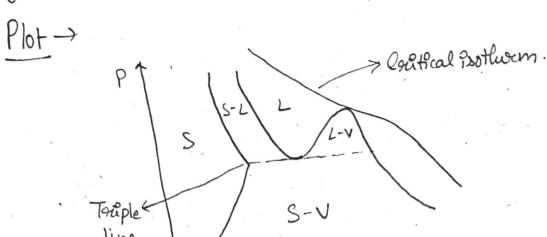
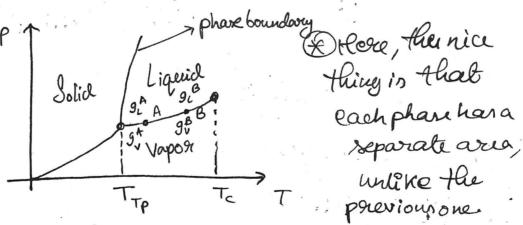
Let us imagine a hydrostatic system described by (P,V,T). It describes a 3D swiface with the constraint of the equation of state—w but this constraint depends on the phase of the system.



In physics we ree P vs. T. grapher.

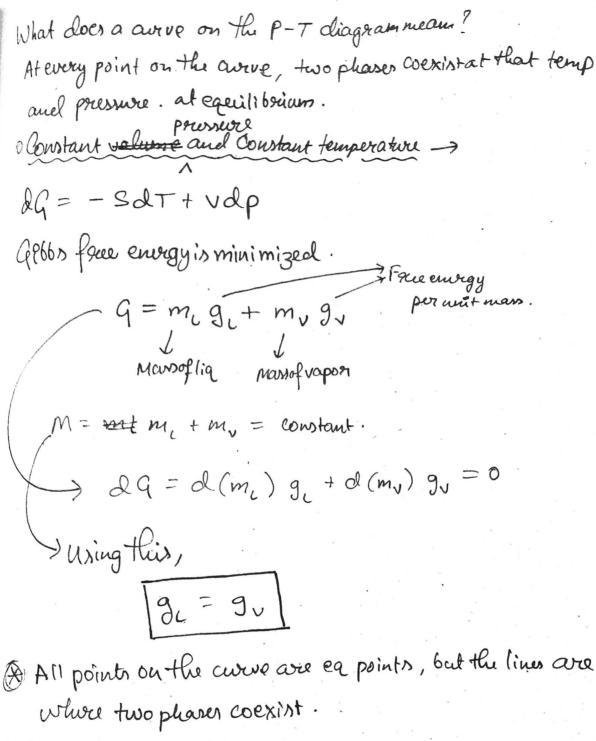
Corouspouding P-T diagram,

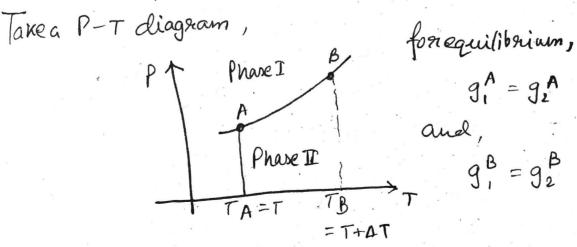


Note: These are for standard liquid - not water.

Goal of condensed matter - predict phase plot from underlying physics.

Those is some sout of interplay b(wthormal omegy and some other cenorgy at phase boundaries.





$$= \begin{array}{c} g_{1}^{B} - g_{1}^{A} = g_{2}^{B} - g_{2}^{A} \\ as G = (P,T, M_{1}, M_{V}) \text{ and } g = g(P,T), \\ + \text{dissin not just } o = 0., i.e., g_{1}^{A} \neq g_{1}^{B} \\ \Rightarrow dg_{1} = dg_{2} \\ \Rightarrow \begin{pmatrix} \frac{2g_{1}}{aP} \end{pmatrix}_{T} dP + \begin{pmatrix} \frac{2g_{1}}{aP} \end{pmatrix}_{Q} dT = dg_{1} \\ \begin{pmatrix} \frac{2g_{1}}{aP} \end{pmatrix}_{T} dP + \begin{pmatrix} \frac{2g_{1}}{aP} \end{pmatrix}_{Q} dT = dg_{1} \\ \begin{pmatrix} \frac{2g_{2}}{aP} \end{pmatrix}_{Q} dP - S_{1} dT = U_{2} dP - S_{2} dT \\ \Rightarrow V_{1} dP - S_{1} dT = U_{2} dP - S_{2} dT \\ \Rightarrow \frac{dP}{dT} = \frac{S_{2}-S_{1}}{V_{2}-V_{1}} = \frac{dQ}{dN} - \frac{dQ}{TAV} \\ \Rightarrow \frac{dP}{dT} = \frac{dQ}{AN} - \frac{dQ}{TAV} \\ \Rightarrow \frac{dP}{dT} = \frac{dQ}{TAV} + \frac{dQ}{TAV} \\ \Rightarrow \frac{dQ}{dT} = \frac{dQ}{TAV} + \frac{dQ}{TAV} + \frac{dQ}{dTAV} \\ \Rightarrow \frac{dQ}{dN} + \frac{dQ}{dN} + \frac{dQ}{dN} + \frac{dQ}{dN} + \frac{dQ}{dN} + \frac{dQ}{dN} \\ \Rightarrow \frac{dQ}{dN} + \frac{d$$

$$\frac{dQ}{dV} = \frac{L}{V_{vap} - V_{liq}} = T \frac{\partial p}{\partial T}$$

Something about Gibbs FE change being discontinuous. at phase change: