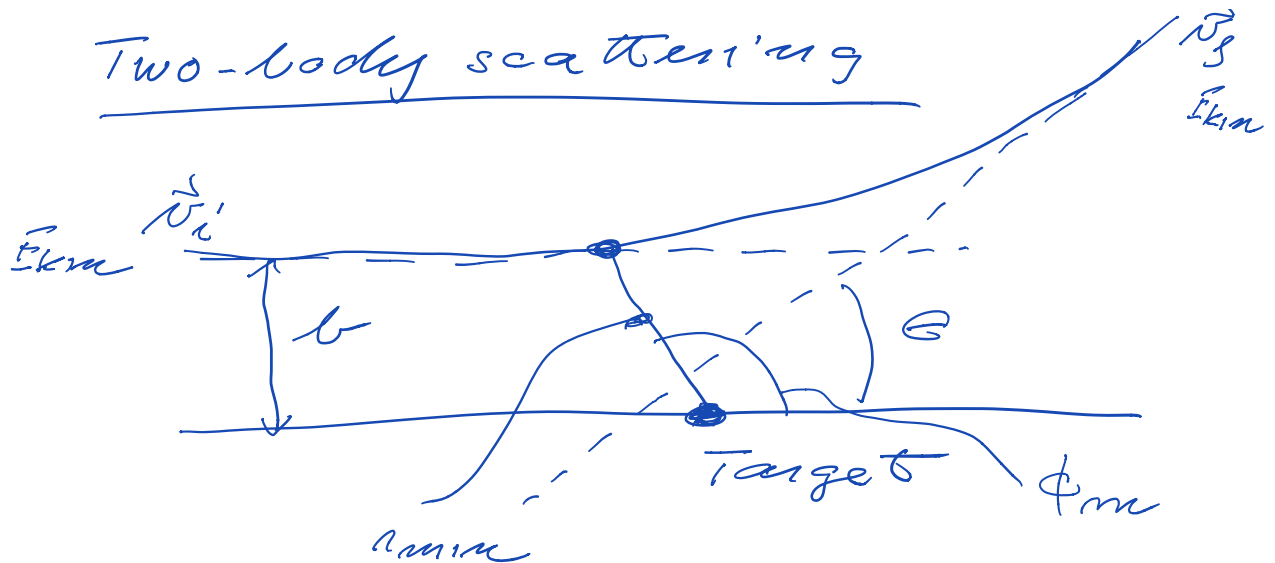


Two-body scattering



$$r(\phi) = \frac{c}{1 + \epsilon \cos \phi} \quad r_{min} \text{ at } \phi = 0$$

$$\frac{d\sigma}{d\Omega} = \frac{b}{\sin \theta} \left| \frac{db}{d\theta} \right|$$

$$c = \left(\frac{\mu \alpha}{L^2 A} \right)^{-1} \quad \left| \quad r(\phi) = \frac{1}{\frac{\mu \alpha}{L^2} + A \cos \phi} \right.$$

$$A = \sqrt{\left(\frac{\mu \alpha}{L^2} \right)^2 + \frac{2\mu E}{L^2}}$$

Conservation of Angular momentum

$$L^2 = \mu^2 b^2 v^2 = 2\mu b^2 E$$

$$A = \sqrt{\left(\frac{\mu \alpha}{L^2} \right)^2 + \frac{1}{b^2}}$$

From geometry

$$\left| \sin \frac{\theta}{2} = \frac{\mu \alpha}{L^2} \right|$$

$$a = \frac{\alpha}{2E}$$

$$1 - \frac{AL^2}{a^2}$$

$$= \frac{a}{\sqrt{a^2 + b^2}}$$

$$(d\sigma = 2\pi b db)$$

$$\frac{1}{2} \cos \frac{\theta}{2} d\theta = \frac{ab db}{(a^2 + b^2)^{3/2}}$$

$$= \frac{b db}{a^2} \frac{1}{2} \cos \frac{\theta}{2} d\theta$$

$$\frac{\pi a^2}{2 \cos^2(\theta/2)} \cos \frac{\theta}{2} d\theta$$

$$= \frac{\pi a^2}{2 \cos^2(\theta/2)} \sin \theta d\theta$$

$$\boxed{\frac{d\sigma}{d\Omega} = \frac{a^2}{4 \cos^4(\theta/2)}}$$

$$\alpha = \frac{d}{2E}$$

same for attractive and repulsive potential.

