

Announcements

Announcements

- HW2 is due today
 - Any questions on HW2?
- HW3 has been posted
- If you have not yet signed up for an oral exam slot, do that today! (Check BB for link)
- Exam questions will be posted on March 7 (Sunday), due March 14
- Exams start March 15

Graphs

Depth First Search

procedure explore(G, v)

Input: $G = (V, E)$ is a graph; $v \in V$

Output: $\text{visited}(u)$ is set to true for
all nodes u reachable from v

$\text{previsit}(v)$

$\text{visited}(v) = \text{true}$

for each edge $(v, u) \in E$:

 if not $\text{visited}(u)$: $\text{explore}(u)$

$\text{postvisit}(v)$

Ignore for now



What is the running time of Depth First Search?

DFS on Directed Graphs

- We can run DFS on directed graphs, making sure to only follow edges in their correct direction
- The starting node is the **root** of the DFS tree
- u is an **ancestor** of v if there is a path from u to v in the DFS tree. v is a **descendant** of u .
- u is the **parent** of v if there is a directed edge from u to v in the DFS tree. v is the **child** of u .

DFS on Directed Graphs

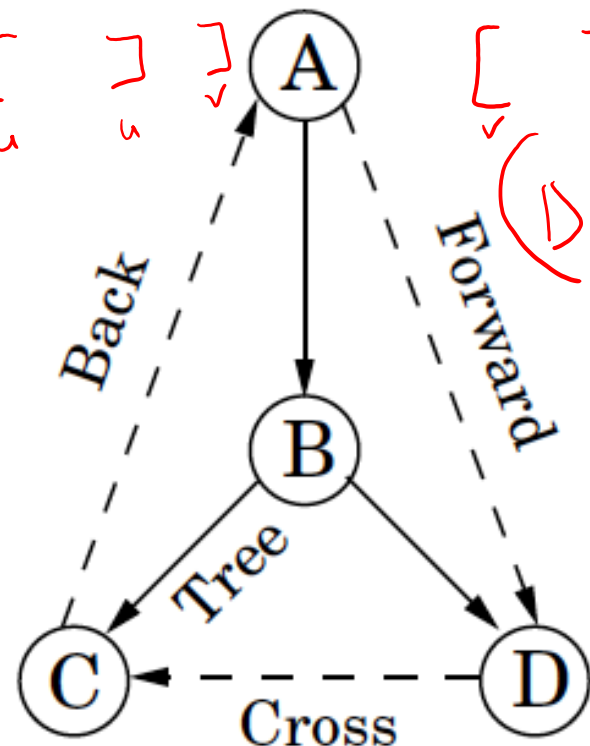
- We can run DFS on directed graphs, making sure to only follow edges in their correct direction

A is the **root**

B is a **child** of A

B is a **parent** of C

A is an **ancestor** of D



[[[[] []]]
A B C C D D B A

tree
forward

can't happen
 $u \rightarrow v$

back

[[]]
u v v u

[[]]
u v v

[[]]
v u s

[] []
v v u u

()
D → C
cross

DFS tree

DFS on Directed Graphs

- How do we know whether u is a parent/child/ancestor/descendant of v ?
- Use pre/post times!

In-Class Exercise

What types of edges are these?

pre/post ordering for (u, v)

$\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$
 u v v u

$\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$
 v u u v

$\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$
 v v u u

$\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$ $\begin{bmatrix} \end{bmatrix}$
 u u v v

- tree/forward

- back

- cross

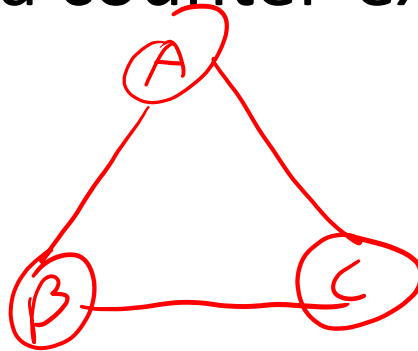
- can't happen

Finding Paths in Graphs

- Remember, a **path** between two nodes is a sequence of ^{adjacent} edges connecting those nodes
- A **shortest path** is the path between two nodes with the fewest edges (unweighted graph)

DFS and Paths

- DFS finds paths between nodes... but does it always find shortest paths?
- Prove or give a counter-example



Breadth-first search (BFS)

$N = \# \text{ nodes}$
 $M = \# \text{ edges}$

procedure bfs(G, s)

Input: Graph $G = (V, E)$, directed or undirected; vertex $s \in V$
Output: For all vertices u reachable from s , dist(u) is set to the distance from s to u .

for all $u \in V$:
 $\text{dist}(u) = \infty$ $O(N)$ $\# \text{ edges in s.p.}$

$\text{pred}[s] = \emptyset$
 $\text{dist}(s) = 0$ $O(1)$

$Q = [s]$ (queue containing just s)

while Q is not empty: $O(N)$

$u = \text{eject}(Q)$ $O(N)$

 for all edges $(u, v) \in E$: $O(M)$

 if $\text{dist}(v) = \infty$: $O(M)$

~~$\text{inject}(Q, v)$~~ $O(N)$

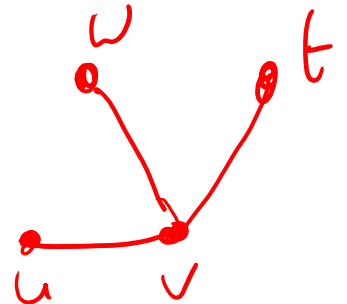
~~$\text{dist}(v) = \text{dist}(u) + 1$~~

