

Full Waveform Inversion Using Generative Adversarial Networks for Breast Sound Speed Reconstruction in 2D Ultrasound Computed Tomography

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Outline

1. Introduction

- Ultrasound computed tomography (USCT)
- Regularization

2. Background

- Waveform inversion for USCT image reconstruction
- Generative adversarial nets (GAN)

3. Method

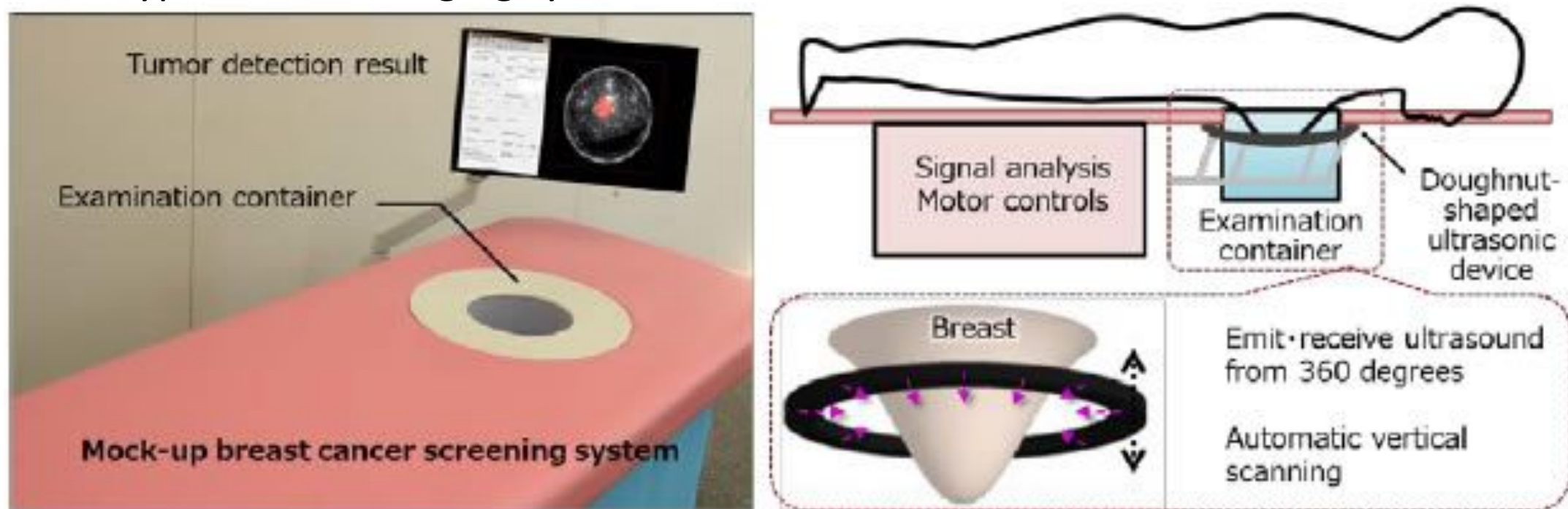
- GAN-based waveform inversion

4. Numerical study

5. Conclusions and future work

Ultrasound computed tomography (USCT)

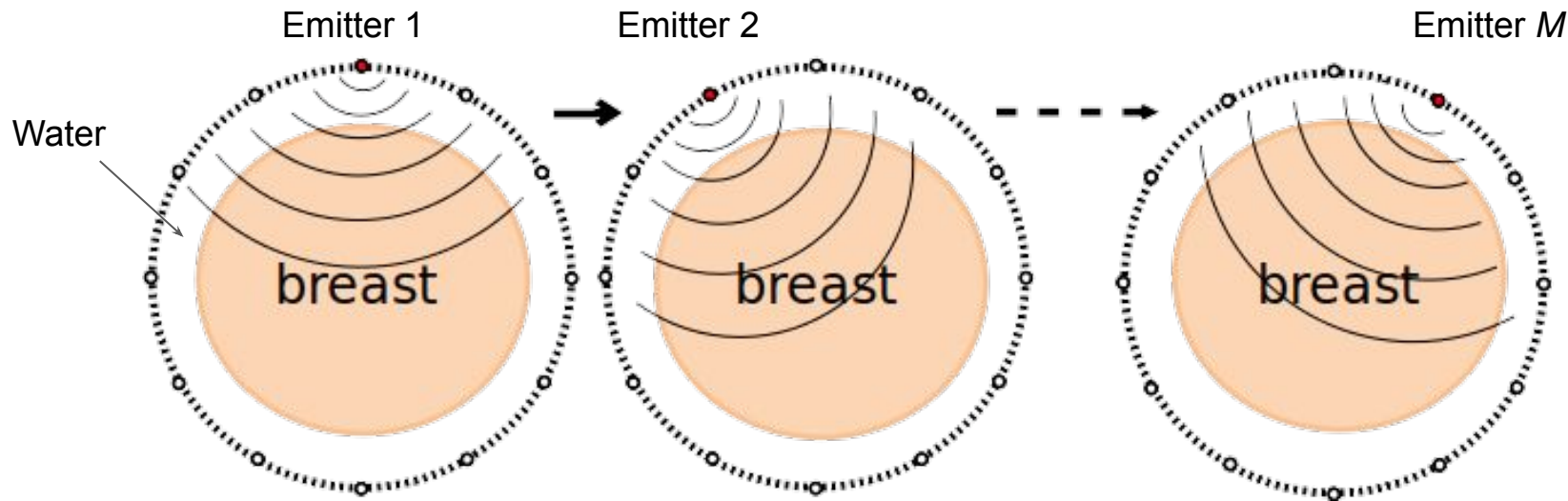
- USCT is a non-invasive **quantitative** imaging technique for detecting breast cancer
 - Non-ionizing radiation
 - Breast-compression-free
 - High contrast profile for early detection
- A typical USCT imaging system



Breast cancer screening system mock-up and prototype configuration [from Hitach website]

Ultrasound computed tomography (USCT)

