

Analyzing the Shape of Data

Construction of Complexes for Persistent Homology

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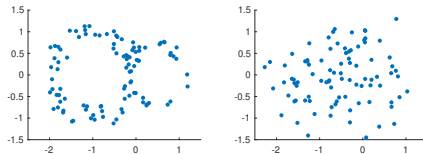
Advisors: Zhixu Su, Chengyuan Ma

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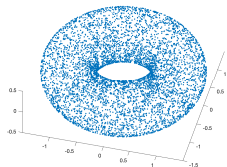


“Shape” of a data set

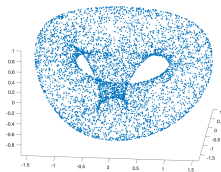
Here are two data sets with the same mean and covariance, but different “shapes”.



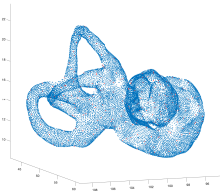
Examples of 3D data set sampled from surfaces:



torus



double torus



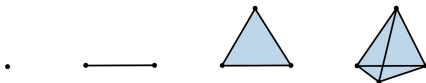
the inner ear

How to characterize the “shape” of a data set in terms of its **connectivity** and **hole structures**?

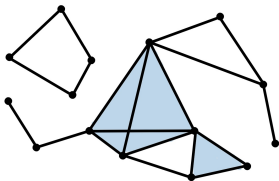


Homology of Simplicial complex

- In topology, the n -th **homology** characterizes the n -dim hole structure of a space.
- A **simplicial complex** is a collection of simplices. A **n -simplex** is the smallest convex set containing $n + 1$ points, $\sigma = [v_0, \dots, v_n]$.



- Simplicial homology** identifies non-trivial n -dim holes as n -cycles that are not boundary of any $n + 1$ simplices.



Betti number $b_n = \#$ of n -dim holes

$b_0 = 2$, 2 connected components

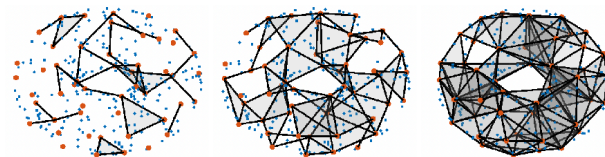
$b_1 = 3$, 3 loop (1-dim hole)

$b_2 = 1$, 1 void (2-dim hole)

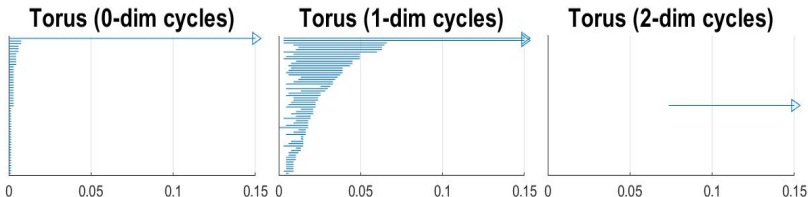


Persistent homology of filtered simplicial complex

Given a data set S , generate a sequence of simplicial complexes $\{\mathcal{K}_t\}$ that capture the topological features at different scales t . (generated by our Matlab implementation)



Then compute homology of the filtered simplicial complexes and identify the t interval in which each homology cycle persists. (computed by existing implementation JavaPlex)



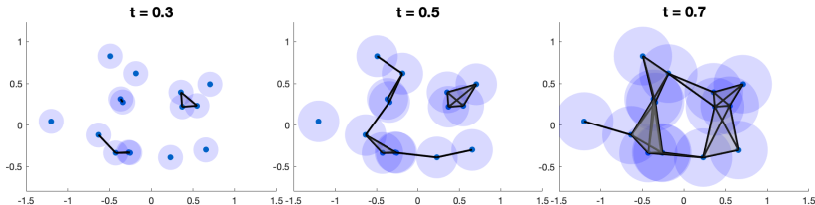
Vietoris-Rips complex

The **Vietoris-Rips complex** of a set of points S at scale t is

$$VR_t(S) = \{\sigma \subseteq S : d(v_i, v_j) \leq 2t \text{ for all } v_i, v_j \in \sigma\}.$$

- Two points are connected by a 1-simplex if their distance is $\leq 2t$.
- Three points are connected by a 2-simplex if the distance between every pair of points is $\leq 2t$.