$\text{pred}(v) = u$ $O(N)$

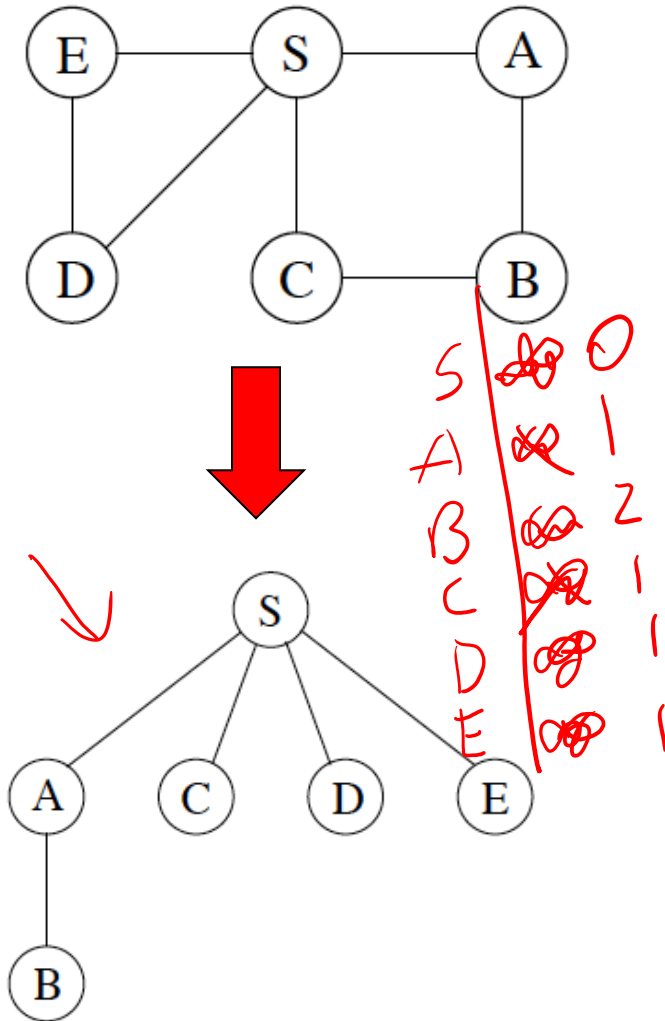
$O(1)$
Put all neighbors
on queue

$O(M + N)$

Distance to neighbor =
1 + distance to current node

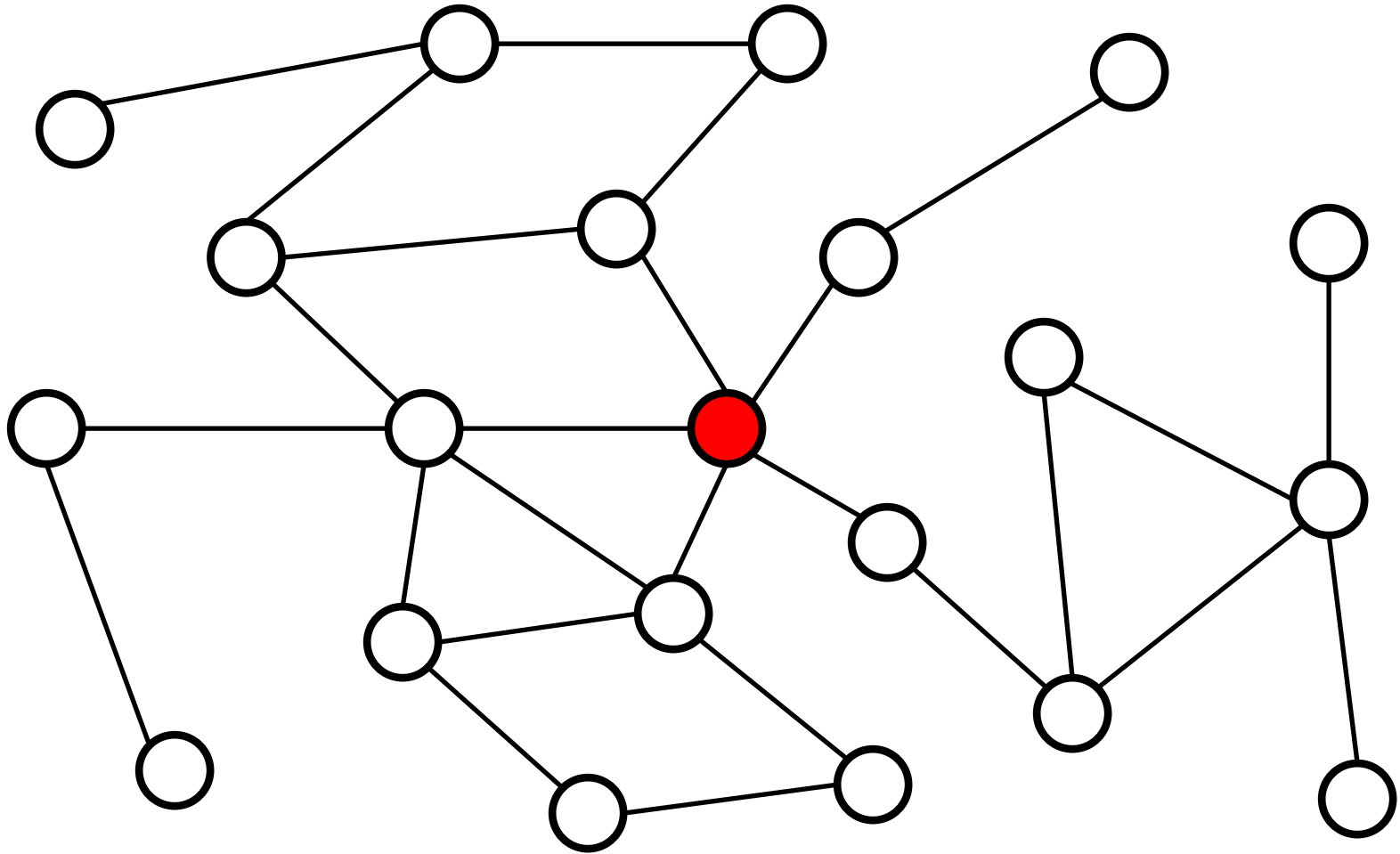