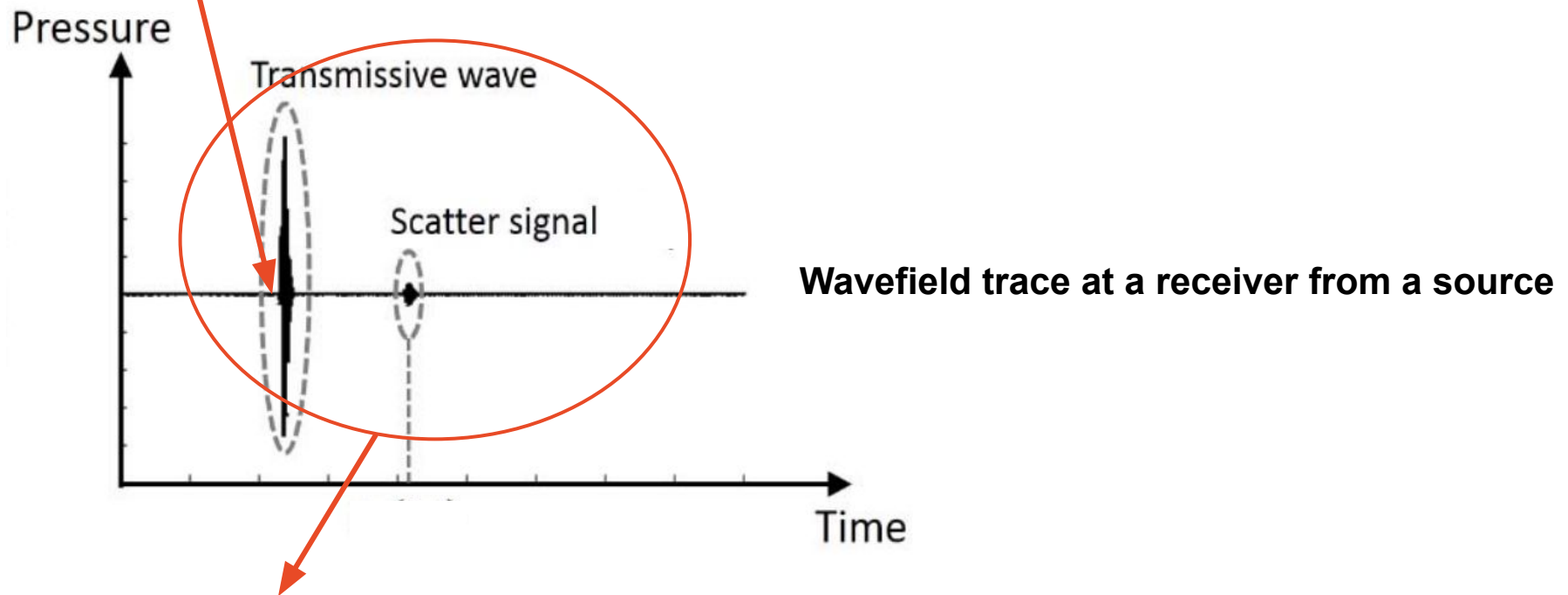
- A typical USCT imaging system [cont'd]



- A transducer (emitter) generates an acoustic pulse (1~20MHz) to insonify a breast
 - All transducers (receivers) measure the resultant wavefield data
 - One dataset contains M single shots
- The **Goal of USCT** is to reconstruct the acoustic properties (e.g., sound speed) from the wavefield dataset

Ultrasound computed tomography (USCT)

- Most USCT image reconstruction methods use simplified approximate models of wave propagation
 - E.g., Time-of-flight tomography: scattering events are not considered (**Poor quality**)



- Waveform inversion methods provide more accurate reconstructions
 - Inversion of the acoustic wave equation to the acoustic properties
 - High computational cost of solving wave equation
 - **Enhanced resolution** with multiple scattering events

Challenges of waveform inversion methods

1. The solution may not be unique due to incomplete measurement data
2. Noise in data may result in a large change in the solutions
 - The uncertainty in data lead to the uncertainty in the solution
3. Many possible solutions may exist, which minimize the closeness between the measured and modeled data
 - The objective functions is usually nonconvex
4. Simulation error may result in inaccurate solutions
 - Mismatch between 3D measurement and 2D simulation
 - Mismatch of transducer locations between measurement and simulation
 - Inaccurate acoustic properties in simulation such as density and attenuation

Regularization methods

- **Regularization** helps promoting “desirable” properties in the accomplished image
 - Regularizer is specified based on a prior knowledge of the sought-after objects
 - Examples of classic regularization methods
 - Tikhonov regularization: promote smoothness
 - Total variation regularization: preserve edges
 - l_1 regularization in a wavelet basis: sparsify
- **Issue:** Classic regularizers may be suboptimal
 - Tikhonov regularization: over-smooth
 - Total variation regularization: low contrast, over-blocky
 - l_1 regularization in a wavelet basis: chosen wavelet may not be optimal

Regularization methods

- **Alternative:** Data-driven regularizers can be formulated from realistic medical image set via machine learning approaches
 - Deep neural network (DNN)-based function can represent the realistic medical images
 - Examples of data-driven regularization
 - Sparse dictionary learning [Singh et al. (2016)]
 - Image patches are restricted to a sparse representation using learnt dictionary
 - Generative model [Bora et al. (2017)] ⇒ **To be elaborated**
 - The solution space is restricted to be near the range of generative model
- The **aim of this study** is to investigate the feasibility of a **Generative model-based data-driven regularizer** learnt on realistic breast sound speed maps for the waveform inversion methods in 2D USCT problem

Full-waveform-based imaging model for USCT

- The acoustic wave equation for the time domain approaches

$$\underbrace{\nabla^2 p_j(\mathbf{r}, t)}_{\text{Pressure at j-th view}} - \frac{1}{\underbrace{c^2(\mathbf{r})}_{\text{Sound speed}}} \partial_{tt} p_j(\mathbf{r}, t) = \underbrace{s_j(\mathbf{r}, t)}_{\text{Source at j-th view}}$$

$$p_j(\mathbf{r}, 0) = 0, \quad \partial_t p_j(\mathbf{r}, 0) = 0$$

- Numerical wave equation solver (solved by pseudospectral k-space method, Mast *et al.* (2001))

$$\underbrace{\mathbf{g}_j}_{\text{Estimated pressure at j-th view}} = \underbrace{\mathbf{M}\mathbf{H}(\mathbf{c})}_{\text{Sampling operator Wave solver depending on } c} \mathbf{s}_j$$

- 2D spatiotemporal domain
- D-D imaging equation
- Matrix-free computation

Standard waveform inversion problem

- The formulation of a minimization problem

$$\hat{\mathbf{c}} = \underset{\mathbf{c}}{\operatorname{argmin}} \{ \underbrace{F(\mathbf{c})}_{\text{Data fidelity}} + \alpha \underbrace{R(\mathbf{c})}_{\text{Regularization}} \}$$

- Data fidelity term

$$F(\mathbf{c}) = \frac{1}{2} \sum_{j=1}^M \left\| \underline{\mathbf{g}}_j - \mathbf{M}\mathbf{H}(\mathbf{c})\mathbf{s}_j \right\|^2$$

Noisy measurement
at j-th view

- Nonlinear and Nonconvex w.r.t \mathbf{c}
 - Good initial guess of \mathbf{c} is required
- The selected regularization term
 - Total variation (TV): smoothing away noise-corruption and preserving edges
 - **Pros:** well-established, simple implementation
 - **Cons:** underestimates the tissue variations, unwanted image degradation

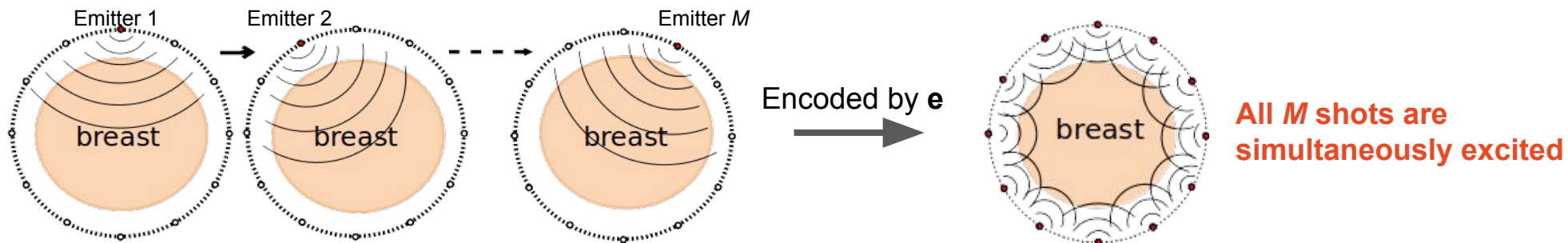
Waveform inversion with source encoding

- The computation of solving wave equation is highly burdensome
⇒ Randomization of the data fidelity term has been proposed [Wang *et al.* (2017)]

- Choose random vector \mathbf{e} to encode the sources and measurements

$$\mathbf{s}^{\mathbf{e}} = \sum_{j=1}^M [\mathbf{e}]_j \mathbf{s}_j \quad \text{and} \quad \underline{\mathbf{g}}^{\mathbf{e}} = \sum_{j=1}^M [\mathbf{e}]_j \underline{\mathbf{g}}_j$$

- Elements of \mathbf{e} from i.i.d *Rademacher* distribution $([-1,1])$



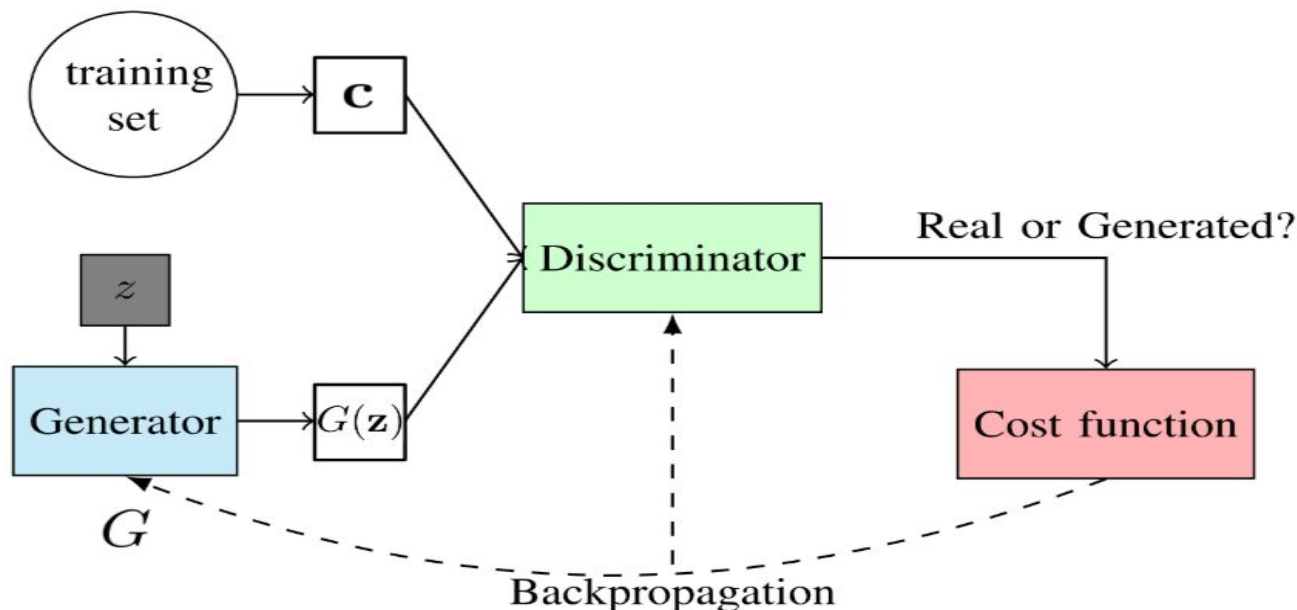
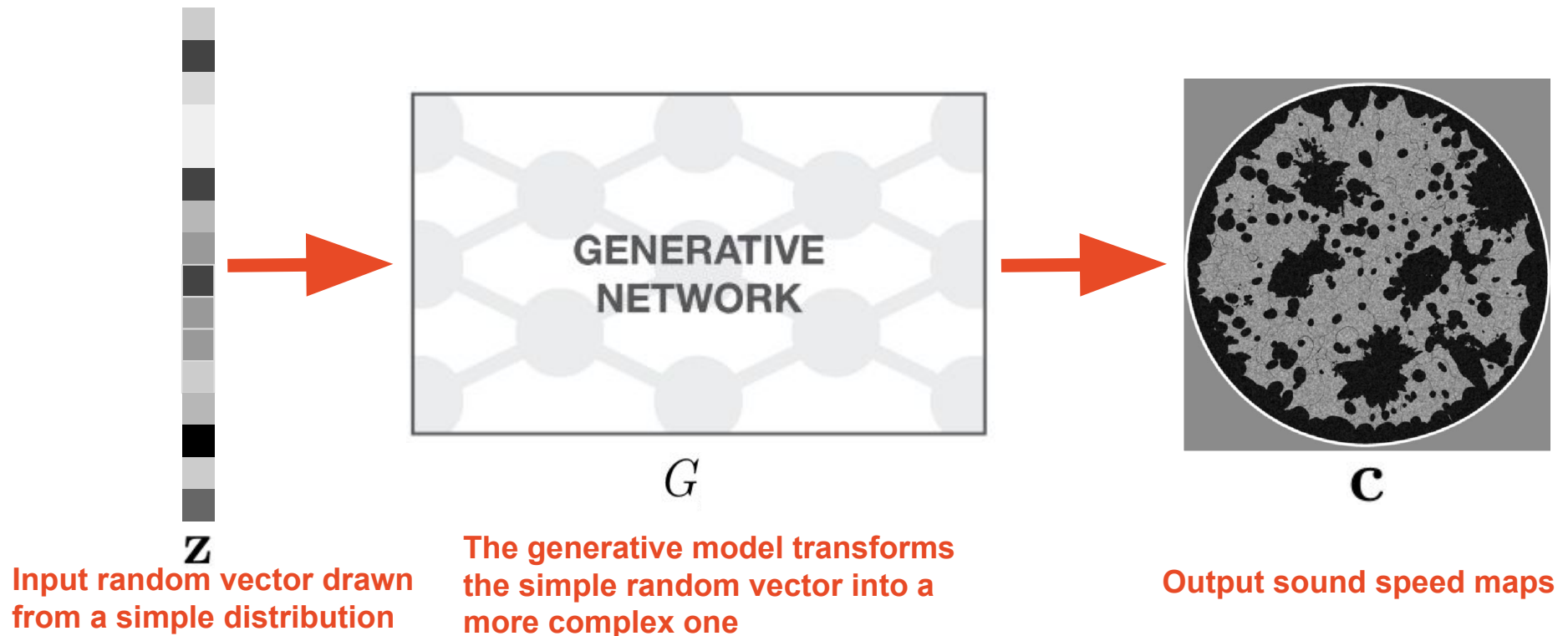
- Stochastic data fidelity term

$$F_s(\mathbf{c}) = \frac{1}{2} \underbrace{\mathbb{E}_{\mathbf{e}}}_{\text{Expectation over } \mathbf{e}} \{ \|\underline{\mathbf{g}}^{\mathbf{e}} - \mathbf{M}\mathbf{H}(\mathbf{c})\mathbf{s}^{\mathbf{e}}\|^2 \} = \underbrace{F(\mathbf{c})}_{\text{Deterministic data fidelity}}$$

- Stochastic gradient descent (SGD) algorithm is used
 - One realization of \mathbf{e} at each iteration

