Solutions

From point P. It attains max hight,

$$h_0 = \frac{u_y^2}{2g} = \frac{u^2 \cos^2 \theta}{2g}$$

.. Total hight from ground,

$$H = a + h + h = a + a sin \theta + \frac{u^2 cr3^2 \theta}{2g}$$

 $\frac{dH}{d\theta} = 0 = \theta \cdot a \cos\theta - \frac{u^2}{9} \cos\theta \sin\theta$ it has two solutions

it has two solutions: $cos \theta = 0$; $\theta = \frac{\pi}{2}$; but this gives go for other solution, $u^2 \le go$ [check and derivation]. So we

$$sin\theta = \frac{ga}{u^2}$$

So,
$$H = d + \frac{u^2}{2g} + \frac{ga^2}{2u^2}$$

 $\theta = \frac{\pi}{2}$ gives a maximum if one assumes $u^2 \le ga$ in 2nd derivative test. Also, HERR H = 2a solution is not somewhat physical.

Prob-2. At the instant the spring compresses at maximum, the projectile m and the target M moves with the same velocity Ve. Conservation of energy:

$$\frac{mV^{2}}{2} = \frac{m^{V}e^{2}}{2} + \frac{MVe^{2}}{2} + \frac{k(\Delta x)^{2}}{2}$$

Conservation of momentum:

$$mV = (m+M) Ve$$

$$\therefore \Delta x = \sqrt{\frac{m M}{k (m+M)}} V$$

of the ball with respect to its center of mass and its angular momentum about point of impact A before and after the collision respectly respectively we have.

 $J = mu(a-h) + \frac{2}{5} ma^2 \omega = \frac{7}{5} mva - mvh$ as $v = a\omega$ for rolling without sliping and,

$$J' = \frac{2}{5} m a^2 \omega' + m \cdot (\omega' a) \cdot a = \frac{7}{5} m a^2 \omega'$$

as the centre of mass of the ball is momentarily at rest after the collision. Conservation of angular momentum gives,

$$\frac{7}{5}m\alpha^2\omega' = \frac{7}{5}m\nu\alpha - m\nu h$$

$$\therefore \omega' = \left(1 - \frac{5h}{7a}\right)\frac{\nu}{a}$$

In order the ball can just tip over the step, its kinetic energy must be sufficient to provide the increase in potential energy.

where, $I' = \frac{2}{5} ma^2 + ma^2 = \frac{7}{5} ma^2$

$$\frac{7}{5} \operatorname{ma}^{2} \left(1 - \frac{5h}{7a}\right)^{2} \left(\frac{V}{a}\right)^{2} = \operatorname{mgh}$$

$$\therefore v = \frac{a\sqrt{70gh}}{7a - 5h}$$

Energy conservation gives,

$$mgR \left(1-\cos\theta_0\right) = \frac{1}{2}mv^2 + \frac{1}{2}I\cdot\left(\frac{\vee}{r}\right)^2 \left[I = \frac{1}{2}mr^2\right]$$

$$\therefore N = \frac{1}{3} \left(7 - 4 \cos \theta_0 \right)$$

(x,y) =
$$((R-r) \sin \theta, -(R-r) \cos \theta)$$

$$\mathcal{Z} = T - V$$

$$= \frac{1}{2} m (R - r)^{2} \dot{\theta}^{2} + \frac{1}{4} m r^{2} \dot{\phi}^{2} + mg (R - r) \cos \theta$$

$$=\frac{3}{4} m (R-r)^2 \dot{\theta}^2 + mg (R-r) \cos \theta$$

So,
$$\frac{1}{1+1}\left(\frac{\partial \mathcal{E}}{\partial \dot{A}}\right) = \frac{\partial \mathcal{E}}{\partial \dot{B}}$$

$$\Rightarrow \sqrt{\ddot{\theta} + \frac{2}{3} \left(\frac{9}{R-r} \right) \sin \theta} = 0$$

$$T = \frac{2\pi}{\omega} = \pi \sqrt{\frac{6(R-r)}{g}}$$