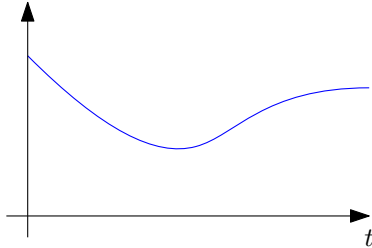
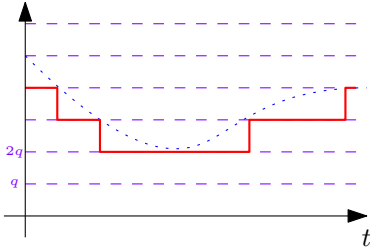


$x(t)$  $x_q(t)$  $x_q(kT_C)$ 