Example. VR complexes of 15 points drawn from a 2D Gaussian distribution
(plot generated by our Matlab implementation)



Cons of VR cx: computationally expensive, it generates large number of simplices.



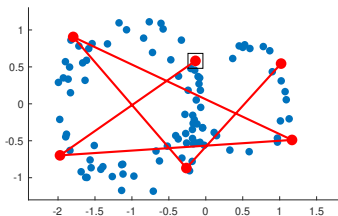
Witness Complex - landmark points

Motivation: Generate smaller number of simplices to speed up the construction of filtered simplicial complexes.

Idea: Choose a subset of data points, called **landmarks**, that can still capture the shape of the original data set.

Algorithm: Sequential MaxMin Method (Farthest-first traversal).

Example. 100 points synthesized from a figure 8 curve, generate 6 landmark points.



$\ell_1 = \text{RANDOMIZED-SELECTED-POINT}$

for $i = 2, \dots, k$ **do**

$$\ell_i = \operatorname{argmax}_{v \in S} \left(\operatorname{argmin}_{j \in \{1, \dots, i-1\}} d(v, \ell_j) \right)$$



Witness complex - construction

At each filtration value t , two landmarks ℓ_i and ℓ_j are connected by a 1-simplex if there exists a **witness** point w such that:

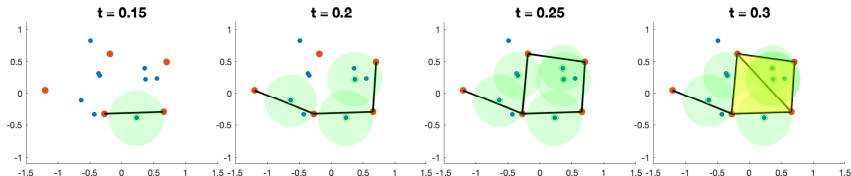
$$\max\{d(\ell_i, w), d(\ell_j, w)\} \leq t + \nu(w)$$

where $\nu(w)$ is the distance between w and its nearest landmark point.

Three landmarks are connected by a 2-simplex if every pair has been connected.

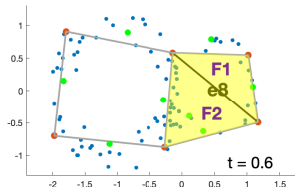
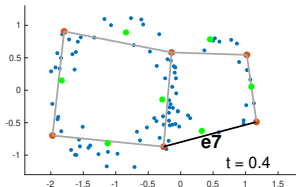
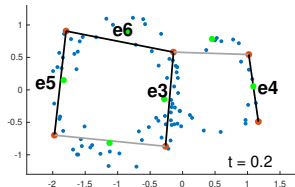
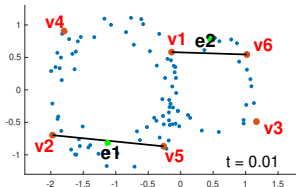
- When $t = 0$, two landmarks ℓ_i and ℓ_j are connected by a 1-simplex if there exists a witness point w such that $d(\ell_i, w) = d(\ell_j, w) = \nu(w)$.

Example. Witness complexes of 15 points and 5 landmarks, $t = 0.15, 0.2, 0.25, 0.3$.

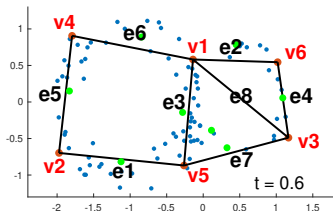


From witness complex to persistent homology

Example. 100 data points synthesized from a figure 8 curve,
6 landmarks points, $t = 0.01, 0.2, 0.4, 0.6$.



