

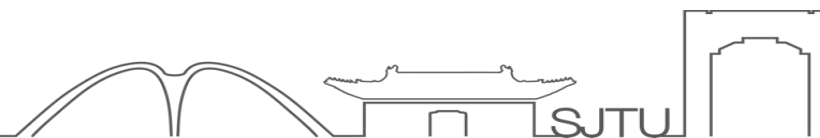


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# ECE2150J Introduction to Circuits

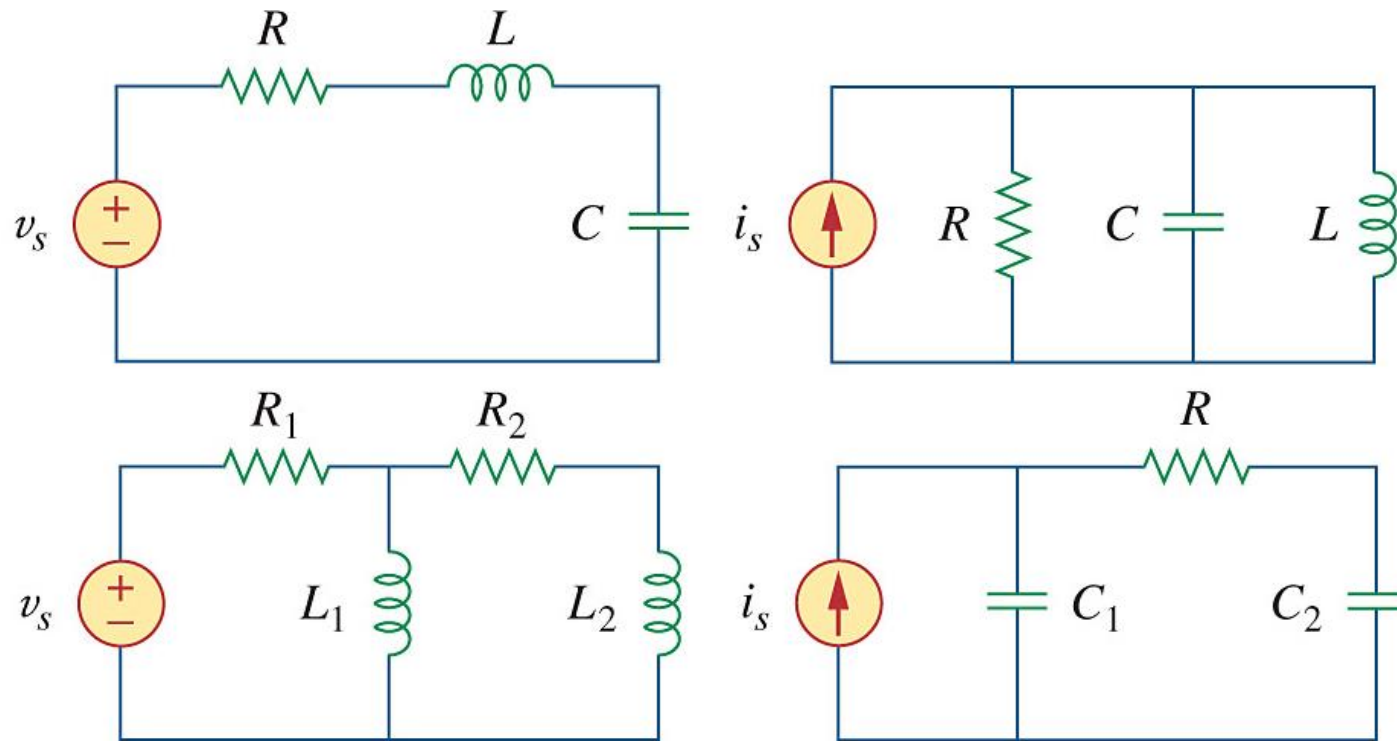
## Chapter 8. Second order circuit

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## 8.1 Introduction

In this chapter, we consider circuits containing **two storage elements**, known as second-order circuits.



