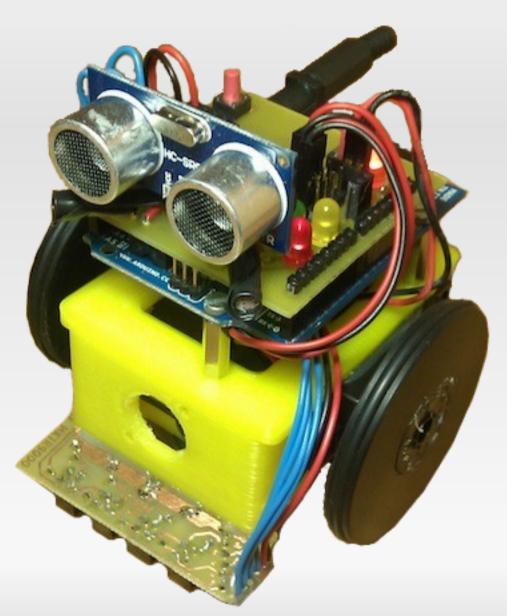
# Lesson 2 – Robot assembly

#### ArduSkyBot 2012 Summer Workshop

#### Today you will learn:

- Components of our robot
- How to build the ArduSkyBot!
- Simple programming examples
- You will program your own sequences!



