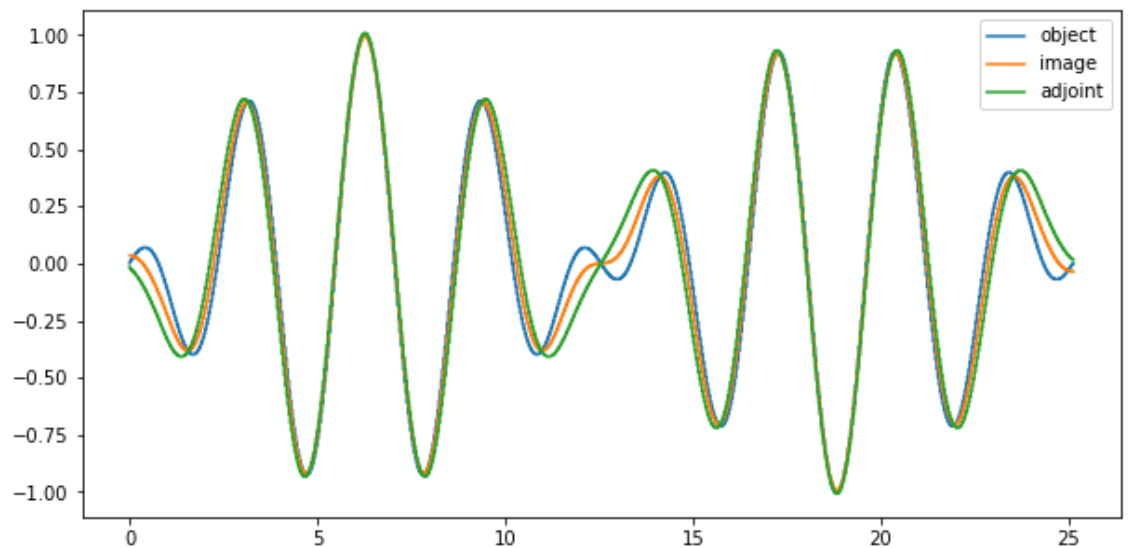


```
In [1]: ▶ 1 import numpy as np
2 import matplotlib.pyplot as plt
3 import skimage.transform as st
4 import imageio
5 import scipy.signal as ss
6
```

```
In [2]: ▶ 1 # Q.1
2 expanded_x = np.linspace(-0.25*np.pi, 8.*np.pi+0.25*np.pi, 851)
3 x = expanded_x[25:826]
4 obj = np.zeros_like(expanded_x)
5 obj[25:826] = np.cos(2.*x)*np.sin(x/4.)
6 kernel = np.ones(51)
7
8 dint= x[1]-x[0]
9
10 ## Hf =
11 img = np.zeros_like(x)
12 for i in range(25,826):
13     for j in range(51):
14         img[i-25] += np.flip(kernel)[j] * obj[i-25+j] * dint
15
16 ## H*g =
17 adj = np.zeros_like(x)
18 eimg = np.zeros_like(expanded_x)
19 eimg[25:826] = img
20 for i in range(25,826):
21     for j in range(51):
22         adj[i-25] += kernel[j] * eimg[i-25+j] *dint
```

```
In [3]: ▶ 1 #Object
2 plt.figure(figsize=(10,5))
3 plt.step(x,obj[25:826])
4 plt.step(x,img)
5 plt.step(x,adj)
6 plt.legend(['object','image','adjoint'])
```

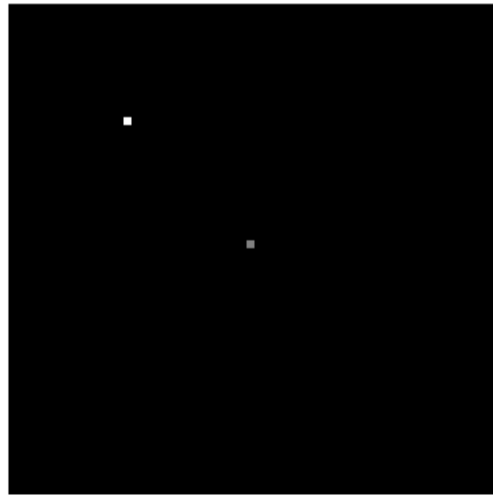
Out[3]: <matplotlib.legend.Legend at 0x7f1c28df77d0>



