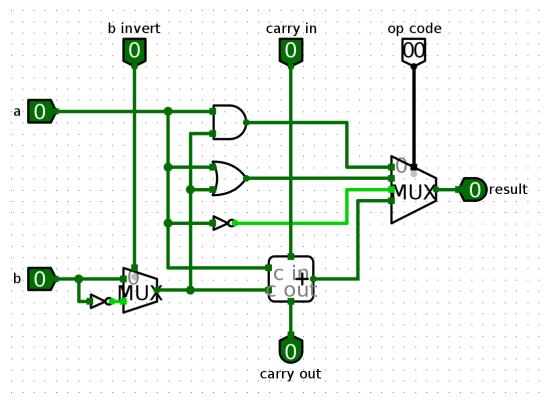
# **Exercício Prático 2**

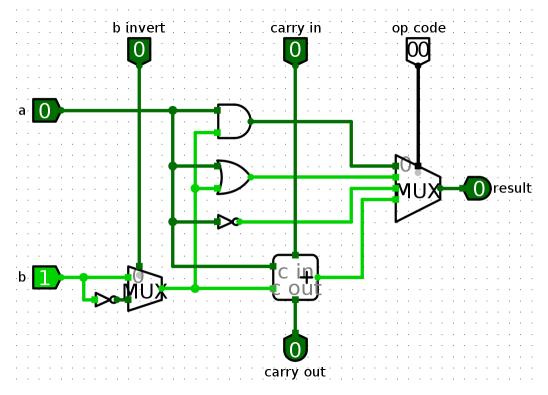
Carolina Morais Nigri - 761400 Pedro Miranda Rodrigues - 761531

## Parte 1 - ULA no Logisim

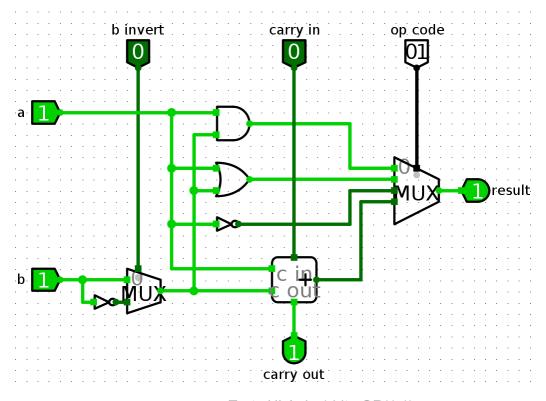
#### ULA de 1 bit



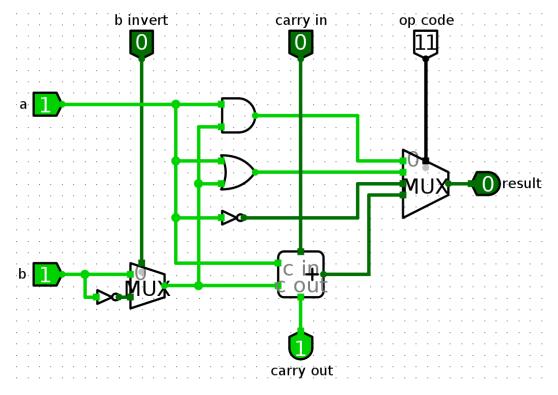
Circuito ULA de 1 bit - Logisim



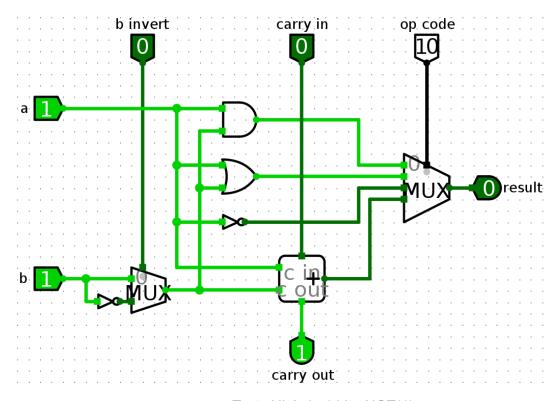
Teste ULA de 1 bit - AND(0,1)



