#### UNIVERSIDAD DE GUADALAJARA



## CENTRO UNIVERSITARIO DE CIENCIAS EXACTAS E INGENIERÍAS

Ingenieria en Computacion Reporte de práctica

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Título de la práctica: "Tarea 6. Convolucionales con el dataset de

bueno o malo"

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#### Introducción

Todos los datos de este conjunto de datos se recopilaron de bases de datos o sitios web de acceso PUBLICO. Este conjunto de datos consta de 2 clases, sabrosos y desagradables. La clase desagradable está poblada de magos faciales de delincuentes convictos. La clase sabrosa está poblada con imágenes faciales de personas comunes". De acuerdo, algunas personas comunes" pueden ser delincuentes condenados, pero espero que el porcentaje sea muy bajo. Todas las imágenes descargadas fueron procesadas por un detector de imágenes duplicadas personalizado antes de dividirse en un conjunto de tren, un conjunto de validación y un conjunto de prueba. Esto está destinado a evitar que las imágenes sean comunes entre estos conjuntos de datos. Todas las imágenes fueron recortadas de la imagen descargada original a solo una imagen facial utilizando el módulo de recorte MTCNN. El recorte es tal que se incluye muy poco fondo extraño en la imagen recortada. Esto es para evitar que el clasificador CNN extraiga características de fondo no relevantes para la tarea de clasificación de una imagen facial. El juego de trenes tiene 5610 imágenes en la clase sabrosa y 5610 imágenes en la clase desagradable. El conjunto de prueba tiene 300 imágenes en la clase

sabrosa y 300 imágenes en la clase desagradable al igual que el conjunto de validación.

# Metodología

## Codigo utilizado:

```
import many as no import marginal policy and import as pit import as pit
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ht, wf, file_count = 0,0,200

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```
classes-list(train_gen.class_indices.keys())
class_indices-list(train_gen.class_indices.values())
class_count=len(classes)
labels=test_gen_labels
print ('test_batch size: ',test_batch_size, ' test_steps: ', test_steps, ' number of classes : ', class_count)
print ('{est_2}=1:2s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_1:1:12s_
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```
x-dropout(rate-.3, seed-123)(x)
x = Dense(128, kernel_regularizer = regularizers.12(1 = 0.016).activity_regularizer-regularizers.11(0.000),
bias_regularizer-regularizers.11(0.000), activation='relu';(x)
v=bropout(rate-.45, seed-123)(x)
v=bropout(rate-.45, see
```

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```
plt.figure(figsize=(20,5))
sdir=r'../input/good-guysbad-guys-image-data-set/images to predict'
flist=sorted(os.listdir(sdir))
 for i,f in enumerate(flist):
     fpath=os.path.join(sdir,f)
      img=plt.imread(fpath)
      plt.subplot(2,6,i +1)
     plt.axis('off')
plt.title(f, color='blue', fontsize=16)
      plt.imshow(img)
plt.show()
 def predictor(sdir,img_size, average=False):
      img_list=[]
     fname=[]
class_list=[]
      savory_probs=[]
      unsavory_probs=[]
     prob_list=[]
flist=sorted(os.listdir(sdir))
      img_count=len(flist)
            fpath=os.path.join(sdir,f)
            img=plt.imread(fpath)
           img=cv2.resize(img, (img_size[1], img_size[0]))
           img_list.append(img)
fname.append(f)
     img_array=np.array(img_list)
preds=model.predict(img_array, steps=img_count)
      for p in preds:
            index=np.argmax(p)
           klass=classes[index]
           class_list.append(klass)
           savory_probs.append(p[0])
           unsavory_probs.append(p[1])
prob_list.append(p[index])
      if average == False:
           average == False:
Fseries=pd.Series(fname, name='file name')
Lseries=pd.Series(class list, name='Prodicted Class')
Pseries=pd.Series(prob_list, name='Probability')
df=pd.concat([Fseries, Lseries, Pseries], axis=1)
print(df.head(img_count))
```

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else: #average the probabilities
savory_sume of unisoroy_sume
unisoroy_sume
for savory_sume = savory/sum_count
for savory_sum = savory/sum_count
for savory_sum
else:
    klass-'suory'
    prob-unsavory_sum
else:
    klass-'suory'
    prob-unsavory_sum
enter(' majority class is (klass) with probability (prob6.2f)')

# call the predictions on the savory and i should be enumery
suffice ".'./supring-dood_system_gove_sum_counts
for savor_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_counts_sum_co
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```
vgg16_model = vGG16(
    include_top=False,
    weights='inagenet',
    input_shape=(224,224,3)
)
vgg16_model.summary()
plot_model(vgg16_model,show_shapes=True,show_layer_names=False)

#freeze base layers?

#freeze base layers:

#freeze base layers?

#freeze base layers?

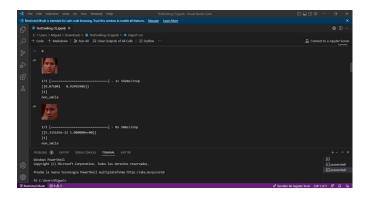
#freeze base layers.

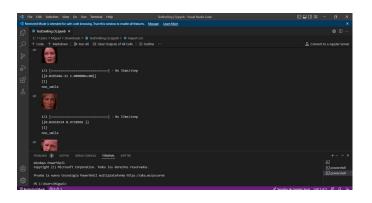
#freeze base layers?

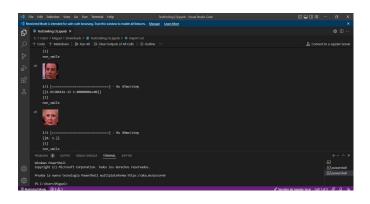
#freeze
```

