Q1:

$$1. \mathbf{x} + \mathbf{y} = \begin{pmatrix} 2 \\ 6 \\ 1 \\ 4 \\ 1 + 5i \end{pmatrix}$$

2. 
$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^{\dagger} * \mathbf{y} = \begin{pmatrix} 1 & 2 & 3 & 4 & -5i \end{pmatrix} * \begin{pmatrix} 1 & 4 \\ -2 & 0 \\ 1 \end{pmatrix}$$
  
=  $1 \times 1 + 2 \times 4 - 3 \times 2 + 0 - 1 \times 5i = 3 - 5i$ 

3. 
$$\mathbf{y}^{\dagger}\mathbf{x} = \begin{pmatrix} 1 & 4 & -2 & 0 & 1 \end{pmatrix} * \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5i \end{pmatrix} = 1 \times 1 + 4 \times 2 - 2 \times 3 + 0 + 5i = 3 + 5i$$

$$4. \mathbf{x} \circ \mathbf{y} = \begin{pmatrix} 1 \times 1 \\ 2 \times 4 \\ 3 \times -2 \\ 4 \times 0 \\ 5i \times 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 8 \\ -6 \\ 0 \\ 5i \end{pmatrix}$$

5. 
$$\mathbf{x}\mathbf{y}^{\dagger} = \begin{pmatrix} 1\\2\\3\\4\\5i \end{pmatrix} * \begin{pmatrix} 1&4&-2&0&1\\2*\begin{pmatrix}1*\begin{pmatrix}1&4&-2&0&1\\2*\begin{pmatrix}1&4&-2&0&1\\3*\begin{pmatrix}1&4&-2&0&1\\3*\begin{pmatrix}1&4&-2&0&1\\3*\begin{pmatrix}1&4&-2&0&1\\3*\begin{pmatrix}1&4&-2&0&1\\2&8&-4&0&2\\3&12&-6&0&3\\4&16&-8&0&4\\5i&20i&-10i&0&5i \end{pmatrix}$$

6. Because  $\mathbf{x}\mathbf{y}^{\dagger}$  is the linear combination of  $\mathbf{y}^{\dagger}$  and  $\mathbf{y}^{\dagger}$  is a real matrix, so  $\mathbf{y}^{\dagger} = \mathbf{y}^{\mathbf{T}}$  and  $Rank(xy^{\dagger}) = Rank(y^{\dagger}) = Rank(y^{T}) = Rank(y) = 1$ 

**Q2**:

1. 
$$\|\mathbf{x}\|_2 = \left(\sum_{i,j=1}^n |x_{i,j}|\right)^{\frac{1}{2}} = \sqrt{1^2 + 2^2 + 3^2 + 4^2 + |5i^2|} = \sqrt{55} = 7.4162$$

2. 
$$\|\mathbf{x}\mathbf{y}^{\dagger}\| = \sqrt{1210} = 34.7851$$
  
In MATLAB, use  $norm(x, 2)$ 

## Q3

1. For **A**,

$$det(\mathbf{A}) = 1 * \begin{vmatrix} 1 & 2 & 4 \\ 2 & 1 & 3 \\ 4 & 3 & 1 \end{vmatrix} - (-1) * \begin{vmatrix} -1 & 2 & 4 \\ 0 & 1 & 3 \\ i & 3 & 1 \end{vmatrix} + 0 * \begin{vmatrix} -1 & 1 & 4 \\ 0 & 2 & 3 \\ i & 4 & 1 \end{vmatrix} - (-i) * \begin{vmatrix} -1 & 1 & 2 \\ 0 & 2 & 1 \\ i & 4 & 3 \end{vmatrix}$$
$$= 20 + 8 + 2i + 3 - 2i = 31 > 0$$

Because  $det(\mathbf{A}) > 0$ , **A** is the full-rank matrix.  $Rank(\mathbf{A}) = 4$ 

For any matrix  $\mathbf{x}$ ,  $Rank(\mathbf{x}) + nullity(\mathbf{x}) = n$ , so the dimension of  $\mathbf{x}$ 's null space is:

$$nullity(\mathbf{A}) = 4 - Rank(\mathbf{A}) = 0$$

2. For **B**,

$$\mathbf{B} = \begin{pmatrix} 1 & 4 & 3 \\ 2 & 3 & 1 \\ 3 & 2 & -1 \end{pmatrix} \stackrel{rref}{=} \begin{pmatrix} 1 & 4 & 3 \\ 0 & -5 & -5 \\ 0 & 0 & 0 \end{pmatrix}$$

 $Rank(\mathbf{B}) = 2$ 

$$nullity(\mathbf{B}) = 3 - 2 = 1$$

3. For **C**,

$$\mathbf{C} = \begin{pmatrix} 2 & 3 \\ -3 & 0.5 \end{pmatrix} \stackrel{rref}{=} \begin{pmatrix} 2 & 3 \\ 0 & 5 \end{pmatrix}$$

$$Rank(\mathbf{C}) = 2$$

$$nullity(\mathbf{C}) = 2 - 2 = 0$$

$$det(\mathbf{C}) = \begin{vmatrix} 2 & 3 \\ -3 & 0.5 \end{vmatrix} = 1 - (-9) = 10$$

$$\mathbf{C}^{-1} = \frac{1}{\det(\mathbf{C})} \begin{pmatrix} 0.5 & -3 \\ 3 & 2 \end{pmatrix} = \begin{pmatrix} 0.05 & -0.3 \\ 0.3 & 0.2 \end{pmatrix}$$

$$\mathbf{C} + \mathbf{C}^T = \begin{pmatrix} 2 & 3 \\ -3 & 0.5 \end{pmatrix} + \begin{pmatrix} 2 & -3 \\ 3 & 0.5 \end{pmatrix} = \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix}$$

eigenvalues of  $\mathbf{C} + \mathbf{C}^T$  is  $\lambda_1 = 4, \lambda_2 = 1$ 

$$\mathbf{C} - \mathbf{C}^T = \begin{pmatrix} 2 & 3 \\ -3 & 0.5 \end{pmatrix} - \begin{pmatrix} 2 & -3 \\ 3 & 0.5 \end{pmatrix} = \begin{pmatrix} 0 & 6 \\ -6 & 0 \end{pmatrix}$$

eigenvalues of  $\mathbf{C} - \mathbf{C}^T$  is  $\lambda_1 = 6i, \lambda_2 = -6i$ 

## **Q4**:

1. First, calculate the inverse of  $\mathbf{A}\mathbf{A}^T$ :

$$\mathbf{A}\mathbf{A}^{T} = \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & -2 \end{pmatrix} * \begin{pmatrix} 1 & 2 \\ 0 & -1 \\ 3 & -2 \end{pmatrix} = \begin{pmatrix} 10 & -4 \\ -4 & 9 \end{pmatrix} \Longrightarrow (\mathbf{A}\mathbf{A}^{T})^{-1} = inv(\mathbf{A}\mathbf{A}) = \frac{1}{74} \begin{pmatrix} 9 & 4 \\ 4 & 10 \end{pmatrix} = \begin{pmatrix} 0.1216 & 0.0541 \\ 0.0541 & 0.1351 \end{pmatrix}$$
Then 
$$\mathbf{A}^{T}(\mathbf{A}\mathbf{A}^{T})^{-1} = \begin{pmatrix} 1 & 2 \\ 0 & -1 \\ 3 & -2 \end{pmatrix} * \begin{pmatrix} 9 & 4 \\ 4 & 10 \end{pmatrix} = \begin{pmatrix} 0.2297 & 0.3243 \\ -0.0541 & -0.1351 \\ 0.2568 & -0.1081 \end{pmatrix}$$

2. 
$$\mathbf{A}\mathbf{A}^+ = \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & -2 \end{pmatrix} * \begin{pmatrix} 0.2297 & 0.3243 \\ -0.0541 & -0.1351 \\ 0.2568 & -0.1081 \end{pmatrix} = I_2$$
. So its dimension is 2.

3. 
$$\mathbf{A}^{+}\mathbf{A} = \begin{pmatrix} 0.2297 & 0.3243 \\ -0.0541 & -0.1351 \\ 0.2568 & -0.1081 \end{pmatrix} * \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & -2 \end{pmatrix} = \begin{pmatrix} 0.8784 & -0.3243 & 0.0405 \\ -0.3243 & 0.1351 & 0.1081 \\ 0.0405 & 0.1081 & 0.9865 \end{pmatrix}$$

$$\stackrel{rref}{=} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}. \text{ Its dimension is } 3 \times 2.$$

**Q5**:

 $\mathbf{ABC}(\mathbf{ABC})^{\mathbf{T}} = \mathbf{I} \Longrightarrow \mathbf{ABC} = (.)_{M \times Q}$  is semi-orthogonal if M < Q or orthogonal if M = Q. So when  $\mathbf{A}, \mathbf{B}, \mathbf{C}$  are semi-orthogonal so that  $\mathbf{AA^T} = \mathbf{I_M}; \mathbf{BB^T} = \mathbf{I_N};$   $\mathbf{CC^T} = \mathbf{I_P}$  if M < N, N < P, P < Q or orthogonal so that  $\mathbf{AA^T} = \mathbf{BB^T} = \mathbf{CC^T} = \mathbf{I_M}$  if M = N = P = Q, then:

 $\mathbf{ABC}(\mathbf{ABC})^{\mathbf{T}} = \mathbf{AB}(\mathbf{CC^T})\mathbf{B^TA^T} = \mathbf{A}(\mathbf{BI_PB^T})\mathbf{A^T} = \mathbf{AI_NA^T} = \mathbf{I_M}$  So its dim(.) = M

Q6:

$$\mathbf{A}\mathbf{A}^{\dagger} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1+i & 1-i & 1+i \\ 1-i & 1+i & 1-i \\ 1+i & 1-i & 1+i \end{pmatrix} * \frac{1}{\sqrt{2}} \begin{pmatrix} 1-i & 1+i & 1-i \\ 1+i & 1-i & 1+i \\ 1-i & 1+i & 1-i \end{pmatrix} = \begin{pmatrix} 3 & 0 & 3 \\ 0 & 2 & 0 \\ 3 & 0 & 3 \end{pmatrix}$$

$$\mathbf{B}\mathbf{B}^{\mathbf{T}} = \mathbf{B} * \mathbf{B} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{C}\mathbf{C}^{\mathbf{T}} = \frac{1}{3} \begin{pmatrix} 1 & 2 & 2 \\ -2 & -1 & 2 \\ 2 & -2 & 1 \end{pmatrix} * \frac{1}{3} \begin{pmatrix} 1 & -2 & 2 \\ 2 & -1 & -2 \\ 2 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Because **B** is a symmetric matrix,  $\mathbf{B} = \mathbf{B^T} \Longrightarrow \mathbf{BB^T} = \mathbf{BB} = \mathbf{B^2}$ 

**A** is not a Hermitian matrix, not conjugate symmetric, therefore  $\mathbf{A}\mathbf{A}^{\dagger} \neq \mathbf{A}^{2}$ . **C** is not a symmetric matrix, therefore  $\mathbf{C}\mathbf{C}^{T} \neq \mathbf{C}^{2}$ .

$$\begin{aligned} &\mathbf{Q7:} \\ &\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} = e^{-\frac{1}{2}\mathbf{x^T}\mathbf{K^{-1}x}} * \left(-\frac{1}{2}\mathbf{x^T}\mathbf{K^{-1}x}\right)' = e^{-\frac{1}{2}\mathbf{x^T}\mathbf{K^{-1}x}} * -\frac{1}{2}(2\mathbf{K^{-1}x}) = e^{-\frac{1}{2}\mathbf{x^T}\mathbf{K^{-1}x}}\mathbf{K^{-1}x} \end{aligned}$$

As for its dimension, 
$$\mathbf{K}^{-1}\mathbf{x} = (.)_{N\times 1}$$
 and  $\mathbf{x}^{\mathbf{T}}\mathbf{K}^{-1}\mathbf{x} = (.)_{1\times 1}$   
 $\Longrightarrow dim(\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}}) = dim(\mathbf{K}^{-1}\mathbf{x}) = N \times 1$ 