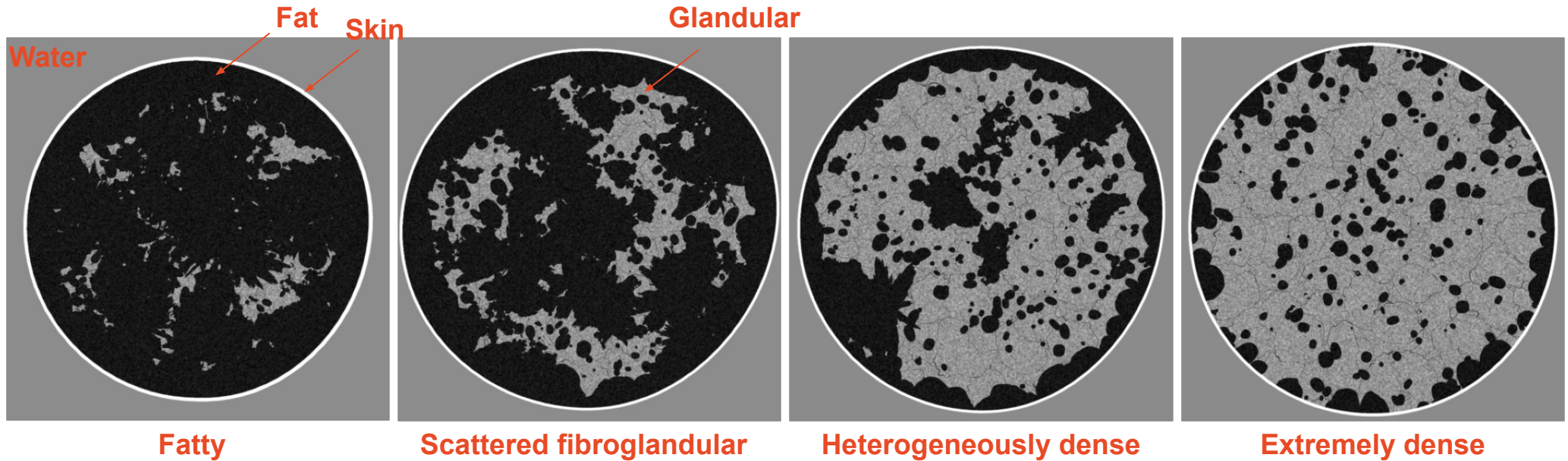
Generative adversarial nets (GANs)

- Generative models based on DNN to represent realistic breast sound speed maps



Generation of training dataset for GAN

- FDA's numerical breast phantoms (NBPs) [Badano *et al.* (2018)]
 - Generation of 3D random numerical phantoms for mammographic studies
 - Breast size, shape, location, density, and extent of different tissues
 - Extension for USCT study [Li *et al.* (2021)]
 - Adjustment of breast shape consistent with a prone imaging position
 - Stochastic assignment of tissue specific acoustic properties
 - Modeling of acoustic heterogeneity within fatty and glandular tissues
- Example of 2D coronal slices of NBPs ('**real**' **samples**, pixel size=0.2mm)



* Dynamic range: [1.42, 1.58] mm/ μ s

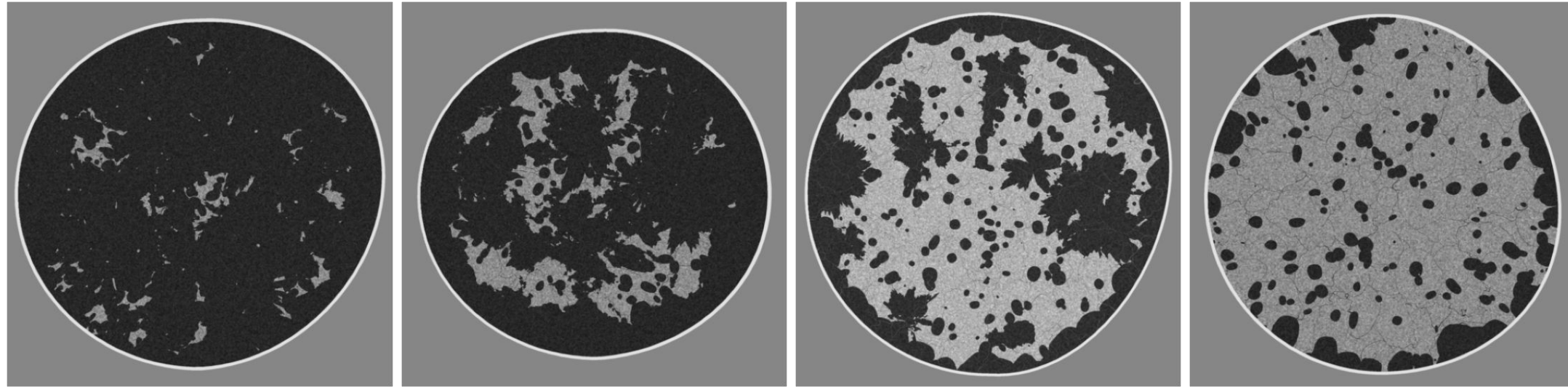
StyleGAN2-based generative model

- One of state-of-art GAN architecture (*StyleGAN2*) was used [Kerras *et al.* (2020)] to represent high-quality NBPs
 - Originally developed to model high-quality human face images
 - High-capacity generator with successive CNN blocks
- *StyleGAN2*-based generator for high-quality NBPs
 - Input random vectors
 - Style vectors \mathcal{W} control overall style of breasts
 - Noise vectors \mathcal{N} control minor changes of features
 - Training dataset: 33,000 2D coronal slices from 1,800 3D NBPs
 - Generated breast sound speed map: $\mathbf{c} = G(\mathcal{W}, \mathcal{N})$

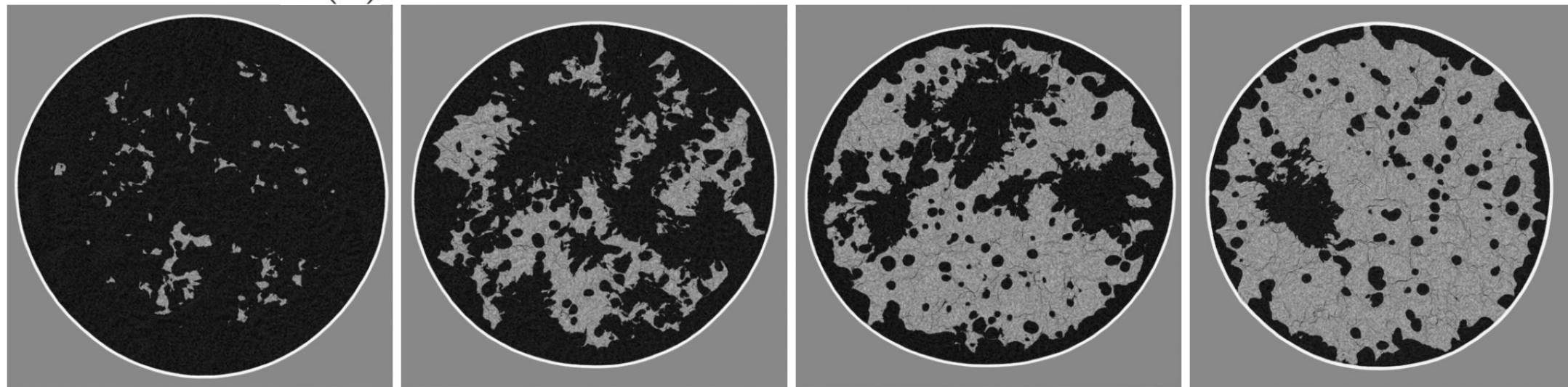
Visual comparison between 'real' and 'fake' samples

- Examples of 'real' and 'fake' breast sound speed maps, $[1.412, 1.58] \text{ mm}/\mu\text{s}$

