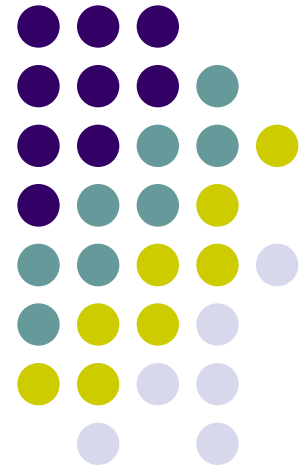
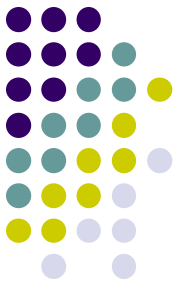


Flow Fields

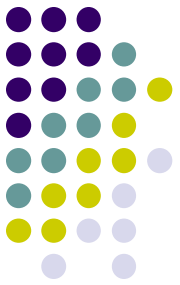
Hao Li and Howard Hamilton



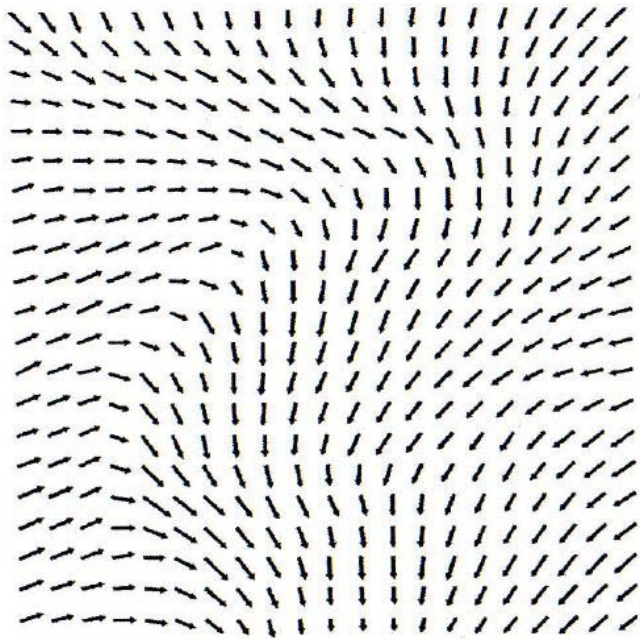


Motivation for Flow Fields

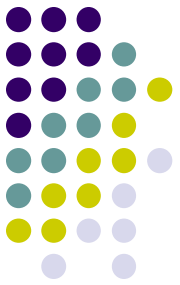
- Multiple AI algorithms in a computer game can produce conflicting results. The AI must resolve these conflicts and find a simultaneous solution.



Example Flowfield

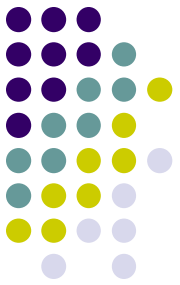


- Simple definition: A **flow field** is a grid of vectors.
- If you are here, go this way.
- Or: one influence on your motion is captured in this flow field, e.g., magnetic attraction.



Flow Field

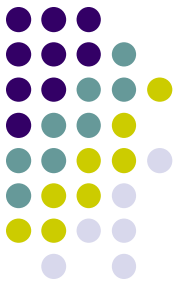
- “A **flow field** consists of a three-dimensional sample space that returns a vector at every point, indicating an attraction toward objects of interest or repulsion away from objects to be avoided” [Alexander, 2006].
- We will concentrate on two-dimensional flow fields.