Boundary Matrix - 1-simplices



$$B(k,j) = 1 \text{ if } [v_k] \in \partial[e_j]$$

	e1	e2	e3	e4	e5	e6	e7	e8
v1		1	1			1		1
v2	1				1			
v3				1			1	1
v4					1	1		
v5	1		1				1	
v6		1		1				

For each column e_j , $L(e_j)$ = largest row index of nonzero entry in column e_j

```

for column  $j = 1$  to  $n$  do
  while  $i < j$  with  $L(i) = L(j)$  do
    add column  $i$  to column  $j$ 
  end while
end for
    
```

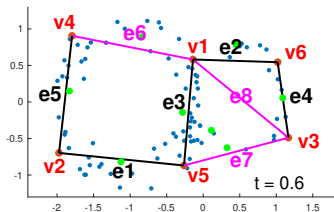
$$\partial[e_3] \xrightarrow{+\partial[e_1]} [v_1] + \cancel{[v_5]} + [v_2] + \cancel{[v_5]}$$

$$\partial[e_6] \xrightarrow{+\partial[e_5]} [v_1] + \cancel{[v_4]} + [v_2] + \cancel{[v_4]}$$

$$\partial[e_6] \xrightarrow{+\partial[e_5]} \cancel{[v_1]} + \cancel{[v_2]} + \cancel{[v_1]} + \cancel{[v_2]}$$



Boundary matrix - reduction and interpretation



Reduced boundary matrix:

	e1	e2	e3	e4	e5	e6	e7	e8
v1		1	1	1		0	0	0
v2	1		1		1	0	0	0
v3				1		0	0	0
v4					1	0	0	0
v5	1					0	0	0
v6		1				0	0	0

$L(e_j) = v_i \Leftrightarrow$ The occurrence of 1-simplex $[e_j]$ at time t kills the 0-dim cycle (connected component) of v_i by connecting it with an earlier point.

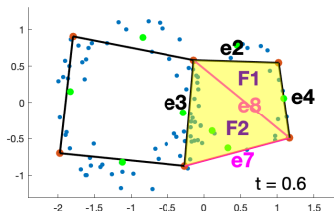
At $t = 0.01$, $[e_2]$ kills the component of $[v_6]$ by connecting $[v_6]$ with $[v_1]$.

$L(e_j) = \emptyset \Leftrightarrow$ The occurrence of 1-simplex $[e_j]$ at time t creates a 1-dim cycle.

At $t = 0.2$, $[e_6]$ creates the 1-dim cycle $[e_1] + [e_3] + [e_5] + [e_6]$ by closing up the loop.



Boundary matrix - 2-simplices



$$\begin{array}{c} e2 \\ e3 \\ e4 \\ e7 \\ e8 \end{array} \begin{array}{c|c} F1 & F2 \\ \hline \begin{pmatrix} 1 & \\ & 1 \\ 1 & \\ & 1 \\ 1 & 1 \end{pmatrix} \end{array} \rightarrow \begin{array}{c} e2 \\ e3 \\ e4 \\ e7 \\ e8 \end{array} \begin{array}{c|c} F1 & F2 \\ \hline \begin{pmatrix} 1 & 1 \\ & 1 \\ 1 & 1 \\ & 1 \\ 1 & \end{pmatrix} \end{array}$$

$L(F_j) = e_i$ and $L(e_i) = \emptyset \Leftrightarrow$ The occurrence of 2-simplex $[F_j]$ at time t kills the 1-dim cycle created by $[e_i]$ by covering the loop.

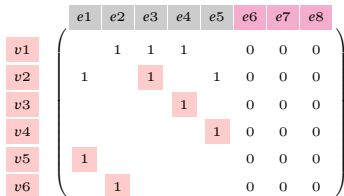
At $t = 0.6$, $[F1]$ kills the 1-dim cycle $[e_2] + [e_4] + [e_8]$ created by $[e_8]$.