'real' samples

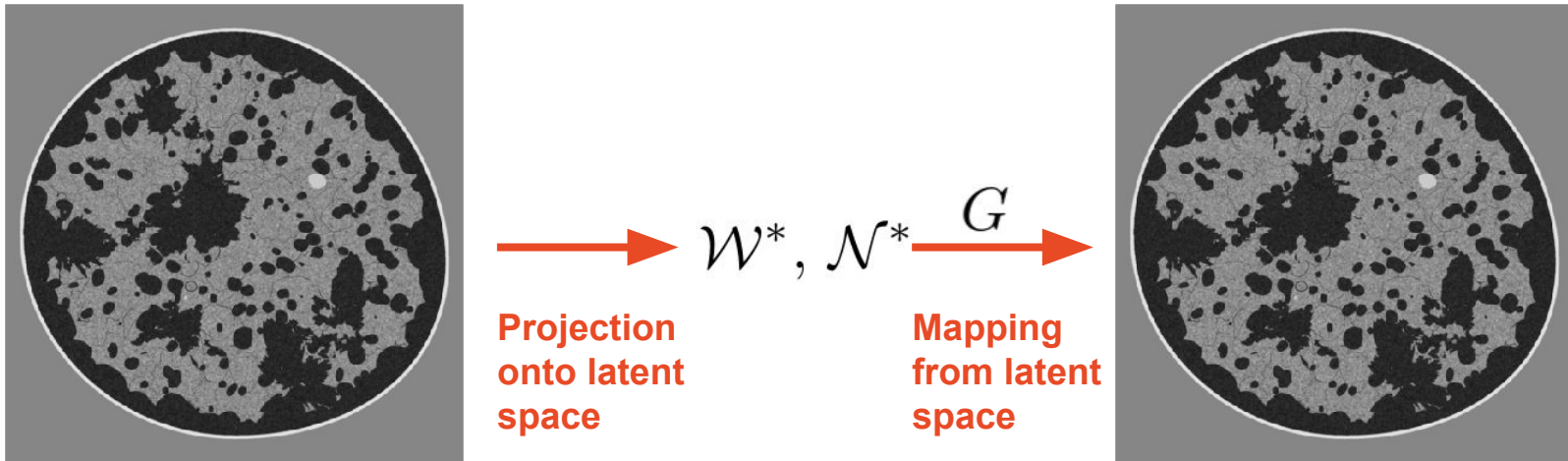


'fake' samples $G(\mathbf{z})$



Evaluation of GAN

- Representation ability of the learnt generative model



A breast sound speed map sampled from 'real' objects distribution

$G(\mathcal{W}^*, \mathcal{N}^*)$ SSIM: 0.99997

- The formulation of the projection problem
$$\mathcal{W}^*, \mathcal{N}^* = \operatorname{argmin}_{\mathcal{W}, \mathcal{N}} \|\mathbf{c} - G(\mathcal{W}, \mathcal{N})\|_2^2$$
- SSIM values evaluated on 150 samples of testing dataset
 - Mean(SSIM): 9.9996E-1
 - Stdev(SSIM): 9.21162E-6

Waveform inversion using GAN-based regularizer

- Data fidelity term with the generative model

$$F_s(G(\mathcal{W}, \mathcal{N})) = \frac{1}{2} \mathbb{E}_{\mathbf{e}} \{ \|\underline{\mathbf{g}}^{\mathbf{e}} - \mathbf{M}\mathbf{H}(G(\mathcal{W}, \mathcal{N}))\mathbf{s}^{\mathbf{e}}\|^2 \}$$

- The breast sound speed map \mathbf{c} is replaced with $G(\mathcal{W}, \mathcal{N})$
- Highly nonlinear and nonconvex

- The formulation of a minimization problem

$$\hat{\mathcal{W}}, \hat{\mathcal{N}} = \underset{\mathcal{W}, \mathcal{N}}{\operatorname{argmin}} F_s(G(\mathcal{W}, \mathcal{N}))$$

- The final estimate $\hat{\mathbf{c}} = G(\hat{\mathcal{W}}, \hat{\mathcal{N}})$

- The optimization process

- SGD update formula based on the chain rule

$$\mathcal{W}_{k+1} = \mathcal{W}_k - \beta_k \{ \nabla_{\mathbf{c}} f(\mathbf{c}_k, \mathbf{e}_k) \nabla_{\mathcal{W}} G(\mathcal{W}_k, \mathcal{N}_k) \}$$

$$\mathcal{N}_{k+1} = \mathcal{N}_k - \beta_k \{ \nabla_{\mathbf{c}} f(\mathbf{c}_k, \mathbf{e}_k) \nabla_{\mathcal{N}} G(\mathcal{W}_k, \mathcal{N}_k) \}$$

Numerical study

- Sparse view USCT data, forward modeling, and reconstruction

Simulation of pressure measurement data

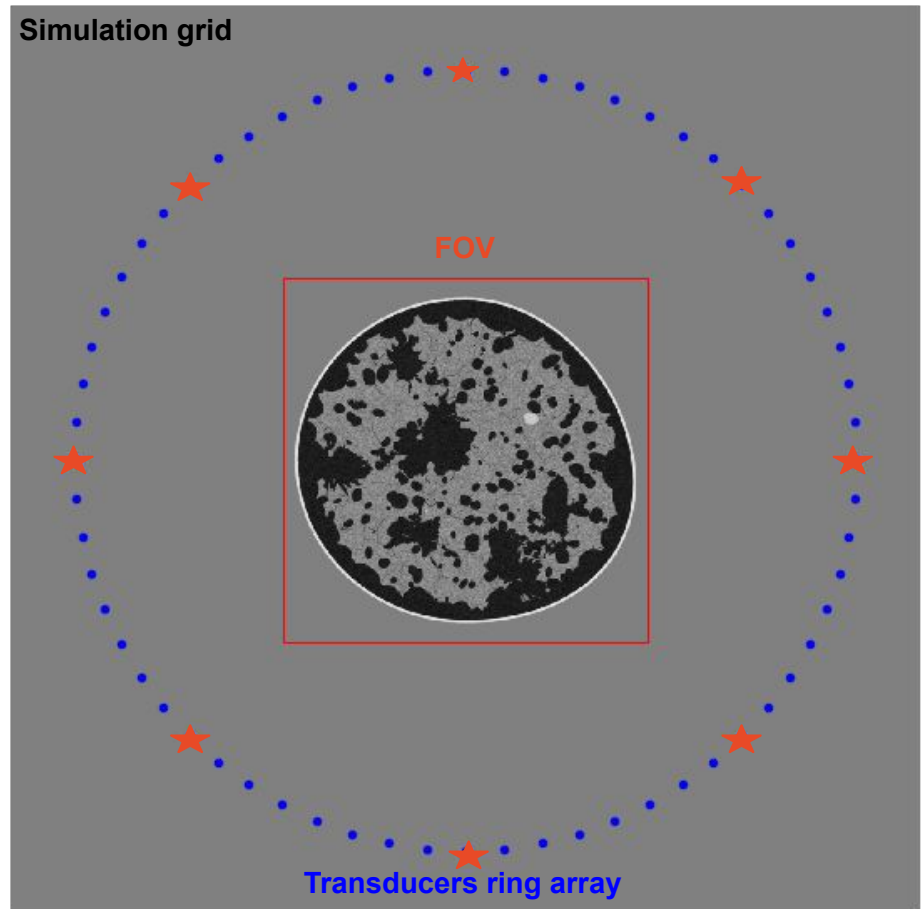
- Grid points: 1280 X 1280
- Pixel size: 0.2 mm (256 X 256 mm)
- Number of time points: 4250
- Time step: 0.04 μ s
- No measurement noise

Transducers

- Pointwise type
- Number of emitters and receivers: 8, 64
⇒ **less than common USCT setting**
- Radius of transducer array: 110 mm