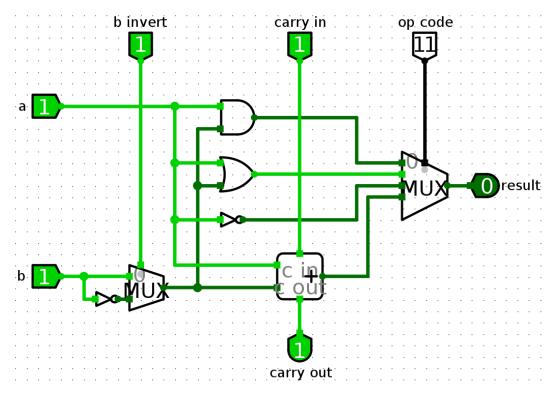
Teste ULA de 1 bit - OR(1,1)



Teste ULA de 1 bit - SOMA(1,1)

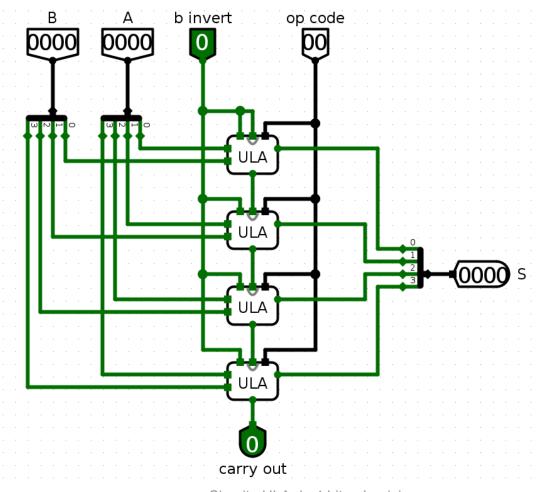


Teste ULA de 1 bit - NOT(1)

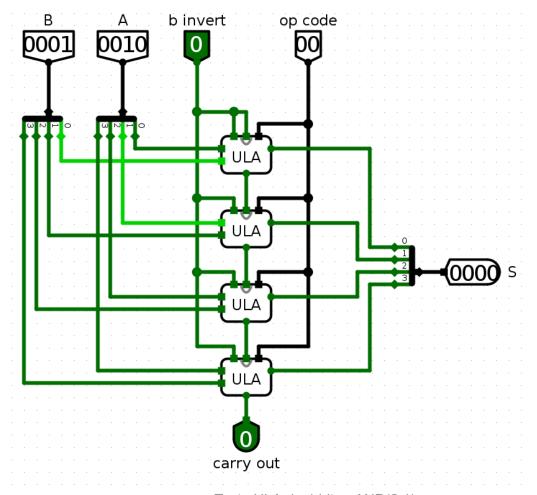


Teste ULA de 1 bit - SOMA(1,-1)