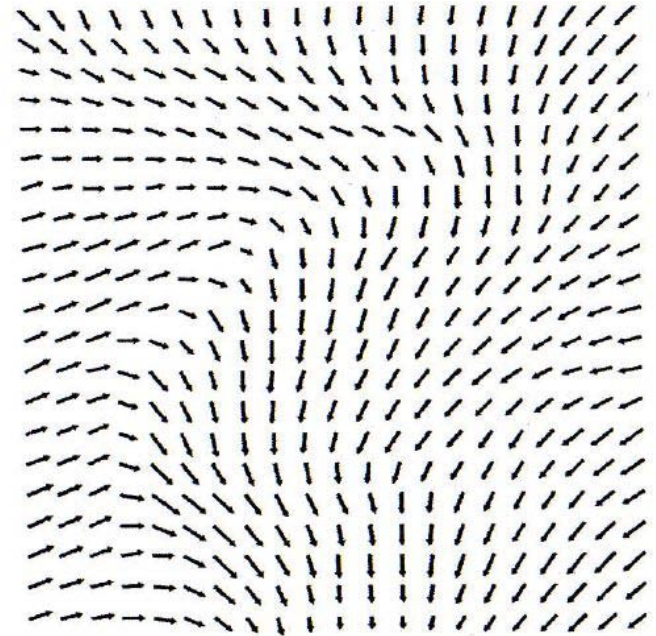
A flow field has two components:

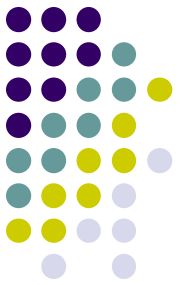
- A **static** data set constructed around static objects (e.g. terrain)
- A **dynamically** generated data set constructed around dynamic objects (e.g. vehicles)

Static Fields



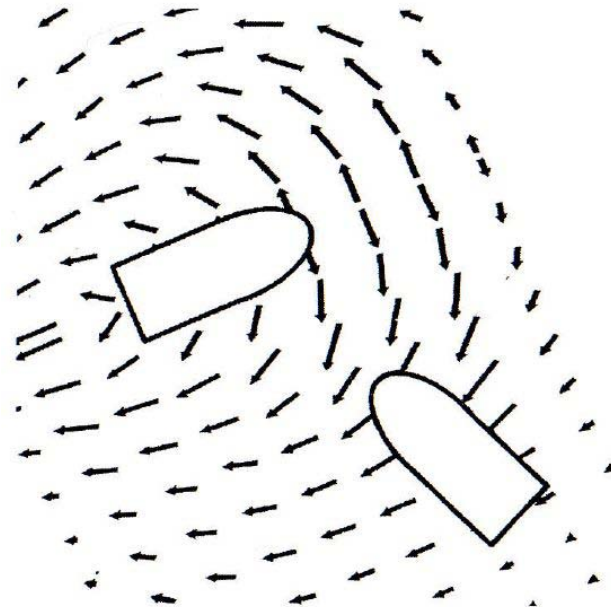
- “A **static field** is time-invariant: it will always return the same output vector for any given input vector” [Alexander 2006].
- We can use it as a function: we give it an (x, y) vector representing a position and it returns an (x, y) vector representing a velocity.

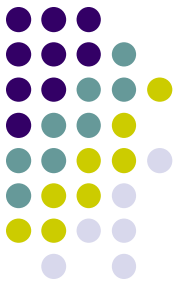




Dynamic Fields

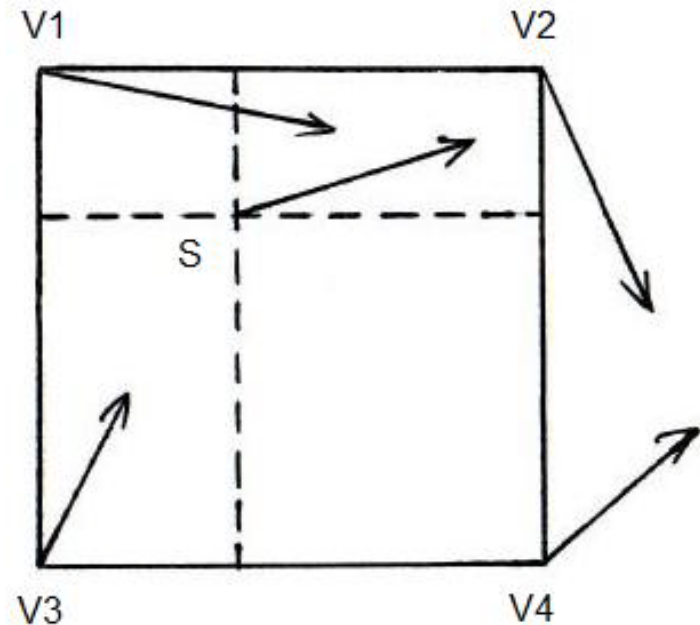
- “A **dynamic field** can vary with time to produce different output vectors for a given input vector” [Alexander 2006].
- It is usually controlled by parameters other than the input vector.