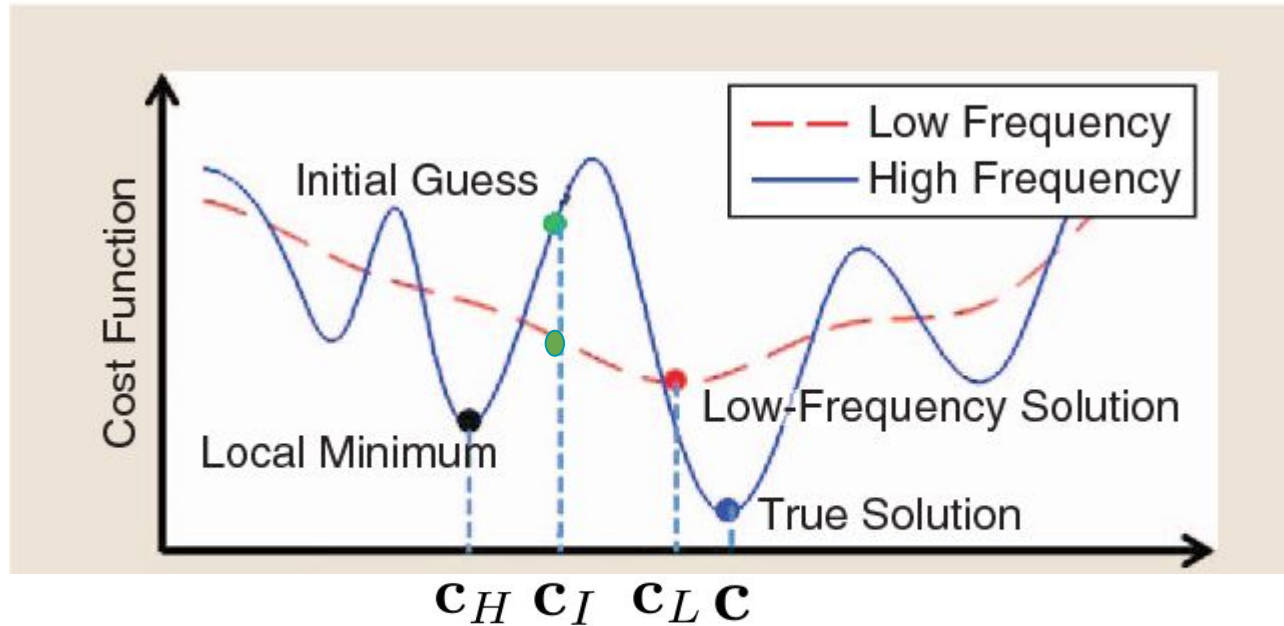
Reconstruction

- Same discretization parameters as those used to generate data (**Inverse crime setting**)
- FOV: 512 X 512 (102.4 X 102.4 mm)



Inversion strategy

- Nonlinearity and nonconvexity of the cost function [Hu et al. (2017)]



- Due to cycle-skipping phenomena
- Even worse due to the nonlinearity of the generative model

- Inversion strategy

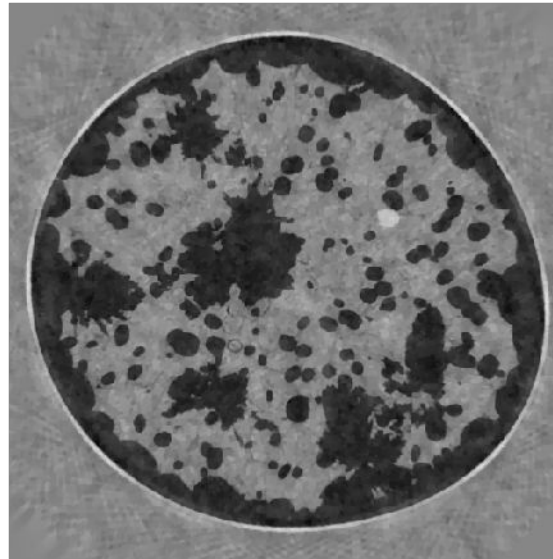
Step 1. Low-frequency waveform inversion

Step 2. Full-frequency waveform inversion

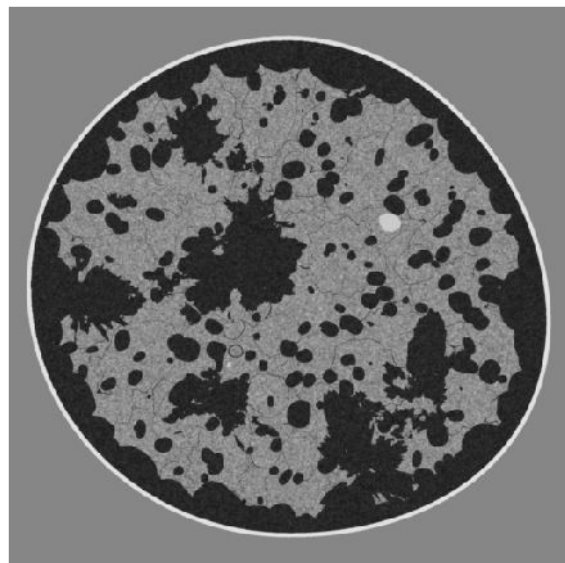
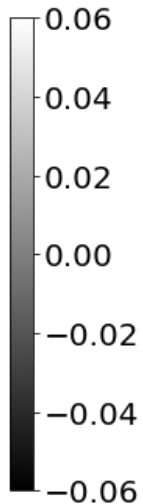
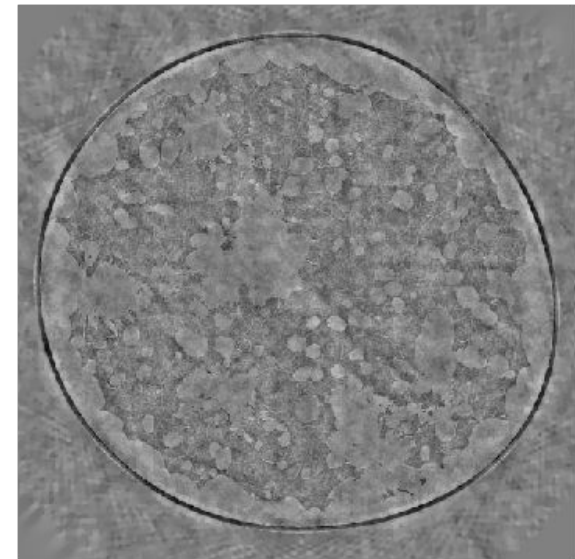
Numerical study

- Waveform inversion results from sparse views, $[1.42, 1.58]$ (mm/ μ s)

