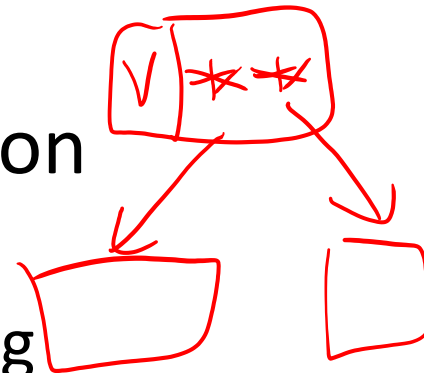


Announcements

Announcements

- HW3 has just been updated- problem 3b removed, Extra Credit updated accordingly
- If you have not yet signed up for an oral exam slot, do that today! (Check BB for link)
- Exam questions have been posted, due on Sunday
 - Please look soon so you can clarify anything needed!



- Note on use of “advanced” data structures

$h(1) \rightarrow h(3)$
 $[1, 3, 1, 5, 6, 1, 3]$
 $\{1, 3, \dots\}$

$[1, 3, 5, \dots]$

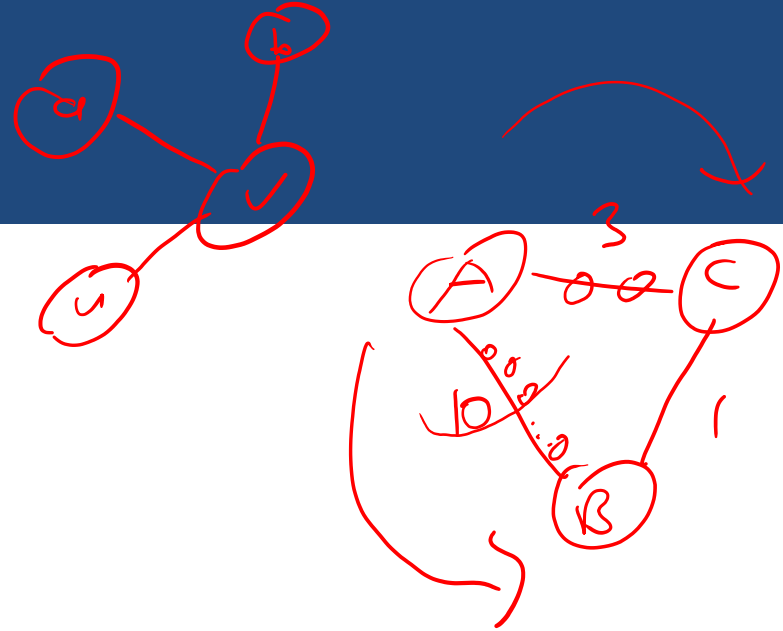
sets, hash maps

Announcements

- Exam procedure:
 - Join your examiner's "room" on BB Collaborate
 - Join at the start of your timeblock 3/6 block
 - The examiner will create a "breakout room" for the person being examined
 - Process: 15 minutes/problem
 - 4 • Present your solution (3-4 minutes). You can refer to your submitted solution.
 - 4 • Answer questions (~ 5 minutes)
 - 4 • Propose a solution for a modified version of the problem (6-7 minutes)
 - You can leave after your exam is over
 - Have camera on!

Graphs

Dijkstra's Algorithm



for all $u \in V$:
 $\text{dist}(u) = \infty$
 $\text{prev}(u) = \text{nil}$
 $\text{dist}(s) = 0$

$H = \text{makequeue}(V)$ (using dist -values as keys)

while H is not empty:

$u = \text{deletemin}(H)$

for all edges $(u, v) \in E$:

if $\text{dist}(v) > \text{dist}(u) + l(u, v)$:

$\text{dist}(v) = \text{dist}(u) + l(u, v)$

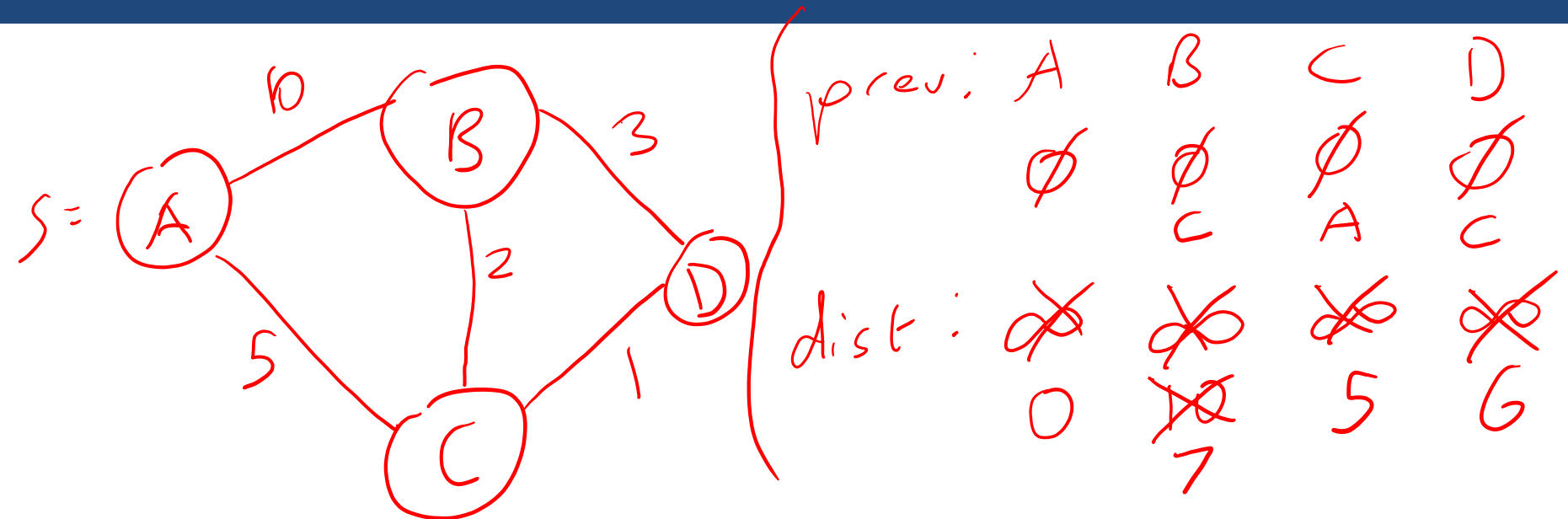
$\text{prev}(v) = u$

$\text{decreasekey}(H, v)$

if v is still in H :

Dijkstra's Algorithm

$A \rightarrow \cancel{E} \rightarrow B$



H: ~~A: 0~~

~~B: ~~10~~ 7~~

~~C: ~~5~~~~

~~D: ~~6~~~~

In-Class Exercise

$N = \# \text{ nodes}$
 $M = \# \text{ edges}$

- Suppose we implement the priority queue using an array ($A[i] =$ key value of node i)
- What is the running time?

```
for all  $u \in V$ :
     $\text{dist}(u) = \infty$ 
     $\text{prev}(u) = \text{nil}$ 
 $\text{dist}(s) = 0$ 
```

$O(N)$

$\rightarrow O(N)$

$O(N) + O(M) +$
 $O(N^2) = O(N^2)$
 $(M \leq N^2)$

$\rightarrow H = \text{makequeue}(V)$ (using dist-values as keys)
 while H is not empty:

$\rightarrow u = \text{deletemin}(H) \rightarrow O(N) \cdot N = O(N^2)$

for all edges $(u, v) \in E$:

if $\text{dist}(v) > \text{dist}(u) + l(u, v)$: $O(M)$

$\text{dist}(v) = \text{dist}(u) + l(u, v)$ $O(M)$

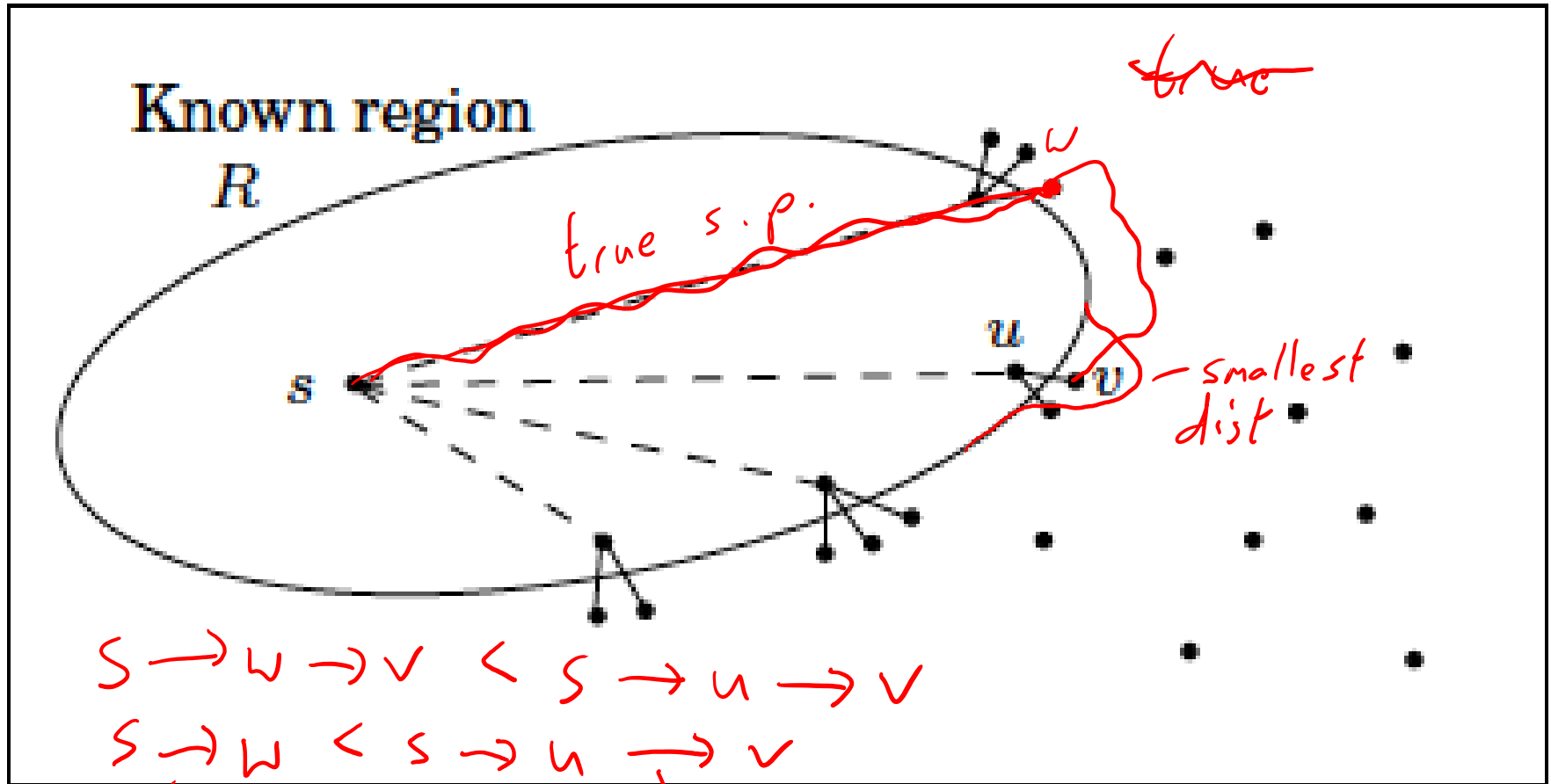
$\text{prev}(v) = u$ $O(M)$

$\rightarrow \text{decreasekey}(H, v)$ $O(N) \cdot O(M)$

$O(M) \left\{$

Another Way to Think About This

$$s \rightarrow w < s \rightarrow u \rightarrow v$$



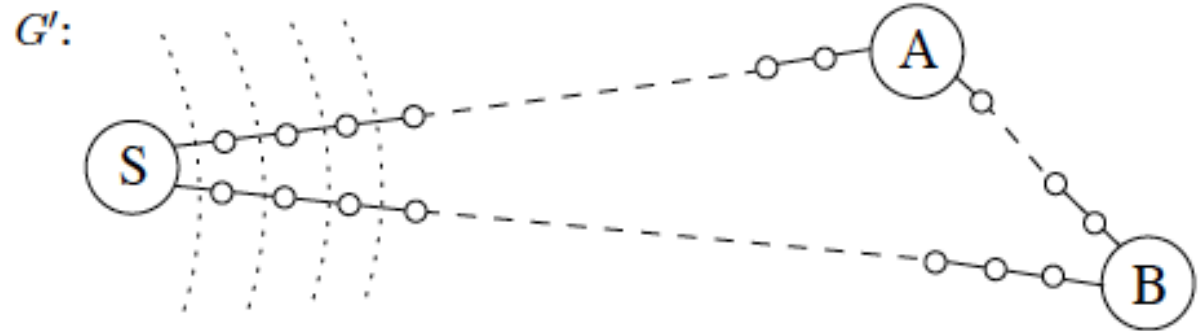
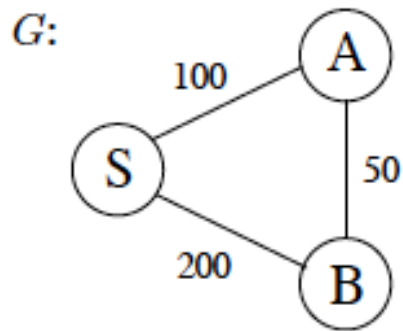
$$s \rightarrow w \rightarrow v < s \rightarrow u \rightarrow v$$

$$s \rightarrow w < s \rightarrow u \rightarrow v$$

\downarrow
 $\text{dist}(w)$

\downarrow
 $\text{dist}(v)$

Dijkstra's Algorithm




Dijkstra's Algorithm: Running Time

- Dijkstra's algorithm uses a priority queue:
 - Insert
 - Decrease-key
 - Delete-min
- Suppose we implement as an array, where $A[i]$ holds key of node i
- What is the running time for delete-min?
 $O(N)$
- For decrease-key? $O(1)$