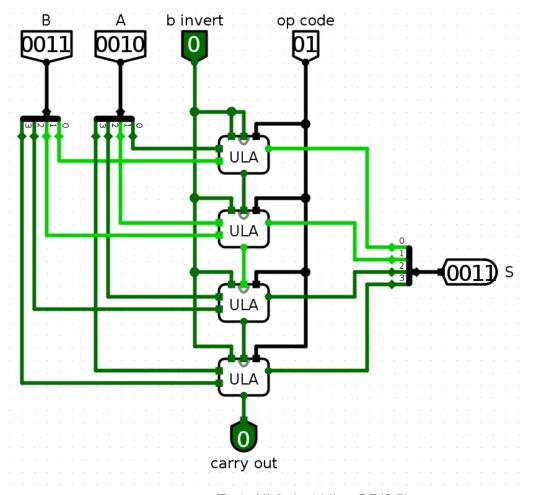
#### ULA de 4 bits



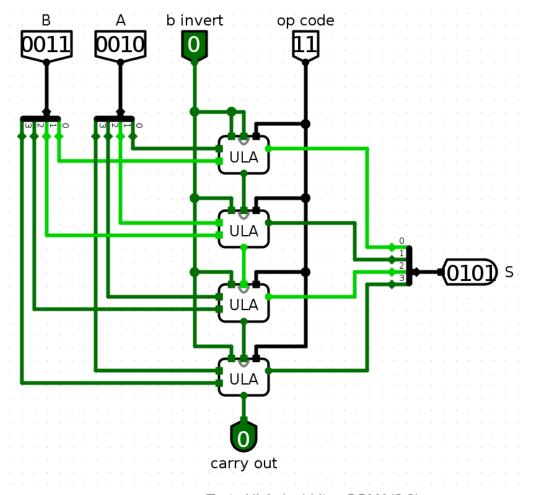
Circuito ULA de 4 bits - Logisim



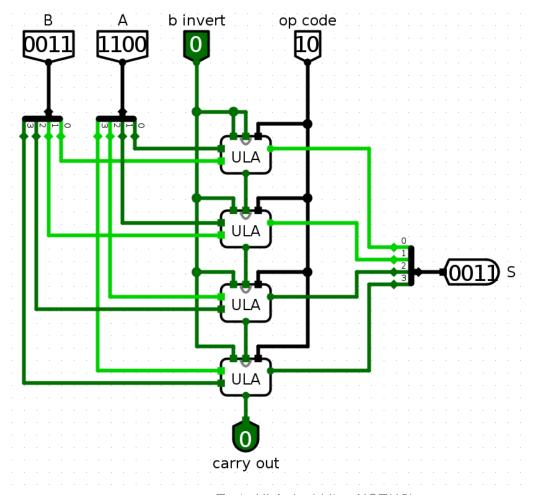
Teste ULA de 4 bits - AND(2,1)



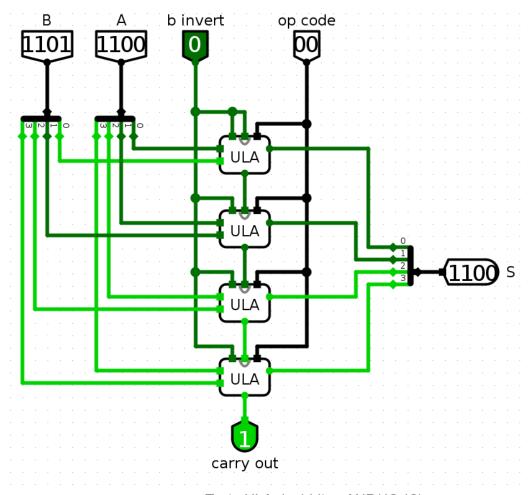
Teste ULA de 4 bits - OR(2,3)



Teste ULA de 4 bits - SOMA(2,3)



Teste ULA de 4 bits - NOT(12)

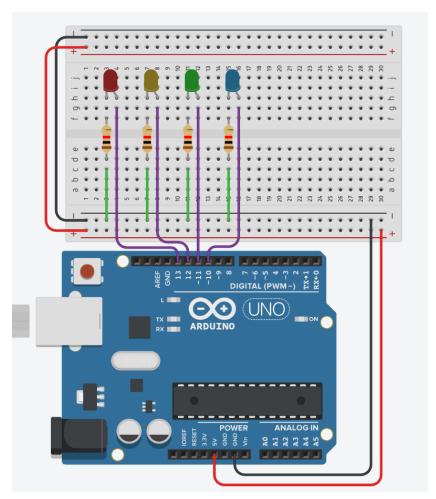


Teste ULA de 4 bits - AND(12,13)

#### <u>Tabela</u>

| Instrução<br>realizada | Binário (A,B,<br>Op.code) | Valor em Hexa (0x)                      | Resultado em binário |
|------------------------|---------------------------|---|----------------------|
| AND(A,B)               | 0010 0001 00              | $(0000\ 1000\ 0100) = 0x084$            | 0000                 |
| OR(A,B)                | 0010 0011 01              | $(0000\ 1000\ 1101) = 0x08D$            | 0011                 |
| SOMA(A,B)              | 0010 0011 11              | (00 <mark>00 10</mark> 00 1111) = 0x08F | 0101                 |
| NOT(A)                 | 1100 0011 10              | (0011 0000 1110) = 0x30E                | 0011                 |
| AND(B,A)               | 1100 1101 00              | $(0011\ 0011\ 0100) = 0x334$            | 1100                 |