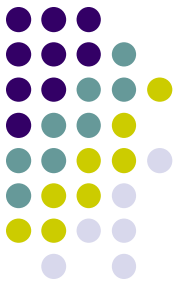




Representing Flow Fields

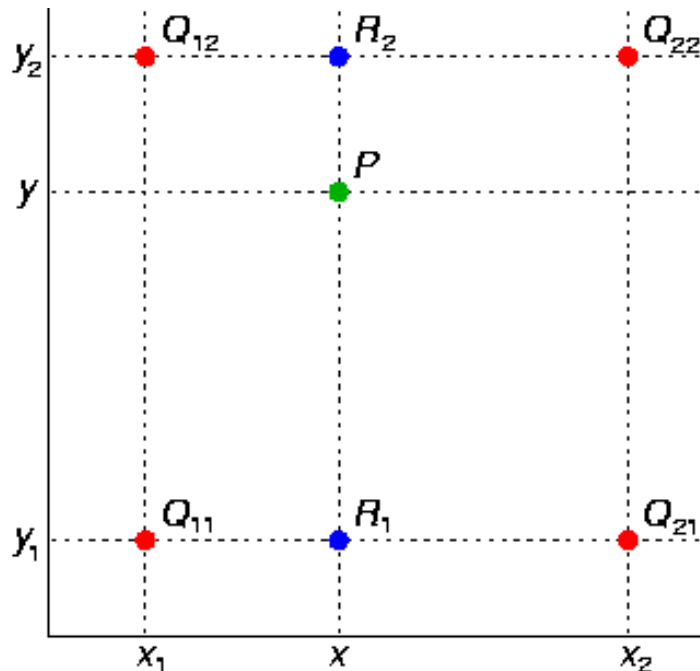
- Storing the Field
 - Use a grid to store the data (vectors) that represent the state of the flow field
- Sampling the Field
 - Interpolate values between data points



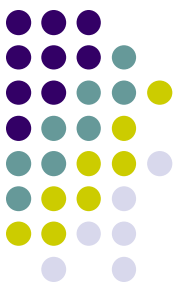


Bilinear Interpolation

- **Bilinear interpolation** interpolates a function of two variables, defined at grid points, to the continuous space between.



- Suppose the function's values are defined at grid points $Q_{11} = (x_1, y_1)$, Q_{12} , Q_{21} , and Q_{22} .
- We want to find the value at point $P = (x, y)$.



Step 1: linear interpolation in the x-direction

$$f(R_1) \approx \frac{x_2 - x}{x_2 - x_1} f(Q_{11}) + \frac{x - x_1}{x_2 - x_1} f(Q_{21}) \quad \text{where } R_1 = (x, y_1),$$

$$f(R_2) \approx \frac{x_2 - x}{x_2 - x_1} f(Q_{12}) + \frac{x - x_1}{x_2 - x_1} f(Q_{22}) \quad \text{where } R_2 = (x, y_2).$$

Step 2: interpolating in the y-direction

$$f(P) \approx \frac{y_2 - y}{y_2 - y_1} f(R_1) + \frac{y - y_1}{y_2 - y_1} f(R_2).$$

