

DS-GA 3001.009

Modeling Time Series Data

Lab 1

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- **Time & Location**
 - 6:45 PM - 7:35 PM, Thursday, 60 FA C12
- **TA Office Hour**
 - 11:00 AM - 12:00 PM, Thursday, 60 FA 660
- **Lab Agenda**
 - Recitation / Lecture
 - Interactive coding work
- **Submission**
 - Submit your lab work before **6:45 PM at the following Thursday**

- Recap
 - Basic Time Series Models
 - Measures of Dependence
 - Stationary
 - Sample Statistics
- Exercise
- Programming
 - ACF Analysis
 - CCF Analysis

- **White Noise**

$$X_t \sim N(0, \sigma^2)$$

- **Moving Average**

$$v_t = \frac{1}{3} (w_{t-1} + w_t + w_{t+1})$$

- **Autoregressive**

$$x_t = x_{t-1} - 0.9x_{t-2} + w_t$$

- **Random Walk**

$$x_t = \delta + x_{t-1} + w_t$$

- **Autocovariance**

- Measures the **linear dependence** between two points on the same series

$$\gamma_x(s, t) = cov(x_s, x_t) = E[(x_s - \mu_s)(x_t - \mu_t)]$$

- **Autocorrelation (ACF)**

$$\rho(s, t) = \frac{\gamma(s, t)}{\sqrt{\gamma(s, s)\gamma(t, t)}}$$

- **Cross-covariance**

- Measures the linear dependence between two series

$$\gamma_{xy}(s, t) = cov(x_s, y_t) = E[(x_s - \mu_x)(y_t - \mu_y)]$$

- **Cross-correlation (CCF)**

- $$\rho_{xy}(s, t) = \frac{\gamma_{xy}(s, t)}{\sqrt{\gamma_x(s, s)\gamma_y(t, t)}}$$

• Strictly Stationary

- For any two collections of values: $\{x_{t_1}, x_{t_2}, \dots, x_{t_k}\} \{x_{t_1+h}, x_{t_2+h}, \dots, x_{t_k+h}\}$
- Their joint CDF match

$$Pr\{x_{t_1} \leq c_1, \dots, x_{t_k} \leq c_k\} = Pr\{x_{t_1+h} \leq c_1, \dots, x_{t_k+h} \leq c_k\}$$

• Weakly Stationary

- Mean is constant
- ACF only depends on lag and variance is finite.
- Let $h = s - t$,

$$\gamma(s, t) = cov(x_s, x_t) = cov(x_{t+h}, x_t) = cov(x_h, x_0) = \gamma(h)$$

$$\rho(s, t) = \frac{\gamma(t+h, t)}{\sqrt{\gamma(t+h, t+h)\gamma(t, t)}} = \frac{\gamma(h)}{\gamma(0)} = \rho(h)$$

- ACF is symmetric around the origin:

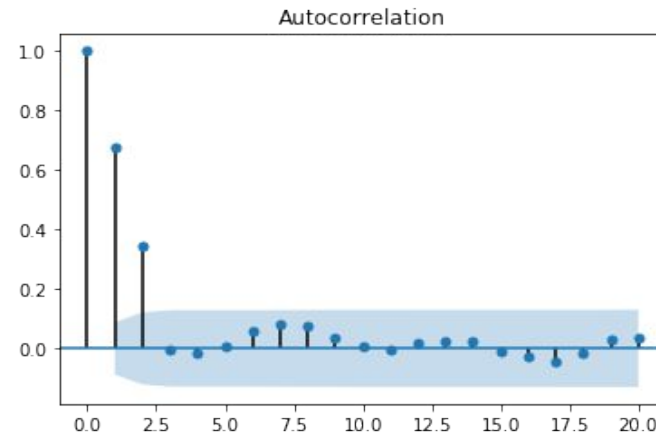
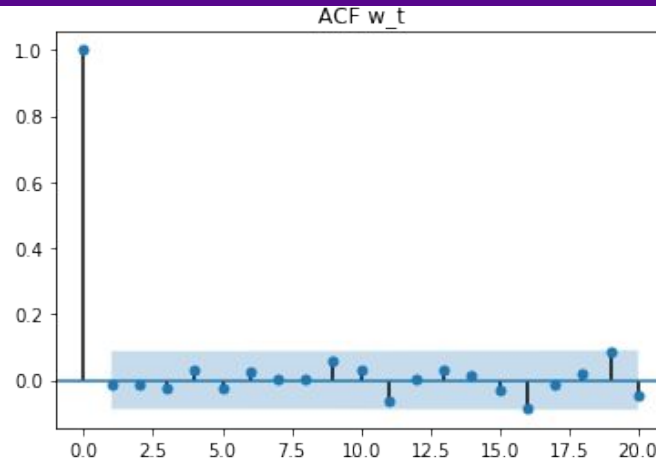
$$\rho(h) = \rho((t+h) - t) = cov(x_{t+h}, x_t) = cov(x_t, x_{t+h}) = \rho(t - (t+h)) = \rho(-h)$$