**Q8**:

For  $\mathbf{A}$ ,  $det(\mathbf{A} - \lambda I) = 0 \Longrightarrow eig(A)$  in MATLAB: Then its eignevalues are:  $\lambda_1 = 11.0632, \lambda_2 = 2.922, \lambda_3 = -0.9791 + 0.3559i, \lambda_4 = -0.9791 - 0.3559i$ A's corresponding diagonal matrix D is:

$$\mathbf{D} = \begin{pmatrix} 11.0632 \\ 2.922 \\ -0.9791 + 0.3559i \\ -0.9791 - 0.3559i \end{pmatrix}$$
The corresponding possingular matrix  $\mathbf{A}$  (via  $[\mathbf{A}, \mathbf{D}] = \mathbf{eig}(\mathbf{A})$ 

The corresponding nonsingular matrix  $\Lambda$  (via  $[\Lambda, \mathbf{D}] = \mathbf{eig}(\mathbf{A})$ ):

$$\Lambda = \begin{pmatrix}
-0.5140 & 0.5688 & 0.5378 + 0.0107i & 0.5378 - 0.0107i \\
-0.3665 & -0.7124 & 0.4333 - 0.1353i & 0.4333 + 0.1353i \\
-0.5291 & 0.2034 & -0.6356 & -0.6356 \\
-0.5671 & -0.3573 & -0.2862 + 0.1366i & -0.2862 - 0.1366i
\end{pmatrix}$$

so that  $\Lambda D \Lambda^{-1} = 1$ 

For **B**, same operation as **A**, then its eigenvalues are:

$$\lambda_1 = -2.1487, \lambda_2 = 0.0770, \lambda_3 = 4.3554, \lambda_4 = 9.7164$$

 $\mathbf{B}$ 's diagonal matrix  $\mathbf{D}$  is:

$$\mathbf{D} = \begin{pmatrix} -2.1487 & & & \\ & 0.0770 & & \\ & & 4.3554 & \\ & & & 9.7164 \end{pmatrix}$$

$$\mathbf{D} = \begin{pmatrix} -2.1487 \\ 0.0770 \\ 4.3554 \end{pmatrix}$$
 and corresponding nonsingular matrix  $\mathbf{\Lambda} = \begin{pmatrix} 0.2041 & 0.6932 & -0.3318 & 0.6064 \\ 0.6640 & -0.2284 & 0.6081 & 0.3704 \\ -0.1256 & -0.6754 & -0.4595 & 0.5630 \\ -0.7083 & 0.1054 & 0.5559 & 0.4221 \end{pmatrix}$ 

Before calculating the eigenvalues, its easy to predict **B** has real eignevalues, since its a real symmetric matrix.

**Proof:** B is a real symmetric matrix, so  $\mathbf{B} = \mathbf{B^T} = \bar{\mathbf{B}}$ . Assume  $\lambda$  is a complex eigenvalue and  $\mathbf{x}$  is the complex eigenvector of  $\mathbf{B}$ , and  $\bar{\lambda}$  and  $\bar{\mathbf{x}}$  are the corresponding conjugate complex and conjugate vector, then we have

$$\mathbf{B}\bar{\mathbf{x}} = \bar{\mathbf{B}}\bar{\mathbf{x}} = (\bar{\mathbf{B}}\mathbf{x}) = (\bar{\lambda}\mathbf{x}) = \bar{\lambda}\bar{\mathbf{x}}$$

$$\bar{\mathbf{x}}^{\mathbf{T}}\mathbf{B}\mathbf{x} = \bar{\mathbf{x}}^{\mathbf{T}}(\mathbf{B}\mathbf{x}) = \bar{\mathbf{x}}^{\mathbf{T}}\lambda\mathbf{x} = \lambda\bar{\mathbf{x}}^{\mathbf{T}}\mathbf{x}$$
(1)

$$\bar{\mathbf{x}}^{\mathrm{T}}\mathbf{B}\mathbf{x} = (\mathbf{x}^{\mathrm{T}}\mathbf{B}^{\mathrm{T}})\mathbf{x} = (\mathbf{B}\bar{\mathbf{x}})^{\mathrm{T}}\mathbf{x} = (\bar{\lambda}\bar{\mathbf{x}})^{\mathrm{T}}\mathbf{x} = \bar{\lambda}\bar{\mathbf{x}}^{\mathrm{T}}\mathbf{x}$$
 (2)

Let (1)-(2), we get  $(\lambda - \bar{\lambda})\bar{\mathbf{x}}^{\mathbf{T}}\mathbf{x} = 0$ . Since  $\mathbf{x}$  is not  $0, \lambda = \bar{\lambda}$ . Therefore,  $\lambda$  is real.

