$

- Predicted probability of zero regardless of everything else if certain values don't occur for all levels of the outcome...
- Think "quasi-complete separation"ish ...

Problems of Zero Probability

Size	Color	Accident
Large	Blue	Yes
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Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{P(N) \times \left(\frac{0}{4}\right) \times P(B \mid N)}{P(M) \times P(B)} = 0$$

	Yes	No
Small	1	2
Medium	3	0
Large	2	2

Laplace Correction (Laplace Estimator)

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{P(N) \times \left(\frac{0}{4}\right) \times P(B \mid N)}{P(M) \times P(B)} = 0$$

	Yes	No
Small	1.01	2.01
Medium	3.01	0.01
Large	2.01	2.01

Laplace Correction (Laplace Estimator)

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{P(N) \times \left(\frac{0.01}{4.03}\right) \times P(B \mid N)}{P(M) \times P(B)}$$

	Yes	No
Small	1.01	2.01
Medium	3.01	0.01
Large	2.01	2.01

Laplace Correction (Laplace Estimator)

Size	Color	Accident
Large	Blue	Yes
Large	Red	Yes
Large	Blue	No
Large	Blue	No
Medium	Red	Yes
Medium	Blue	Yes
Medium	Red	Yes
Small	Blue	No
Small	Red	Yes
Small	Red	No

$$P(N \mid M \& B) = \frac{\left(\frac{4}{10}\right) \times \left(\frac{0.01}{4.03}\right) \times \left(\frac{3}{4}\right)}{\left(\frac{3}{10}\right) \times \left(\frac{4}{10}\right)}$$

$$= 0.0062$$

Creating Output Probabilities

 The final probabilities will not likely sum to one so we force them to by dividing by their sum.

$$P(Y \mid M\&B) = \frac{\binom{2}{3}}{0.0062 + \binom{2}{3}} = 0.991$$

$$P(N \mid M\&B) = \frac{0.0062}{0.0062 + \left(\frac{2}{3}\right)} = 0.009$$



NAÏVE BAYES IN R

Classification Target

Inputs:

- Categorical variables determine probability based on cross-tabulation of each variable with target variable.
- Numerical variables determine probability based on either values from a Normal distribution with same mean and standard deviation as data OR kernel density estimation of the data.

Output:

 Probability that each observation belongs to each category of target variable.

Continuous Target

- Inputs:
 - Categorical variables determine probability based on cross-tabulation of each variable with target variable.
 - Numerical variables determine probability based on either values from a Normal distribution with same mean and standard deviation as data OR kernel density estimation of the data.

Output:

- Value of the target variable that is the highest probability.
- Treats the continuous target as a large number of categories.

Ames Data

```
set.seed(4321)
training <- ames %>% sample_frac(0.7)
testing <- anti_join(ames, training, by = 'id')</pre>
training <- training %>%
  select(Sale_Price,
         Bedroom_AbvGr,
         Year_Built,
         Mo_Sold,
         Lot Area,
         Street,
         Central_Air,
         First_Flr_SF,
         Second_Flr_SF,
         Full_Bath,
         Half Bath,
         Fireplaces,
         Garage Area,
         Gr_Liv_Area,
         TotRms_AbvGrd)
```

Naïve Bayes

```
set.seed(12345)
nb.ames <- naiveBayes(Sale_Price ~ ., data = training, laplace = 0, usekernel = TRUE)</pre>
```

Naïve Bayes – Tuning (ONLY CLASSIFICATION)



SUMMARY

Naïve Bayes Summary

Advantages

- Simple to implement.
- Good at predictions.
 - Especially good classification for few categories.
- Perform best with categorical variables / text.
- Fast computational time.
- Robust to noise and irrelevant variables.

Disadvantages

- Independence assumption.
- Careful about normality assumption for continuous variables.
- Requires more memory storage than most variables.
- Trust predicted categories more than probabilities.