3

```
In [4]: ▶ 1 #Q.3
2 obj = np.zeros([64,64])
3 obj[31,31] = 64
4 obj[15,15] = 128
5 theta = np.linspace(0,180,256)
6 img = st.radon(obj, theta)
```

```
In [5]: ▶ 1 figure,ax = plt.subplots(2,1,figsize=(10,10))
2 shows = [obj, img]
3 for i in range(2):
4     ax[i].imshow(shows[i],cmap='gray')
5     ax[i].axis('off')
```



```

In [6]: ► 1 # b will be included in c, this is not full description for b
2 import scipy.signal as ssig
3
4 # def width(profile,point):
5 #     profile = profile[point-5:point+14]
6 #     print(len(profile))
7 #     return ssig.peak_widths(profile,[5])# +([point],[point],[p
8 def width(profile,point):
9     return ssig.peak_widths(profile,[point])# +([point],[point],
10
11
12 iradon = st.iradon(img,theta,filter=None)
13 #plt.imshow(iradon,cmap='gray')
14 profile_center = iradon[:,31]
15 profile_corner = iradon[:,15]
16 width_center = width(profile_center,31)
17 width_corner = width(profile_corner,15)
18 print(width_corner)
19 plt.plot(profile_corner)

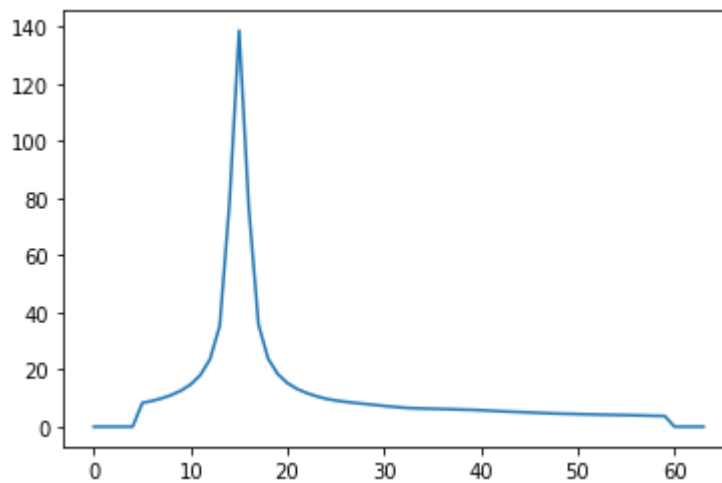
```

```

(array([2.38473877]), array([69.36492032]), array([13.796978]), arr
ay([16.18171677]))

```

Out[6]: [



In [56]:

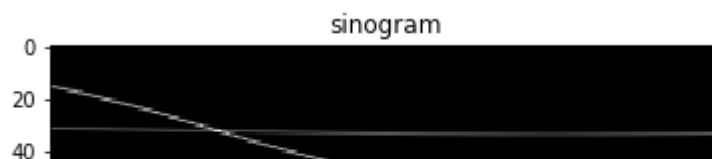
```
1 #c (including b)
2 N= [256,128,64,32,16,8]
3 wct=[]; wcn=[];
4 for n in N:
5     theta = np.linspace(0,180,n)
6     img = st.radon(obj, theta)
7     plt.figure()
8     plt.imshow(img,cmap='gray')
9     plt.title('sinogram')
10    # plt.show()
11
12    # iradon = st.iradon(img,theta,filter=None)
13    iradon = st.iradon(img,theta,filter=None)
14
15    plt.figure()
16    plt.imshow(iradon,cmap='gray')
17    plt.title('BP')
18    # plt.show()
19
20    profile_center = iradon[:,31]
21    width_center = width(profile_center,31)
22    plt.figure()
23    plt.plot(profile_center)
24    plt.plot(31,profile_center[31])
25    plt.hlines(width_center[1], width_center[2], width_center[3]
26
27    profile_corner = iradon[:,15]
28    width_corner = width(profile_corner,15)
29    plt.figure()
30    plt.plot(profile_corner)
31    plt.plot(15,profile_corner[15])
32    plt.hlines(width_corner[1], width_corner[2], width_corner[3]
33    print('N: ',str(n),', peak value at corner:',iradon[15,15],
34
```

e.max_open_warning`).

from ipykernel import kernelapp as app

/home/gangwon/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:22: RuntimeWarning: More than 20 figures have been opened. Figures created through the pyplot interface (`matplotlib.pyplot.figure`) are retained until explicitly closed and may consume too much memory. (To control this warning, see the rcParam `figure.e.max_open_warning`).

/home/gangwon/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:29: RuntimeWarning: More than 20 figures have been opened. Figures created through the pyplot interface (`matplotlib.pyplot.figure`) are retained until explicitly closed and may consume too much memory. (To control this warning, see the rcParam `figure.e.max_open_warning`).