Breadth-first search (BFS)

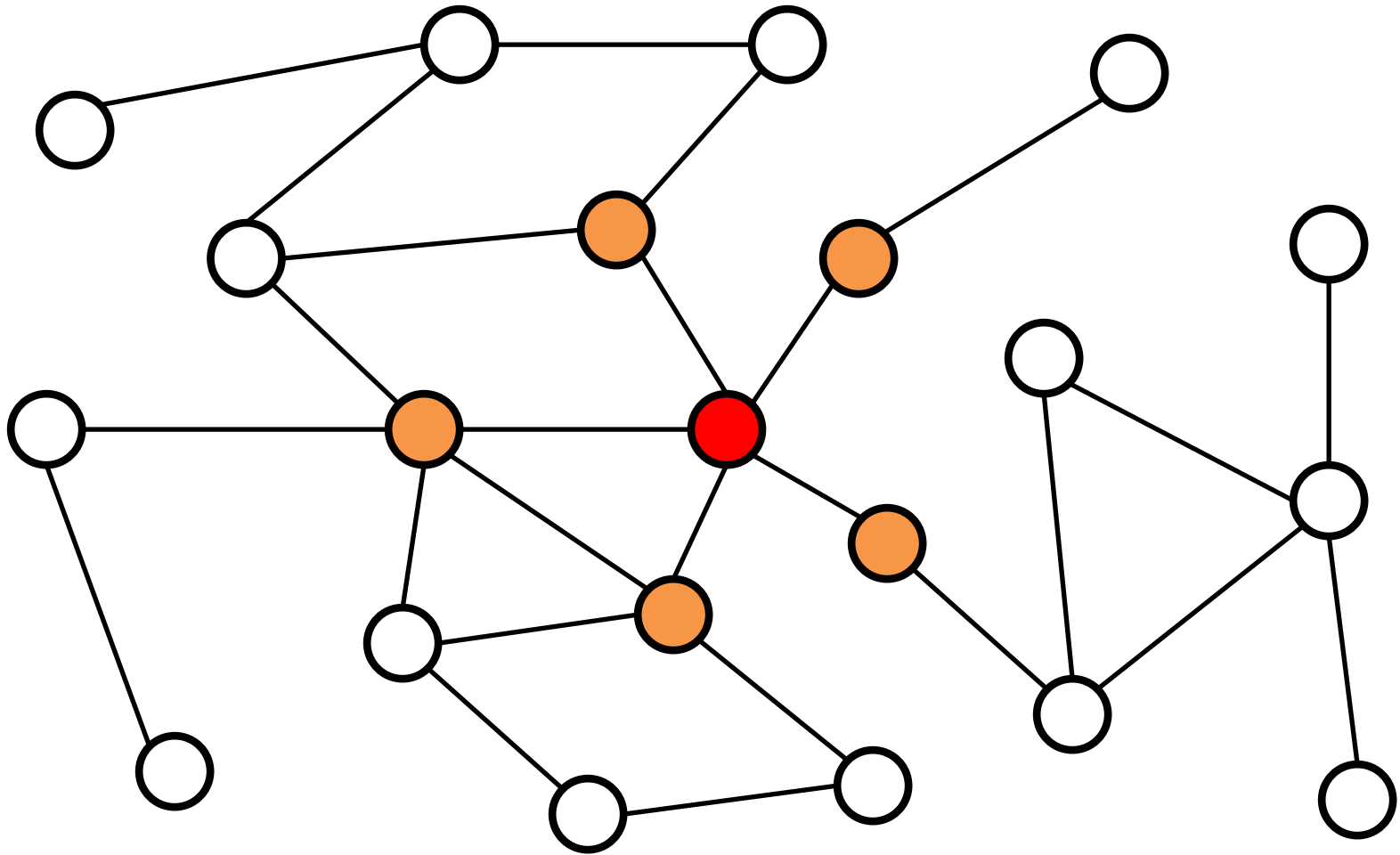


Order of visitation	Queue contents after processing node
	[S]
S	[A C D E] ✓
A	[C D E B] ✓
C	[D E B]
D	[E B]
E	[B]
B	[]