- ACF of a white noise**

$$w_t \sim N(0, \sigma^2)$$

- ACF of a Moving Average**

$$v_t = \frac{1}{3}(w_t, w_{t+1}, w_{t+2})$$



- Sample Mean**

$$\bar{x} = \frac{1}{n} \sum_{t=1}^n x_t \quad \text{var}(\bar{x}) = \frac{1}{n} \sum_{h=-n}^n \left(1 - \frac{|h|}{n}\right) \gamma_x(h)$$

- Sample Autocovariance / Cross-covariance**

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(x_t - \bar{x})$$

$$\hat{\gamma}_{xy}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (x_{t+h} - \bar{x})(y_t - \bar{y})$$

- Sample ACF / CCF**

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)} \quad \hat{\rho}_{xy}(h) = \frac{\hat{\gamma}_{xy}(h)}{\sqrt{\hat{\gamma}_x(0)\hat{\gamma}_y(0)}}$$

Suppose that series y_t is linearly determined by series x_t with a lag l : $y_t = Ax_{t-l} + w_t$. How can we determine the value of l ?

- By definition, cross-covariance is defined as $\gamma_{yx}(h) = \text{cov}(y_{t+h}, x_t) = \text{cov}(Ax_{t+h-l} + w_{t+h}, x_t) = \text{cov}(Ax_{t+h-l}, x_t) = A\gamma_x(h-l)$
- As a matter of fact, $\gamma_x(h-l)$ reaches its maximum when $h = l$.
- Since $\gamma_{yx}(h)$ is linearly depends on $\gamma_x(h-l)$, at $h = l$, $\gamma_{yx}(h)$ will also reaches at its maximum / minimum depends on A .
- We can determine the lag l by locating the maximum / minimum on the CCF plot.

Given a Moving Average process $x_t = w_{t-1} + 2w_t + w_{t+1}$, where w_t are independent with zero means and variance σ_w^2 , determine the autocorrelation function (ACF).

- First of all, we need to calculate the autovariance $\gamma(t+h, t) = cov[(w_{t+h-1} + 2w_{t+h} + w_{t+h+1}), (w_{t-1} + 2w_t + w_{t+1})]$.
- Note that because of the independent property of w_t , $cov(w_s, w_t) = \begin{cases} 0 & s \neq t \\ \sigma_w^2 & s = t \end{cases}$
- We can break the covariance of two summation into the sum of several bi-variate covariance using property of covariance:

$$cov(aX + bY, cW + dV) = ab * cov(X, W) + ad * cov(X, V) + bc * cov(Y, W) + bd * cov(Y, V)$$

- When $s = t$, we have

$$\begin{aligned}\gamma(t, t) &= \text{cov}[(w_{t-1} + 2w_t + w_{t+1}), (w_{t-1} + 2w_t + w_{t+1})] \\ &= \text{cov}(w_{t-1}, w_{t-1}) + \text{cov}(2w_t, 2w_t) + \text{cov}(w_{t+1}, w_{t+1}) \\ &= \sigma_w^2 + 4\sigma_w^2 + \sigma_w^2 \\ &= 6\sigma_w^2\end{aligned}$$