Generally, the width increases as the number of views decreases. By sampling enough, the point to-be-estimated becomes more localized. The values at the points become more deviated as the number of views decreases. Likewise, under-determined system with a few views may yield less accurate solution.

In [59]: ▶

```
1 #d (including b)
2 N= [256,128,64,32,16,8]
3 wct=[]; wcn=[];
4 for n in N:
5     theta = np.linspace(0,180,n)
6     img = st.radon(obj, theta)
7     plt.figure()
8     plt.imshow(img,cmap='gray')
9     plt.title('sinogram')
10    # plt.show()
11
12    # iradon = st.iradon(img,theta,filter=None)
13    iradon = st.iradon(img,theta,filter='ramp')
14
15    plt.figure()
16    plt.imshow(iradon,cmap='gray')
17    plt.title('BP')
18    # plt.show()
19
20    profile_center = iradon[:,31]
21    width_center = width(profile_center,31)
22    plt.figure()
23    plt.plot(profile_center)
24    plt.plot(31,profile_center[31])
25    plt.hlines(width_center[1], width_center[2], width_center[3]
26
27    profile_corner = iradon[:,15]
28    width_corner = width(profile_corner,15)
29    plt.figure()
30    plt.plot(profile_corner)
31    plt.plot(15,profile_corner[15])
32    plt.hlines(width_corner[1], width_corner[2], width_corner[3]
33    print('N: ',str(n),', peak value at corner:',iradon[15,15],',
34
```

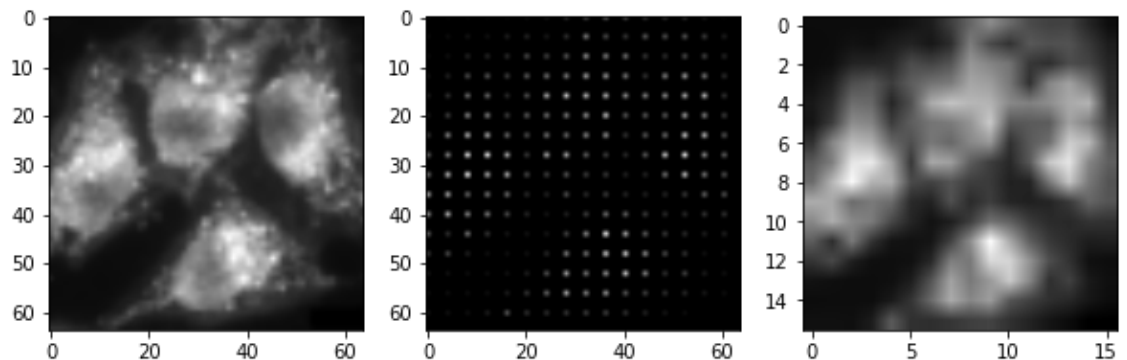
N: 256 , peak value at corner: 55.745188615899785 , peak width at corner: [1.38430638] , peak value at center: 25.93417626126006 , peak width at corner: [1.62446058]
N: 128 , peak value at corner: 56.11857138580631 , peak width at corner: [1.38331912] , peak value at center: 26.000173489126098 , peak width at corner: [1.6212462]
N: 64 , peak value at corner: 55.50480358440926 , peak width at corner: [1.48279811] , peak value at center: 26.16596540040996 , peak width at corner: [1.64747854]
N: 32 , peak value at corner: 60.004825303687475 , peak width at corner: [1.46980989] , peak value at center: 26.377474105320307 , peak width at corner: [1.63426961]
N: 16 , peak value at corner: 59.85050229080789 , peak width at corner: [1.69109141] , peak value at center: 25.825790384774788 , peak width at corner: [1.79947563]
N: 8 , peak value at corner: 65.11349556088027 , peak width at corner: [2.07854235] , peak value at center: 28.749467174723357 , peak width at corner: [1.51434154]

Width are sharper than the backprojection cases for the same number of views because of filtering-effects of ramp function in the freq-domain. The values at the points are diminished because of filtering effect. It should be noted that the point object has lots of low-frequency components. Even though the ramp filter is derived analytically in the inversion process, the filtering-effect may harm significantly the object components that contain low-frequency components.

