Stochastic Differential Equations Introduction

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- 1 Background on Shrimpy
- 2 Brownian Motion
- 3 Modeling
- 4 Nondimensionalization

Background on Shrimpy

- Background on Shrimpy The Problem
- - Fundamental Concepts
- Nondimensionalization

The Problem

Southern German water routes have had several drastic population changes concerning gammarids (Kinzler, 2008) [2].

Much of this is due to canal construction.

Native Species:

Gammarus pulex (Gp)

Invasive Species:

Dikerogammarus villosus (Dv) Dikerogammarus haemobaphes (Dh) Dikerogammarus bispinosus (Db) Echinogammarus berilloni (Eb)

Killer Shrimp



http://www.arkive.org/killer-shrimp/dikerogammarus-villosus/image-G143154.html

Killer Shrimp



http://www.arkive.org/killer-shrimp/dikerogammarus-villosus/image-G143155.html

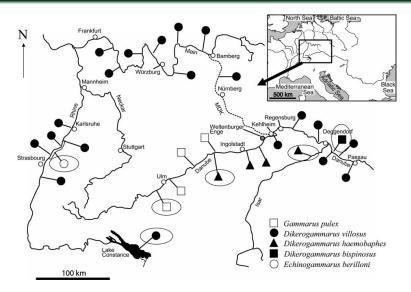


Killer Shrimp



http://www.arkive.org/killer-shrimp/dikerogammarus-villosus/image-G143156.html

Background on Shrimpy 00000000



(Kinzler, 2008)

Years	Species
<1976	<i>Gp</i> native
1976-1994	Dh invades
1992-1995	Dv invades, Dh declines
>1995	All but Dv coexist separate from Dv

Isolated pairs of specimens in a controlled environment

- One freshly moulted (prey)
- One predator
- Total of 279 experiments
- Grouped by age, sex, and species *

Results

- Found Dv to be clear strongest predator
- Found *Dh* to have highest cannibalism rate
- * Intraguild: predation between different species; Intraspecific: predation within species (cannibalism) [3]



Determine long term population trends!

Does *Dv* totally dominate in the end?

Which species survive?

Is there an equilibrium?

- 2 Brownian Motion
 - Fundamental Concepts
 - Integration
 - Itô's Formula
- Nondimensionalization

Markov Process

(Markov Process) is a stochastic process with the following properties:

- 1 The number of possible outcomes or states is finite
- ② The outcome at any stage depends only on the outcome of the previous stage.
- The probabilities are constant over time.

Brownian Motion

Definition

(**Brownian Motion**) is a stochastic process that models random continuous motion. The stochastic process $B = \{B(t), t \ge 0\}$ is standard Brownian Motion if the following holds:

- B has independent increments.
- ② For $0 \le s < t$,

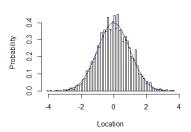
$$B(t) - B(s) \sim N(0, t - s).$$

- \odot The paths of B are continuous with probability 1.
- B(0) = 0

Monte Carlo Simulation - Brownian Motion

Recorded final step of 5000 Brownian Motions over [0,1] We expect the distribution to be N(0,1).

Distribution of Location at time T



$$\bar{x} = 0.019311$$
, $s^2 = 0.9933$, $t - test \ p - value = 0.16924$

CI: $\mu \in (-0.00822, 0.046844)$

Brownian Motion

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Scaling a Brownian Motion

If x(t) is a Brownian Motion then $\frac{x(\lambda t)}{\sqrt{\lambda}}$ is a Brownian motion.

$$P\left(a \le \frac{x(\lambda t)}{\sqrt{\lambda}} - \frac{x(\lambda s)}{\sqrt{\lambda}} \le b\right)$$

$$= P\left(a\sqrt{\lambda} \le x(\lambda t) - x(\lambda s) \le b\sqrt{\lambda}\right),$$

$$= \frac{1}{\sqrt{2\pi(\lambda t - \lambda s)}} \int_{a\sqrt{\lambda}}^{b\sqrt{\lambda}} e^{\frac{-x^2}{2}(\lambda t - \lambda s)} dx,$$

$$= \frac{1}{\sqrt{2\pi(t - s)}} \int_{a}^{b} e^{\frac{-u^2}{t - s}} du.$$

Wiener Process

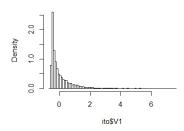
A standard Wiener process (also called Brownian Motion) is a stochastic process $\{W_t\}_{t\geq 0}$, which has properties mutually consistent with those of Brownian motion.

