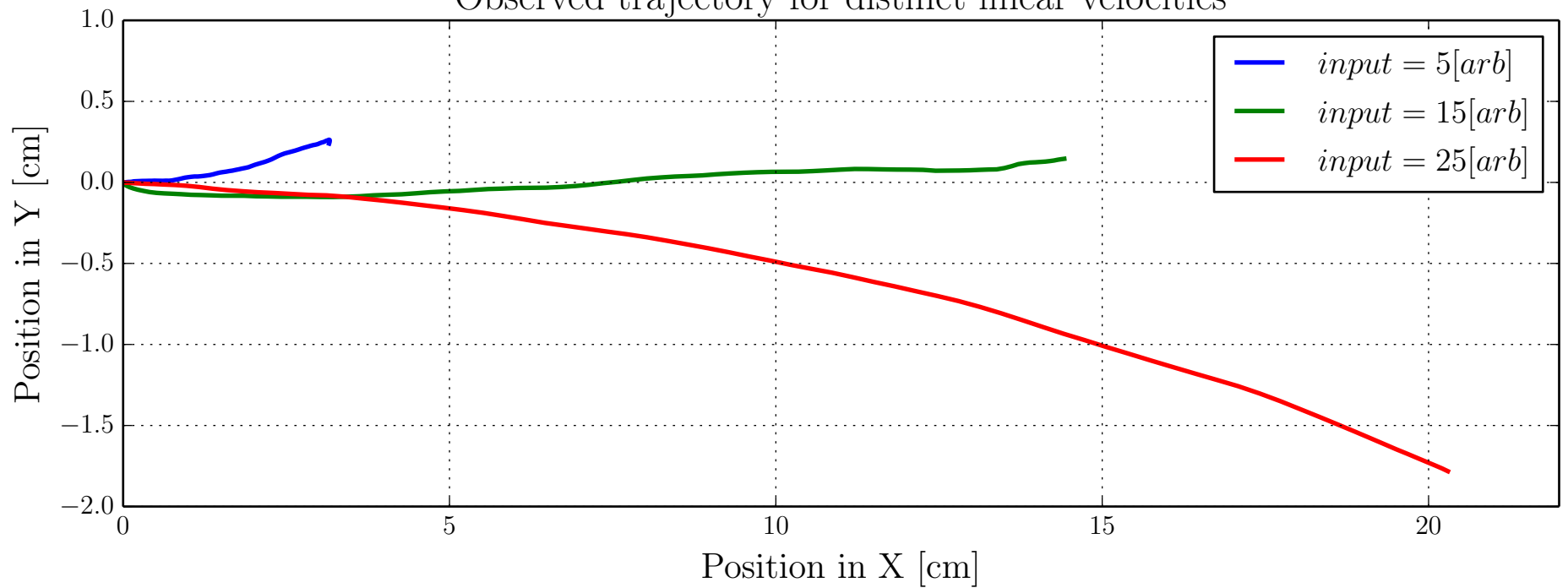


Observed trajectory for distinct linear velocities



Deviation from a straight path (yaw), measured with the on-board gyroscope

