



# DATA STRUCTURES

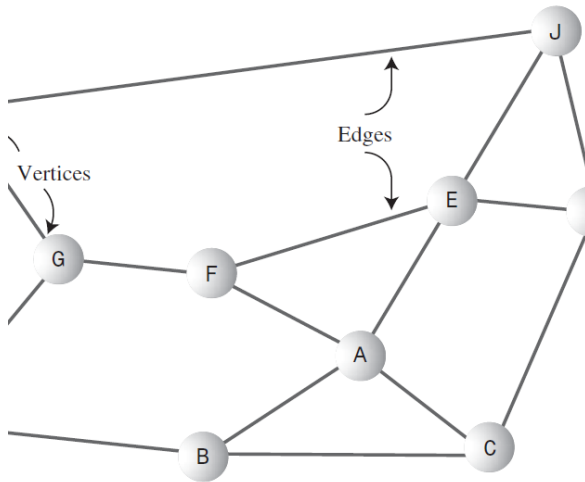
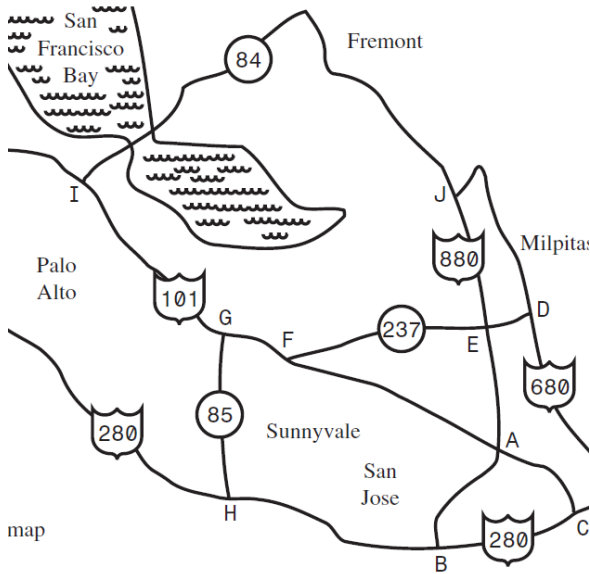
WENYE LI  
CUHK-SZ

# OUTLINE

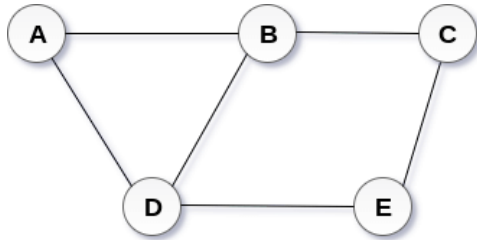
- Concepts
- Implementations
- Examples

# GRAPH

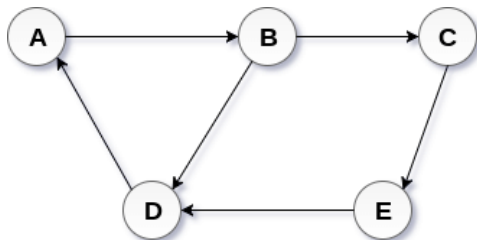
- A graph: a group of vertices and edges that are used to connect these vertices.
- A graph can be seen as a cyclic tree, where the vertices (nodes) maintain any complex relationship among them instead of having parent child relationship.
- Definition: A graph  $G$  can be defined as an ordered set  $G(V, E)$ 
  - $V(G)$  represents the set of vertices
  - $E(G)$  represents the set of edges which are used to connect these vertices



# UNDIRECTED VS DIRECTED



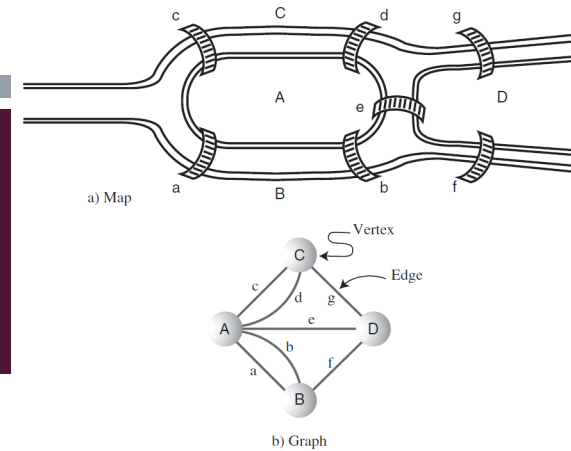
**Undirected Graph**



**Directed Graph**

- In an undirected graph, edges are not associated with the directions with them.
  - If an edge exists between vertex A and B then the vertices can be traversed from B to A as well as A to B.
- In a directed graph, edges form an ordered pair.
  - Edges represent a specific path from some vertex A to another vertex B.
  - Node A is called initial node while node B is called terminal node.

# TERMINOLOGY



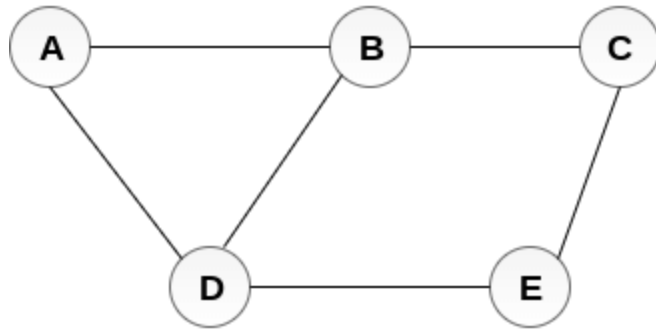
- Path: a sequence of edges connecting initial node  $V_0$  to terminal node  $V_N$ .
- Closed Path: A path where the initial node is same as terminal node, ie,  $V_0 = V_N$ .
- Simple Path: all the nodes of the path are distinct, with the exception  $V_0 = V_N$ .
- Closed Simple Path: a simple path with  $V_0 = V_N$ .
- Cycle: a path which has no repeated edges or vertices except the first and last vertices.
- Adjacent Nodes: two nodes  $u$  and  $v$  are connected via an edge  $e$ .
  - the nodes  $u$  and  $v$  are also called as neighbours.
- Degree of a Node: the number of edges that are connected with the node.
  - A node with degree 0 is called as isolated node.