Dijkstra's Algorithm: Running Time

```
for all  $u \in V$ :  
     $\text{dist}(u) = \infty$   
     $\text{prev}(u) = \text{nil}$   
 $\text{dist}(s) = 0$ 
```

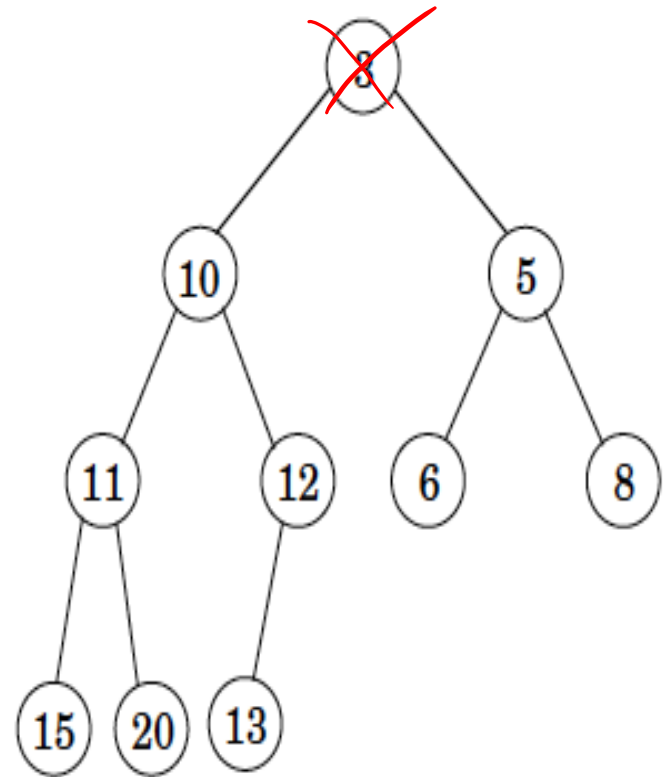


```
 $H = \text{makequeue}(V)$  (using  $\text{dist}$ -values as keys)  
while  $H$  is not empty:  
     $u = \text{deletemin}(H)$   
    for all edges  $(u, v) \in E$ :  
        if  $\text{dist}(v) > \text{dist}(u) + l(u, v)$ :  
             $\text{dist}(v) = \text{dist}(u) + l(u, v)$   
             $\text{prev}(v) = u$   
             $\text{decreasekey}(H, v)$ 
```

Binary heaps

- A binary heap is a complete binary tree
 - Every level must be full before a new level is started
 - Fill from L → R
- The key-value of any node is less than or equal to those of its children
- Which element has the smallest value? *root*