This gives us the desired estimate of $f(x, y)$

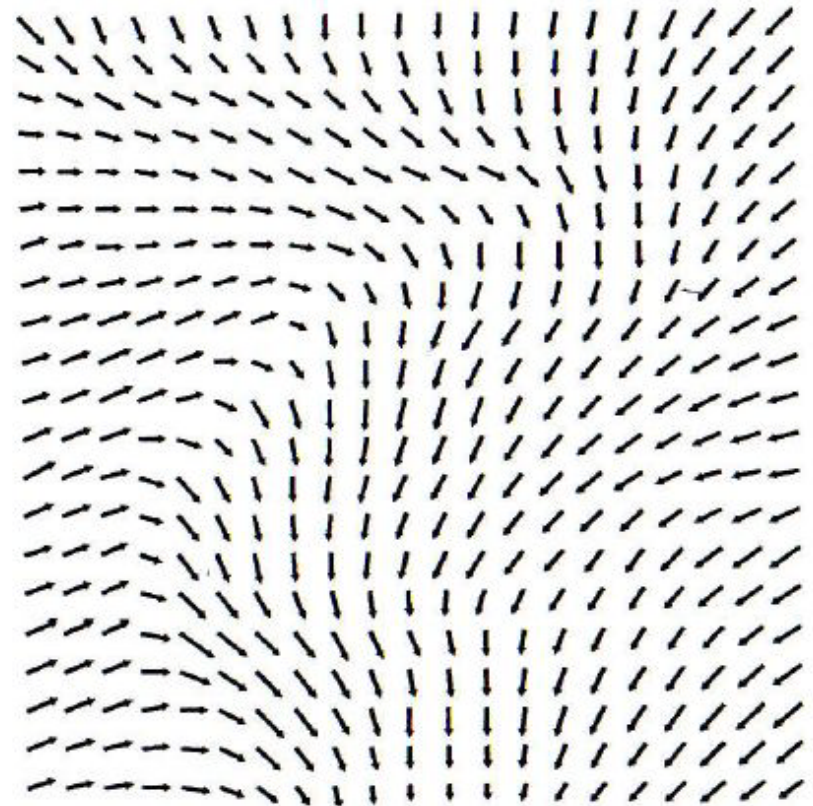
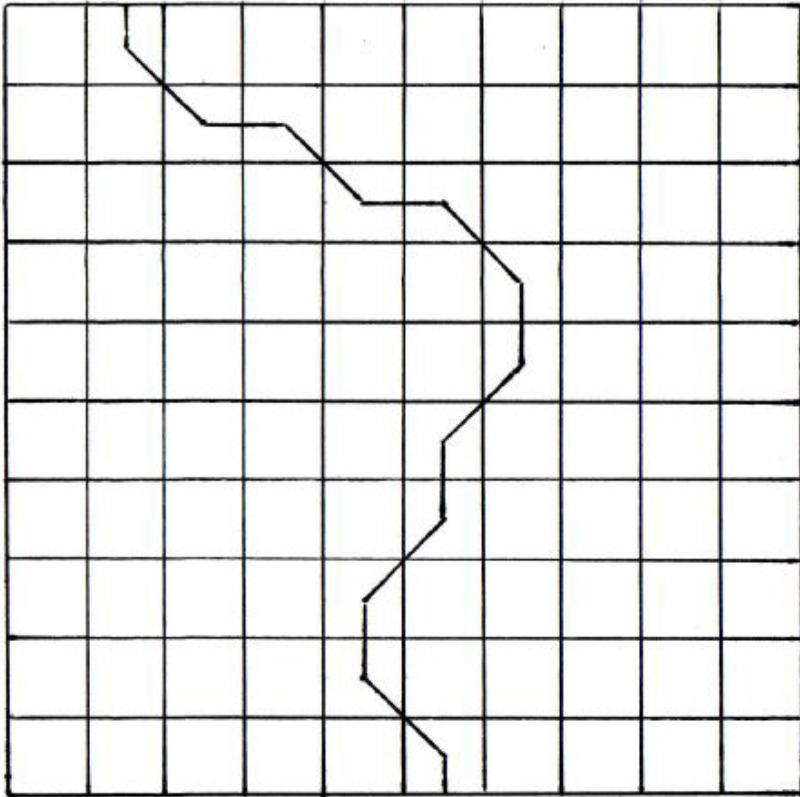
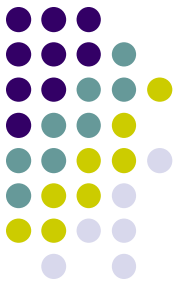
$$\begin{aligned} f(x, y) \approx & \frac{f(Q_{11})}{(x_2 - x_1)(y_2 - y_1)} (x_2 - x)(y_2 - y) \\ & + \frac{f(Q_{21})}{(x_2 - x_1)(y_2 - y_1)} (x - x_1)(y_2 - y) \\ & + \frac{f(Q_{12})}{(x_2 - x_1)(y_2 - y_1)} (x_2 - x)(y - y_1) \\ & + \frac{f(Q_{22})}{(x_2 - x_1)(y_2 - y_1)} (x - x_1)(y - y_1). \end{aligned}$$