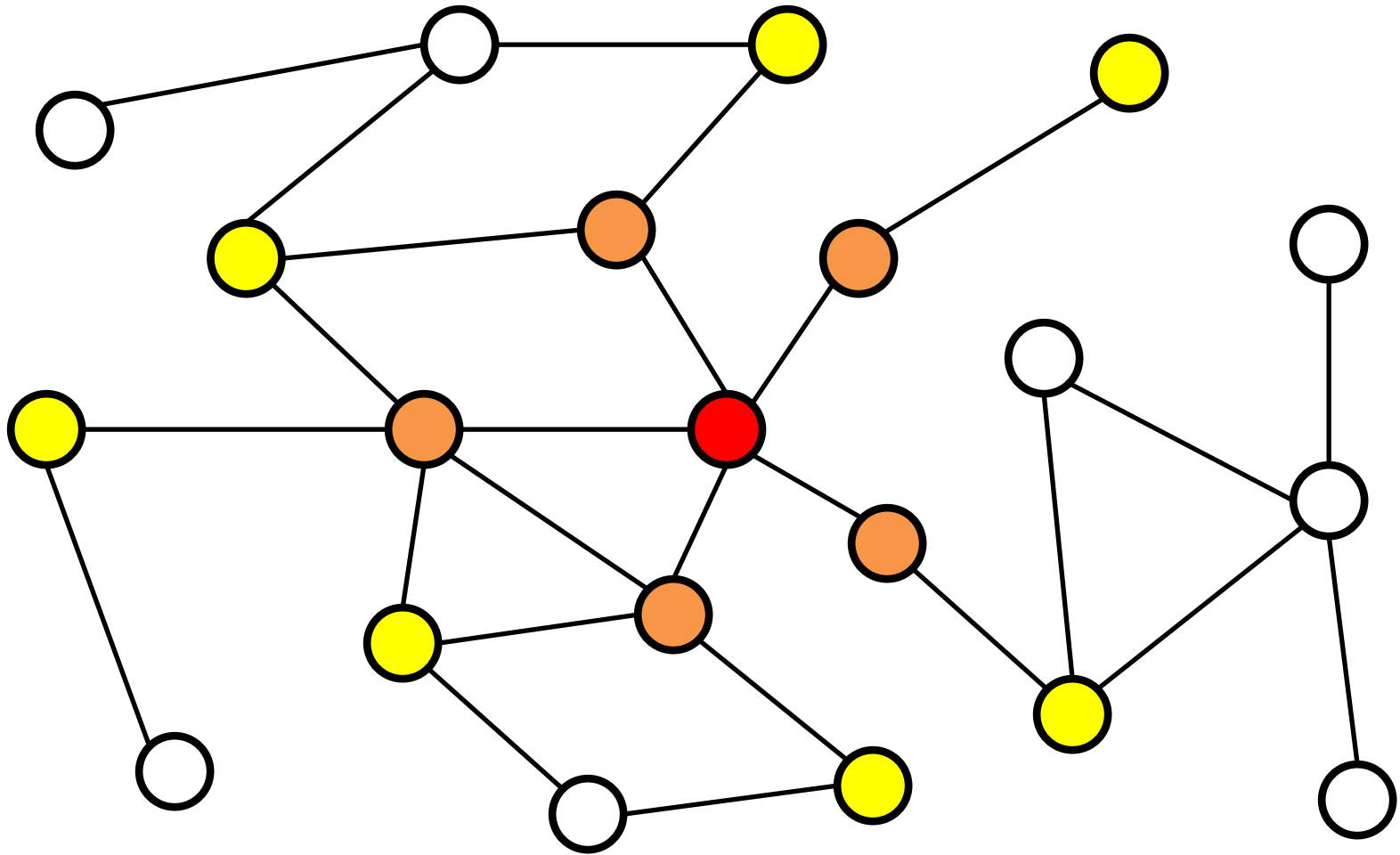
BFS



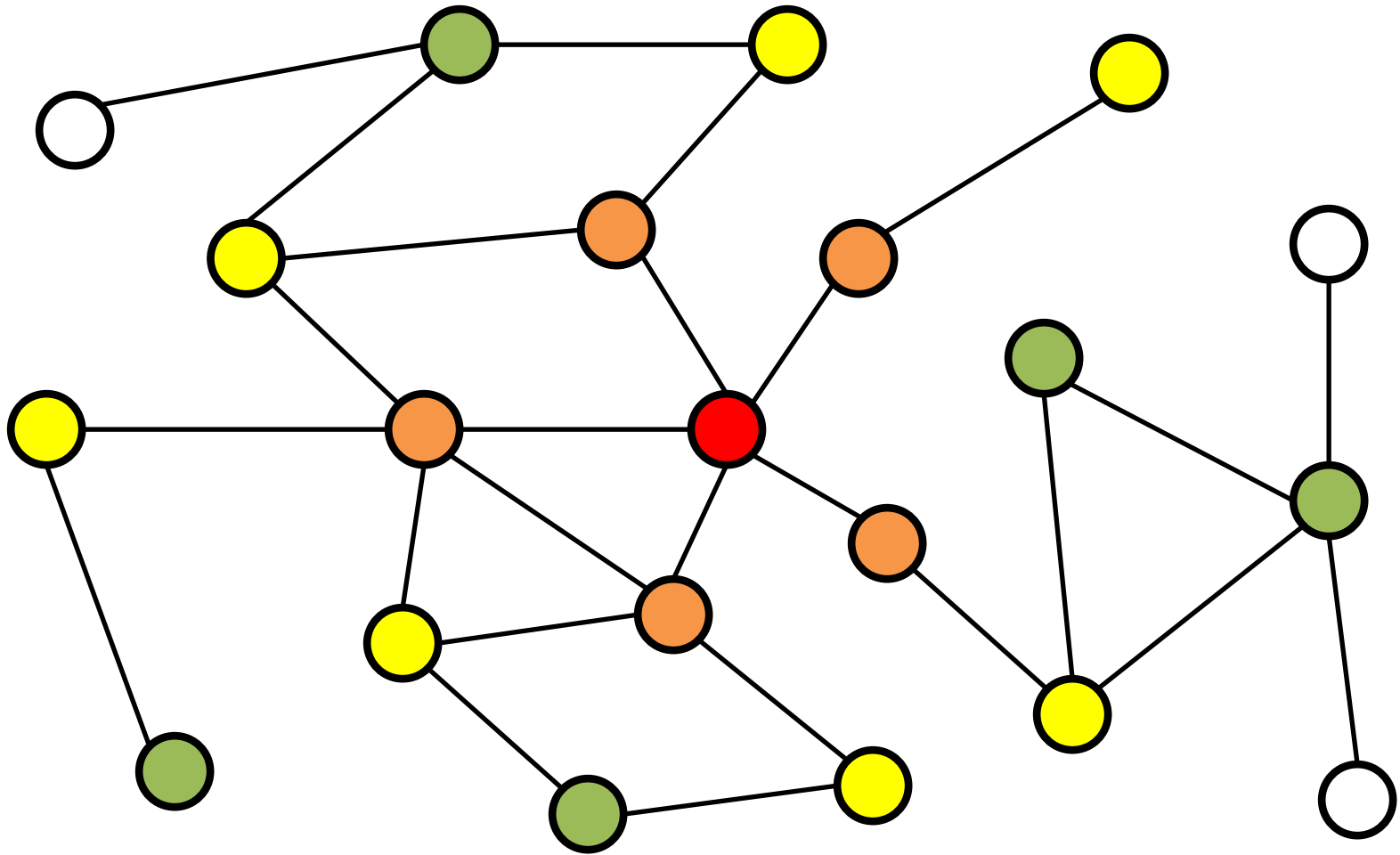
BFS



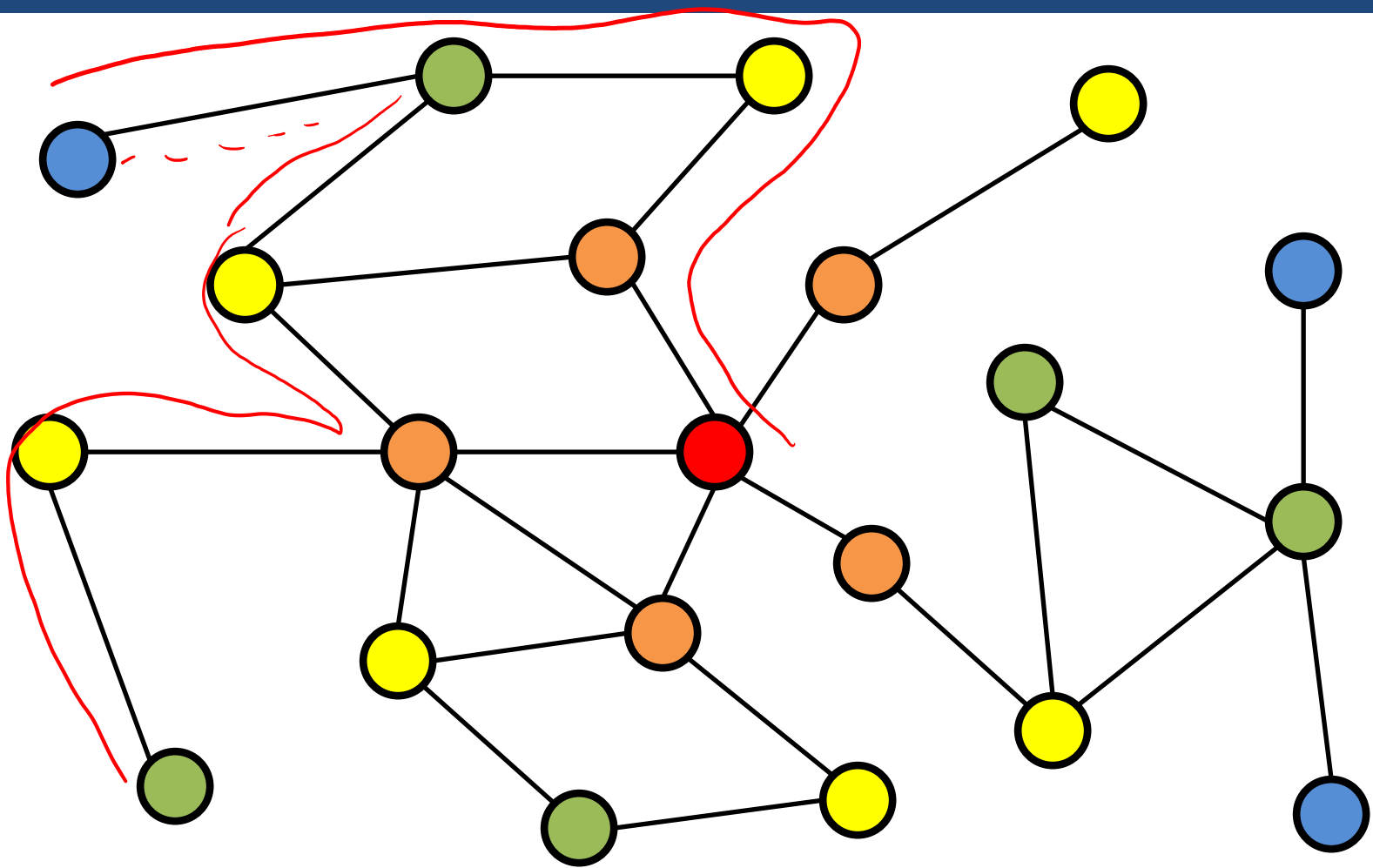
BFS



BFS



BFS



In-Class Exercise

dist

- Does the BFS tree always give you the shortest path from the starting node to every other node? Prove or give a counter-example.