## 8.2 Finding Initial and Final Values

Find the initial and final values, not only  $v$  and  $i$  but also their derivatives  $dv/dt$  and  $di/dt$ .

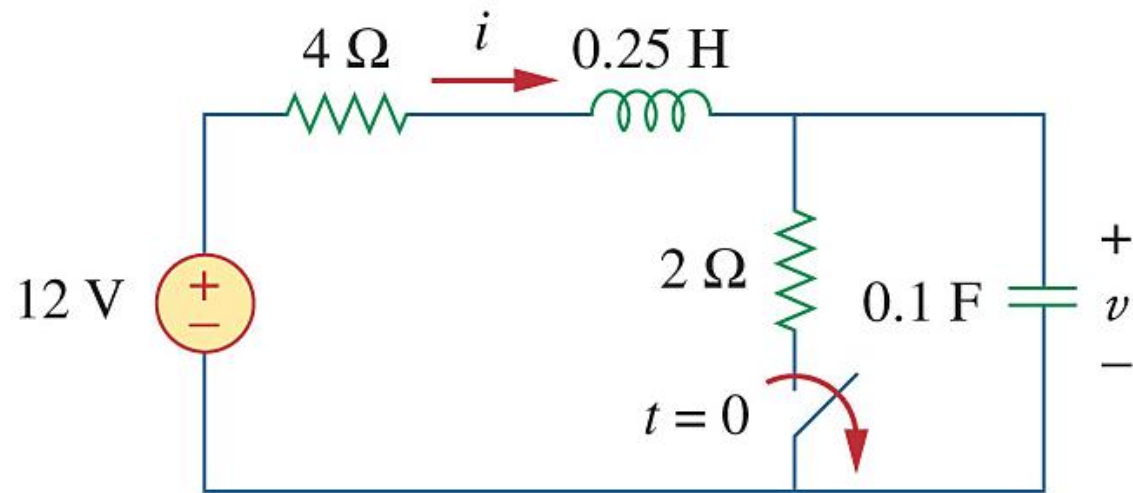
There are **two key points** to keep in mind in determining the initial conditions.

**First**, the polarity of  $V_C$  and  $I_L$ : the passive sign convention.

**Second**, keep in mind that the  $V_C$  and  $I_L$  are always continuous.

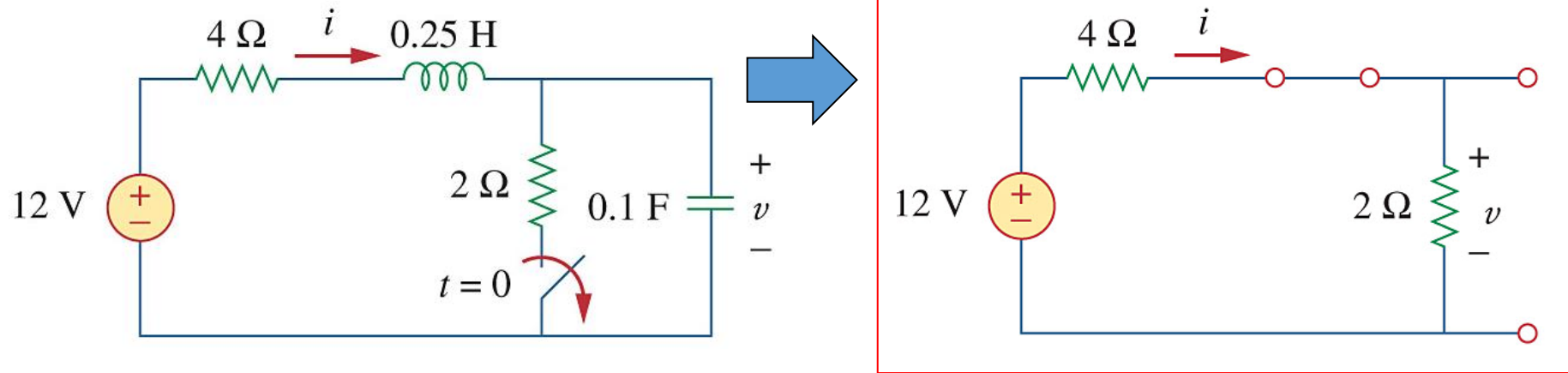
$$v(0^+) = v(0^-) \quad i(0^+) = i(0^-)$$