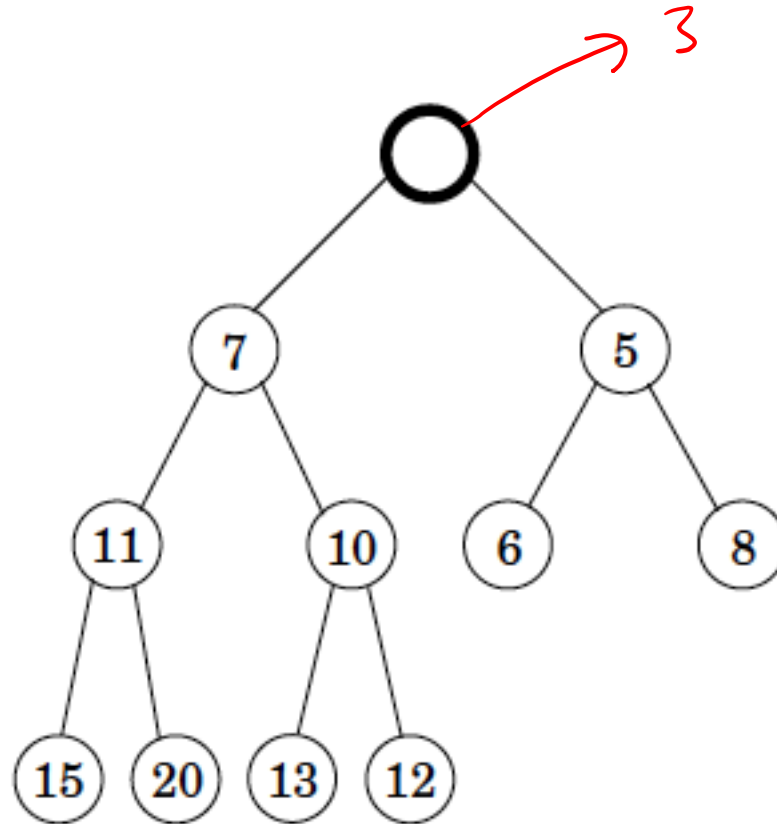
min-heap



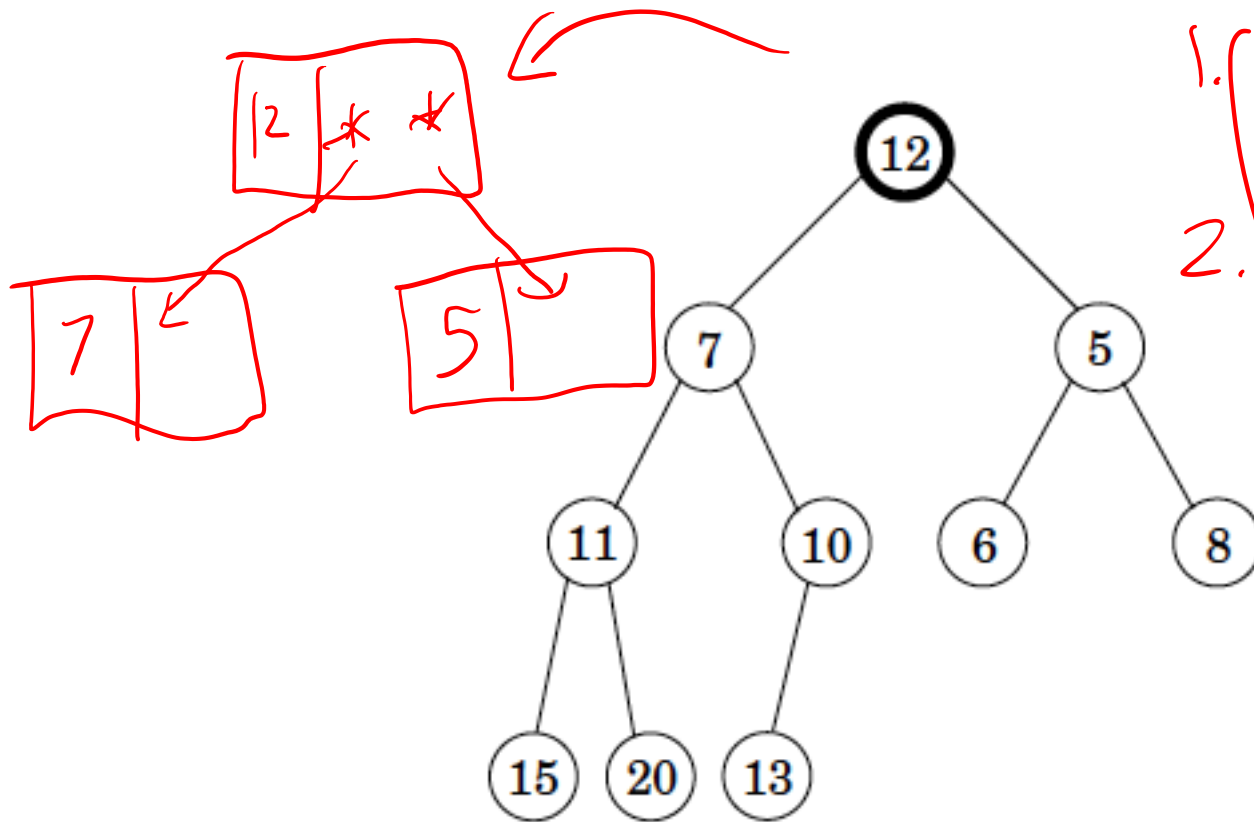
Binary heaps

- How do we delete-min?
 - Return the root value
 - Delete the root
 - Take the “last” element in the tree (lowest level, furthest right), and put it in the root element
 - Swap that element with whichever of its children are smallest, and let it “sift down”