# TERMINOLOGY

- Connected Graph: a graph in which a path exists between every two vertices  $(u, v)$  in  $V$ .
  - There are no isolated nodes in connected graph.
- Complete Graph: a graph in which there is an edge between each pair of vertices.
  - A complete graph contain  $n(n-1)/2$  edges where  $n$  is the number of nodes in the graph.
- Weighted Graph: each edge is assigned with some data such as length or weight.
  - The weight of an edge  $e$ ,  $w(e)$ , must be positive indicating the cost of traversing the edge.
- Digraph: each edge of the graph is associated with some direction.
  - The traversing can be done only in the specified direction.

# SEQUENTIAL REPRESENTATION

- Use adjacency matrix to store the mapping represented by vertices and edges.
- In adjacency matrix, the rows and columns are represented by the graph vertices.
- For a graph having  $n$  vertices, the adjacency matrix will have a dimension  $n \times n$ .



Undirected Graph

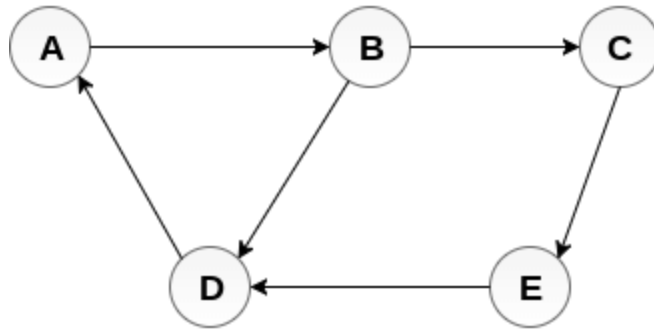
	A	B	C	D	E
A	0	1	0	1	0
B	1	0	1	1	0
C	0	1	0	0	1
D	1	1	0	0	1
E	0	0	1	1	0

Adjacency Matrix

## SEQUENTIAL REPRESENTATION

- Undirected: an entry  $M_{ij}$  in the adjacency matrix will be 1 if there exists an edge between  $V_i$  and  $V_j$ .





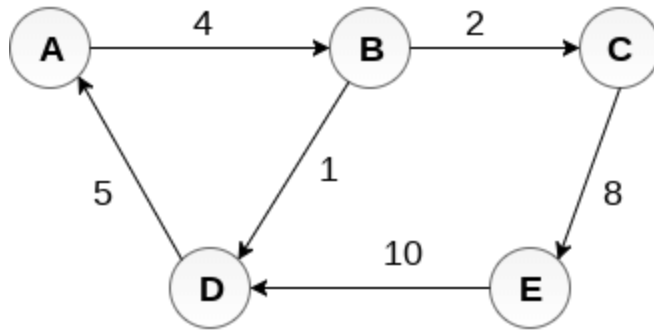
**Directed Graph**

	A	B	C	D	E
A	0	1	0	0	0
B	0	0	1	1	0
C	0	0	0	0	1
D	1	0	0	0	0
E	0	0	0	1	0

**Adjacency Matrix**

## SEQUENTIAL REPRESENTATION

- Directed: an entry  $A_{ij}$  in the adjacency matrix will be 1 if there exists an edge directly from  $V_i$  to  $V_j$ .



**Weighted Directed Graph**

	A	B	C	D	E
A	0	4	0	0	0
B	0	0	2	1	0
C	0	0	0	0	8
D	5	0	0	0	0
E	0	0	0	10	0

**Adjacency Matrix**

## SEQUENTIAL REPRESENTATION

- Weighted Directed: non-zero entries of the adjacency matrix are represented by the weight of respective edges.

```

1 class Vertex
2 {
3     public char label; // label (e.g. 'A')
4     public boolean wasVisited;
5     public Vertex(char lab) // constructor
6     {
7         label = lab;
8         wasVisited = false;
9     }
10 } // end class Vertex