Example

particle of mass m and charge Z with kinetic energy E scatters on a heavy nucleus of mass M and charge Z and Radius R

what is the angle where the classical scattering formula breaks down?

$$\alpha = \frac{Z_1 Z_2 e^2}{4\pi \epsilon_0}$$

$$\sin \theta/2 = \frac{a}{\sqrt{a^2 + b^2}}$$

Point of closest approach

$b = R$, can find it from conservation of angular momentum

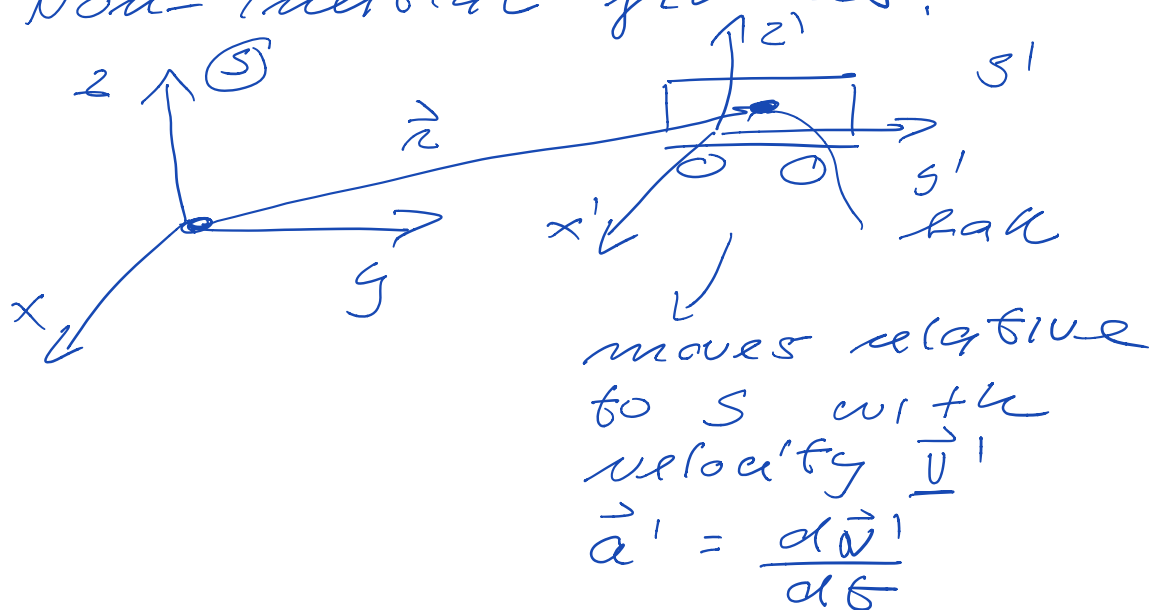
$$L = \underbrace{\mu \cdot v_i \cdot b} = b \sqrt{2\mu E} = \underbrace{\mu v_f R}$$
$$= R \sqrt{2\mu(E - \alpha/R)}$$

$$b = \frac{R \sqrt{2\mu(E - \alpha/R)}}{\sqrt{2\mu E}}$$

$$\underline{b} = R \sqrt{1 - \frac{\alpha}{ER}}$$

$$\theta = 2 \sin^{-1} \left[\frac{a}{\sqrt{a^2 + b^2}} \right]$$

Non-inertial frames:



S is an inertial frame
Newton's 2nd Law

$$m \vec{\ddot{r}} = \vec{F}$$

\vec{r} is the ball's position relative to S

The ball's motion relative to the accelerating frame S' is determined by \vec{r}'

$$\vec{\dot{r}} = \vec{\dot{r}'} + \vec{v}'$$

Ball's velocity relative to S

= Ball's velocity relative to train car + car's velocity relative to S ,

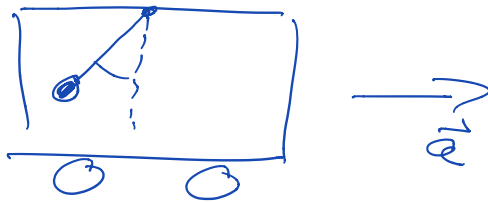
$$\vec{a}' = \vec{a} - \vec{a}'$$

$$m \vec{a} = \vec{F} - m \vec{a}'$$

sum of all forces in
inertial system

Extra force / inertial force

Example



Taylor 9.1-9.3