## ArduSkyBot's features

**Push buttons** 

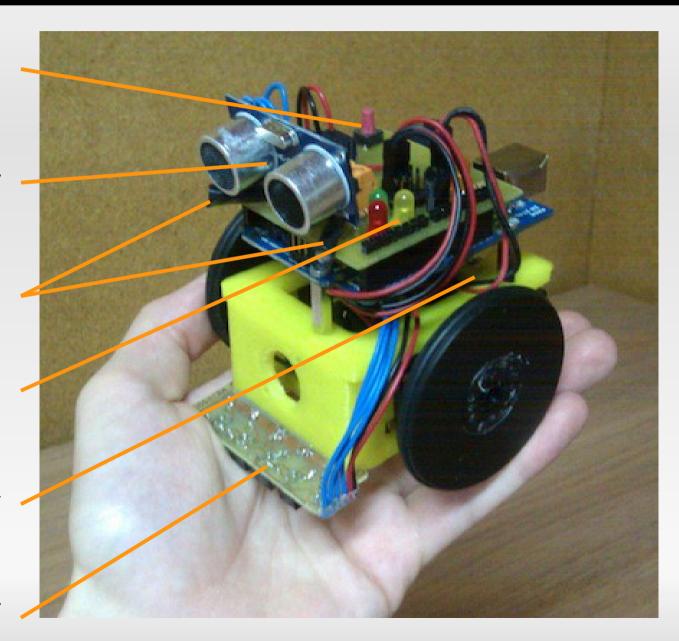
Frontal distance sensor

Two light sensors

**Lots of LED lights** 

**Speaker** 

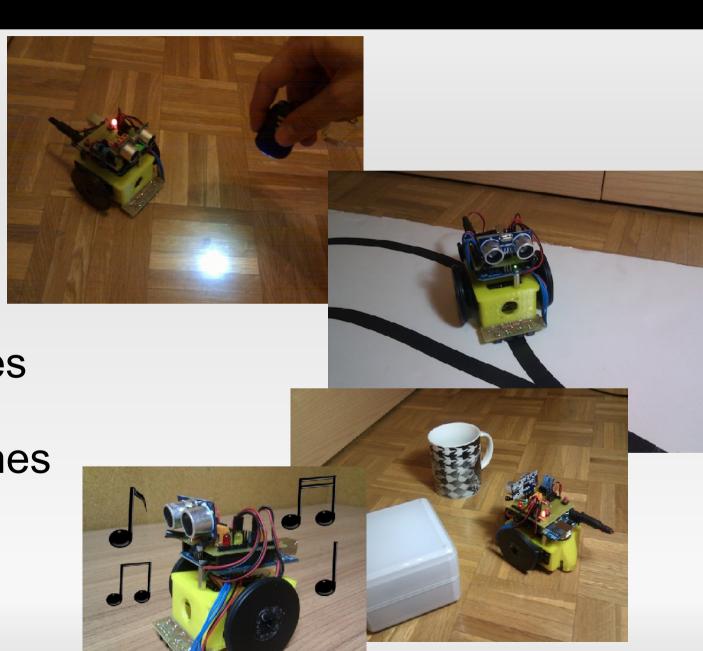
Line sensor

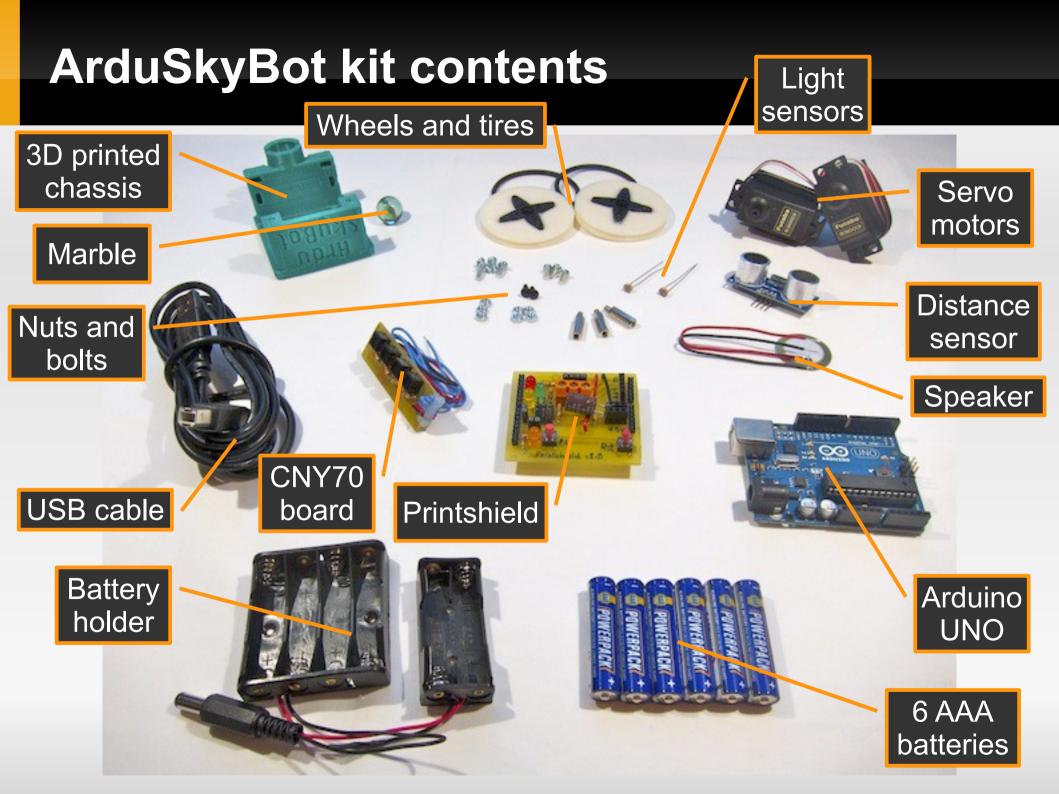


#### What can the ArduSkyBot do?

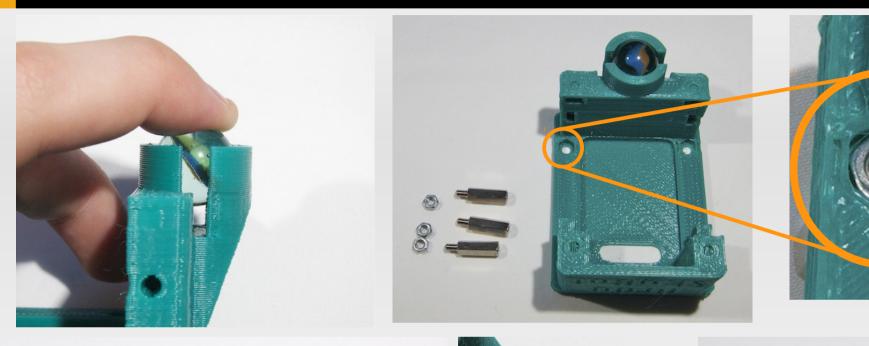
#### Some examples:

- Follow light
- Line follower
- Avoid obstacles
- Play music tones

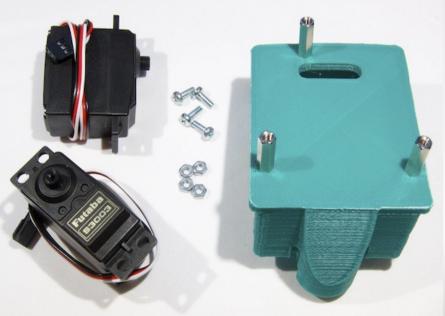


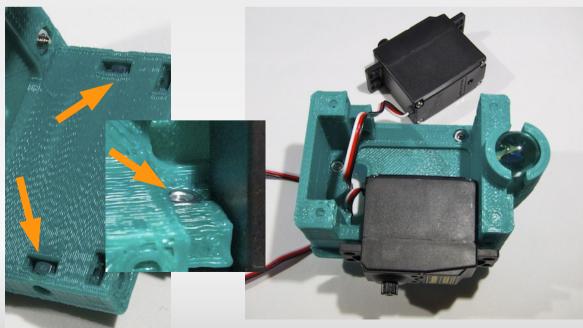


### Assembly of the ArduSkyBot (1)

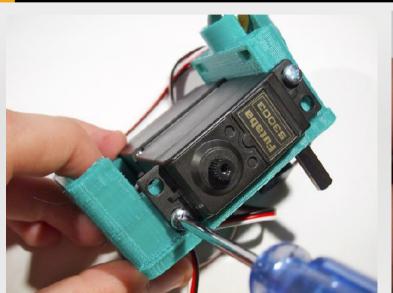








#### Assembly of the ArduSkyBot (2)

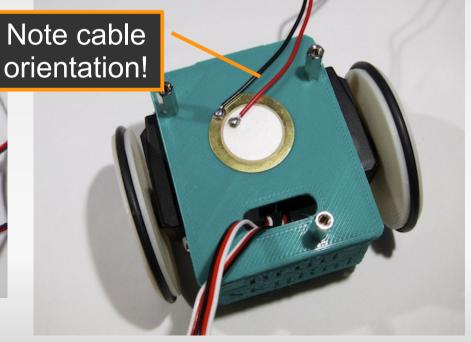




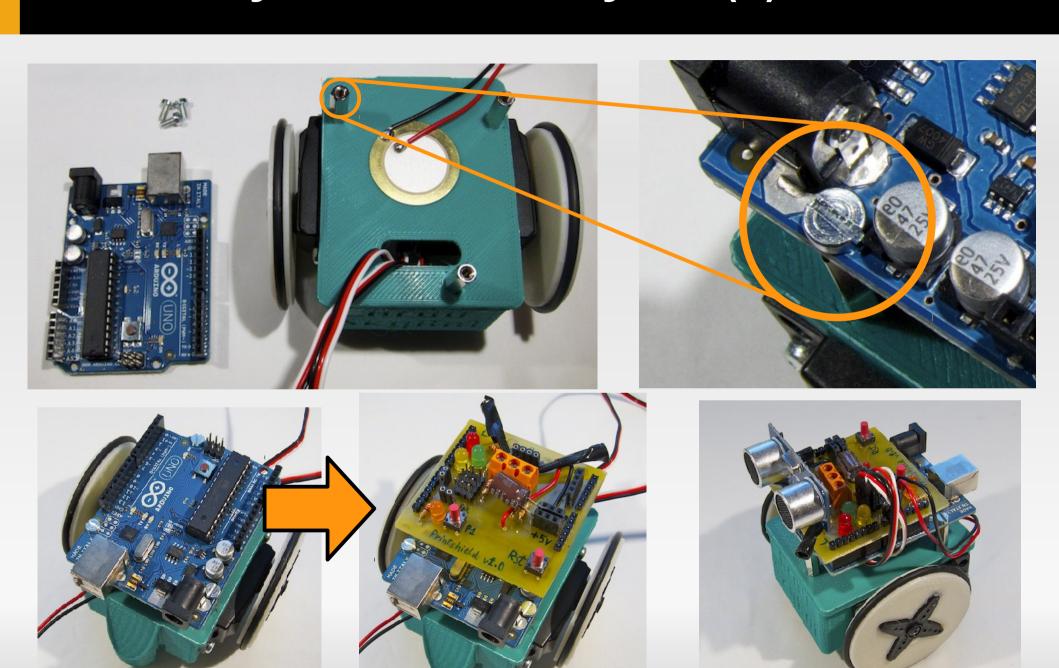