5

```
In [9]: ▶ 1 #Q. 5
2 f= imageio.imread('../BIOE580_hw01_data/BIOE580_hw01_data/hw01_e
3 # np.shape(f) 64 X 64
4 # a
5 comb = np.zeros([64,64])
6 comb[::4,::4] = 1
7 combf = f * comb
8 obj_d = combf[::4,::4]
9 figure,ax = plt.subplots(1,3,figsize=(10,10))
10 ax[0].imshow(f, cmap='gray', interpolation='bilinear')
11 ax[1].imshow(combf,cmap='gray',interpolation='bilinear')
12 ax[2].imshow(obj_d,cmap='gray',interpolation='bilinear')
```

Out[9]: <matplotlib.image.AxesImage at 0x7f1c28854ed0>



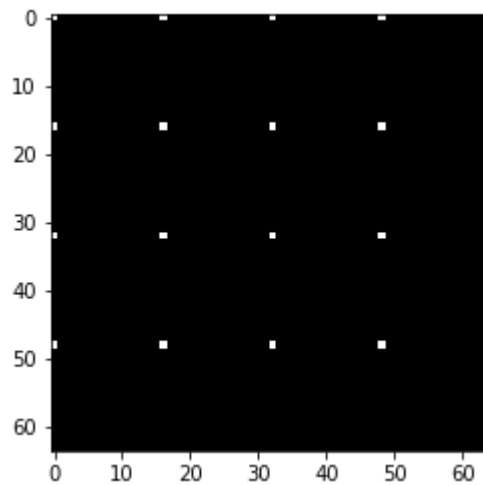
```
In [10]: ▶ 1 # b
2 img = np.fft.fft2(obj_d)
```

```
In [11]: ▶ 1 # c
2 fcomb = np.fft.fft2(comb)
```



```
In [12]: 1 plt.imshow(np.abs(np.fft.fftshift(fcomb)), cmap='gray')#, interp
```

```
Out[12]: <matplotlib.image.AxesImage at 0x7f1c28be4090>
```

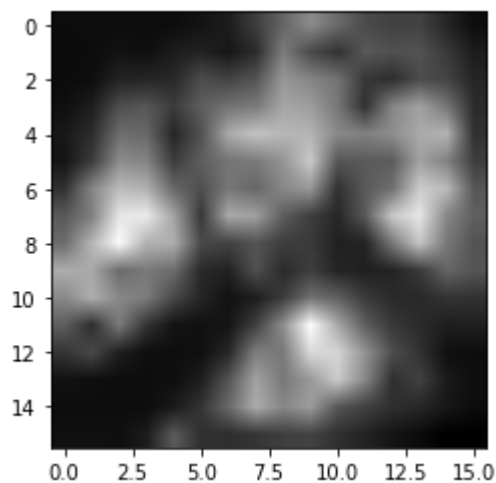


```
In [13]: 1 #d
2 img_diminished = ss.convolve2d(img, fcomb, 'same')
```

```
In [14]: 1 #e
2 inv_diminished = np.fft.ifft2(img_diminished)/(16* 16)
```

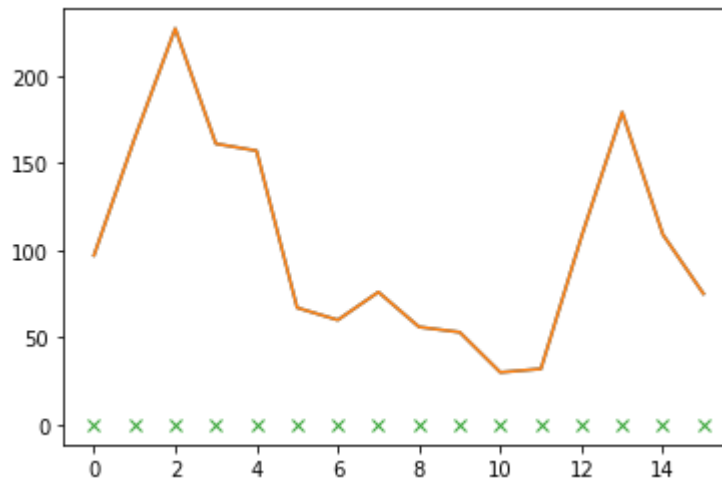
```
In [15]: 1 plt.imshow(np.abs(inv_diminished), cmap='gray', interpolation='bil
```

```
Out[15]: <matplotlib.image.AxesImage at 0x7f1c287fde90>
```



```
In [16]: ▶ 1 objv =f[:,4,::4]
2 invv = np.abs(inv_diminished)
3 plt.plot(objv[8,:])
4 plt.plot(invv[8,:])
5 plt.plot(objv[8,:]-invv[8,:], 'x')
```

Out[16]: [<matplotlib.lines.Line2D at 0x7f1c2869c290>]

