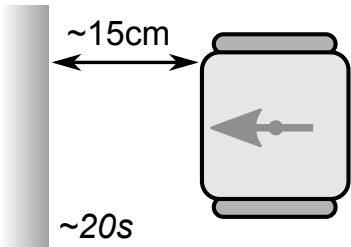
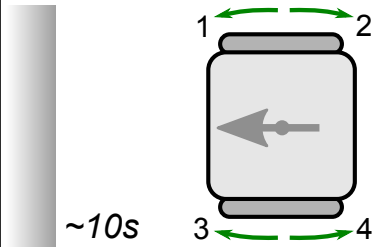


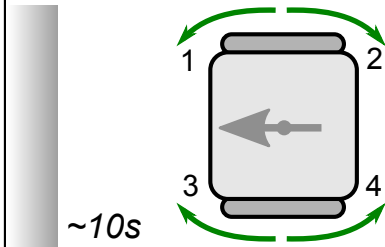
a) Gyroscope drift



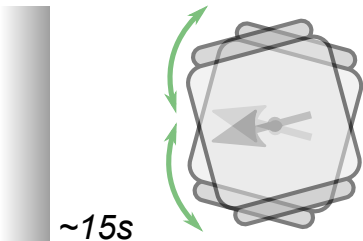
b) Min. motor velocity



c) Max. motor velocity



d) PID auto-tuning



e) Linear velocity calibration (using the IR rangefinder)

