

Problem 1

When $x_1 > x_2 > x_3 > x_4$,

$$\Rightarrow \left(W^{(1)} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} + b^{(1)} \right)^T W^{(2)} + b^{(2)} \geq 0$$

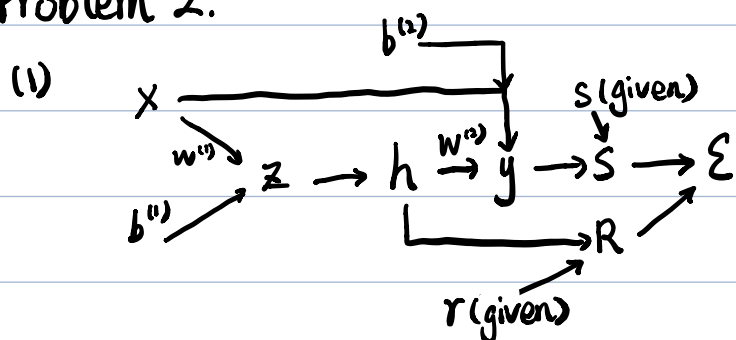
else < 0

\therefore

$$W^{(1)} = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \end{pmatrix}, \quad b^{(1)} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad W^{(2)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad b^{(2)} = -3$$

can correctly implement this function.

Problem 2.



(2) $\bar{\epsilon} = 1$

$$\bar{r} = \bar{\epsilon} \frac{d\epsilon}{dR} = \bar{\epsilon} = 1$$

$$\bar{s} = \bar{\epsilon} \frac{d\epsilon}{ds} = \bar{\epsilon} = 1$$

$$\bar{y} = \bar{s} \frac{ds}{dy} = \bar{s} (y - s) = y - s$$

$$\bar{h} = \bar{y} \cdot \frac{dy}{dh} + \bar{r} \cdot \frac{dr}{dh} = (y - s) \cdot W^{(3)} + r$$

$$\bar{z} = \bar{h} \cdot \frac{dh}{dz} = ((y - s)W^{(3)} + r) \sigma'(z)$$

$$\bar{x} = \bar{z} \cdot \frac{dz}{dx} + \bar{y} \cdot \frac{dy}{dx} = ((y - s)W^{(3)} + r) \sigma'(z) \cdot W^{(1)} + (y - s)$$

(3) $W^{(1)} = \bar{y} \cdot \frac{dy}{dw^{(1)}} = (y - s) \cdot h$

$$b^{(1)} = \bar{y} \cdot \frac{dy}{db^{(1)}} = (y - s)$$

$$W^{(2)} = \bar{z} \cdot \frac{dz}{dw^{(2)}} = ((y - s)W^{(3)} + r) \sigma'(z) \cdot x$$

$$b^{(2)} = \bar{z} \cdot \frac{dz}{db^{(2)}} = ((y - s)W^{(3)} + r) \sigma'(z)$$

Problem 3.

$$\bar{L} = 1$$

$$\bar{y} = \bar{L} \cdot \frac{\partial L}{\partial y} = (\log y - \log t) \cdot \frac{1}{y}$$

$$\bar{z} = \bar{y} \cdot \frac{\partial y}{\partial z} = \bar{y} e^z$$

$$\bar{w}_2 = \bar{z} \cdot \frac{\partial z}{\partial w_2} = \bar{z} x^2 = \bar{L} (\log y - \log t) \frac{1}{y} e^z x^2$$

$$\frac{\partial L}{\partial w_2} = (\log y - \log t) \frac{1}{y} e^z x^2$$

Problem 4

$$(1) \quad \bar{o}^{(t)} = \bar{h}^{(t)} \tanh(c^{(t)})$$

$$\bar{c}^{(t)} = \bar{h}^{(t)} \bar{o}^{(t)} [1 - \tanh^2(c^{(t)})] + \bar{c}^{(t-1)} f^{(t+1)}$$

$$\bar{g}^{(t)} = \bar{c}^{(t)} i^{(t)}$$

$$\bar{f}^{(t)} = \bar{c}^{(t)} c^{(t-1)}$$

$$\bar{i}^{(t)} = \bar{c}^{(t)} g^{(t)}$$

$$\begin{aligned} \bar{h}^{(t-1)} &= \bar{i}^{(t)} \sigma'(W_{ix} x^{(t)} + W_{ih} h^{(t-1)}) W_{ih} + \bar{f}^{(t)} \sigma'(W_{fx} x^{(t)} + W_{fh} h^{(t-1)}) W_{fh} \\ &\quad + \bar{o}^{(t)} \sigma'(W_{ox} x^{(t)} + W_{oh} h^{(t-1)}) W_{oh} + \bar{g}^{(t)} (1 - \tanh^2(W_{fg} x^{(t)} + W_{gh} h^{(t-1)})) W_{gh} \end{aligned}$$

$$\begin{aligned} \therefore \bar{h}^{(t)} &= \bar{i}^{(t+1)} \sigma'(W_{ix} x^{(t+1)} + W_{ih} h^{(t)}) W_{ih} \\ &\quad + \bar{f}^{(t+1)} \sigma'(W_{fx} x^{(t+1)} + W_{fh} h^{(t)}) W_{fh} \\ &\quad + \bar{o}^{(t+1)} \sigma'(W_{ox} x^{(t+1)} + W_{oh} h^{(t)}) W_{oh} \\ &\quad + \bar{g}^{(t+1)} (1 - \tanh^2(W_{fg} x^{(t+1)} + W_{gh} h^{(t)})) W_{gh} \end{aligned}$$

$$(2) \quad \bar{w}_{ix} = \sum_t \bar{i}^{(t)} \sigma'(W_{ix} x^{(t)} + W_{ih} h^{(t-1)}) x^{(t)}$$

$$(3) \quad \bar{x}^{(t)} = \bar{i}^{(t)} \frac{\partial i^{(t)}}{\partial x^{(t)}} + \bar{f}^{(t)} \frac{\partial f^{(t)}}{\partial x^{(t)}} + \bar{g}^{(t)} \frac{\partial g^{(t)}}{\partial x^{(t)}} + \bar{o}^{(t)} \frac{\partial o^{(t)}}{\partial x^{(t)}}$$

$$= \bar{i}^{(t)} \sigma'(W_{ix} x^{(t)} + W_{ih} h^{(t-1)}) W_{ix} + \bar{g}^{(t)} \sigma'(W_{fx} x^{(t)} + W_{fh} h^{(t-1)}) W_{fx} \\ + \bar{g}^{(t)} (1 - \tanh^2(W_{gx} x^{(t)} + W_{gh} h^{(t-1)})) W_{gx} \\ + \bar{o}^{(t)} \sigma'(W_{ox} x^{(t)} + W_{oh} h^{(t-1)}) W_{ox}$$

When $i^{(t)} \rightarrow 0$, $o^{(t)} \rightarrow 0$, $f^{(t)} \rightarrow 1$

by changing value of o.f.i, one can control the amount of information the network retains or discards over the entire input series as well as control depending on individual inputs.

$$c(t) \approx c(t-1), h(t) = o^{(t)} \tanh(c^{(t)}) \approx o^{(t)} \tanh(c^{(t-1)})$$

Both $c^{(t)}$ and $h^{(t)}$ stay almost the same as before

Hence, the gradient won't explode.

Problem 5.

$$\text{suppose } \mathcal{L} = \frac{1}{2} (y - t)^2$$

$$\bar{\mathcal{L}} = 1$$

$$\bar{y} = \bar{\mathcal{L}} \cdot (y - t) = y - t$$

$$\bar{u}_1 = \bar{y} \cdot h_1 = h_1 (y - t) = 0$$

$$\bar{u}_2 = \bar{h}_1 \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_2} \quad \text{where } \frac{\partial h_1}{\partial z_1} = 0 \quad \text{since } z_1 = -1 \quad (\text{ReLU}'(-1) = 0) \quad \text{Yes}$$

$$= (y - t) \cdot w_1 \cdot 0 \cdot h_3 = 0$$

$$\bar{w}_3 = \bar{h}_3 \times \frac{\partial h_3}{\partial w_3} = \left(\bar{h}_1 \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial h_3} + \bar{h}_2 \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial h_3} \right) \times 1 \quad \text{Yes}$$

$$= (\bar{h}_1 \cdot 0 \cdot w_2 + \bar{h}_2 \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_3}{\partial h_3}) \times 1$$

$$= \bar{h}_2 \frac{\partial h_2}{\partial z_2} \frac{\partial z_3}{\partial h_3} \times 1$$

No