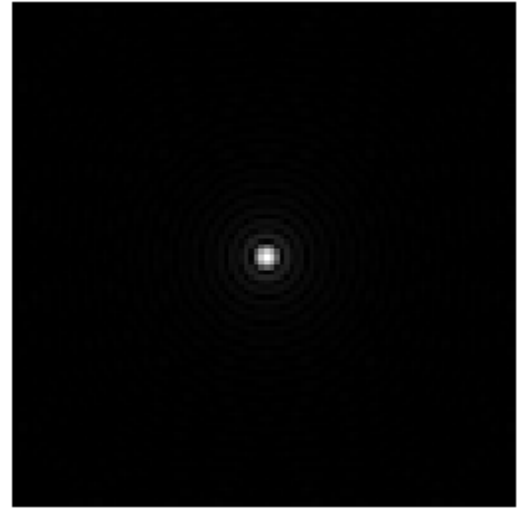
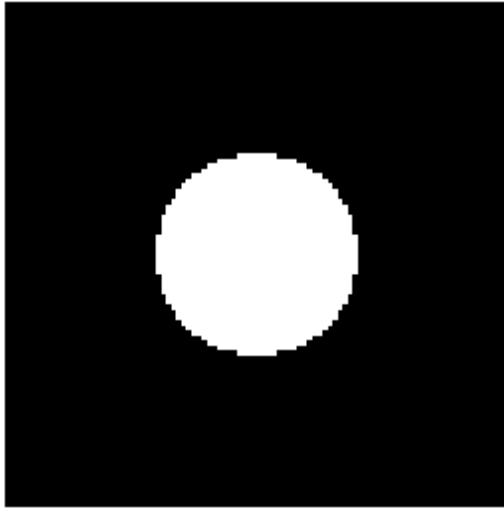


In this problem, we sampled the object at each 4th point using comb function. The FT of the comb function is sum of phase-shifted exponential functions with a period of $1/T$ in the freq domain. The FT of comb function does not involve aliasing because the envelop at each point in the freq domain does not overlapped with the adjacent points. So, the sampled object and the inverse FT of image (FT of sampled object) are the same

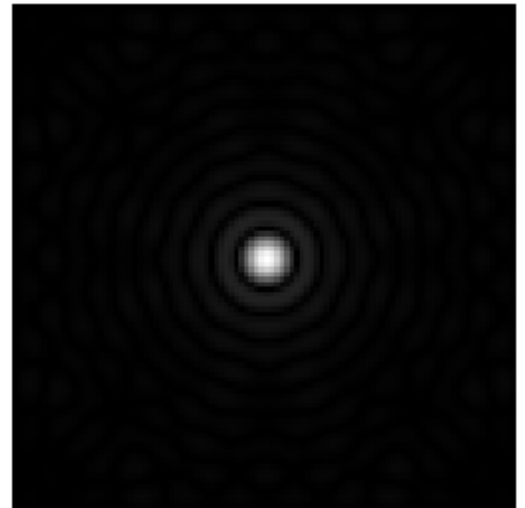
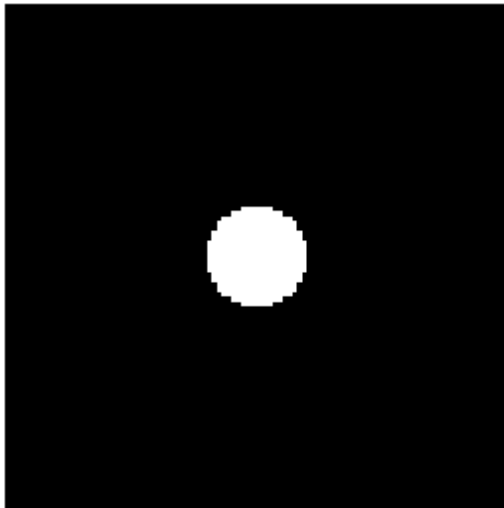
6.

```
In [43]: ▶ 1 def circ(r,N,dx):
2   grid = np.linspace(-(N-1)/2*dx,(N-1)/2*dx,N)
3   # print(grid)
4   xx, yy = np.meshgrid(grid,grid)
5   disk = np.sqrt(np.array(xx**2+yy**2))
6   disk[np.where(disk>r)] = 0
7   disk[np.where(disk!=0)] = 1
8   return disk
```