Combining Fields

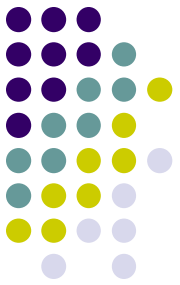


- **Weighted Addition (+)**
Take all of the component fields into account and provide the ability to prioritize some fields.
- **Conditional Operation (OR)**
Allow one field to completely override other fields.
- **Field Multiplication (*)**
Scaling value for each point in the field is the result of sampling another field. (Scaling or dot product)

Example 1: A* Smoothing

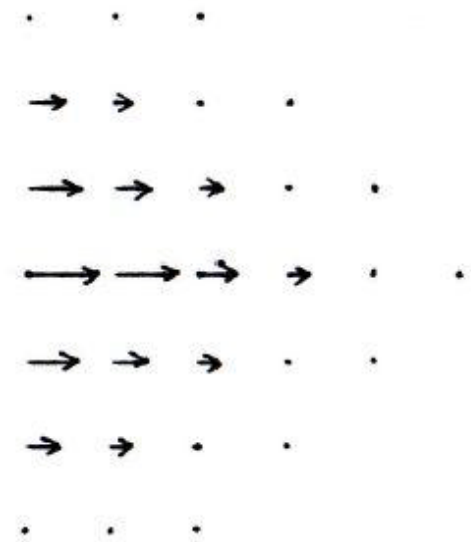
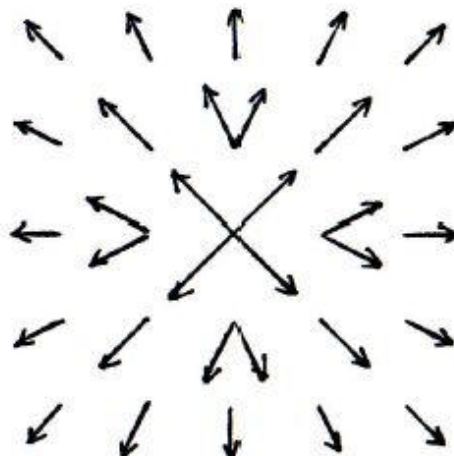
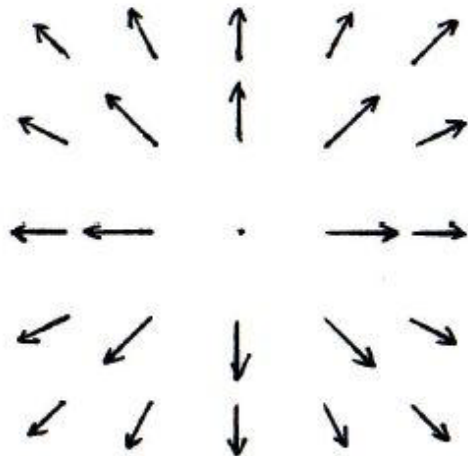