```

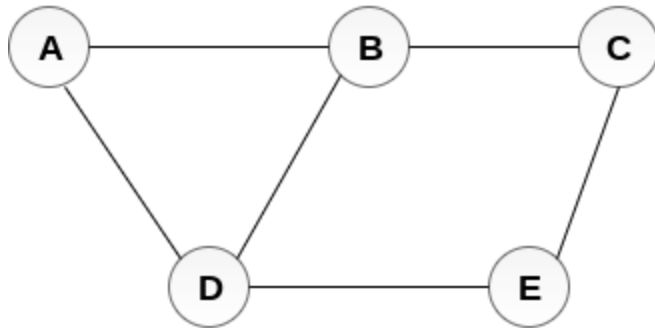
```

1 class Graph
2 {
3     private final int MAX_VERTS = 20;
4     private Vertex vertexList[]; // array of vertices
5     private int adjMat[][]; // adjacency matrix
6     private int nVerts; // current number of vertices
7     // -----
8     public Graph() // constructor
9     {
10         vertexList = new Vertex[MAX_VERTS];
11         // adjacency matrix
12         adjMat = new int[MAX_VERTS][MAX_VERTS];
13         622 CHAPTER 13 Graphs
14         nVerts = 0;
15         for(int j = 0; j < MAX_VERTS; j++) // set adjacency
16             for(int k = 0; k < MAX_VERTS; k++) // matrix to 0
17                 adjMat[j][k] = 0;
18     } // end constructor
19     // -----
20     public void addVertex(char lab) // argument is label
21     {
22         vertexList[nVerts++] = new Vertex(lab);
23     }
24     // -----
25     public void addEdge(int start, int end)
26     {
27         adjMat[start][end] = 1;
28         adjMat[end][start] = 1;
29     }
30     // -----
31     public void displayVertex(int v)
32     {
33         System.out.print(vertexList[v].label);
34     }
35     // -----
36 } // end class Graph

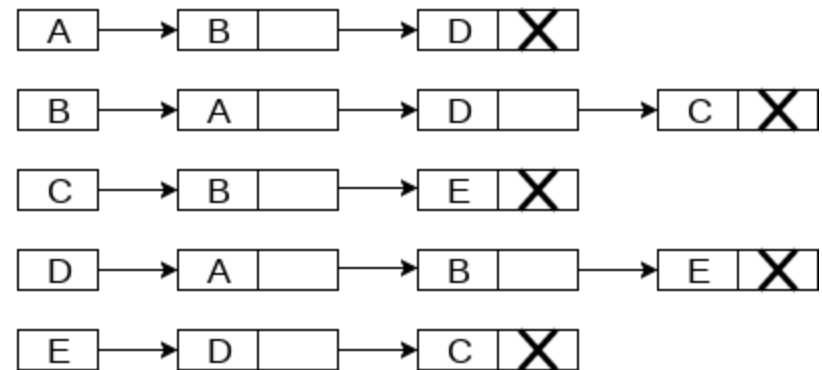
```

# LINKED REPRESENTATION

- An adjacency list is used to store the Graph into the computer's memory.
- An adjacency list is maintained for each node present in the graph which stores the node value and a pointer to the next adjacent node to the respective node.
- If all the adjacent nodes are traversed, then store the NULL in the pointer field of last node of the list.



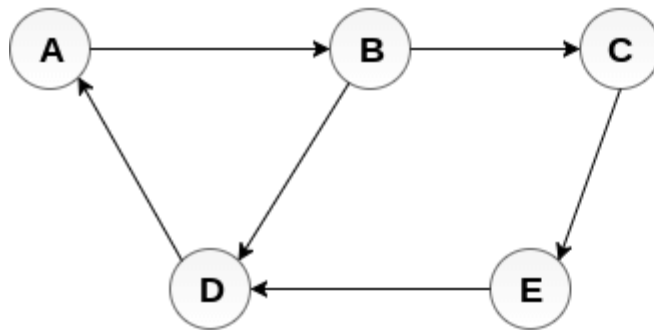
Undirected Graph



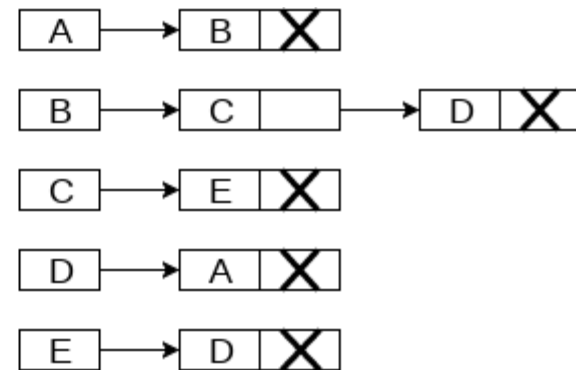
Adjacency List

## LINKED REPRESENTATION

- Undirected: The sum of the lengths of adjacency lists is equal to the twice of the number of edges.



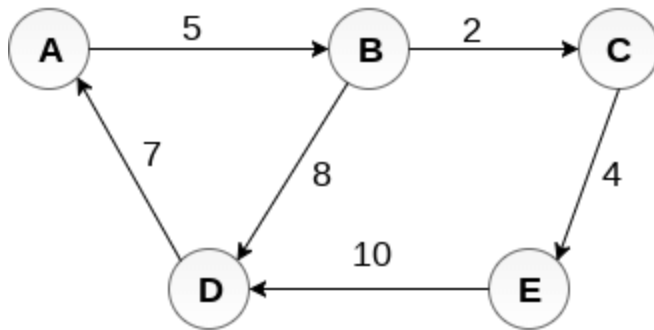
**Directed Graph**



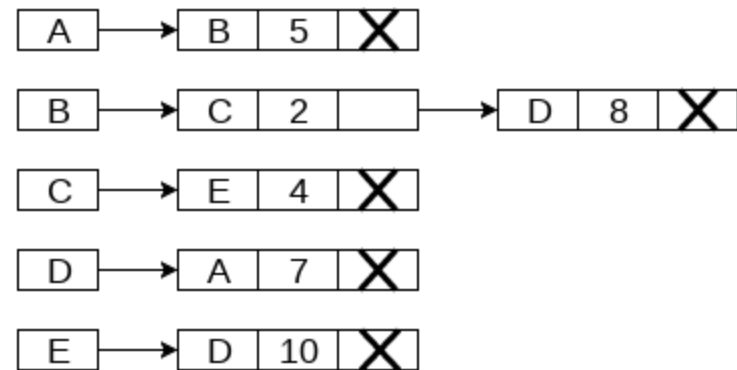
**Adjacency List**

## LINKED REPRESENTATION

- Directed: The sum of the lengths of adjacency lists is equal to the number of edges.