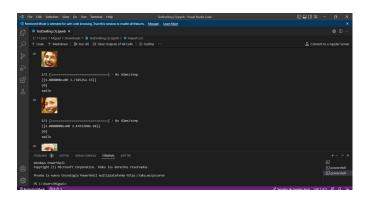
# Resultados

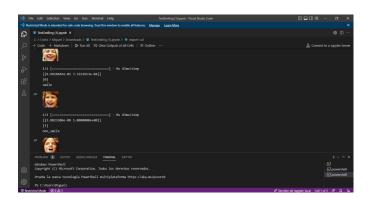
Usamos de base el de feliz y enojado











## Resultados:



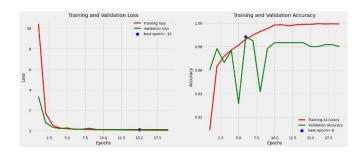
Found 11220 validated image filenames belonging to 2 classes. Found 600 validated image filenames belonging to 2 classes. Found 600 validated image filenames belonging to 2 classes. test batch size: 75 test steps: 8 number of classes: 2 class name class index

savory 0 unsavory 1

```
374/374 [============] - 242s 595ms/step - loss: 10.4381 - accuracy:
0.9090 - val_loss: 3.3489 - val_accuracy: 0.9600
Epoch 2/20
9632 - val_loss: 0.7961 - val_accuracy: 0.9783
Epoch 3/20
9718 - val_loss: 0.3514 - val_accuracy: 0.9667
Epoch 4/20
9771 - val_loss: 0.2406 - val_accuracy: 0.9767
Epoch 5/20
9813 - val_loss: 0.2990 - val_accuracy: 0.9317
Epoch 6/20
9863 - val_loss: 0.1546 - val_accuracy: 0.9883
Epoch 7/20
9898 - val_loss: 0.1679 - val_accuracy: 0.9850
Epoch 8/20
9929 - val_loss: 0.2550 - val_accuracy: 0.9417
```

```
Epoch 00008: ReduceLROnPlateau reducing learning rate to 0.0005000000237487257.
Epoch 9/20
374/374 [===========] - 219s 586ms/step - loss: 0.1247 - accuracy: 0.
9953 - val_loss: 0.1501 - val_accuracy: 0.9783
9984 - val_loss: 0.1413 - val_accuracy: 0.9833
Epoch 11/20
9986 - val_loss: 0.1369 - val_accuracy: 0.9833
Epoch 12/20
374/374 [===========================] - 219s 586ms/step - loss: 0.1023 - accuracy: 0.
9978 - val_loss: 0.1329 - val_accuracy: 0.9833
Epoch 13/20
9986 - val_loss: 0.1299 - val_accuracy: 0.9833
Epoch 14/20
374/374 [============] - 219s 585ms/step - loss: 0.0915 - accuracy: 0.
9989 - val_loss: 0.1391 - val_accuracy: 0.9833
374/374 [========] - 218s 583ms/step - loss: 0.0886 - accuracy: 0.
9989 - val_loss: 0.1242 - val_accuracy: 0.9800
Epoch 16/20
9995 - val_loss: 0.1303 - val_accuracy: 0.9800
Fpoch 17/29
9993 - val_loss: 0.1289 - val_accuracy: 0.9817
```

Epoch 00019: ReduceLROnPlateau reducing learning rate to 0.0001250000059371814. Restoring model weights from the end of the best epoch. Epoch 00019: early stopping



	file name	Predicted Class	Probability
0	01.jpg	savory	0.992805
1	02.jpg	savory	0.996700
2	03.jpg	savory	0.994198
3	04.jpg	savory	0.987547
4	05.jpg	savory	0.981984
5	06.jpg	savory	0.983529
6	07.jpg	savory	0.991409
7	08.jpg	savory	0.990148
8	09.jpg	savory	0.992387
9	10.jpg	savory	0.985571
10	11.jpg	unsavory	0.996345



Links de los codigos:

https://colab.research.google.com/drive/1CpVsgPjCdXXDmfICw7bWmfXyUhh198DX?usp=sharinghttps://colab.research.google.com/drive/1c44c7vr

https://colab.research.google.com/drive/1q44c7xr

RRQ1YA0Z7e7WBi-e-xUAutIYy?usp=sharing

 $\rm https://drive.google.com/file/d/1VoM80lDfrCkrZeg$ 

67E5p9SDgUwtNYRw1/view?usp=sharing

## Conclusiones

Las Redes neuronales convolucionales son un tipo de redes neuronales artificiales donde las «neuronas» corresponden a campos receptivos de una manera muy similar a las neuronas en la corteza visual primaria (V1) de un cerebro biológico.

## Referencias

https://www.kaggle.com/datasets/gpiosenka/good-guysbad-guys-imagedata-set

https://www.kaggle.com/code/irenewang345/dl-project-goodguybadguy?scriptVersionId=95580795