- Use flow field to create a smooth path

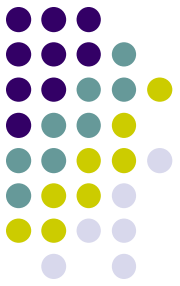


Example 2: Collision Avoidance

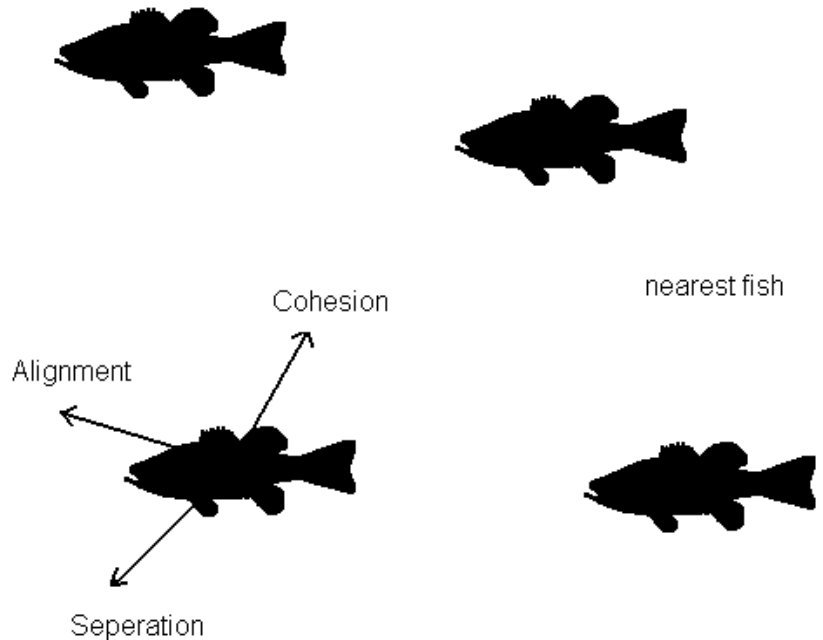
- Dynamic Object Avoidance
 1. Non-mirrored radial repulsion field – has dead zone at center
 2. Mirrored radial repulsion field – avoids dead zone
 3. Sideways repulsion



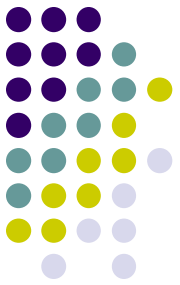
Flocking



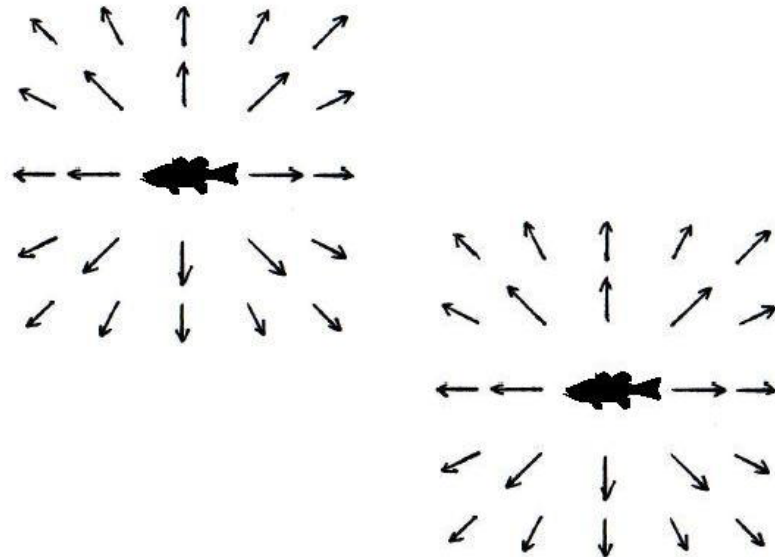
- Reynolds's boids
 - **Separation:** steer to avoid crowding nearby fish (provides collision avoidance).
 - **Alignment:** steer towards the average heading of nearby fish (helps keep school together).
 - **Cohesion:** steer to move toward the average position of nearby members (helps flock centering).

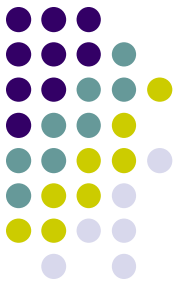


Flocking System with Flow Field



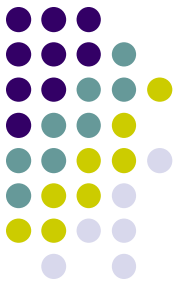
- Generate a local dynamic flow field around each fish according to their movement.
- Combine all local fields together before adjusting fish's movement.





Sources of Flow Fields

- Visualization and editing tools can be used to create flow fields.
- Convert from a 2-D sample to a 3-D sample.
- Brushes can be used to create a good flow field.



Conclusion

- Flow fields provide elegant solutions to a wide variety of problems.
- They greatly reduce problems such as oscillation by representing smooth flow rather than giving different results at nearby samples.