### Assembly of the ArduSkyBot (3)



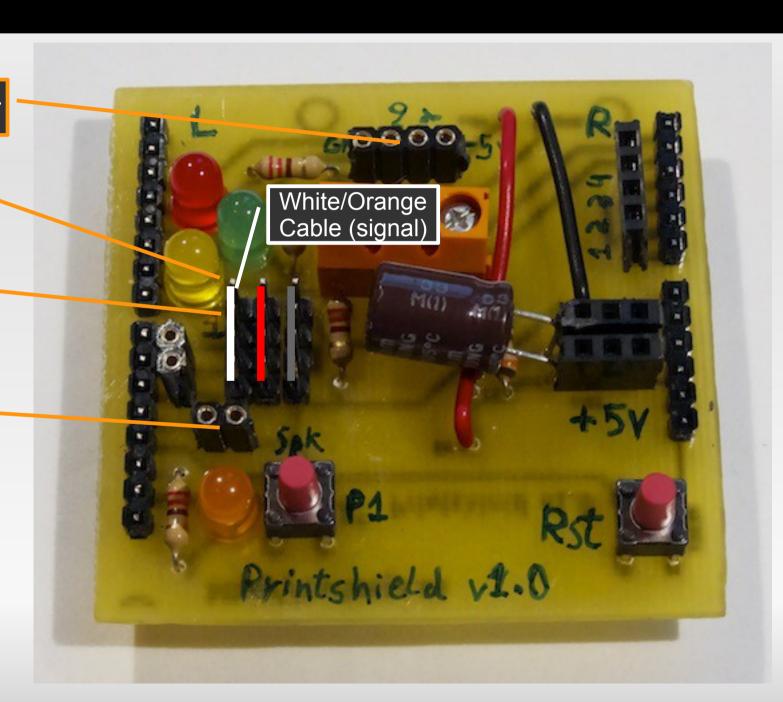
### Printshield connections

Distance sensor

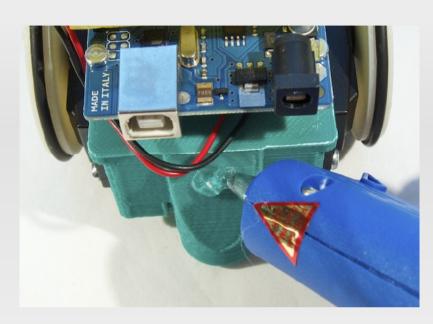
Left motor

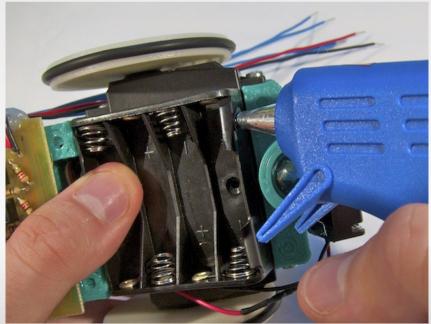
Right motor

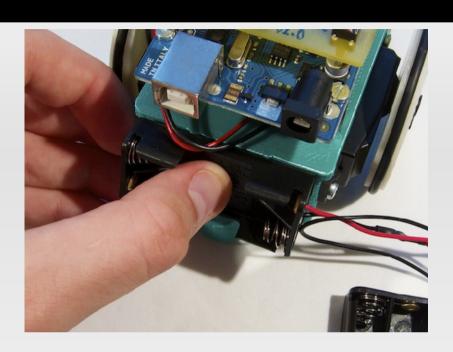
Speaker



### Assembly of the ArduSkyBot (4)

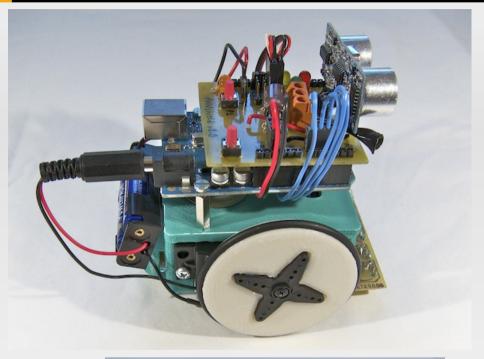