**Weighted Directed Graph**



**Adjacency List**

## LINKED REPRESENTATION

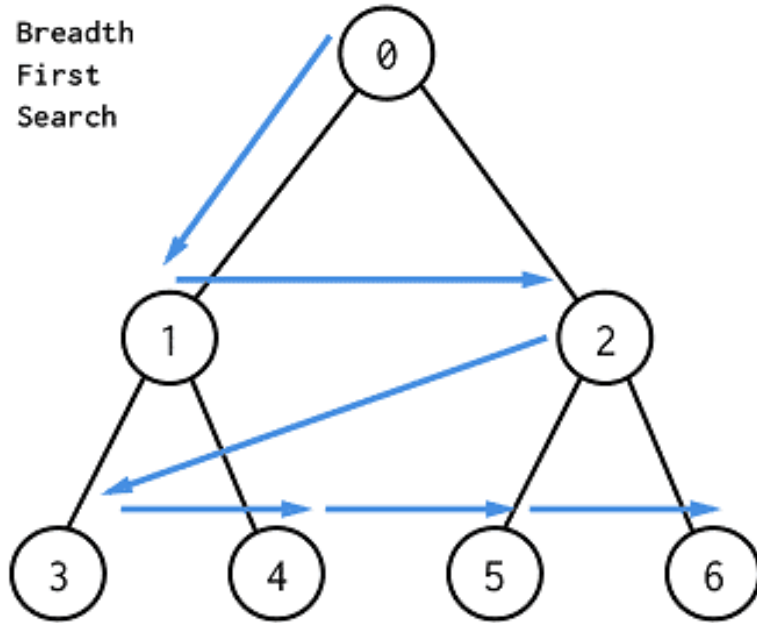
- Weighted Directed: each node contains an extra field, called the weight of the node.

# OUTLINE

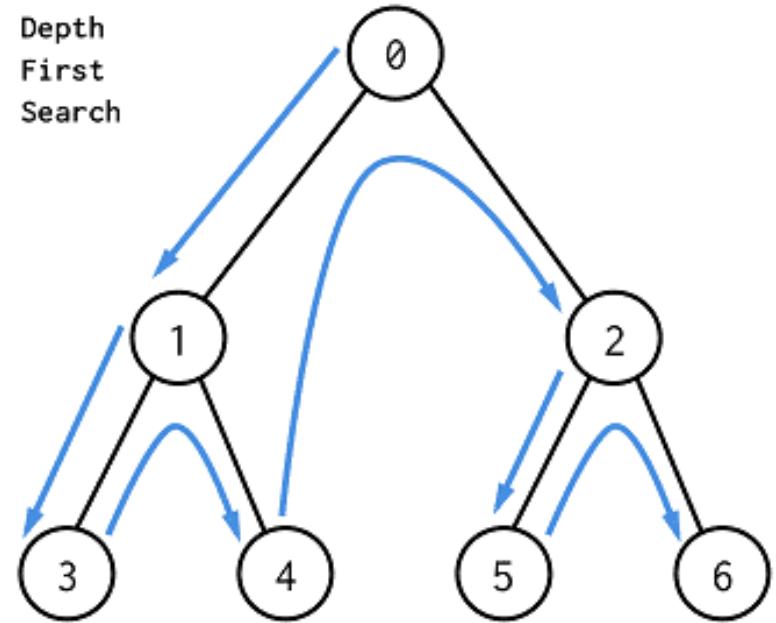
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Breadth  
First  
Search



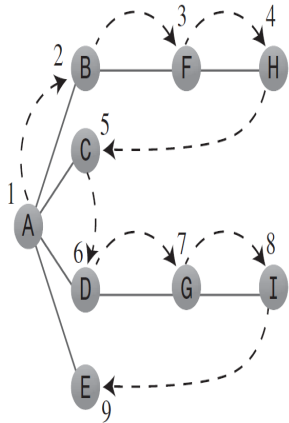
Depth  
First  
Search



# GRAPH TRAVERSAL

- Traversing the graph means examining all the nodes and vertices of the graph
- Two standard methods to traverse graphs
  - Breadth First Search
  - Depth First Search

# DEPTH FIRST SEARCH

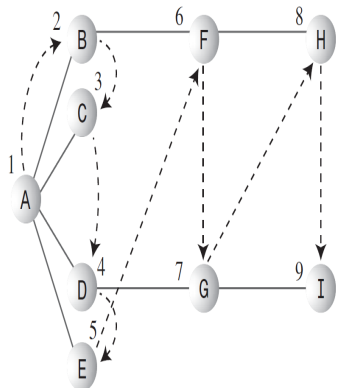


Event	Stack
Visit A	A
Visit B	AB
Visit F	ABF
Visit H	ABFH
Pop H	ABF
Pop F	AB
Pop B	A
Visit C	AC
Pop C	A
Visit D	AD
Visit G	ADG
Visit I	ADGI
Pop I	ADG
Pop G	AD
Pop D	A
Visit E	AE
Pop E	A
Pop A	
Done	

- Rule 1: If possible, visit an adjacent unvisited vertex, mark it, and push it on the stack.
- Rule2 : If you can't follow Rule 1, then, if possible, pop a vertex off the stack.
- Rule 3: If you can't follow Rule 1 or Rule 2, you're done.

```
1 // returns an unvisited vertex adjacent to v
2 public int getAdjUnvisitedVertex(int v)
3 {
4     for(int j = 0; j < nVerts; j++)
5         if(adjMat[v][j] == 1 && vertexList[j].wasVisited == false)
6             return j; // return first such vertex
7     return -1; // no such vertices
8 } // end getAdjUnvisitedVertex()
9
10 public void dfs() // depth-first search
11 {
12     // begin at vertex 0
13     vertexList[0].wasVisited = true; // mark it
14     displayVertex(0); // display it
15     theStack.push(0); // push it
16     while( !theStack.isEmpty() ) // until stack empty,
17     {
18         // get an unvisited vertex adjacent to stack top
19         int v = getAdjUnvisitedVertex( theStack.peek() );
20         if(v == -1) // if no such vertex,
21             theStack.pop(); // pop a new one
22         Searches 629
23         else // if it exists,
24         {
25             vertexList[v].wasVisited = true; // mark it
26             displayVertex(v); // display it
27             theStack.push(v); // push it
28         }
29     } // end while
30     // stack is empty, so we're done
31     for(int j = 0; j < nVerts; j++) // reset flags
32         vertexList[j].wasVisited = false;
33 } // end dfs
```