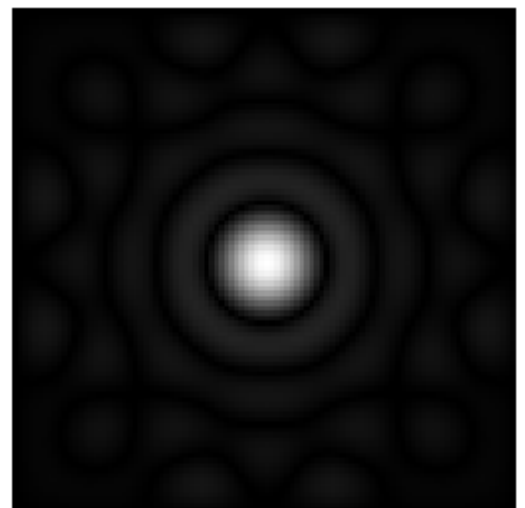
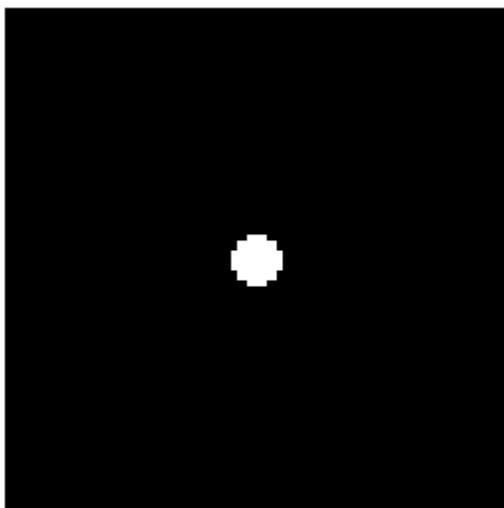
```
In [44]: ▶ 1 figure,ax = plt.subplots(1,2,figsize=(10,10))
2   apert= circ(2,100,0.1)
3   img = np.abs(np.fft.fftshift(np.fft.fft2(apert)))
4   shows = [apert, img]
5   for i in range(2):
6       ax[i].imshow(shows[i],cmap='gray')
7       ax[i].axis('off')
```



```
In [45]: 1 figure,ax = plt.subplots(1,2,figsize=(10,10))
2         apert= circ(1,100,0.1)
3         img = np.abs(np.fft.fftshift(np.fft.fft2(apert)))
4         shows = [apert, img]
5         for i in range(2):
6             ax[i].imshow(shows[i],cmap='gray')
7             ax[i].axis('off')
```



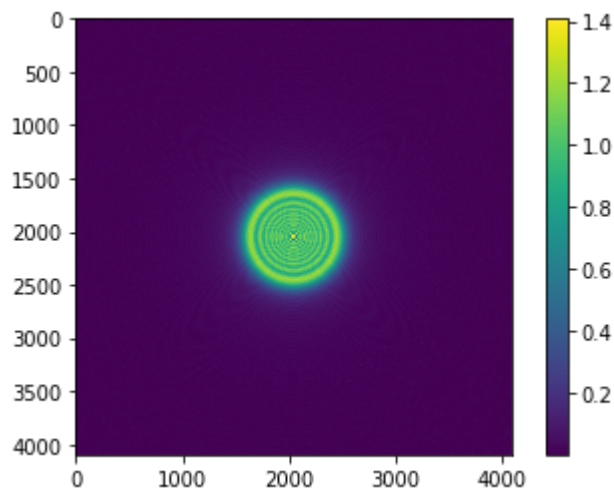
```
In [46]: 1 figure,ax = plt.subplots(1,2,figsize=(10,10))
2         apert= circ(0.5,100,0.1)
3         img = np.abs(np.fft.fftshift(np.fft.fft2(apert)))
4         shows = [apert, img]
5         for i in range(2):
6             ax[i].imshow(shows[i],cmap='gray')
7             ax[i].axis('off')
```



When the object is broader when a is large, bandwidth of the spatial frequency become narrower. This is reflected in the visualization (Left: object, Right: its reciprocal domain). Just note that the object in the frequency domain (Right) is also circular as described in the hand-written paper. Also, the results are consistent with the uncertainty principle.