Let p_u denote the actual s.p. length from $s \rightarrow u$. Induction on p_u .

Base case: $p_u = 0$. This occurs when $u = s$. BFS sets $\text{dist}(s)$ before loop. \checkmark

I.H.: Assume that BFS is correct for all nodes u with $p_u \leq k$.

In-Class Exercise

I.S. : Show that if $p_u = k+1$, BFS sets $\text{dist}(u) = k+1$.

Suppose there is a path of length $k+1$ $s \rightarrow u$.

~~The~~ Let w denote the node right before u on the s.p. This means that the s.p. $s \rightarrow w$ has length k . By I.H. $\text{dist}(w) = k$ correctly. When we set $\text{dist}(w)$, we look at all its neighbors. u is one of them, so $\text{dist}(u) = \text{dist}(w) + 1 = k + 1$. \square

Running Time of BFS

- What is the running time of BFS?

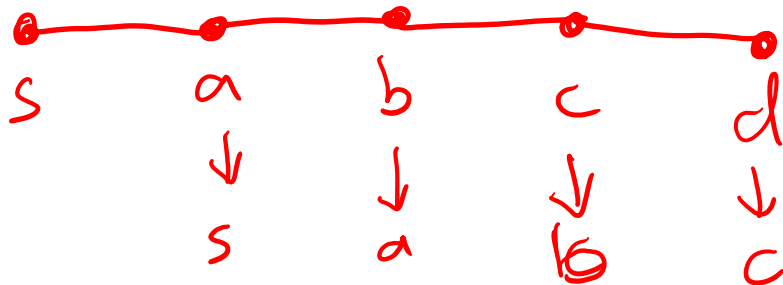
$O(\#nodes + \#edges)$

Shortest Paths via BFS

- In an unweighted graph, the visit time of a BFS search gives the length of the shortest path from the source!
- How can we modify the BFS code to keep track of what the edges in the shortest path are?

store predecessor

~~linked list for each node?~~



$a: s \rightarrow a$

$b: s \rightarrow a \rightarrow b$

$c: s \rightarrow a \rightarrow b \rightarrow c$

$d: s \rightarrow a \rightarrow b \rightarrow c \rightarrow d$

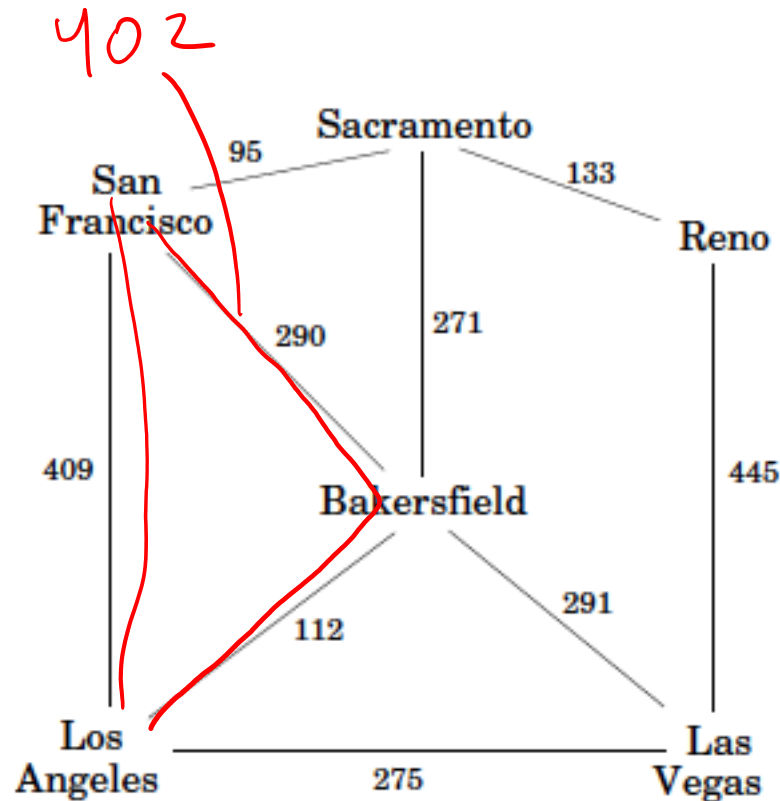
In-Class Exercise

- How can we modify the code to keep track of what the edges on the shortest paths are?

```
for all  $u \in V$ :  
     $\text{dist}(u) = \infty$   
 $\text{pred}(s) = \emptyset$   
     $\text{dist}(s) = 0$   
     $Q = [s]$  (queue containing just  $s$ )  
    while  $Q$  is not empty:  
         $u = \text{eject}(Q)$   
        for all edges  $(u, v) \in E$ :  
            if  $\text{dist}(v) = \infty$ :  
                inject( $Q, v$ )  
                 $\text{dist}(v) = \text{dist}(u) + 1$   
                 $\text{pred}(v) = u$ 
```