At $t = 0.6$, $[F2]$ kills the 1-dim cycle $[e_2] + [e_3] + [e_4] + [e_7]$ created by $[e_7]$.

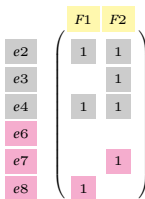
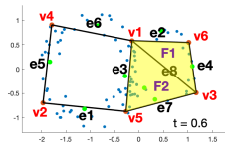
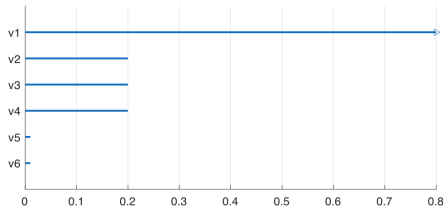


Persistent homology

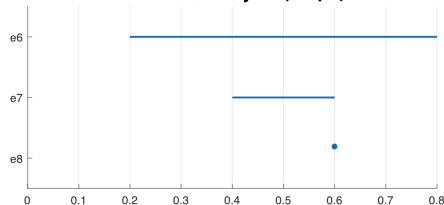
The “**barcode**” of each cycle illustrates the time interval $[t_b, t_d]$ from its birth to death. The longer it persists, the more significant the feature is.



0-dim cycle (connected components)



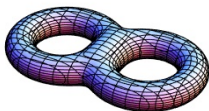
1-dim cycle (loops)



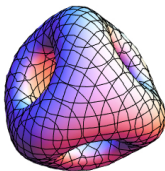
Experiment with 3D data synthesized from genus g surfaces

A **compact orientable surface of genus g** is a connected sum of g copies of tori.

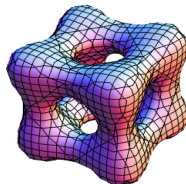
Betti numbers of genus g surface: $b_0 = 1$, $b_1 = 2g$, $b_2 = 1$



$g = 2$



$g = ?$



$g = ?$

- sample synthesized data points from implicit surface equations.
- generate and plot Witness complexes of the data points using our Matlab/Python implementation.
- used JavaPlex to compute persistent homology within "appropriate" maximum filtration value t .



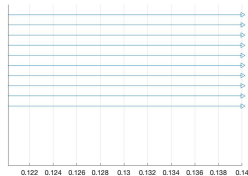
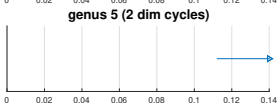
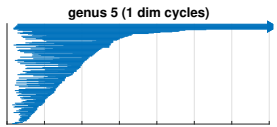
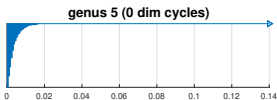
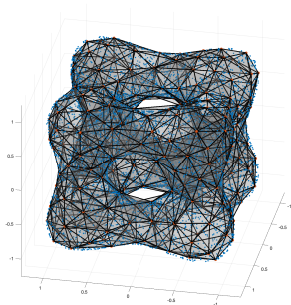
Witness complexes and persistent homology of 3D data points

Example. Witness complexes generated by 10000 data points sampled from

genus 5 surface: $3 + 8(x^4 + y^4 + z^4) = 8(x^2 + y^2 + z^2)$

with 300 landmark points generated by Sequential Max-Min.

We choose maximum filtration value around $t = 0.14$, observing that additional 2-cycles starts to form after $t = 0.15$.



References

- [1] N. Otter, M. Porter, U. Tillmann, P. Grindrod, H. Harrington, A Roadmap for the Computation of Persistent Homology, *EPJ Data Science*, (2017) 6:17.
- [2] H. Adams, A. Tausz, JavaPlex tutorial,
<https://www.math.colostate.edu/~adams/research/javaplex/tutorial.pdf>

