
CS5112: Algorithms and Data Structures for Applications

Reductions, lower bounds, hashing

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Some content from: Wikipedia;

J. Leskovec, A. Rajaraman, J. Ullman: Mining of Massive Datasets, <http://www.mmids.org>



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Administrivia

- Class average on the duck problem (reductions) was by far the lowest on the prelim
- This is core CS material
 - Dynamic programming, NP completeness, hashing
 - The other hard problem (MST) was not core
- A duck problem will be on the final exam
- Today we're going to go over this again
 - Bring your questions!

Lecture outline

- Reductions to prove hardness
- Lower bounds
- Example problems
- Universal and perfect hashing
- String search with hashing
- Distributed hash tables

Reduction key ideas

- Turning one problem into another is incredibly powerful
- Often to make a problem easy
 - PageRank, intelligent scissors, etc.
 - Most of the ‘greatest hits’ in CS
- Sometimes to show a problem is hard
 - NP-hardness or lower bounds
 - Utility is not quite as obvious but it’s still important

Traveling Salesman Problem

- Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city and returns to the origin city?
 - The decision version is whether there exists a route whose total distance is no greater than L .
- Seems awfully similar to Hamiltonian cycle
 - They're both graph problems
 - They're both looking for cycles
 - Biggest difference seems to be the edge weights
- Idea: we know Hamiltonian cycle is NP-complete. If we can reduce Hamiltonian cycle to Traveling Salesman Problem, we'll know TSP is NP-complete as well.
 - Intuitively: we know Hamiltonian cycle is hard. If it's easy to take the solution to TSP and determine a solution for Hamiltonian, that must mean TSP is hard too.

Example reduction

- Suppose we can efficiently solve the duck problem by using the rabbit problem as our key subroutine
- What follows from this?
 - What if we knew that the duck problem was NP hard?
 - What if we knew that the duck problem could not be solved in polynomial time?

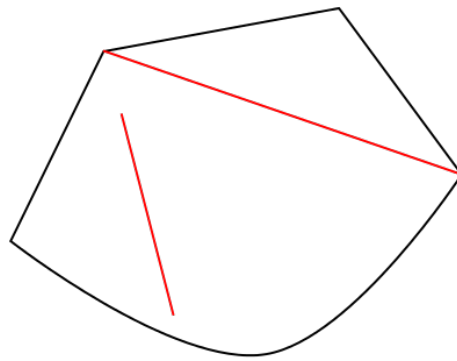
Going in the other direction

- Suppose we knew that there was a polynomial time duck problem algorithm.
 - We can do this if we had a polynomial time rabbit algorithm
- What does this tell us about the rabbit problem?
- Can you write a sorting algorithm that calls SAT? Or TSP?

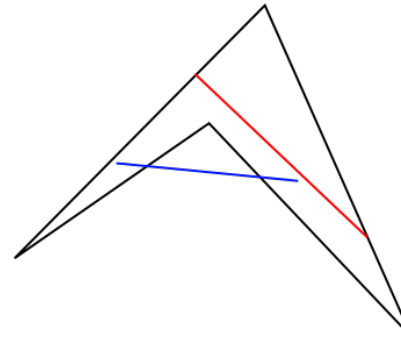
Example problems (reductions)

- Assume rabbit is in P. Show duck is in P.
- Assume rabbit is NP-hard. Show duck is NP-hard.
- Assume rabbit is NP-complete. Show duck is NP-complete.