Standard waveform
inversion with TV

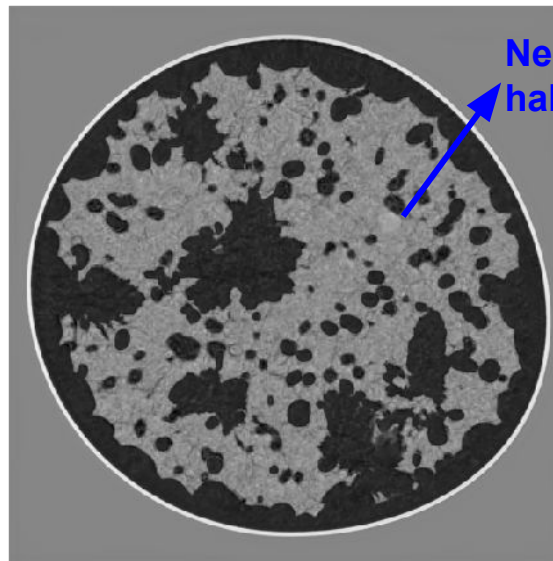


Estimate w/ TV regularization
SSIM: 0.7108

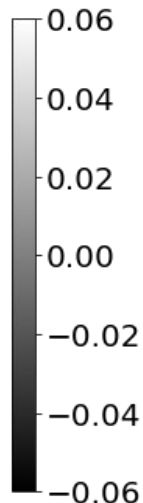
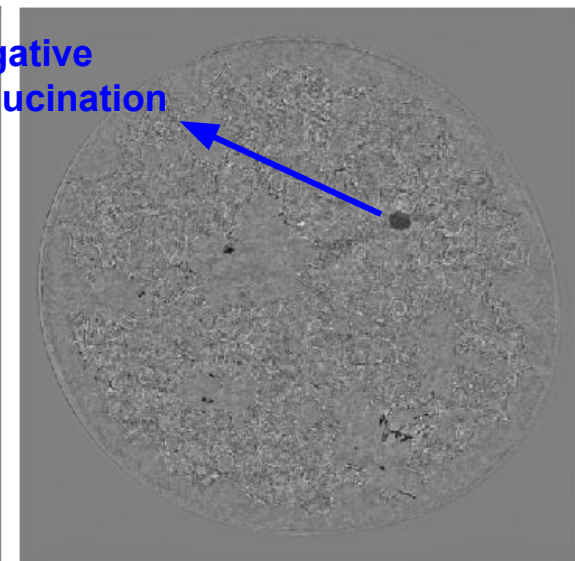


True sound speed map

GAN-based waveform
inversion



Estimate w/ GAN-based regularization
SSIM: 0.8293



Negative
hallucination

Conclusions and future work

1. Waveform inversion is a method to reconstruct quantitatively accurate breast sound speed map
2. However, classic regularization method may not be sufficient to compensate ill-posedness
3. Generative models can successfully model the distribution of realistic breast sound speed maps
4. This preliminary study suggests that the waveform inversion method with the data-driven regularizer may be a better alternative to the classic regularizer (e.g., TV) when the measurement data is extremely sparse.
5. However, there may be possibility of bad hallucinations for performing detection tasks.

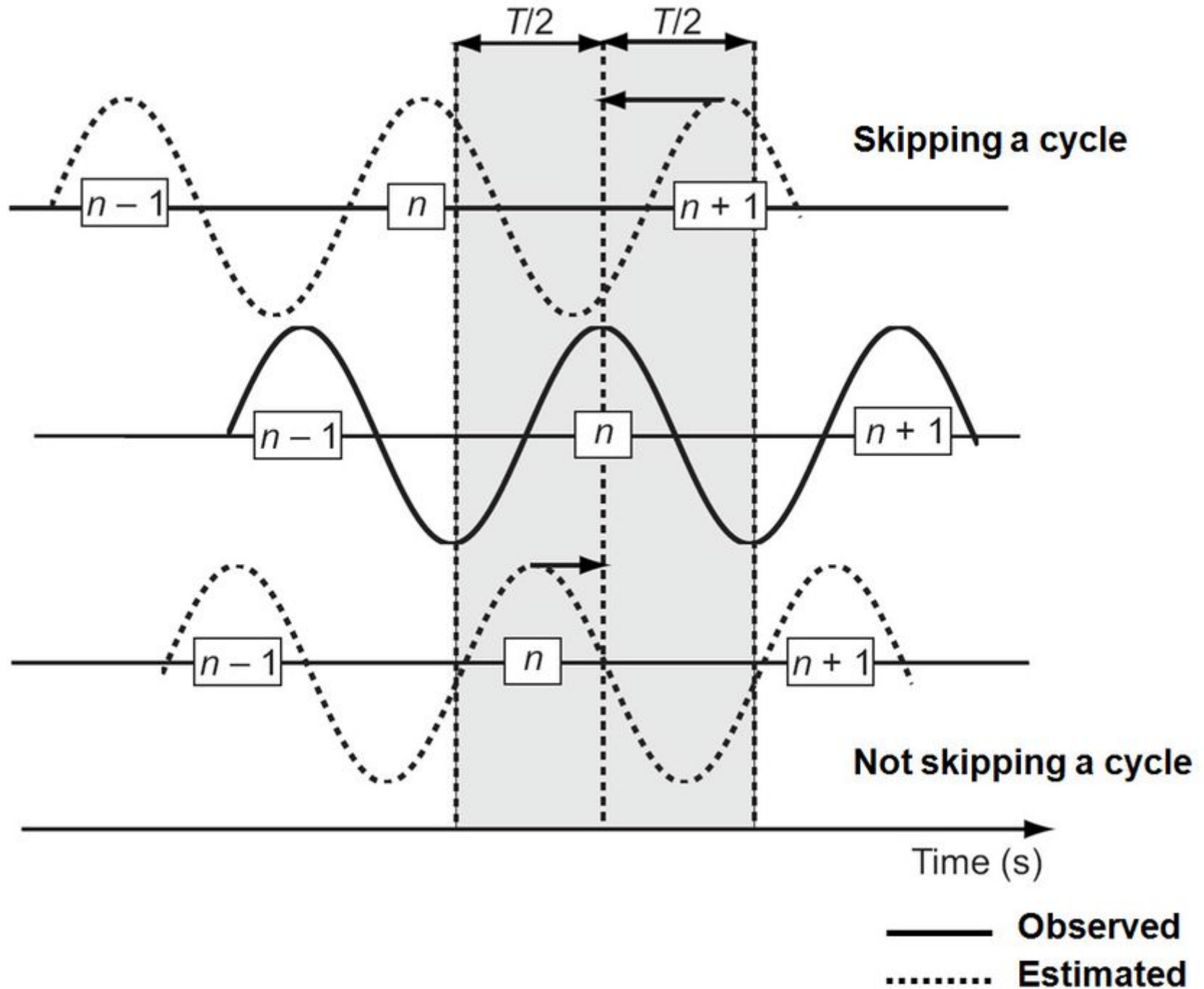
Future work: Systematic analyses for other sparse view settings, noisy measurements, and model mismatch

References

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Thank you

Cycle-skipping phenomena



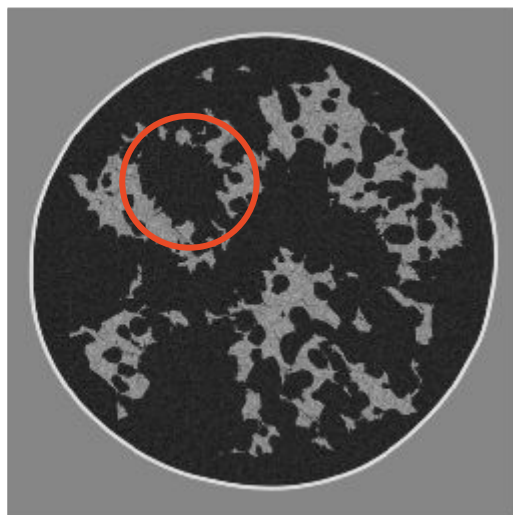
Generated NBPs using StyleGAN2

\mathcal{W} : style latent vectors
 \mathcal{N} : noise latent vectors

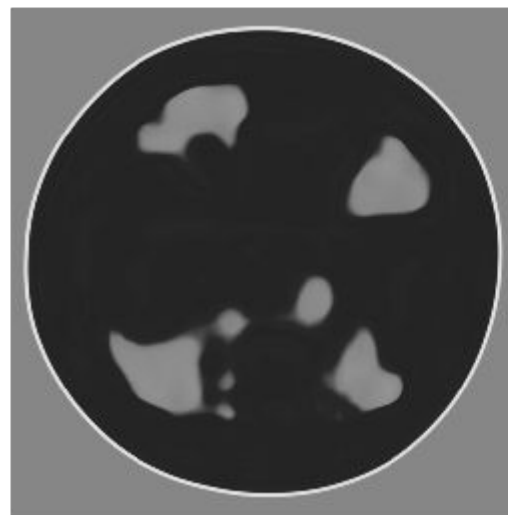
- Different style vectors with the same noise vectors