**Example 8.1** The switch in Fig. 8.2 has been closed for a long time. It is open at  $t = 0$ . Find: (a)  $i(0^+)$ ,  $v(0^+)$ , (b)  $di(0^+) / dt$ ,  $dv(0^+) / dt$ , (c)  $i(\infty)$ ,  $v(\infty)$ .



## Example 8.1

(i)  $t=0^-$

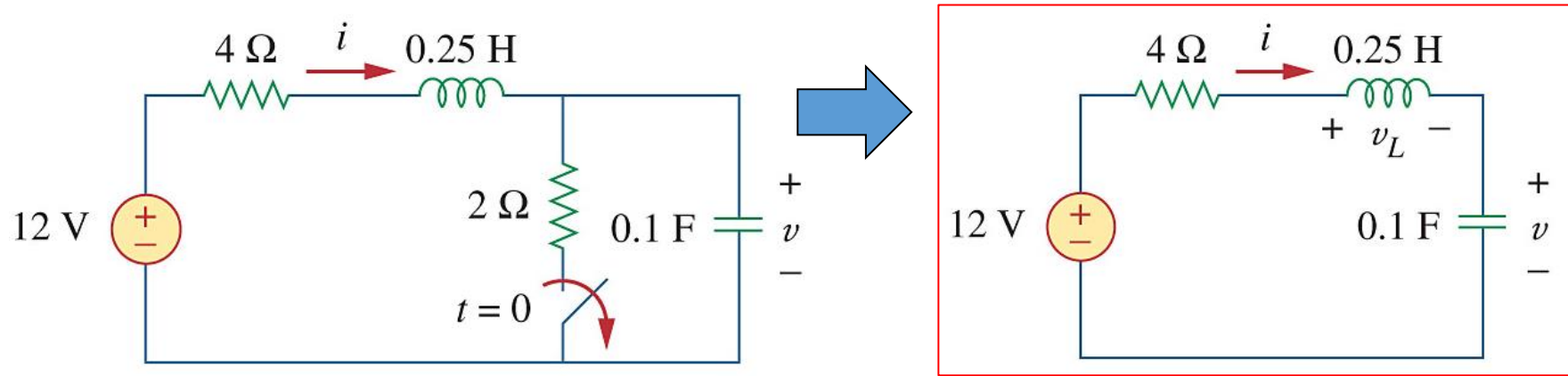


Before  $t=0$ , at DC steady state: **An equivalent circuit**

$$i(0^+) = i(0^-) = \frac{12}{4 + 2} = 2\text{ (A)}$$

$$v(0^+) = v(0^-) = 2i(0^-) = 4\text{ (V)}$$

(ii)  $t=0^+$



After  $t=0$ , switch opens: **An equivalent circuit**

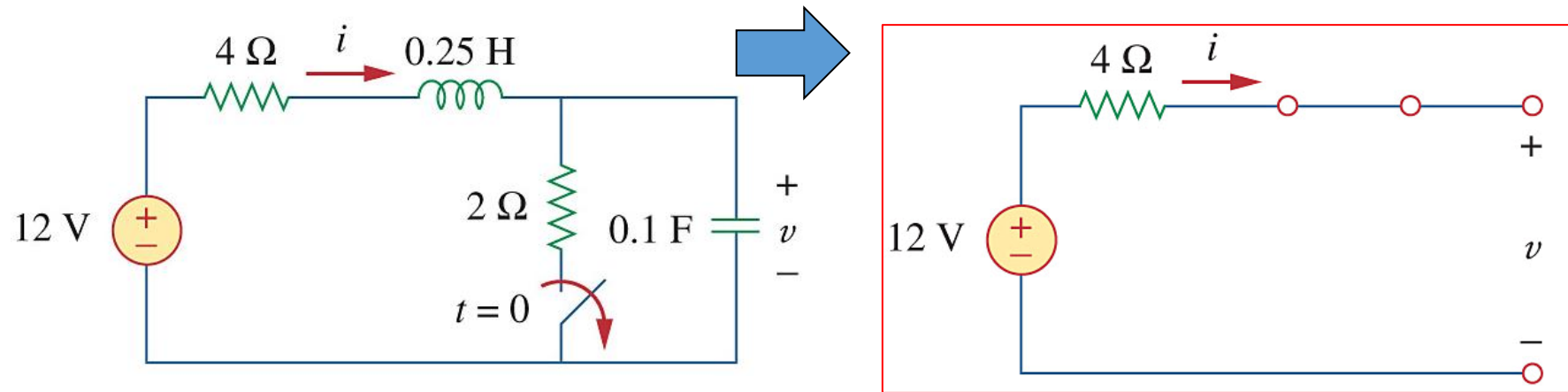