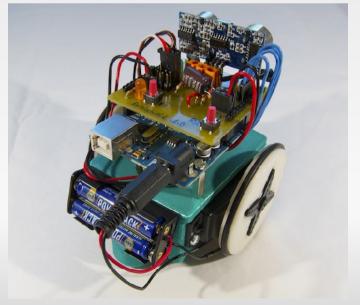


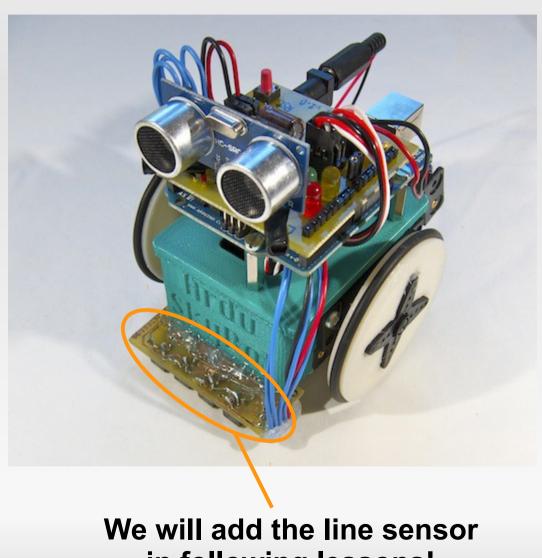




#### You have built an ArduSkyBot!

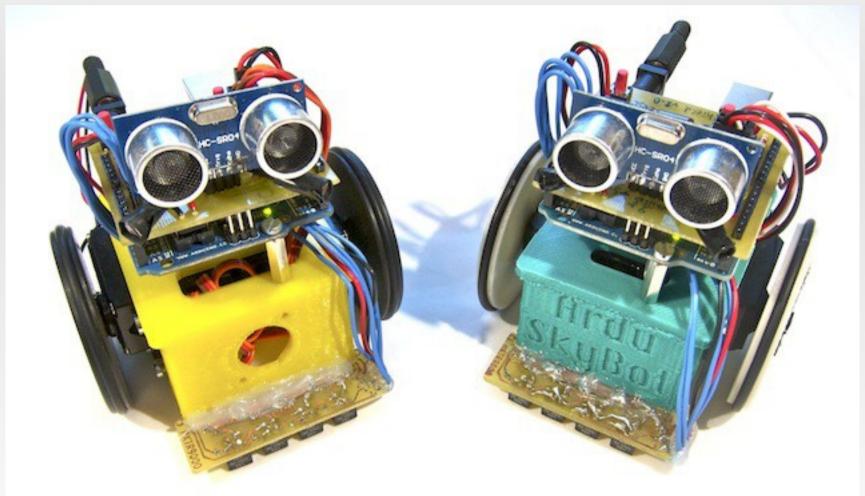






in following lessons!

#### Now we can begin with the programming!



Download the example code from http://www.carlosgs.es/2012-summer-workshop

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