### Parte 2 - Arduino



Montagem do circuito - Arduino

#### Exercício 1 - Semáforo temporizado

```
1 int azul = 10;
 2 int verde = 11;
 3 int amarelo = 12;
 4 int vermelho = 13;
 5 void setup() {
      pinMode(azul, OUTPUT);
      pinMode(verde, OUTPUT);
 8
       pinMode(amarelo, OUTPUT);
      pinMode(vermelho, OUTPUT);
 10
 12 void loop() {
 13
       digitalWrite(vermelho, HIGH);
       digitalWrite(azul, HIGH);
 14
 15
       delay(1000);
       digitalWrite(azul, LOW);
 16
 17
       delay(1000);
       digitalWrite(azul, HIGH);
       delay(1000); // Wait for 1000 millisecond(s)
 19
 20
       digitalWrite(azul, LOW);
 21
       delay(1000);
 22
       digitalWrite(azul, HIGH);
       delay(1000); // Wait for 1000 millisecond(s)
 23
 24
       digitalWrite(azul, LOW);
 25
       delay(1000);
 26
      digitalWrite(vermelho, LOW);
 27
       digitalWrite(verde, HIGH);
      digitalWrite(azul, HIGH);
delay(1000); // Wait for 1000 millisecond(s)
 28
 29
       digitalWrite(azul, LOW);
 31
       delay(1000);
 32
       digitalWrite(azul, HIGH);
 33
       delay(1000); // Wait for 1000 millisecond(s)
       digitalWrite(azul, LOW);
 34
 35
       delay(1000);
 36
       digitalWrite(azul, HIGH);
 37
       delay(1000); // Wait for 1000 millisecond(s)
 38
       digitalWrite(azul, LOW);
 39
       delay(1000);
 40
       digitalWrite(azul, HIGH);
       delay(1000); // Wait for 1000 millisecond(s)
 41
       digitalWrite(azul, LOW);
 42
 43
       delay(1000);
 44
       digitalWrite(verde, LOW);
 45
       digitalWrite(amarelo, HIGH);
 46
       digitalWrite(azul, HIGH);
       delay(1000); // Wait for 1000 millisecond(s)
 47
       digitalWrite(azul, LOW);
 48
 49
       delay(1000);
 50
       digitalWrite(azul, HIGH);
       delay(1000); // Wait for 1000 millisecond(s)
 52
       digitalWrite(azul, LOW);
 53
       delay(1000);
 54
       digitalWrite(amarelo, LOW);
```