Binary heaps: Delete-min

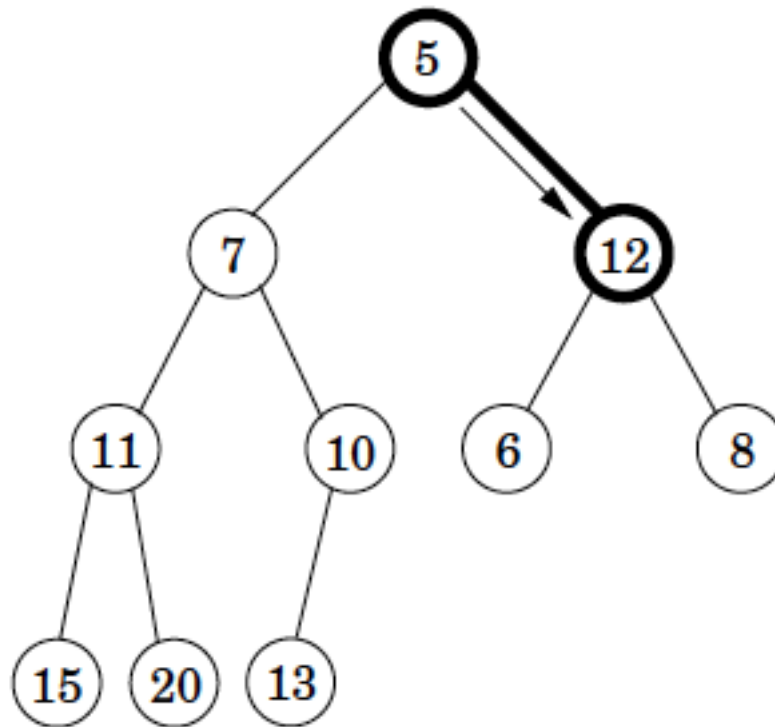


Binary heaps: Delete-min

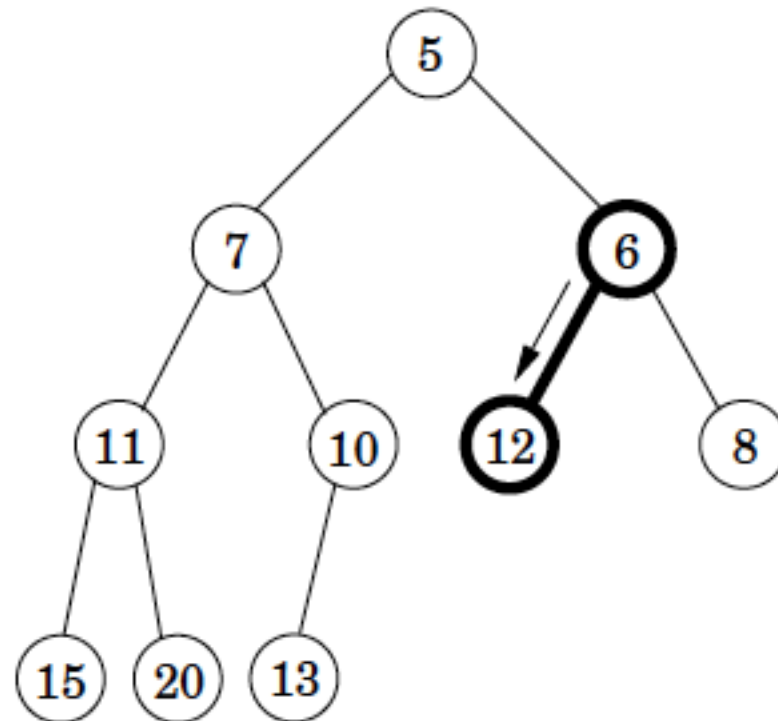


1. Who are 5's children?
2. Who is 12's other child?
3. Have 5 \rightarrow 12, 7
4. Have 12 \rightarrow 5's children
5. Update 7, 6, 8 parent