$$\begin{cases} i = 0.1 \frac{dv}{dt} \\ 12 = 4i + 0.25 \frac{di}{dt} + v \end{cases} \Rightarrow \begin{cases} \frac{dv}{dt} = \frac{i}{0.1} \\ \frac{di}{dt} = \frac{12 - 4i - v}{0.25} \end{cases}$$

$$dv(0^+) / dt = i(0^+) / 0.1 = 2 / 0.1 = 20 \text{ (V/s)}$$

$$di(0^+) / dt = [12 - 4i(0^+) - v(0^+)] / 0.25$$

$$= [12 - 4 \times 2 - 4] / 0.25 = 0 \text{ (A/s)}$$

(iii)  $t \rightarrow \infty$



$t = \infty$ , at DC steady state: **An equivalent circuit**

$$i(\infty) = 0$$

$$v(\infty) = 12 \text{ (V)}$$

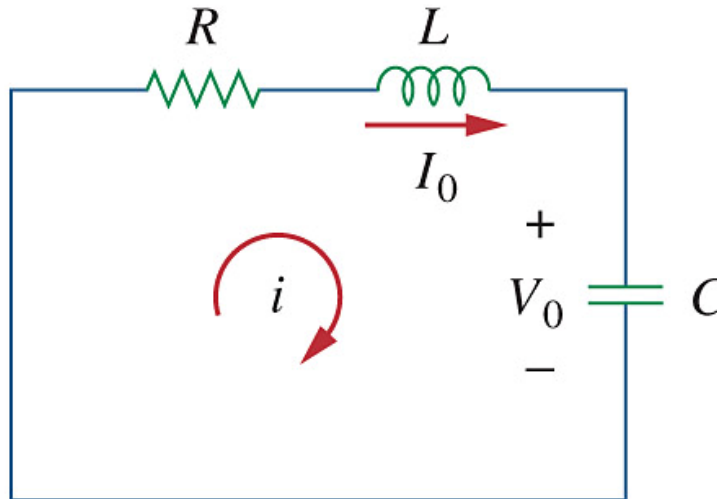
## 8.3 The Source-Free Series *RLC* Circuit

The natural response of the series *RLC* circuit. The circuit is being excited by the energy **initially stored** in the capacitor and inductor.