In [47]: 1 *## c and d*

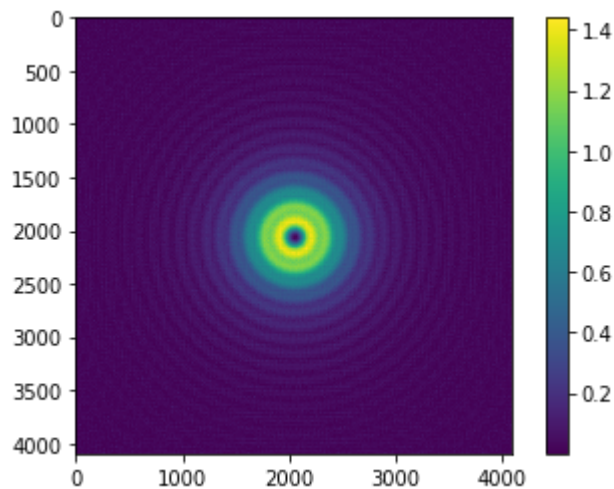
```
In [48]: 1 # part-c
2 # create a meshgrid with pixel size 2e-6
3 N=2*(12)
4 r=1e-3 # 1mm
5 dx=2e-6
6 apert = circ(r, N, dx)
7 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
8 kx,ky = np.meshgrid(dk,dk)
9 FTapert = np.fft.fft2(apert)
10
11 wavelength = 5e-7 # 500nm
12 k = 2*np.pi/wavelength
13 distance = 0.1 # 10cm
14 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
15 H = np.fft.fftshift(H)
16
17 Hf = H*FTapert
18 InvHf = np.fft.ifft2(Hf)
19
20 plt.figure()
21 plt.imshow(np.abs(InvHf))
22 plt.colorbar()
23 plt.show()
```



```

In [49]: ▶ 1
2 apert = circ(r, N, dx)
3 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
4 kx,ky = np.meshgrid(dk,dk)
5 FTapert = np.fft.fft2(apert)
6
7 wavelength = 5e-7 # 500nm
8 k = 2*np.pi/wavelength
9 distance = 1 # 10cm
10 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
11 H = np.fft.fftshift(H)
12
13 Hf = H*FTapert
14 InvHf = np.fft.ifft2(Hf)
15
16 plt.figure()
17 plt.imshow(np.abs(InvHf))
18 plt.colorbar()
19 plt.show()

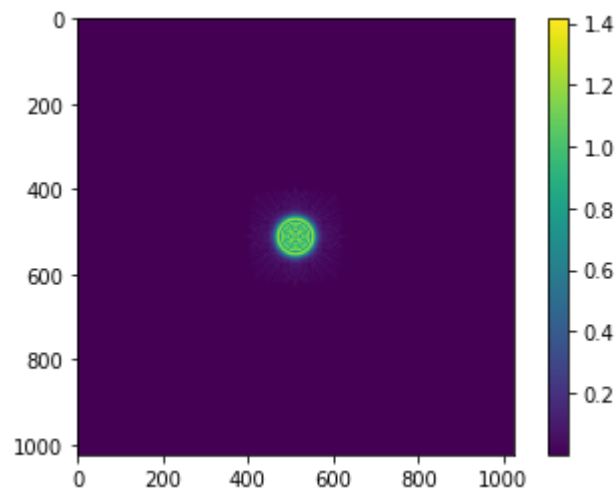
```



The results are very intuitive. If the distance between detector and aperture become larger, the wave transmitted through the edge of aperture are more likely to deviate from the center point of detector, which makes larger diffraction pattern in the detector.

