

### Problem 3.4

using Bayes rule:

$$f(\theta|x) \propto f(x|\theta)g(\theta)$$

Same with the whole sample:

$$\begin{aligned}\mathcal{L}(\theta|X) &\propto g(\theta) \prod_{i=1}^n f(x_i|\theta) \\ &= \frac{\beta^\alpha}{\Gamma(\alpha)} \theta^{\alpha-1} \exp(-\beta\theta) \theta^n \exp\left(-\theta \sum_{i=1}^n x_i\right) \\ &= \frac{\beta^\alpha}{\Gamma(\alpha)} \theta^{\alpha-1+n} \exp\left(-\left(\beta + \sum_{i=1}^n x_i\right)\theta\right)\end{aligned}$$

So functionally it's a gamma distribution:

$$\theta|X \sim \text{Gamma}\left(\alpha + n, \beta + \sum_{i=1}^n x_i\right)$$

**b)**

$$\begin{aligned}\mathbb{E}((\theta - \delta(x))^2) &= \mathbb{E}(\theta^2 - 2\theta\delta(x) + \delta(x)^2) \\ &= \theta^2 - 2\theta\mathbb{E}(\delta(x)) + \mathbb{E}(\delta(x)^2)\end{aligned}$$

On starting on the other side:

$$\begin{aligned}\text{Var}(\delta(x)) + (\mathbb{E}(\delta(x)) - \theta)^2 &= \mathbb{E}(\delta(x)^2) - \mathbb{E}(\delta(x))^2 + (\mathbb{E}(\delta(x)) - \theta)^2 \\ &= \mathbb{E}(\delta(x)^2) - \mathbb{E}(\delta(x))^2 + \mathbb{E}(\delta(x))^2 - 2\theta\mathbb{E}(\delta(x)) + \theta^2 \\ &= \mathbb{E}(\delta(x)^2) - 2\theta\mathbb{E}(\delta(x)) + \theta^2\end{aligned}$$

Which is the same as above, showing equality.

**c)**

The conditional mean will always minimize the Bayes risk under quadratic loss:

$$\implies \delta_g(X) = \frac{\alpha + n}{\beta + \sum_{i=1}^n x_i}$$

d)

Yes, the rule is unique, because there is just one solution.

Only admissible, if  $R(\theta, \delta_g)$  is continuous on  $\Theta$

### Problem 3.5

a)

$$\begin{aligned}\Theta &= [0, 1] \\ \mathcal{X} &= \{0, \dots, k\}^n = \{0, \dots, k\} \\ D &= \Theta \\ L(\theta, \delta) &= \frac{(\theta - d)^2}{\theta(1 - \theta)}\end{aligned}$$

b)

$$\begin{aligned}f(\theta|X) &\propto f(X|\theta)g(\theta) \\ &= f(X|\theta)\end{aligned}$$

So posterior = likelihood because of uninformative prior. But also:

$$f(\theta|x_1) \propto \theta^{x_1}(1 - \theta)^{k-x_1} 1_{[0,1]}(\theta)$$

You can eliminate the binomial coefficient as well to keep the posterior risk simpler

c)

First we define the Bayes risk:

$$\begin{aligned}B(\delta, \pi) &= \int_0^1 L(\delta, \theta) f(\theta|x_1) d\theta \\ &\propto \int_0^1 \frac{(\delta - \theta)^2}{\theta(1 - \theta)} \theta^{x_1} (1 - \theta)^{k-x_1} d\theta \\ &= \int_0^1 (\delta - \theta)^2 \theta^{x_1-1} (1 - \theta)^{k-x_1-1} d\theta\end{aligned}$$

FOC:

$$\begin{aligned}
\frac{\partial B(\delta, \pi)}{\partial \delta} &= 0 \\
\frac{\partial}{\partial \delta} \int_0^1 (\delta - \theta)^2 \theta^{x_i-1} (1 - \theta)^{k-x_i-1} d\theta &= 0 \\
\int_0^1 \frac{\partial}{\partial \delta} (\delta - \theta)^2 \theta^{x_1-1} (1 - \theta)^{k-x_1-1} d\theta &= 0 \\
\int_0^1 2(\delta - \theta) \theta^{x_1-1} (1 - \theta)^{k-x_1-1} d\theta &= 0 \\
\delta \int_0^1 \theta^{x_1-1} (1 - \theta)^{k-x_1-1} d\theta &= \int_0^1 \theta^{x_1} (1 - \theta)^{k-x_1-1} d\theta \\
\delta(x_1) &= \frac{\int_0^1 \theta^{x_1} (1 - \theta)^{k-x_1-1} d\theta}{\int_0^1 \theta^{x_1-1} (1 - \theta)^{k-x_1-1} d\theta}
\end{aligned}$$

d)

