Stochastic Differential Equations Introduction

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Outline

- 1 Background on Shrimpy
- 2 Brownian Motion
- 3 Stochastic Calculus
- 4 Modeling
- 5 Nondimensionalization

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The Problem

Southern German water routes have had several drastic population changes concerning gammarids[2].

Much of this is due to canal construction.

Native Species:

Gammarus pulex (Gp)

Invasive Species:

Dikerogammarus villosus (Dv)
Dikerogammarus haemobaphes (Dh)
Dikerogammarus bispinosus (Db)
Echinogammarus berilloni (Eb)

Killer Shrimp



http://www.arkive.org/killer-shrimp/dikerogammarus-villosus/image-G143154.html

Killer Shrimp



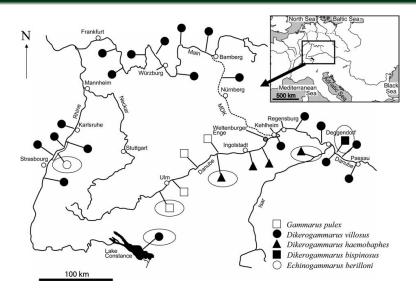
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(Kinzler, 2008)

Time Line

The time to prominence.

Years	Species
<1976	<i>Gp</i> native
1976-1994	Dh invades
1992-1995	Dv invades, Dh declines
>1995	All but <i>Dv</i> coexist separate from <i>Dv</i>

Terminology

Intraguild Predation

Mutual Predation

Mutual Interference

Intraspecific Predation

Cannibalism

[3]

Kinzler, 2008 Study

Isolated pairs of specimens in a controlled environment

- One freshly moulted (prey)
- One predator
- Total of 279 experiments
- Grouped by age, sex, and species

Results

- Found Dv to be clear strongest predator
- Found Dh to have highest cannibalism rate

Basic Goals

Determine long term population trends!

Does *Dv* totally dominate in the end?

Which species survive?

Is there an equilibrium?

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Markov Process

(Markov Process) is a stochastic process with the following properties:

- 1 The number of possible outcomes or states is finite
- ② The outcome at any stage depends only on the outcome of the previous stage.
- 3 The probabilities are constant over time.

Brownian Motion

Definition

(**Brownian Motion**) is a stochastic process that models random continuous motion. The stochastic process $B = \{B(t), t \ge 0\}$ is standard Brownian Motion if the following holds:

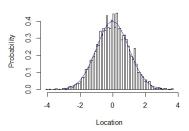
- B has independent increments.
- ② For $0 \le s < t$,

$$B(t) - B(s) \sim N(0, t - s).$$

- 3 The paths of B are continuous with probability 1.
- B(0) = 0

Random Walk Random Walk [1] Recorded final step of 5000 Brownian Motions over [0,1] We expect the probability to be N(0,1).

Distribution of Location at time T



$$\bar{x} = 0.01931075$$
, $s^2 = 0.993332$, $p - value = 0.1692423$
CI: $\mu \in (-0.0082225, 0.04684401)$

Scaling a Brownian Motion

If x(t) is a Brownian Motion then $\frac{x(\lambda t)}{\sqrt{\lambda}}$ is a Brownian motion.

$$P\left(a \le \frac{x(\lambda t)}{\sqrt{\lambda}} - \frac{x(\lambda s)}{\sqrt{\lambda}} \le b\right)$$

$$= P\left(a\sqrt{\lambda} \le x(\lambda t) - x(\lambda s) \le b\sqrt{\lambda}\right),$$

$$= \frac{1}{\sqrt{2\pi(\lambda t - \lambda s)}} \int_{a\sqrt{\lambda}}^{b\sqrt{\lambda}} e^{\frac{-x^2}{2}(\lambda t - \lambda s)} dx,$$

$$= \frac{1}{\sqrt{2\pi(t - s)}} \int_{a}^{b} e^{\frac{-u^2}{t - s}} du.$$

Riemann-Stieltjes

(Riemann-Stieltjes Integral):

$$\int_a^b f(g)dg = \lim_{n o \infty} \sum_{i=1}^N f(g(t_i)) \cdot (g(t_{i+1})) - g(t_i)$$

The main motivation for the Riemann-Stieltjes Integral comes from the concept of Cumulative Distribution Function (CDF) of a random variable.

Weiner Integral

Weiner Integral

$$\int_a^b f(t)dW(t)$$
 $1[t_{i+1},t_i](t) = egin{cases} 1 & ext{if } t_{i+1} \leq t < t_i \ 0 & ext{otherwise} \end{cases}$

Modeling

Itô's Formula is used in Itô Calculus to find the differential of a time-dependent function of a stochastic process.

Differential Form

$$\partial x_t = \left(\frac{\partial x}{\partial t} + \frac{1}{2}\left(\frac{\partial^2 x}{\partial B^2}\right)\right) \cdot dt + \frac{\partial x}{\partial B} \cdot dB$$

Integral Form

$$F(t,B(t)) - F(a,B(a)) = \int_{a}^{t} \frac{\partial F}{\partial s} + \frac{1}{2} \frac{\partial^{2} F}{\partial B^{2}} ds + \int_{a}^{t} \frac{\partial F}{\partial B} dB$$

Modeling

Itô's Formula

Let
$$F = tB^2$$

$$\frac{dF}{dt} = B^2$$

$$\frac{dF}{dB} = 2t + B$$

$$\frac{d^2F}{dB^2} = 2t$$

$$tB^{2}(t) - aB^{2}(a) = \int_{a}^{t} B^{s} ds + \int_{a}^{t} 2sBdB + \int_{a}^{t} \frac{1}{2}2sds$$
$$= \int_{a}^{b} B^{2} + sds + \int_{a}^{t} 2sBdB$$
OR

$$tB^{2}(t) - aB^{2}(a) = \int_{a}^{t} B^{s} ds + \int_{a}^{t} 2sBdBt + \frac{1}{2}t^{2} - \frac{1}{2}a^{2}$$

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Overview

The governing Equations:

$$\dot{a} = L_1 a + N_1(a, g),$$

 $\dot{g} = L_2 g + N_2(a, g).$

Calculating Stochastic Integrals

As an example consider the integral

$$Z_t = \int_0^t B(s) dB(s)$$

This integral can be calculated as

$$\int_0^t B(s)dB(s) = \frac{1}{2}(B^2(t) - B^2(0)) - \frac{1}{2}$$

$$x \rightarrow \bar{X}\xi,$$
 $t \rightarrow \bar{T}s.$

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Nondimensionalization

The initial model is:

$$\frac{dx}{ds} = rx\left(1 - \frac{x}{k}\right) - \alpha xy,$$

$$\frac{dy}{ds} = \rho y\left(1 - \frac{y}{l}\right) - \beta xy.$$

Let

$$x \to A\hat{x}(s)$$

 $y \to B\hat{y}(s)$
 $t \to \tau \cdot s$

When you substitute and group terms the system becomes nondimensionalized.

Modeling

$$\frac{dx}{ds} = rx(1-x) - \alpha xy,$$

$$\frac{dy}{ds} = y(1-y) - \beta xy.$$

Heun's Method

- Heun's method is a numerical procedure for approximating ordinary differential equations with a given initial value.
- First you calculate the intermediate value \tilde{y}_{i+1} and then the final approximation y_{i+1} at the next generation point.

$$\tilde{y}_{i+1} = y_i + \Delta t \ f(t_i, y_i)$$

$$y_{i+1} = y_i + \frac{\Delta t}{2} \left[f(y_i, t_i) + f(\tilde{y}_{i+1}, t_{i+1}) \right]$$

Acknowledgments

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