# BREADTH FIRST SEARCH

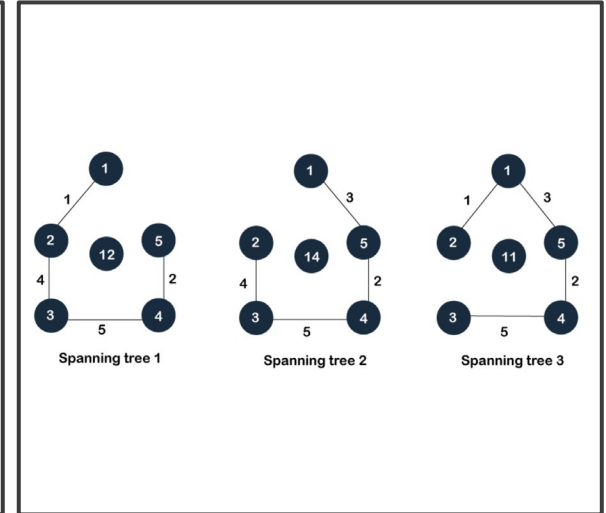
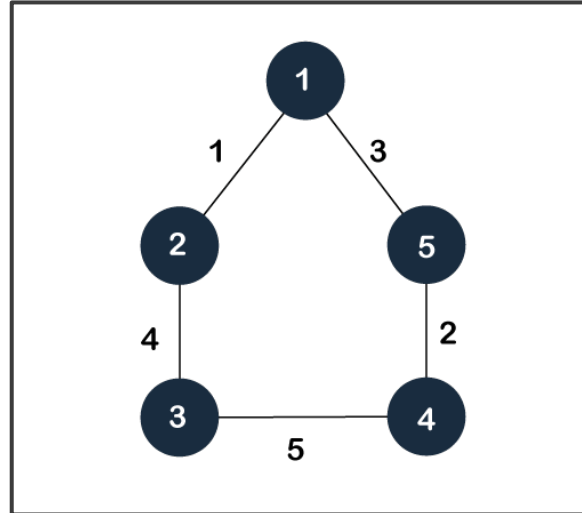


Event	Queue (Front to Rear)
Visit A	
Visit B	B
Visit C	BC
Visit D	BCD
Visit E	BCDE
Remove B	CDE
Visit F	CDEF
Remove C	DEF
Remove D	EF
Visit G	EFG
Remove E	FG
Remove F	G
Visit H	GH
Remove G	H
Visit I	HI
Remove H	I
Remove I	
Done	

- Rule 1: Visit the next unvisited vertex (if there is one) that's adjacent to the current vertex, mark it, and insert it into the queue.
- Rule 2: If you can't carry out Rule 1 because there are no more unvisited vertices, remove a vertex from the queue (if possible) and make it the current vertex.
- Rule 3: If you can't carry out Rule 2 because the queue is empty, you're done.

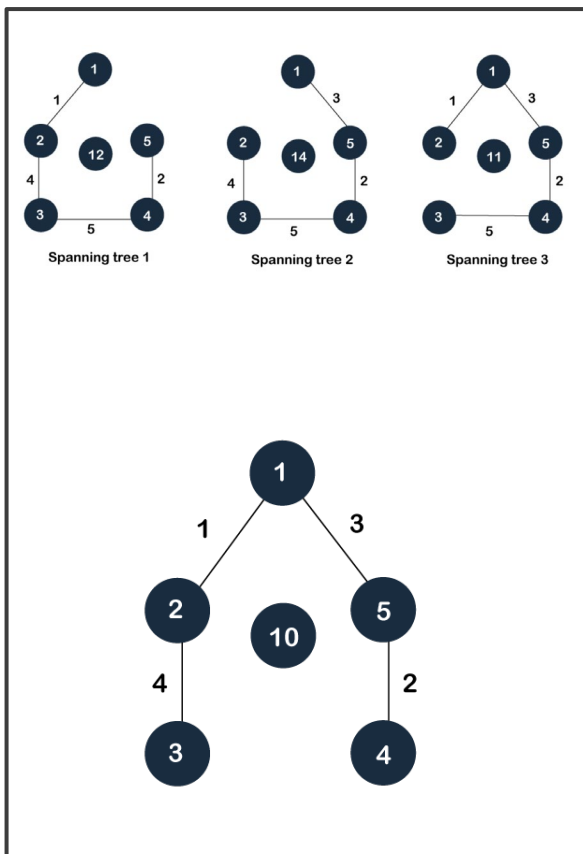
```
1 public void bfs() // breadth-first search
2 {
3     // begin at vertex 0
4     vertexList[0].wasVisited = true; // mark it
5     displayVertex(0); // display it
6     theQueue.insert(0); // insert at tail
7     int v2;
8     while( !theQueue.isEmpty() ) // until queue empty,
9     {
10         int v1 = theQueue.remove(); // remove vertex at head
11         // until it has no unvisited neighbors
12         while( (v2 = getAdjUnvisitedVertex(v1)) != -1 )
13         {
14             // get one,
15             vertexList[v2].wasVisited = true; // mark it
16             displayVertex(v2); // display it
17             theQueue.insert(v2); // insert it
18         } // end while(unvisited neighbors)
19     } // end while(queue not empty)
20     // queue is empty, so we're done
21     for(int j = 0; j < nVerts; j++) // reset flags
22         vertexList[j].wasVisited = false;
23 } // end bfs()
```

# SPANNING TREE



- Idea: for any connected set of vertices and edges, remove any extra edges
- For a graph  $G=(V, E)$ , its spanning tree
  - have the same number of vertices as the graph.
  - the edges = the number of vertices in the graph - 1.
- Represent the spanning tree by  $G' = (V', E')$ 
  - $V' = V$
  - $E' \subseteq E$
  - $|E'| = |V| - 1$

# MINIMUM SPANNING TREE



- the total edge weight of the spanning tree 1 is 12
- the total edge weight of the spanning tree 2 is 14
- the total edge weight of the spanning tree 3 is 11

- Minimum spanning tree: the spanning tree whose sum of edge weights is minimum.
  - The minimum spanning tree has a weight of 10.