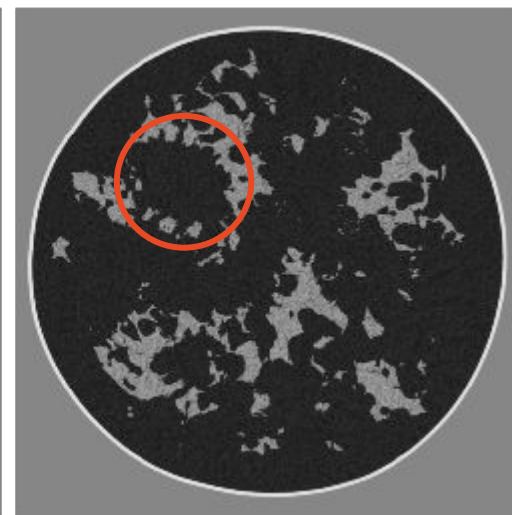
$G(\mathcal{W}_1, \mathbf{0})$



$G(\mathcal{W}_1, \mathcal{N}_1)$



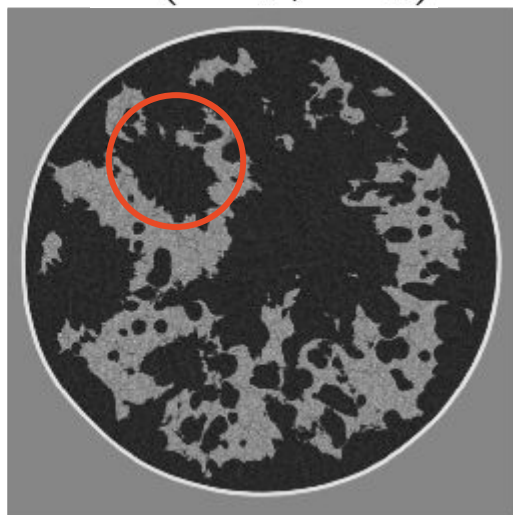
$G(\mathcal{W}_2, \mathbf{0})$



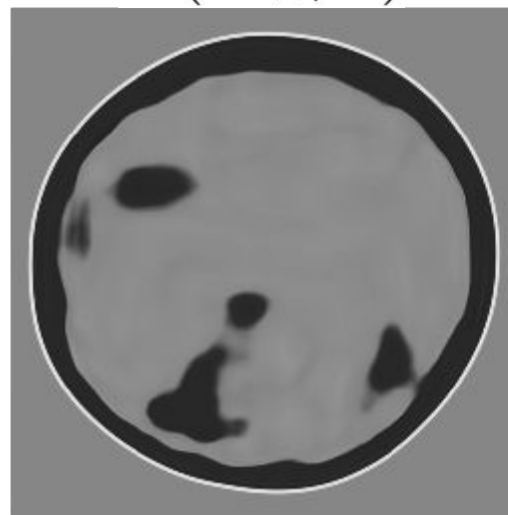
$G(\mathcal{W}_2, \mathcal{N}_1)$



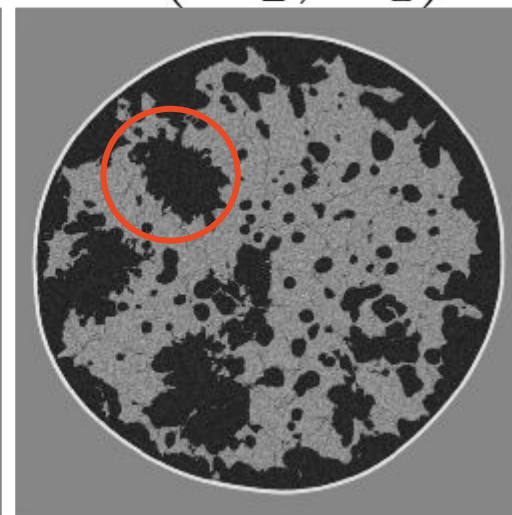
$G(\mathcal{W}_3, \mathbf{0})$



$G(\mathcal{W}_3, \mathcal{N}_1)$



$G(\mathcal{W}_4, \mathbf{0})$

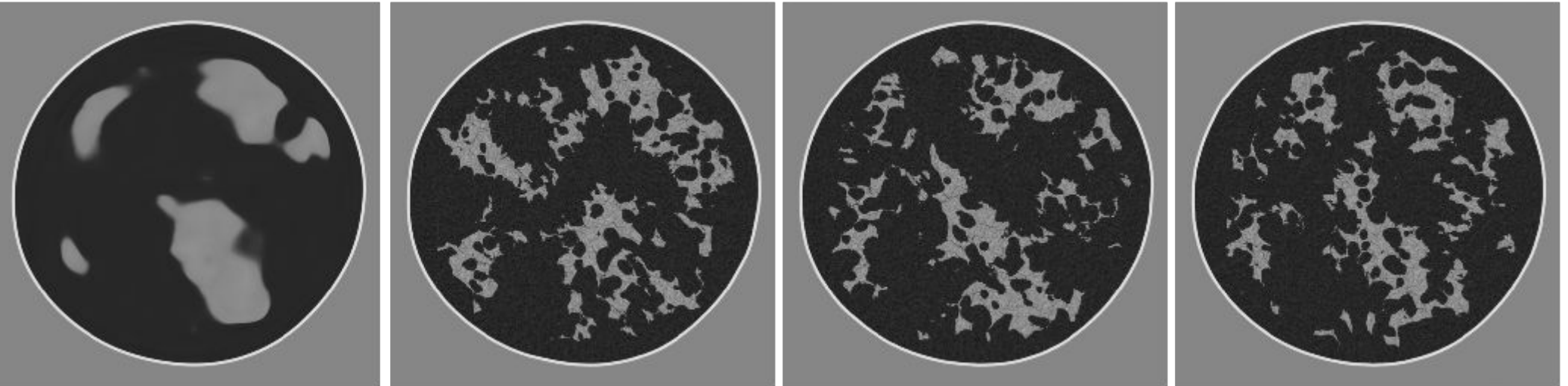


$G(\mathcal{W}_4, \mathcal{N}_1)$

Generated NBPs using StyleGAN2

\mathcal{W} : style latent vectors
 \mathcal{N} : noise latent vectors

- The same style vectors with the different noise vectors



$G(\mathcal{W}_1, \mathbf{0})$

$G(\mathcal{W}_1, \mathcal{N}_1)$

$G(\mathcal{W}_1, \mathcal{N}_2)$

$G(\mathcal{W}_1, \mathcal{N}_3)$

- Style vectors determine
 - The breast size, shape, location, concentration of density, ...
- Noise vectors determine
 - The details of fat, glandular, ligaments, vein, heterogeneous texture, ...