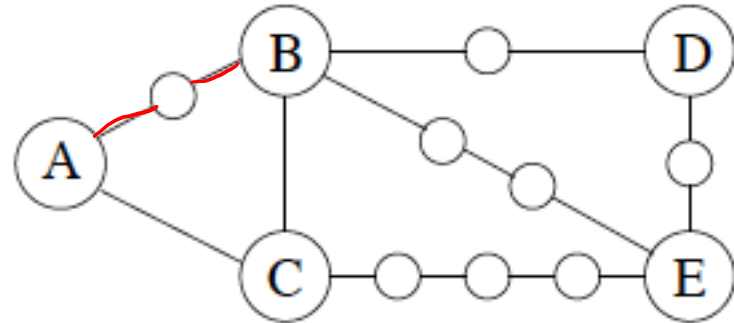
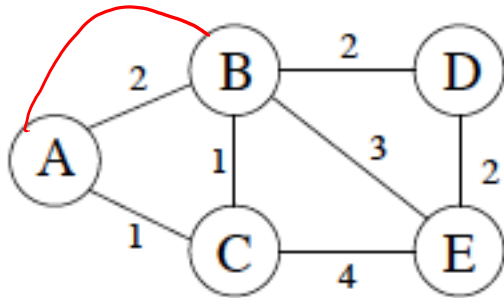
Shortest Paths via BFS

- What about in **weighted graphs**?



Dijkstra's Algorithm

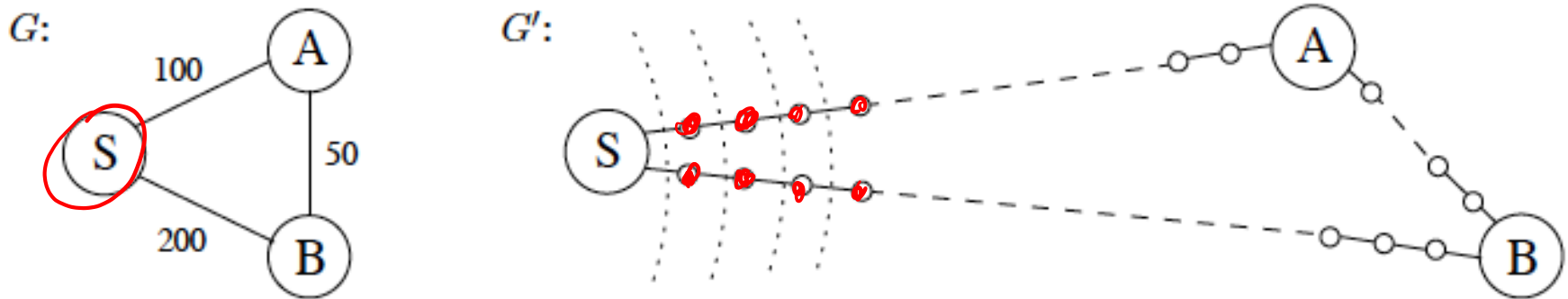
- One way to deal with edges with positive, integer weights is to use dummy nodes



- What does this do to the running time? *vastly increases!*

Dijkstra's Algorithm

- With dummy nodes, most of the search process is uninteresting



- Idea: set alarm clocks to go off when we expect something interesting to happen

Dijkstra's Algorithm

- To implement this, we're going to use a **priority queue** *from G*
- Each element (node) has a key value
- Added operations: *with value*
 - Insert (add new element to set)
 - Decrease-key (reduce the value of the key)
 - Delete-min (find the element with the smallest key value, return it and delete from priority queue)
 - Make queue (build queue)

Dijkstra's Algorithm

assumes that all weights ≥ 0
weight 0 = no edge

```
for all  $u \in V$ :  
    ( $\text{dist}(u) = \infty$   
    ( $\text{prev}(u) = \text{nil}$   
( $\text{dist}(s) = 0$ 
```

lower is better

```
 $H = \text{makequeue}(V)$  (using dist-values as keys)
```

```
while  $H$  is not empty:
```

```
     $\rightarrow u = \text{deletemin}(H)$ 
```

```
    for all edges  $(u, v) \in E$ :
```

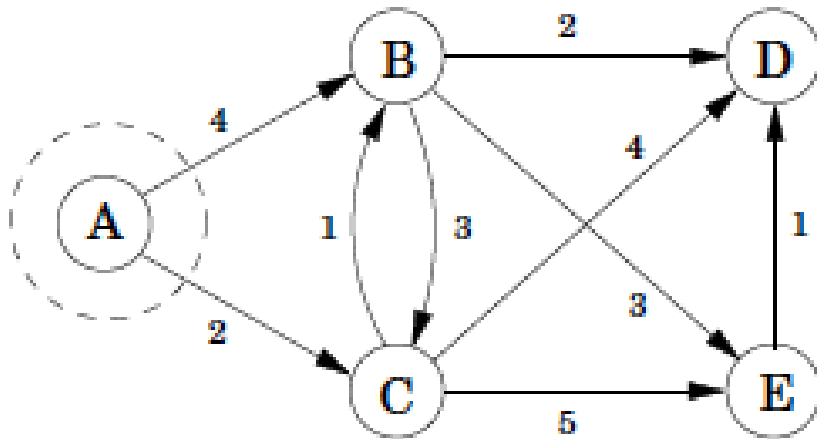
```
        if  $\text{dist}(v) > \text{dist}(u) + l(u, v)$ :
```

```
             $\rightarrow \text{dist}(v) = \text{dist}(u) + l(u, v)$ 
```

```
             $\text{prev}(v) = u$ 
```

```
             $\text{decreasekey}(H, v)$ 
```