## MINIMUM SPANNING TREE

- MST can be obtained with a slight modification of depth-first search, or breadth-first search.

```
1 public void mst() // minimum spanning tree (depth first)
2 {
3     // start at 0
4     vertexList[0].wasVisited = true; // mark it
5     theStack.push(0); // push it
6     while( !theStack.isEmpty() ) // until stack empty
7     {
8         // get stack top
9         int currentVertex = theStack.peek();
10        // get next unvisited neighbor
11        int v = getAdjUnvisitedVertex(currentVertex);
12        if(v == -1) // if no more neighbors
13            theStack.pop(); // pop it away
14        else // got a neighbor
15        {
16            vertexList[v].wasVisited = true; // mark it
17            theStack.push(v); // push it
18            // display edge
19            displayVertex(currentVertex); // from currentV
20            displayVertex(v); // to v
21            System.out.print(" ");
22        }
23    } // end while(stack not empty)
24    // stack is empty, so we're done
25    for(int j = 0; j < nVerts; j++) // reset flags
26        vertexList[j].wasVisited = false;
27 } // end tree
```



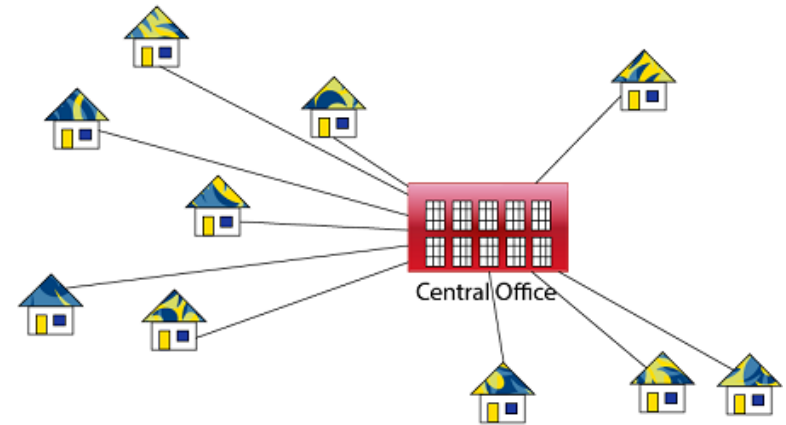
# PROPERTIES OF SPANNING TREE

- A connected graph can contain more than one spanning tree.
- All the possible spanning trees that can be created from the given graph  $G$  have the same number of vertices.
- The number of edges in the spanning tree would be equal to the number of vertices in the given graph minus 1.
- The spanning tree does not contain any cycle.
- The spanning tree cannot be disconnected.
- If two or three edges have the same edge weight, then there would be more than two minimum spanning trees.
- If each edge has a distinct weight, then there will be only one or unique minimum spanning tree.
- A complete undirected graph can have  $n^{n-2}$  number of spanning trees where  $n$  is the number of vertices.
  - If  $n=5$ , the number of spanning trees would be equal to 125.
- Each connected and undirected graph contains at least one spanning tree.
- The disconnected graph does not contain any spanning tree.



Central Office

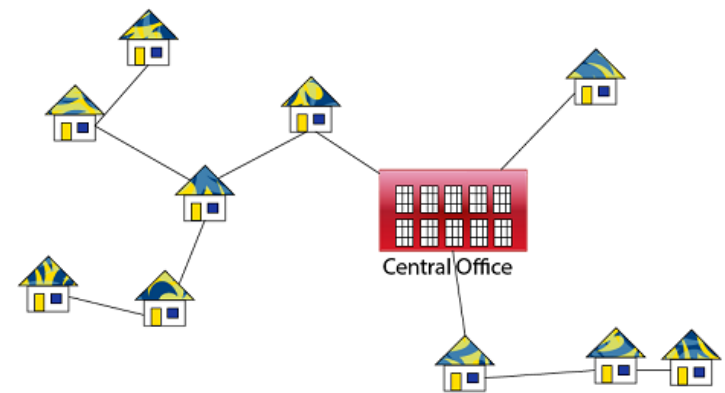
Wiring : Naive Approach



Expensive!

