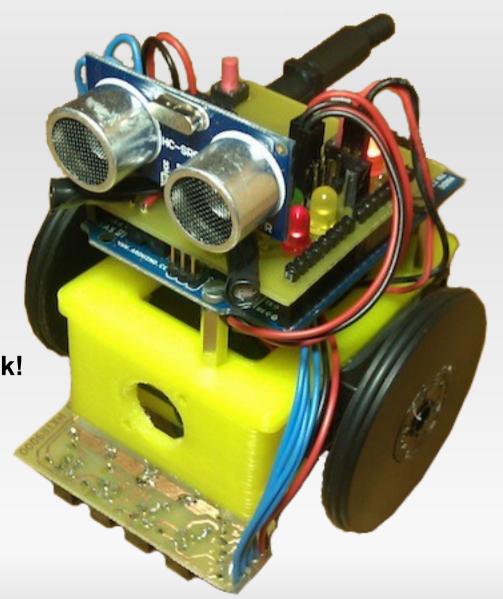
## Lesson 1 - Introduction

#### ArduSkyBot 2012 Summer Workshop

#### Today you will learn:

- Basic components of a robot.
- What is **Arduino** and how to program it.
- Meet the ArduSkyBot!
- You will play music and make LED's blink!



#### What is a robot?

Autonomous device that is able to make pre-programmed tasks





### Components of a robot

#### Sensors



#### **Actuators**

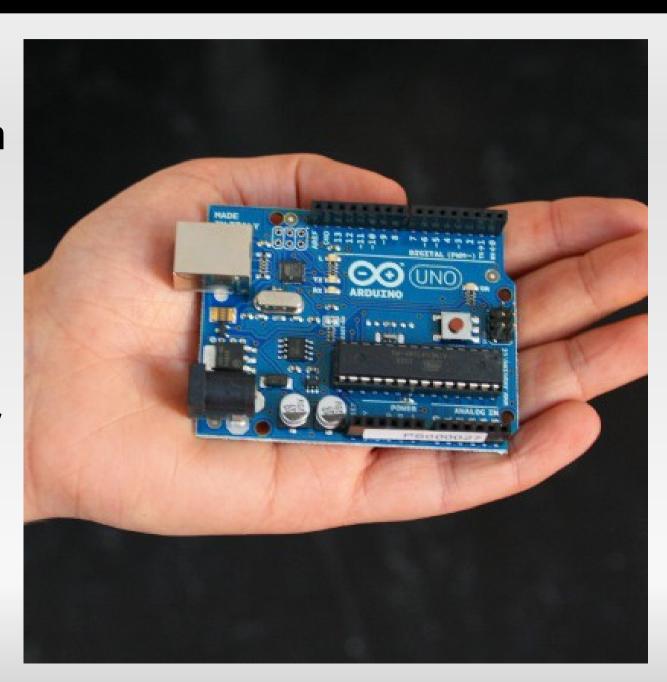


#### **Arduino**

Open source electronics platform

It is the "brain" of our robot!

You can program it with a computer



# Arduino (2)

# People make crazy projects



Automatic feeder



Automatic toilet flush: http://www.youtube.com/watch?v=4k899QWsJwl

Arduino paper cat: http://www.youtube.com/watch?v=ZzZ4\_g4YzxY

#### Arduino (3)

We are using Arduino UNO
It has lots of input/output pins

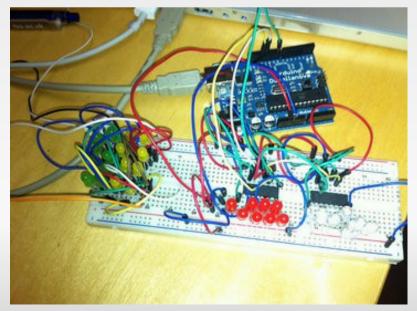
You can connect any kind of sensors and actuators