- When $s = t \pm 1$, we have

$$\begin{aligned}\gamma(t + 1, t) &= \text{cov}[(w_t + 2w_{t+1} + w_{t+2}), (w_{t-1} + 2w_t + w_{t+1})] \\ &= \text{cov}(w_t, 2w_t) + \text{cov}(2w_{t+1}, w_{t+1}) \\ &= 2\sigma_w^2 + 2\sigma_w^2 \\ &= 4\sigma_w^2\end{aligned}$$

- When $s = t \pm 2$, we have

$$\begin{aligned}\gamma(t + 2, t) &= \text{cov}[(w_{t+1} + 2w_{t+2} + w_{t+3}), (w_{t-1} + 2w_t + w_{t+1})] \\ &= \text{cov}(w_{t+1}, w_{t+1}) \\ &= \sigma_w^2\end{aligned}$$

- Therefore, our autocovariance is a function of lag $h = s - t$:

$$\gamma(h) = \begin{cases} 6\sigma_w^2 & h = 0 \\ 4\sigma_w^2 & h = \pm 1 \\ \sigma_w^2 & h = \pm 2 \end{cases}$$

- Using the definition of autocorrelation function (ACF), we have

$$\rho(h) = \frac{\gamma_x(h)}{\gamma_x(0)} = \begin{cases} 1 & h = 0 \\ \frac{2}{3} & h = \pm 1 \\ \frac{1}{6} & h = \pm 2 \end{cases}$$

For a Random Walk process $x_t = \delta + x_{t-1} + w_t$, where w_t is white noise with variance σ_w^2 ,

- (a) find the mean and autocovariance function of x_t
- (b) argue that x_t is not stationary
- (c) show $\rho_x(t-1, t) = \sqrt{\frac{t-1}{t}}$
- (d) suggest a transformation to make the series stationary

- First of all, this series can be re-written as $x_t = \delta t + \sum_{k=1}^t w_k$.
- $\mu_t = E(x_t) = E(\delta t) + \sum_{k=1}^t E(w_k) = \delta t$
- Remember that because of the independent property of w_t , $cov(w_s, w_t) =$

$$\begin{cases} 0 & s \neq t \\ \sigma_w^2 & s = t \end{cases}$$
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$$\begin{aligned} \gamma(s, t) &= cov(\delta s + \sum_{k=1}^s w_k, \delta t + \sum_{j=1}^t w_j) \\ &= cov(\sum_{k=1}^s w_k, \sum_{j=1}^t w_j) \\ &= cov(w_1 + w_2 + \dots + w_s, w_1 + w_2 + \dots + w_t) \\ &= \min(s, t) \sigma_w^2 \end{aligned}$$

- $\rho_x(t-1, t) = \frac{\gamma(t-1, t)}{\sqrt{\gamma(t-1, t-1)\gamma(t, t)}} = \frac{(t-1)\sigma_w^2}{\sqrt{(t-1)t\sigma_w^2}} = \sqrt{\frac{t-1}{t}}$. As t grows, the value of x_t linearly depends more on its previous turn x_{t-1} .
 - One transformation technique is differencing. $\hat{x}_t = x_t - x_{t-1} = \delta + w_t$.
 $E(\hat{x}_t) = \delta$
- $$\gamma(x_t, x_s) = cov(\delta + w_t, \delta + w_s) = cov(w_t, w_s) = \begin{cases} 0 & s \neq t \\ \sigma_w^2 & s = t \end{cases}$$

- **Github:**
 - <https://github.com/charlieblue17/timeseries2018>
- **Dependency**
 - Python 3.6
 - Numpy $\geq 1.13.3$
 - Pandas $\geq 0.20.3$
 - Statsmodels $\geq 0.8.0$
- **Due Date 02/01/2018 06:45 pm on NYU Classes**