Binary heaps: Delete-min



Binary heaps: Delete-min



In-Class Exercise

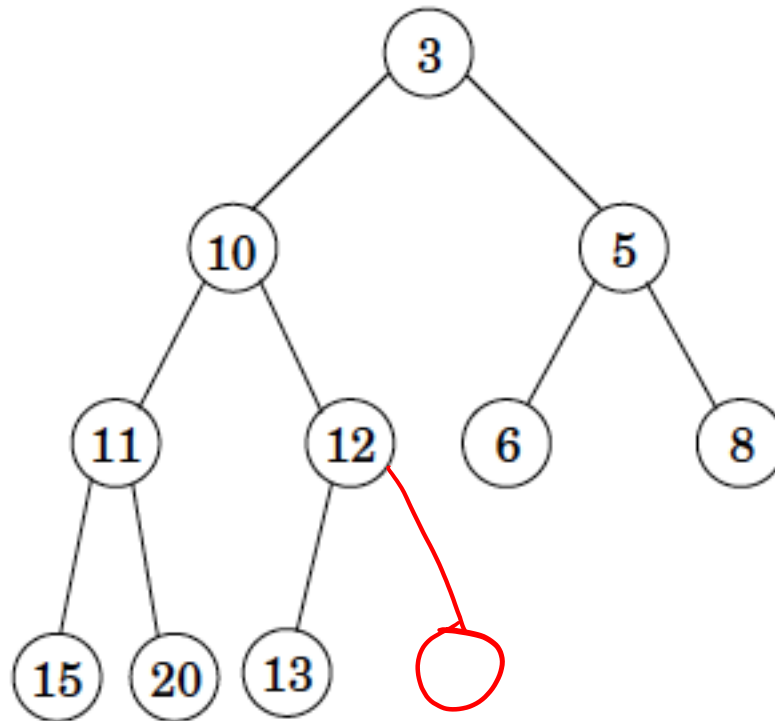
- Suppose the binary heap has n elements
- Analyze the running time of a single delete-min operation $O(\log n)$

\rightarrow depth of tree is $O(\log n)$

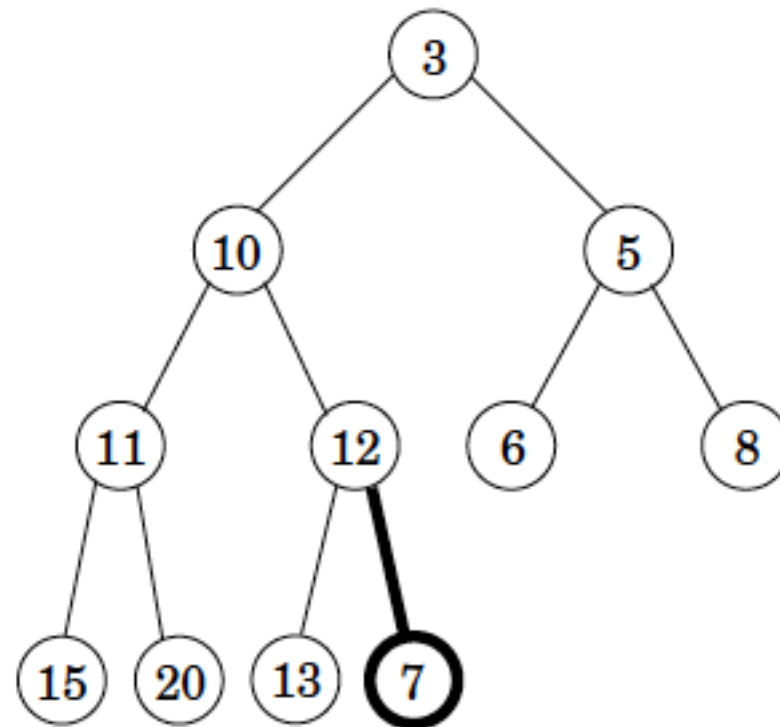
Binary heaps

- How do we insert?
 - Place the new element in the first empty spot (bottom level, furthest right)
 - Let it “bubble up” by swapping it with its parent, for as long as the parent is larger