Is  $\delta_B = \frac{X_1}{k}$  an equalizer rule?

$$\begin{aligned}
R(\delta_B, \pi) &= \mathbb{E}(L(\delta_B, \theta) | \theta) \\
&= \mathbb{E} \left( \frac{(\delta - \theta)^2}{\theta(1 - \theta)} | \theta \right) \\
&= \frac{1}{\theta(1 - \theta)} \mathbb{E} \left( \left( \frac{X_1}{k} \right)^2 - 2 \left( \frac{X_1}{k} \right) \theta + \theta^2 | \theta \right) \\
&= \frac{1}{\theta(1 - \theta)} \left[ \frac{1}{k^2} \mathbb{E}(X_1^2 | \theta) - \frac{2}{k} \theta E(X_1 | \theta) + \theta^2 \right] \\
&= \frac{1}{\theta(1 - \theta)} \left[ \frac{k(\theta(1 - \theta)) + k^2 \theta^2}{k^2} - \frac{2}{k} \theta k \theta + \theta^2 \right] \\
&= \frac{1}{\theta(1 - \theta)} \left[ \frac{\theta(1 - \theta)}{k} - \theta^2 + \theta^2 \right] = \frac{1}{k}
\end{aligned}$$

Which is invariant of  $\theta$ . So it is a equalizer and Bayes rule making it minimax.

### Problem 3.6

a)

$$\begin{aligned}
\Theta &= \mathbb{R}_+ \\
\mathcal{X} &= \mathbb{R}^n \\
D &= \{\delta_1, \delta_0\} = \begin{cases} H_0 \text{ is true} \\ H_1 \text{ is true} \end{cases} \\
L &= 0-1 \text{ loss}
\end{aligned}$$

**b)**

we have a linear combination of normal r.v. this means, that it's normal and we only have to find the mean and the variance:

$$\begin{aligned}\mathbb{E}(T) &= \frac{\mu}{\sqrt{\frac{8}{n}}} \\ &= \frac{\mu}{\sqrt{\frac{\sigma^2}{2n}}} \\ \text{Var}(T) &= \frac{\frac{4}{n^2}}{\frac{8}{n}} \sum_{i=1}^{n/2} \text{Var}(X_i) \\ &= \frac{32}{n^3} \sum_{i=1}^{n/2} \sigma^2 \\ &= \frac{16}{n^2} \sigma^2 = \frac{16^2}{16^2} = 1\end{aligned}$$

So:

$$T \sim \mathcal{N}\left(\frac{\mu}{\sqrt{\frac{\sigma^2}{2n}}}, 1\right)$$

And under  $H_0$  it is standard normal.

**c)**

$$\alpha = P_{H_0}(T \leq -1.645) = \Phi(-1.645) = 1 - \Phi(1.645) = 5\%$$

so significance level is 5%

**d)**

$$\lambda(X) = \frac{\mathcal{L}(X|0)}{\max_{\mu \in \mathbb{R}} \mathcal{L}(X|\mu)}$$

The ML estimator for  $\mu$  is the sample mean  $\bar{x}_n$ .

Now inserting this:

$$\begin{aligned}\lambda(X) &= \frac{\prod_{i=1}^n f(x_i|0, 4)}{\prod_{i=1}^n f(x_i|\bar{X}_n, 4)} \\ &= \frac{\exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2\right)}{\exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x}_n)^2\right)}\end{aligned}$$

And applying the transformation:

$$\begin{aligned}
 -2 \ln \lambda(X) &= -2 \left( -\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2 + \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x}_n)^2 \right) \\
 &= \frac{1}{\sigma^2} \left( \sum_{i=1}^n x_i^2 - \sum_{i=1}^n x_i^2 + 2\bar{x}_n \sum_{i=1}^n x_i - n\bar{x}_n^2 \right) \\
 &= \frac{1}{\sigma^2} (2n\bar{x}_n^2 - n\bar{x}_n^2) \\
 &= \frac{n\bar{x}_n^2}{\sigma^2} \\
 &= \frac{n \left( \frac{1}{n^2} \left( \sum_{i=1}^n x_i \right)^2 \right)}{\sigma^2} \\
 &= \frac{\left( \sum_{i=1}^n x_i \right)^2}{n\sigma^2} \\
 &= \left( \frac{\sum_{i=1}^n x_i}{\sqrt{n}\sigma} \right)^2 \\
 &\rightarrow \chi_1^2 \quad \text{lindeberg levy clt}
 \end{aligned}$$