Convex hull problem

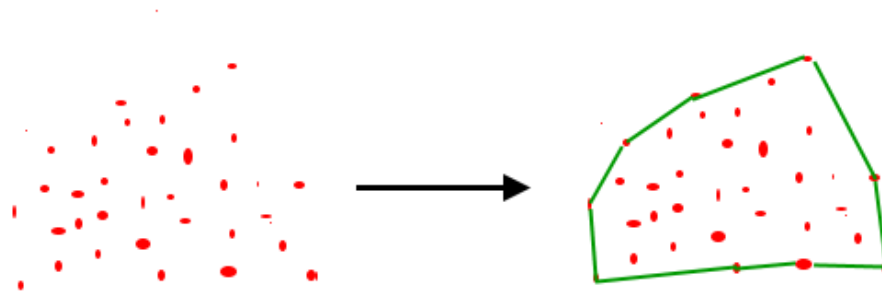


convex



not convex

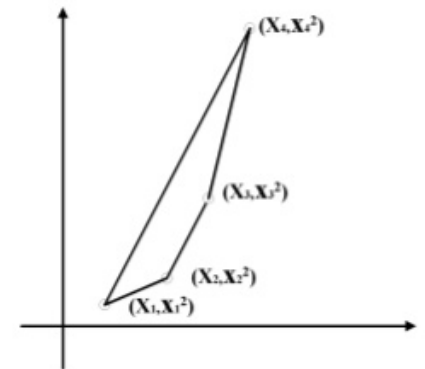
[Figure source](#)



[Figure source](#)

Convex hull lower bound

- Definition: the convex hull of a set of points is the smallest convex set containing those points
 - More precisely, the algorithm contains the points on the hull in a specific order (assume counter-clockwise)
- How fast can we compute the convex hull?
- We can use convex hull to sort!
 - Suppose you want to sort the positive numbers $\{x_i\}$
 - Compute the convex hull of the points $\{(x_i, x_i^2)\}$



[Figure source](#)

Example problems (lower bounds)

- In the following, what do we know about the duck problem's lower bound, if anything?
 - Duck1 can efficiently solve sorting.
 - Sorting can be used to solve duck2.
 - Duck3 is solvable in polynomial time.
 - Duck4 is solvable in exponential time.
 - Duck5 is NP-hard.

Universal and perfect hashing

- Back to hashing
- We talked about perfect hashing (no collisions)
 - Minimal: table is exactly full
- Main application is with fixed input data
 - Example: compilers
- How do we generate perfect hash functions for our data?
 - Give up on minimality

Universal hashing

- We can randomly generate (pick) a hash function h
 - This is NOT the same as the hash function being random
 - Hash function is deterministic!
 - Can re-do this if it turns out to have lots of collisions
- Assume input keys of fixed size (e.g., 32 bit numbers)
- Ideally h will spread out the keys uniformly

$$P[h(x) = h(y) | x \neq y] \leq \frac{1}{2^{32}}$$

- Think of this as fixing $x, y | x \neq y$ and then picking h randomly
- If we had such an h , the expected number of collisions when we hash N numbers is $\frac{N}{2^{32}}$

Universal hashing by matrix multiplication

- This would be of merely theoretical interest if we could not generate such an h
- There's a simple technique, not efficient enough to be practical
 - More practical versions follow the same idea
- Now assume the inputs/outputs are 4 bit numbers/3 bit numbers respectively, i.e. inputs: 0-15, outputs: 0-7
- We will randomly generate a 3x4 array of bits, and hash by 'multiplying' the input by this array

Universal hashing example

- We multiply using AND, and we add using parity
 - Technically this is mod 2 arithmetic

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Balls into bins

- There is an important underlying idea here
 - Shows up surprisingly often
- Suppose we throw m balls into n bins
 - Where for each ball we pick a bin at random
 - How big should n be so that with probability $> \frac{1}{2}$ there are no collisions?
 - This is the opposite of the birthday paradox
- Answer: need $n \approx m^2$
- So to avoid collisions with probability $\frac{1}{2}$ we need our hash table to be about the square of the number of elements

Perfect hashing from universal hashing

- We can use this to create a perfect hash function
- Generate a random hash function h
 - Technically, from a universal family (like binary matrices)
- Use a “big enough” hash table, from before
 - I.e., size is square of the number of elements
- Then the chance of a collision is $< \frac{1}{2}$
- In expectation we do this twice to get a perfect hash function