Código - Semáforo temporizado

<u>Link</u>

#### Exercício 2 - ULA

```
int azul = 10;
int verde = 11;
int amarelo = 12;
int vermelho = 13;
         int a = 0;
int b = 0;
int Op = 0;
void setup() {

11    Serial.begin(9600);

12    pinMode(azul, OUTPUT);

13    pinMode(varde, OUTPUT);

14    pinMode(amarelo, OUTPUT);

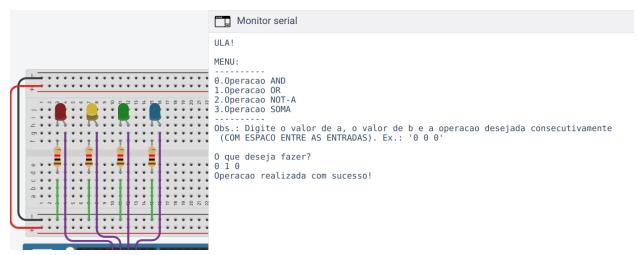
15    pinMode(vermelho, OUTPUT);

16    rint("ULA!\n");

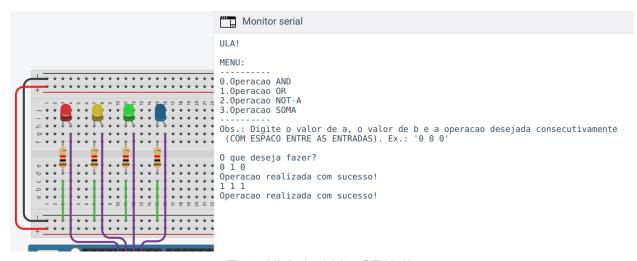
17    Serial.print("UMENU\\n");

18    Serial.print("NMENU\\n");

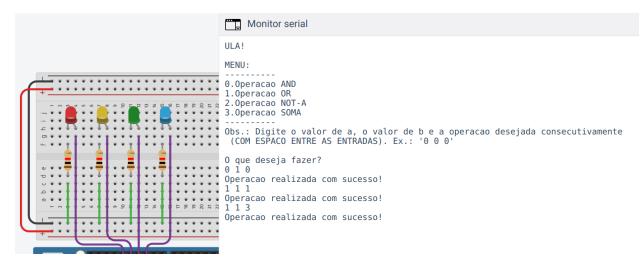
20    Serial.print("INMENU\\n");
                  Serial.print("ULA\\n");
Serial.print("\nHBHU\\n"-\\n0.0peracao AND\n1.0peracao OR\n2.0peracao NOT-A\n3.0peracao SMA\n-----");
Serial.print("\nObs:: Digite o valor de a, o valor de b e a operacao desejada consecutivamente (COM ESPACO ENTRE AS ENTRADAS). Ex.: '0 0 0'\n\n0 que deseja fazer?\n");
20
21 }
         void loop() {
   if(Serial.available() > 0){
      //Entrada serial de dados
      a = Serial.parseInt();
   b = Serial.parseInt();
   op = Serial.parseInt();
23
24
25
26
27
28
30
31
32
33
34
40
41
44
45
46
47
48
49
50
51
52
53
54
55
56
57
57
                               if((a==0 || a==1) && (b==0 || b==1) && (op==0 || op==1 || op==2 || op==3)){ //Verificacao para assegurar que os valores de entrada sao validos
digitalWrite(azul, LOW);//Correcao para o vai 1 da soma
if(a == 1){//Se o bit da entrada 'a' for 1 acende o led vermelho, caso contrario nao acende
digitalWrite(vermelho, HIGH);
                                          delay(1000);
}else{
    digitalWrite(vermelho, LOW);
    delay(1000);
                                         }
}
if(b == 1){//Se o bit da entrada 'b' for 1 acende o led amarelo, caso contrario nao acende
digitalWrite(amarelo, HIGH);
delay(1000);
}else{
digitalWrite(amarelo, LOW);
delay(1000);
};
                                         }
if(Op == 0){//Operacao AND
if(a == 1 && b == 1){
    digitalWrite(verde, HIGH);
    delay(1000);
                                                    }else{
                                                              se{
  digitalWrite(verde, LOW);
  delay(1000);
                                         delay(1000);
                                                     }else{
58
59
60
61
62
63
64
65
66
67
70
71
72
73
74
77
77
78
80
81
82
83
84
84
85
88
89
99
9
                                                   } elemylary,
} else if(Op == 2){//Operacao NOT(a)
    if(a == 0){
        dejatalWrite(verde, HIGH);
        delay(1000);
} else{
        digitalWrite(verde, LOW);
        delay(1000);
                                                              delay(1000);
                                      detay(lovo),
}
}else if(Op == 3){//Operacao SOMA
    if(a == 1 && b == 1){
        digitalWrite(verde, LOW);
        digitalWrite(azul, HIGH);
        delay(1000);
}else if(a == 0 && b == 0){
        digitalWrite(verde, LOW);
        delay(1000);
}else{
                                                              se{
digitalWrite(verde, HIGH);
digitalWrite(azul, LOW);
delay(1000);
                                          }
Serial.println("Operacao realizada com sucesso!");
                              }else(
Serial.println("ERRO: Formato de entrada invalido ou valor de alguma entrada invalido!");
                              }
```



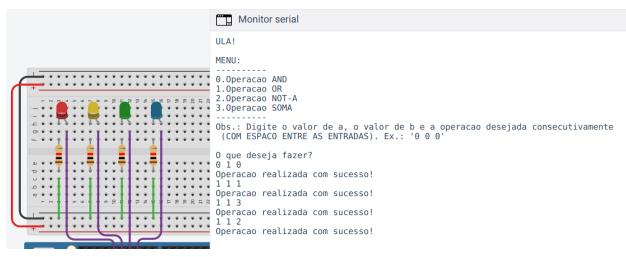
Teste ULA de 1 bit - AND(0,1)



Teste ULA de 1 bit - OR(1,1)



Teste ULA de 1 bit - SOMA(1,1)



Teste ULA de 1 bit - NOT(1)