Dijkstra's Algorithm



→

A: 0	D: ∞
B: ∞	E: ∞
C: ∞	

→

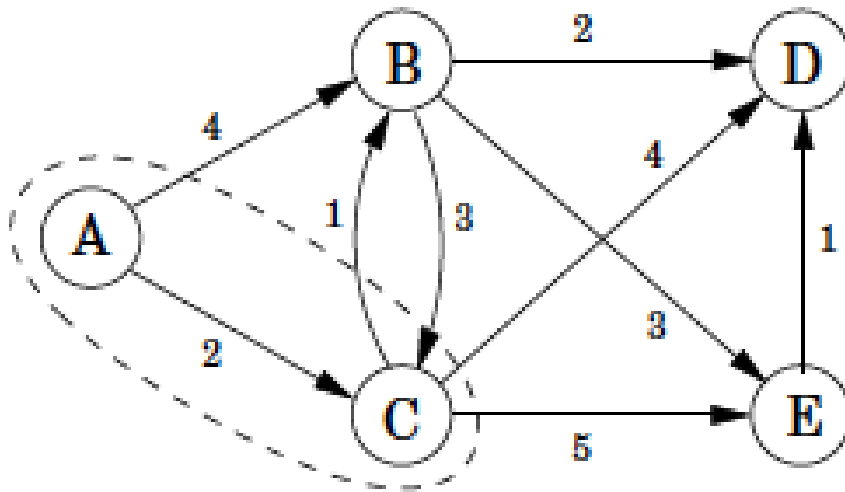
→

A: 0	D: ∞
B: 4	E: ∞
C: 2	

→

~~A~~ B C D E
~~4~~ ~~∞~~ ~~∞~~ ∞ ∞
4 2

Dijkstra's Algorithm

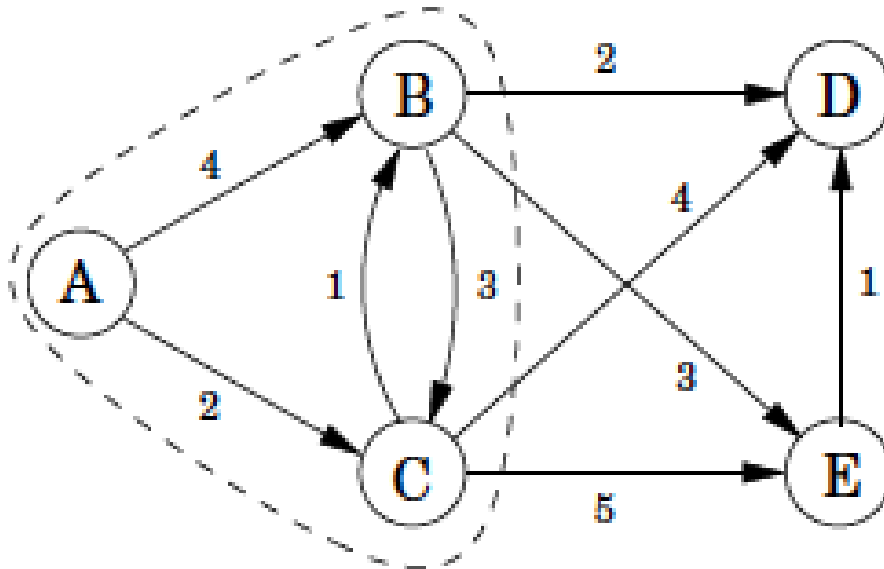


→

A: 0	D: 6	←
B: 3	E: 7	←
C: 2		

B ~~X~~ D E
4 ~~7~~ ~~6~~ ~~7~~

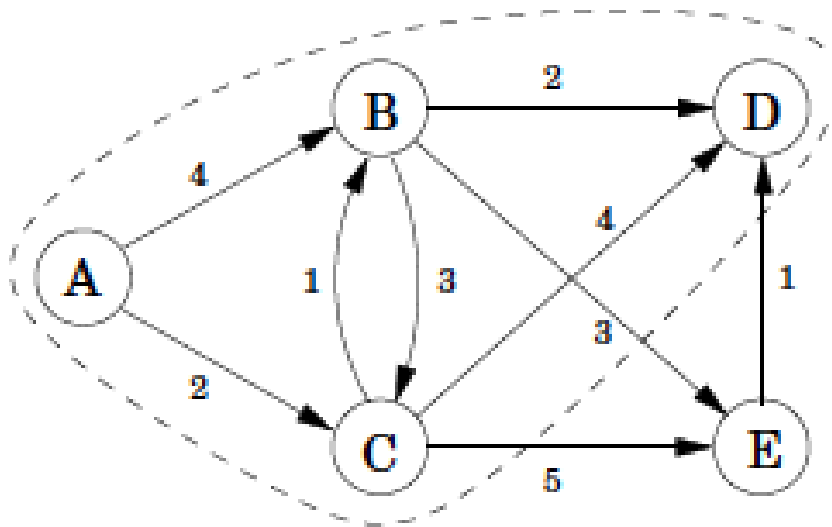
Dijkstra's Algorithm



A: 0	D: 5
B: 3	E: 6
C: 2	

~~B~~ D E
~~4~~ ~~5~~ ~~6~~
5 6

Dijkstra's Algorithm



A: 0	D: 5
B: 3	E: 6
C: 2	

~~D: 5~~ ~~E: 6~~