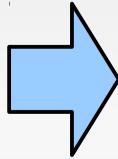


#### **Arduino & Printshield**

# Compact electronics using an Arduino UNO with a Printshield









#### **Printshield**

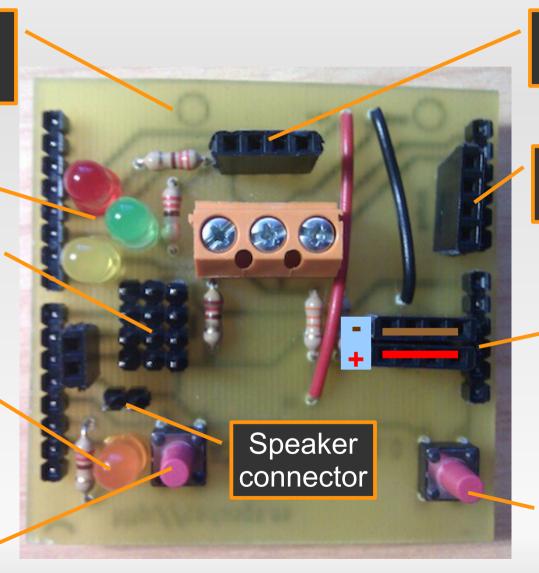
Connector for light sensors

LED lights

Connectors for servo-motors

Another LED light

Push button



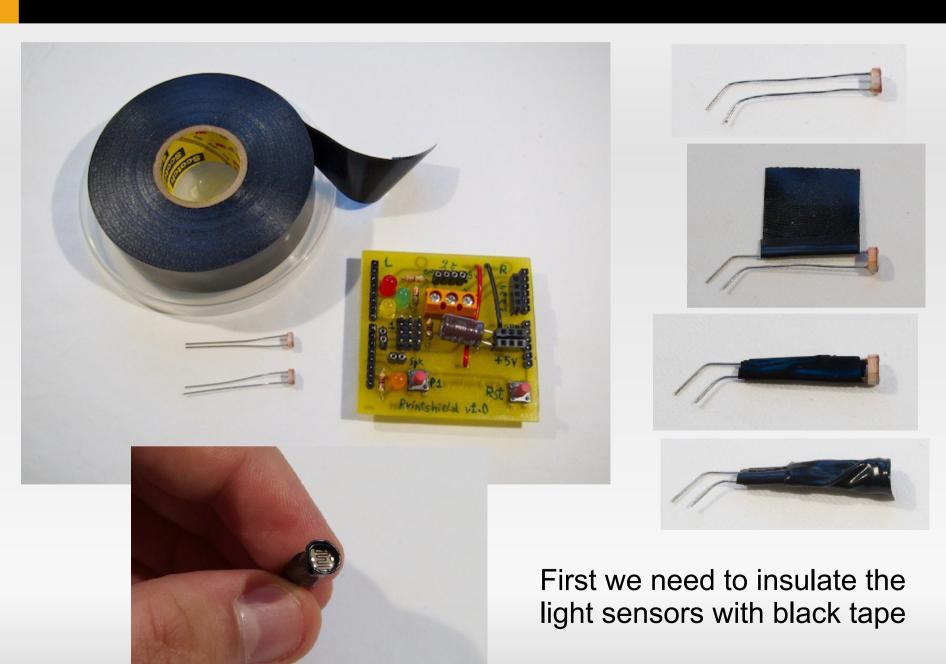
Connector for distance sensor

Connector for line sensor

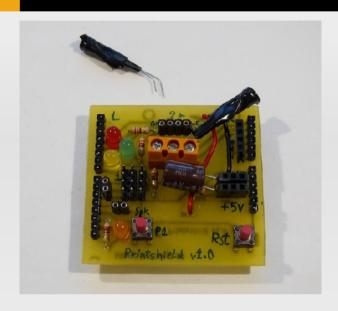
5V Power line

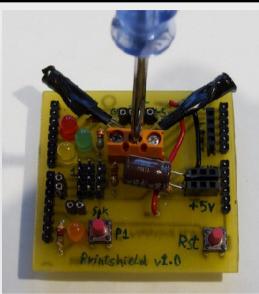
Restart/reset button

# Assembling the Printshield (1)



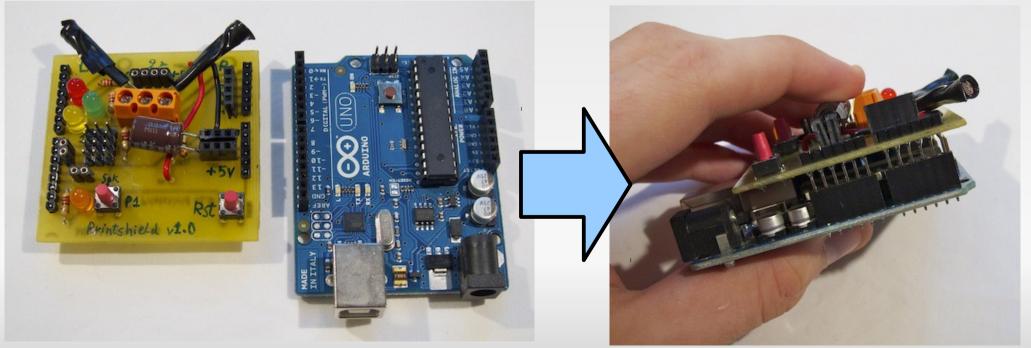
# Assembling the Printshield (2)



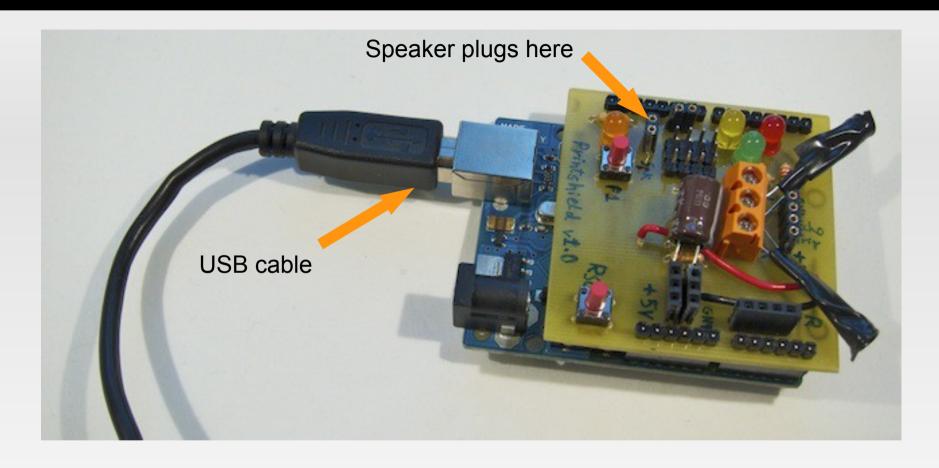


Light sensors need to be screwed into the orange connector

Then we must plug the Printshield on the Arduino UNO board



# Plug it into the computer!



Now we just need to load our programs into the board.

#### Load the "Blink" example

Download more example code from http://www.carlosgs.es/2012-summer-workshop

```
0 0
                           Blink | Arduino 1.0
  Blink
 Blink
 Turns on an LED on for one second, then off for one second, repeatedly.
 This example code is in the public domain.
void setup() {
 // initialize the digital pin as an output.
 // Pin 13 has an LED connected on most Arduino boards:
 pinMode(13, OUTPUT);
void loop() {
 digitalWrite(13, HIGH); // set the LED on
 delay(1000);
                // wait for a second
 digitalWrite(13, LOW); // set the LED off
 delay(1000);
                        // wait for a second
                                       Arduino Uno on /dev/tty.usbmodemfa131
```

#### Say hello to the ArduSkyBot!

It features:

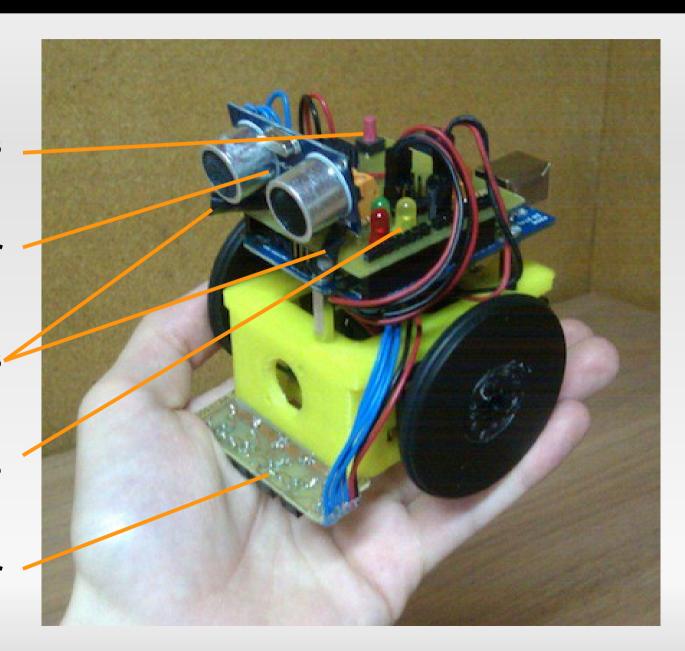
**Push buttons** 

Frontal distance sensor

Two light sensors

**Lots of LED lights** 

Line sensor

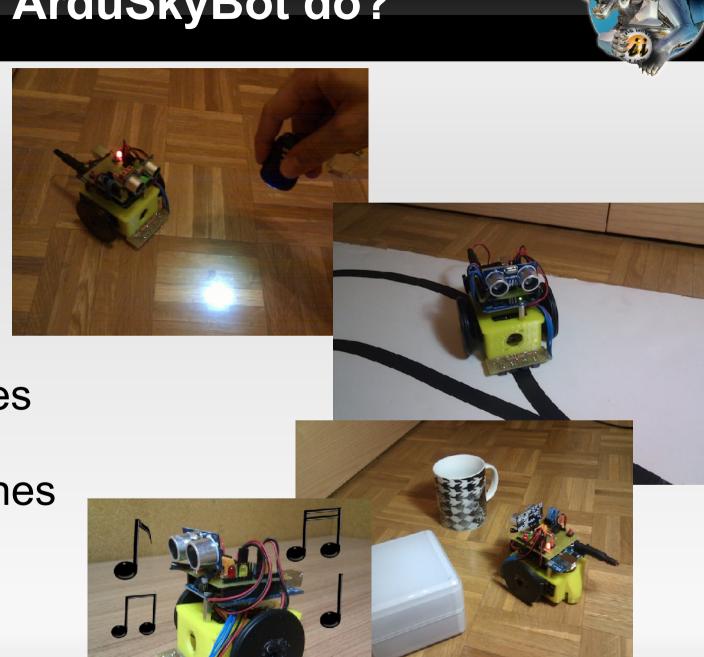


#### What can the ArduSkyBot do?



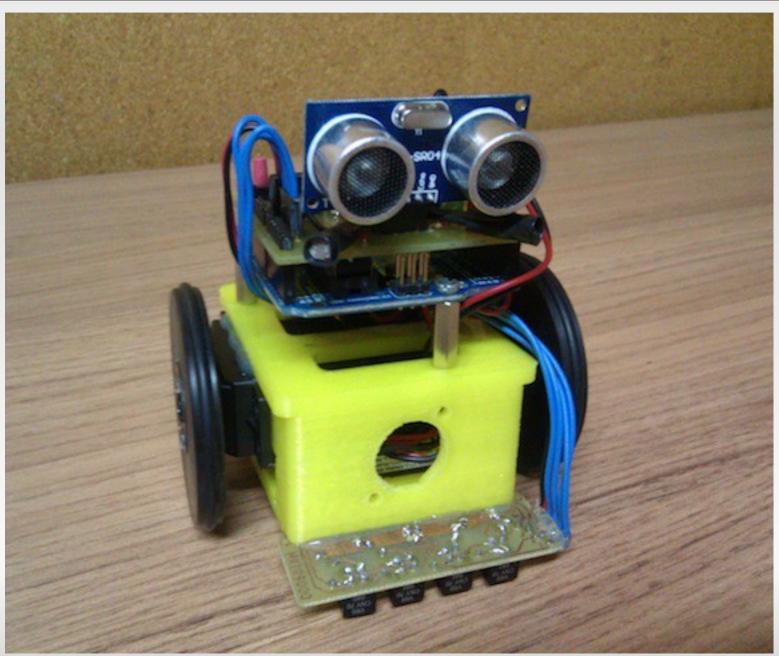
#### Some examples:

- Follow light
- Line follower
- Avoid obstacles
- Play music tones



#### Tomorrow more!





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