## APPLICATIONS OF MINIMUM SPANNING TREE

Wiring : Better Approach

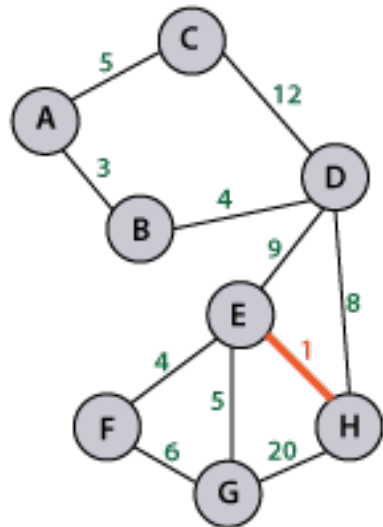


Minimize the total length of wire connecting the customers

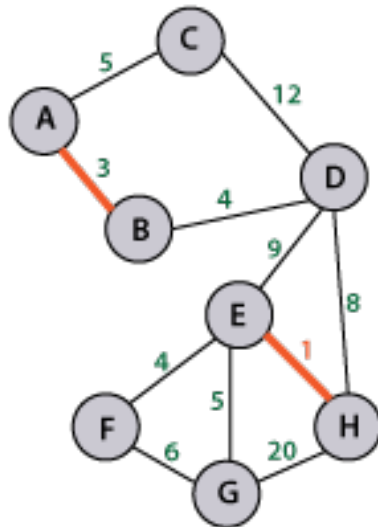
# KRUSKAL'S ALGORITHM

- A greedy algorithm to construct an MST for a connected weighted graph
  - put the smallest weight edge without forming a cycle in the MST constructed so far
- Algorithm
  - Take connected and undirected graph from the user.
  - We then sort all the edges from low weight to high weight.
  - Take the edge with the lowest weight and add it to the spanning tree. If adding the edge created a cycle, then reject this edge.
  - Keep adding edges until we reach all vertices.
- The complexity of the algorithm is  $O(|E| \log |E|) = O(|E| \log |V|)$ .

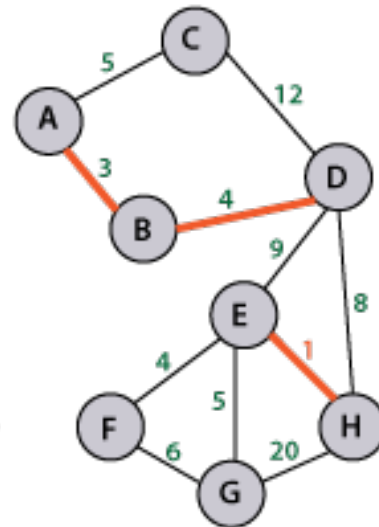
# Kruskal Algorithm



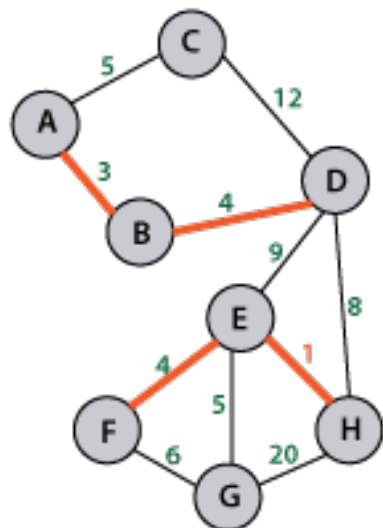
(1)



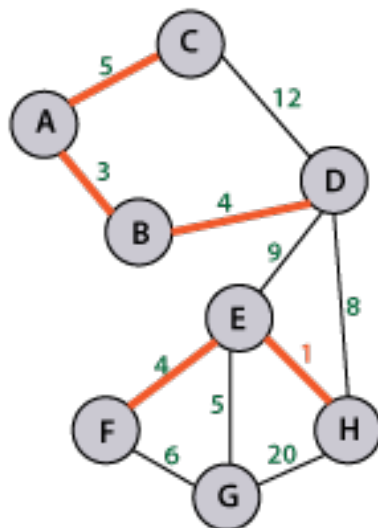
(2)



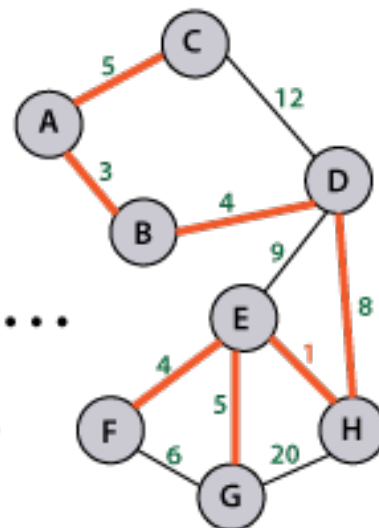
(3)



(4)



(5)

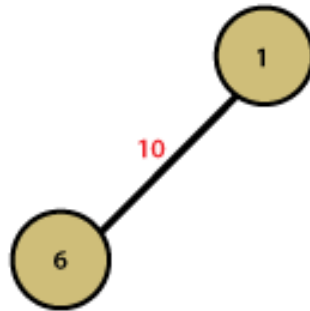
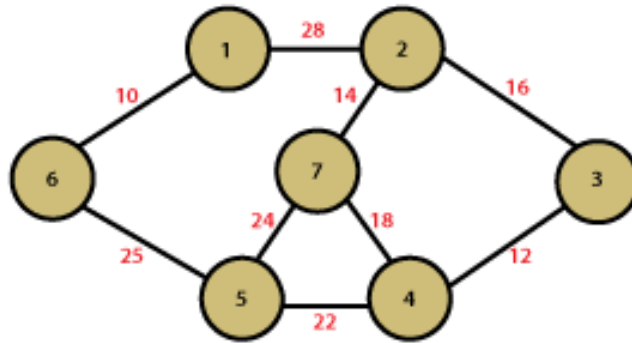


(N)

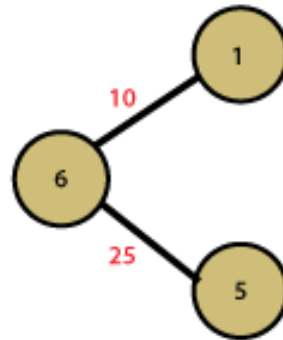
# PRIM'S ALGORITHM

- A greedy algorithm: starts with an empty spanning tree, and maintains two vertices sets:
  - vertices already included in MST; vertices not yet included.
  - At every step, it considers all edges and picks the minimum weight edge. After picking the edge, it moves the other endpoint of edge to set containing MST.
- Algorithm
  - For all vertices, set its key-value to infinite. Set the first vertex's key value to 0.
  - Repeat the following steps until setOfMST contains all vertices.
    - Select vertex  $u$  that is not in setOfMST and having a minimum key-value. Add vertex  $u$  to setOfMST.
    - Change the key-value of all adjacent vertices of  $u$ : for an adjacent vertex  $v$ , if the weight of edge  $u-v$  is less than the previous key value of  $v$ , change the key value as the weight of  $u-v$ .