As for A, the characteristic polynomials format of its eigenvalues is  $det(\mathbf{A} - \lambda \mathbf{E}) =$  $x^4 - 12x^3 + 6x^2 + 48x + 35 = 0$ . According to **Descartes' rule of signs**, we could get the number of positive and negative real roots in a polynomial. Let  $f(x) = x^4 - 12x^3 + 6x^2 + 48x + 35$  and  $f(-x) = x^4 + 12x^3 + 6x^2 - 48x + 35$ , there are both 2 sign changes, indicating 2 or 0 positive roots and 2 or 0 negative roots.

Therefore,  $number of complex roots = n - p - q \ge 0$ , where n is the degree of polynomials (here is 4), and p and q are the number of positive and negataive roots respectively. It's high likely that  $\mathbf{A}$  has complex roots.

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 2 & 2 \\ 1 & 3 & 3 & 2 \\ 3 & 1 & 3 & 2 \\ 2 & 6 & 6 & 4 \end{pmatrix} \stackrel{rref}{=} \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

After adding the noise 
$$\mathbf{N} = \begin{pmatrix} -0.0065 & -0.0085 & -0.0020 & -0.0151 \\ 0.0118 & -0.0057 & 0.0059 & 0.0088 \\ -0.0076 & -0.0056 & -0.0085 & -0.0024 \\ -0.0111 & 0.0018 & 0.0080 & 0.0017 \end{pmatrix}$$
, the bottom row of  $\mathbf{A}$  would be no longer 0. Since the noise row is less likely to be a linear

row of **A** would be no longer 0. Since the noise row is less likely to be a linear combination of previous 3 rows, making the noised matrix  $\mathbf{A} + N$  full rank, which means the inverse matrix exists.

However, because the noise only adds trivial value to original matrix, its eigenvalues changes little. The eigenvalues of  $\bf A$  and eigenvalues of  $\bf A + \bf N$  are:

$$\mathbf{vec}_{\lambda 1} = \begin{pmatrix} 10.5625 \\ 0.2188 + 0.5752i \\ 0.2188 - 0.5752i \\ 0.0000 \end{pmatrix}, \quad \mathbf{vec}_{\lambda 2} = \begin{pmatrix} 10.5552 \\ 0.1969 + 0.5579i \\ 0.1969 - 0.5579i \\ 0.0320 \end{pmatrix}$$

$$\Delta \mathbf{vec}_{\lambda} = \mathbf{vec}_{\lambda 1} - \mathbf{vec}_{\lambda 2} = \begin{pmatrix} 0.0219 + 0.0173i \\ 0.0219 - 0.0173i \\ -0.0320 \end{pmatrix} \text{ and } mean(\Delta \mathbf{vec}_{\lambda}) = 0.0048$$

We can see that the eigenvalues doesn't change a lot when  $\alpha=0.01$ . If the  $\alpha$  increase, the eigenvalues also change more and vice versa, as the following image shows.

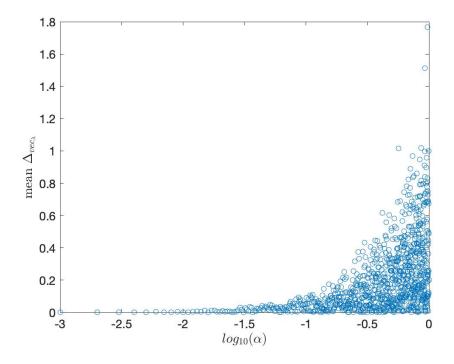


Figure 1: **A**'s eigenvalues change under different noise amplitude  $\alpha$ . Not axis y is the  $mean(\Delta_{\mathbf{vec}_{\lambda}})$ ; axis x is the  $log_{10}$  value of  $\alpha$ . We tested  $\alpha$  from 0.001 to 1 with 0.001 as the stride.