In [50]: ►

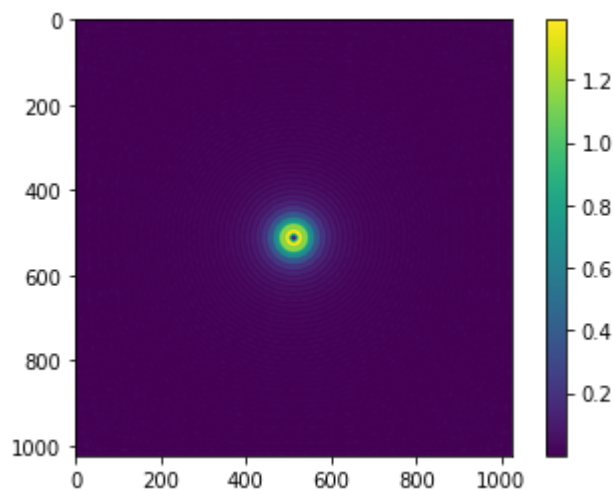
```
1 # part-d
2 # create a meshgrid with pixel size 2e-5 on 1024X 1024 grid
3 N=2*(10)
4 r=1e-3 # 1mm
5 dx=2e-5
6 apert = circ(r, N, dx)
7 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
8 kx,ky = np.meshgrid(dk,dk)
9 FTapert = np.fft.fft2(apert)
10
11 wavelength = 5e-7 # 500nm
12 k = 2*np.pi/wavelength
13 distance = 0.1 # 10cm
14 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
15 H = np.fft.fftshift(H)
16
17 Hf = H*FTapert
18 InvHf = np.fft.ifft2(Hf)
19
20 plt.figure()
21 plt.imshow(np.abs(InvHf))
22 plt.colorbar()
23 plt.show()
```



```

In [51]: 1 # part-d
2 # create a meshgrid with pixel size 2e-5 on 1024X 1024 grid
3
4 apert = circ(r, N, dx)
5 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
6 kx,ky = np.meshgrid(dk,dk)
7 FTapert = np.fft.fft2(apert)
8
9 wavelength = 5e-7 # 500nm
10 k = 2*np.pi/wavelength
11 distance = 1 # 10cm
12 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
13 H = np.fft.fftshift(H)
14
15 Hf = H*FTapert
16 InvHf = np.fft.ifft2(Hf)
17
18 plt.figure()
19 plt.imshow(np.abs(InvHf))
20 plt.colorbar()
21 plt.show()

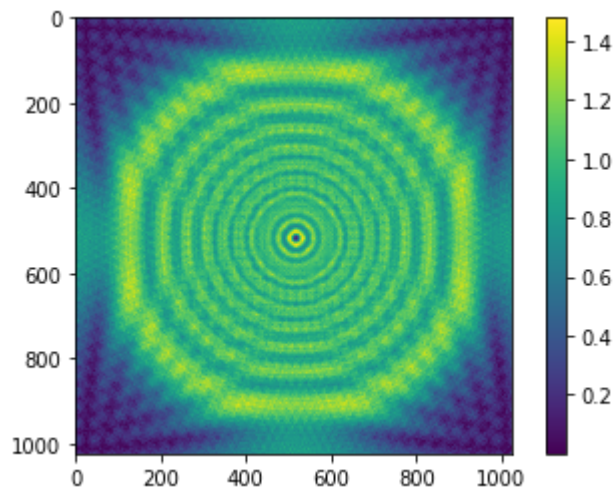
```




```

In [53]: 1 # part-d Recompute part c on 1024X 1024 with smaller pixel size
2 # create a meshgrid with pixel size 2e-5 on 1024X 1024 grid
3 N=2*(10)
4 r=1e-3 # 1mm
5 dx=2e-6
6 apert = circ(r, N, dx)
7 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
8 kx,ky = np.meshgrid(dk,dk)
9 FTapert = np.fft.fft2(apert)
10
11 wavelength = 5e-7 # 500nm
12 k = 2*np.pi/wavelength
13 distance = 0.1 # 10cm
14 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
15 H = np.fft.fftshift(H)
16
17 Hf = H*FTapert
18 InvHf = np.fft.ifft2(Hf)
19
20 plt.figure()
21 plt.imshow(np.abs(InvHf))
22 plt.colorbar()
23 plt.show()

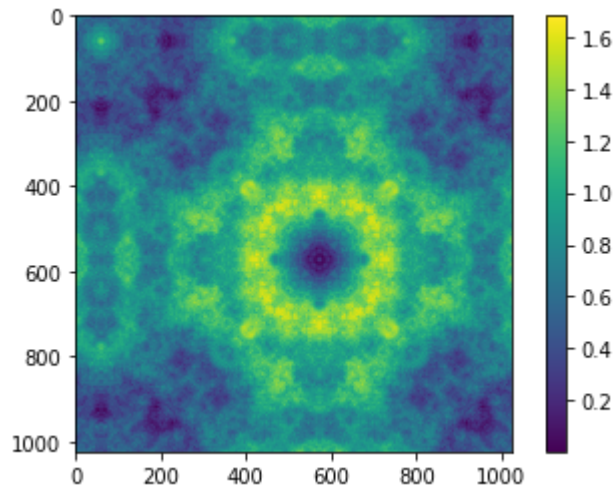
```



```

In [54]: 1 # part-d Recompute part c on 1024X 1024 with smaller pixel size
2 # create a meshgrid with pixel size 2e-5 on 1024X 1024 grid
3 N=2**(10)
4 r=1e-3 # 1mm
5 dx=2e-6
6 apert = circ(r, N, dx)
7 dk = np.linspace(-(1 - 1/N)/(2*dx), (1-1/N)/(2*dx), N)
8 kx,ky = np.meshgrid(dk,dk)
9 FTapert = np.fft.fft2(apert)
10
11 wavelength = 5e-7 # 500nm
12 k = 2*np.pi/wavelength
13 distance = 1 # 10cm
14 H = np.exp(-1j*np.pi*wavelength*distance*(kx**2+ky**2))*np.exp(1
15 H = np.fft.fftshift(H)
16
17 Hf = H*FTapert
18 InvHf = np.fft.ifft2(Hf)
19
20 plt.figure()
21 plt.imshow(np.abs(InvHf))
22 plt.colorbar()
23 plt.show()

```



Effect of discretization

The diffraction effect becomes larger when the pixel-size is small. This is consistent with the physics of diffraction pattern regarding the uncertainty principle