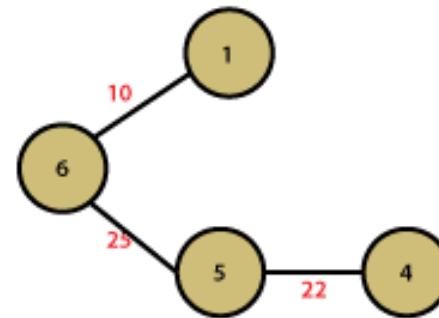
## Prim's Algorithm



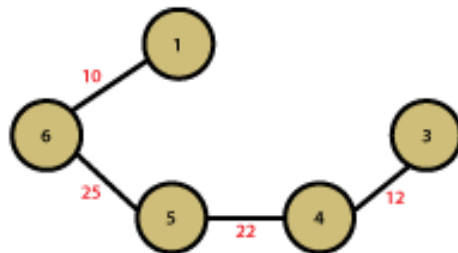
Step 1



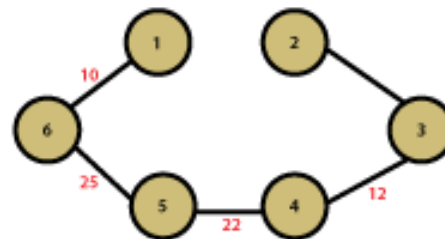
Step 2



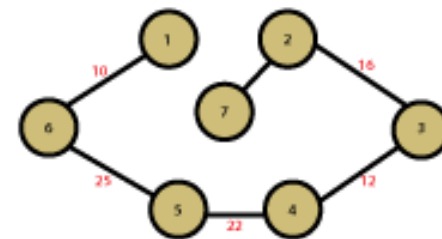
Step 3



Step 4



Step 5

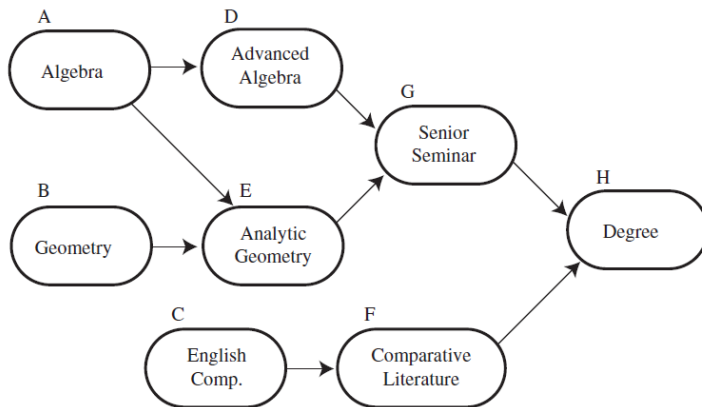


Step 6

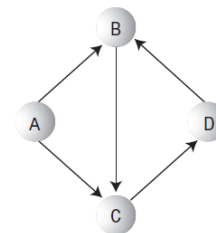
# OUTLINE

- Concepts
- Implementations
- Examples

# TOPOLOGICAL SORTING WITH DIRECTED ACYCLIC GRAPHS



- Arrange events in a specific order
- Repeat until all vertices are gone
  - Find a vertex that has no successors.
  - Delete this vertex from the graph, and insert its label at the beginning of a list.
- Topological-sort cannot handle a graph with cycles.





```

1  public int noSuccessors() // returns vert with no successors
2  {
3      // (or -1 if no such verts)
4      boolean isEdge; // edge from row to column in adjMat
5      for(int row = 0; row < nVerts; row++) // for each vertex,
6      {
7          isEdge = false; // check edges
8          for(int col = 0; col < nVerts; col++)
9          {
10             if( adjMat[row][col] > 0 ) // if edge to
11             {
12                 // another,
13                 isEdge = true;
14                 break; // this vertex
15             } // has a successor
16             } // try another
17             if( !isEdge ) // if no edges,
18                 return row; // has no successors
19         }
20         return -1; // no such vertex
21     } // end noSuccessors()
22
23     public void topo() // topological sort
24     {
25         int orig_nVerts = nVerts; // remember how many verts
26         while(nVerts > 0) // while vertices remain,
27         {
28             // get a vertex with no successors, or -1
29             int currentVertex = noSuccessors();
30             if(currentVertex == -1) // must be a cycle
31             {
32                 System.out.println("ERROR: Graph has cycles");
33                 return;
34             }
35             // insert vertex label in sorted array (start at end)
36             sortedArray[nVerts - 1] = vertexList[currentVertex].label;
37             deleteVertex(currentVertex); // delete vertex
38         } // end while
39         // vertices all gone; display sortedArray
40         System.out.print("Topologically sorted order: ");
41         for(int j = 0; j < orig_nVerts; j++)
42             System.out.print( sortedArray[j] );
43         System.out.println("");
44     } // end topo

```

# SUMMARY

- Graphs consist of vertices connected by edges.
- Graphs can represent many real-world entities.
- Search algorithms allow to visit each vertex in a graph in a systematic way.
- Two main search algorithms: depth-first search (DFS) and breadth-first search (BFS).
- Depth-first search can be based on a stack; breadth-first search can be based on a queue.
- An MST consists of the minimum number of edges necessary to connect all vertices.
- For unweighted graph, depth-first search algorithm yields its MST.
- For weighted graph, Kruskal's algorithm and Prim's algorithm yield its MST.