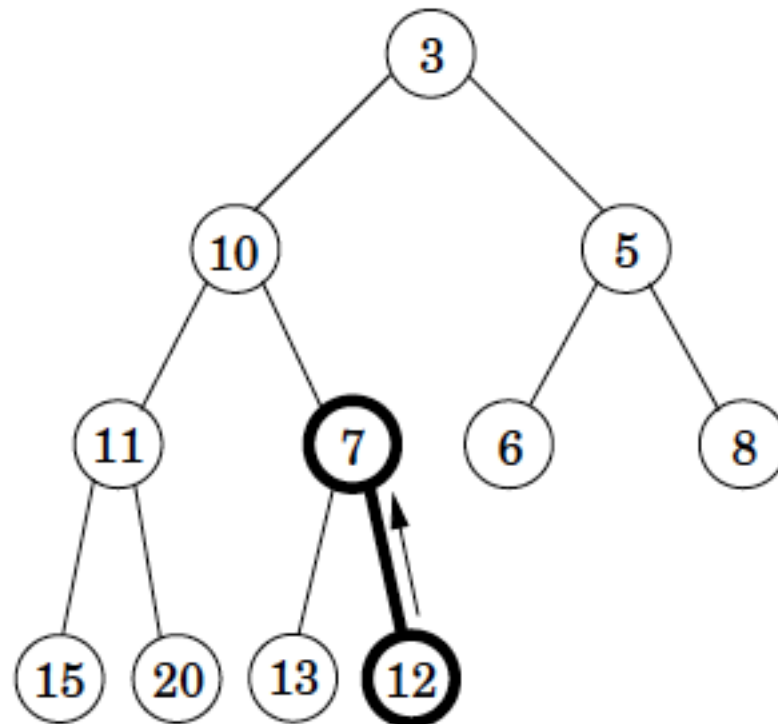
Binary heaps: Insert



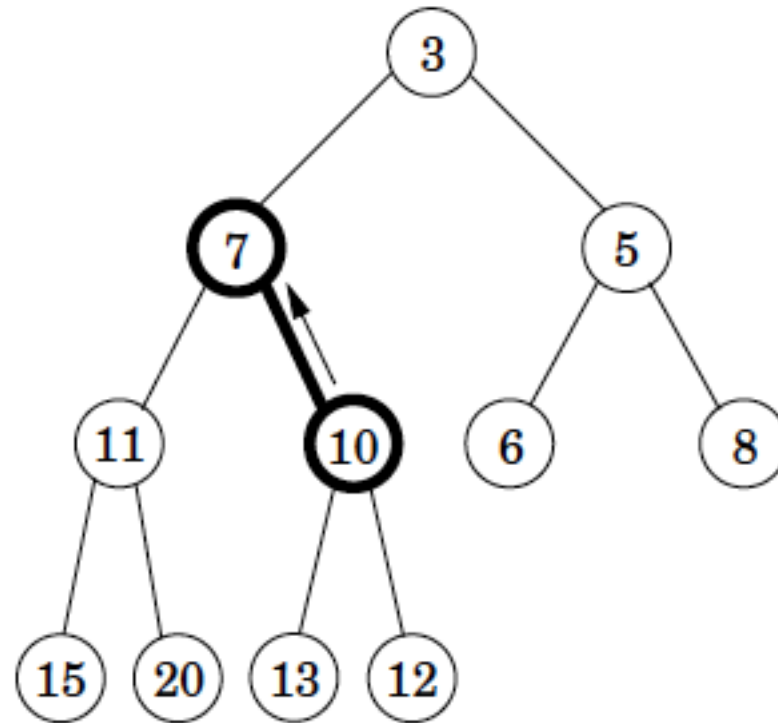
Binary heaps: Insert



Binary heaps: Insert



Binary heaps: Insert



Binary heaps: Insert

- What is the running time of a single insert operation? $O(\log n)$
- Similar implementation for decrease-key: do you see why?

Running time of Dijkstra's Algorithm

```
for all  $u \in V$ :  
     $\text{dist}(u) = \infty$   
     $\text{prev}(u) = \text{nil}$   
 $\text{dist}(s) = 0$ 
```

$O(N)$

$O((N+M) \log N)$

```
 $H = \text{makequeue}(V)$  (using  $\text{dist}$ -values as keys)
```

```
while  $H$  is not empty:
```

```
     $u = \text{deletemin}(H)$ 
```

$N \text{ times} \cdot O(\log N) = O(N \log N)$

```
    for all edges  $(u, v) \in E$ :
```

```
        if  $\text{dist}(v) > \text{dist}(u) + l(u, v)$ :
```

```
             $\text{dist}(v) = \text{dist}(u) + l(u, v)$ 
```

```
             $\text{prev}(v) = u$ 
```

```
             $\text{decreasekey}(H, v)$ 
```

$O(M)$



$O(M) \cdot O(\log N) = O(M \log N)$

$O(M)$

Running time of Dijkstra's Algorithm

```
for all  $u \in V$ :  
     $\text{dist}(u) = \infty$   
     $\text{prev}(u) = \text{nil}$   
 $\text{dist}(s) = 0$ 
```

Running time using
binary heaps:

$$(|V| + |E|) \log |V|$$

```
 $H = \text{makequeue}(V)$  (using  $\text{dist}$ -values as keys)  
while  $H$  is not empty:  
     $u = \text{deletemin}(H)$   
    for all edges  $(u, v) \in E$ :  
        if  $\text{dist}(v) > \text{dist}(u) + l(u, v)$ :  
             $\text{dist}(v) = \text{dist}(u) + l(u, v)$   
             $\text{prev}(v) = u$   
             $\text{decreasekey}(H, v)$ 
```