Wiener Integral For a pair $(W_t, f(t))$ of a Wiener Process W_t , a random process f(t), we define the Itô integral

$$I(f) = \int_0^\infty f(t)dW_t$$

Recorded approximations of 5000 Itô Integrals for $\int_0^{1.5} WdW$ WHAT DO WE EXPECT???? I DON'T KNOW.

Histogram of ito\$V1



$$\bar{x} = 0.000555, \quad s^2 = 0.4925248$$

Itô's Formula is used in Itô Calculus to find the differential of a time-dependent function of a stochastic process.

Differential Form

$$dx_{t} = \left(\frac{\partial x}{\partial t} + \frac{1}{2}\left(\frac{\partial^{2} x}{\partial B^{2}}\right)\right) \cdot dt + \frac{\partial x}{\partial B} \cdot dB$$

Integral Form

$$F(t,B(t)) - F(a,B(a)) = \int_{a}^{t} \frac{\partial F}{\partial s} + \frac{1}{2} \frac{\partial^{2} F}{\partial B^{2}} ds + \int_{a}^{t} \frac{\partial F}{\partial B} dB$$

Itô's Formula

Let
$$F = tR^2$$

$$\frac{dF}{dt} = B^2$$

$$\frac{dF}{dB} = 2t + B$$

$$\frac{d^2F}{dB^2} = 2t$$

$$tB^{2}(t) - aB^{2}(a) = \int_{a}^{t} B^{2} ds + \int_{a}^{t} 2sB dB + \int_{a}^{t} \frac{1}{2}2s ds$$
$$= \int_{a}^{b} (B^{2} + s) ds + \int_{a}^{t} 2sB dB$$
OR

$$tB^2(t) - aB^2(a) = \int_a^t B^2 \ ds + \int_a^t 2sB \ dB + \frac{1}{2}t^2 - \frac{1}{2}a^2$$

Modeling

- - Fundamental Concepts
- Modeling
- Nondimensionalization

Shrimp Model

Our model is

$$\frac{dx}{dt} = rx^{2} \left(1 - \frac{x}{K} \right) - \alpha xy - \frac{x^{2} \gamma_{o}}{x + D},$$

$$\frac{dy}{dt} = \rho y^{2} \left(1 - \frac{y}{L} \right) - \beta xy - \frac{y^{2} \delta_{o}}{y + R},$$

Modeling

where x is the population of Dv and y is the population of Dh, with parameters $[r, K, \alpha, \gamma_0, D, \rho, L, \beta, \delta_0, R]$.

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The initial model is

$$\frac{dx}{dt} = rx^{2} \left(1 - \frac{x}{K} \right) - \alpha xy,$$

$$\frac{dy}{dt} = \rho y^{2} \left(1 - \frac{y}{L} \right) - \beta xy.$$

Let

$$x \to A\hat{x}(s)$$

 $y \to B\hat{y}(s)$
 $t \to \tau \cdot s$

When you substitute and group terms the system becomes nondimensionalized.

After making the following substitutions:

$$A = K,$$

$$B = L,$$

$$\tau = \frac{1}{\rho}.$$

The nondimensionalized system is:

$$\frac{dx}{dt} = rx(1-x) - \alpha xy,$$

$$\frac{dy}{dt} = y(1-y) - \beta xy.$$

Heun's Method

- Heun's method is a numerical procedure for approximating ordinary differential equations with a given initial value.
- First you calculate the intermediate value \tilde{y}_{i+1} and then the final approximation y_{i+1} at the next generation point.

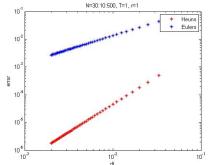
$$\tilde{y}_{i+1} = y_i + \Delta t \ f(t_i, y_i)$$

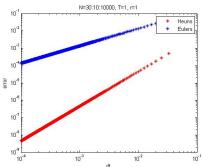
$$y_{i+1} = y_i + \frac{\Delta t}{2} \left[f(y_i, t_i) + f(\tilde{y}_{i+1}, t_{i+1}) \right]$$

For the DE y' = ry on [0, T],

Heun's:
$$\tilde{y}_{i+1} = y_i + \Delta t \ f(t_i, y_i)$$

Euler's: $\tilde{y}_{i+1} = y_i + \Delta t \ f(r, y_i)$





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