at  $t = 0$

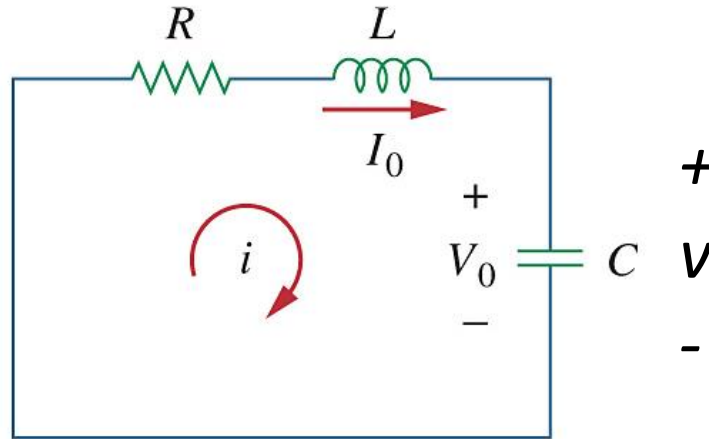
$$v(0) = \frac{1}{C} \int_{-\infty}^0 i \, dt = V_0$$

$$i(0) = I_0$$





## Second Order Equation

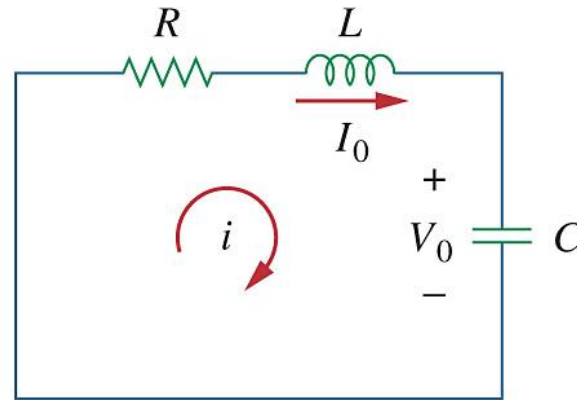


By KVL:

$$iR + L \frac{di}{dt} + v = 0 \quad \Rightarrow \quad iR + L \frac{di}{dt} + \frac{1}{C} \int_{-\infty}^t i dt = 0 \quad \text{Differentiate the equation}$$

$$\frac{di}{dt} R + L \frac{d^2 i}{dt^2} + \frac{1}{C} i = 0 \quad \Rightarrow \quad \frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0$$

## Second Order Equation – Initial conditions



$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0$$

To solve a second-order differential equation, two initial conditions are required:  
**i or v and its first derivative**

(i)  $i(0^+) = i(0^-) = I_0$

(ii) From  $iR + L \frac{di}{dt} + v = 0 \Rightarrow i'(0^+) = -\frac{1}{L} (i(0^+)R + v(0^+))$   
 $= -\frac{1}{L} (i(0^-)R + v(0^-))$   
 $= -\frac{1}{L} (I_0 R + V_0)$

## Second Order Equation – Characteristic Eq.

Our experience in the preceding chapter on first-order circuits suggests that the solution is of exponential form. So we use a test solution  $i = Ae^{st}$  where A and s are constants to be determined.

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0 \quad \Rightarrow \quad As^2 e^{st} + \frac{AR}{L} s e^{st} + \frac{A}{LC} e^{st} = 0$$

$$Ae^{st} \left( s^2 + \frac{R}{L}s + \frac{1}{LC} \right) = 0$$

only this part can become 0

**Characteristic equation**

$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$

## Second Order Equation – Characteristic Eq.

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0$$

$$s^2 + \frac{R}{L} s + \frac{1}{LC} = 0$$

$$s = \frac{-R/L \pm \sqrt{(R/L)^2 - 4 \times 1 \times (1/(LC))}}{2 \times 1}$$

$$= -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$= -\alpha \pm \sqrt{\alpha^2 - \omega_o^2} \quad \text{where } \alpha = \frac{R}{2L} \text{ and } \omega_o = \frac{1}{\sqrt{LC}}$$

\*Note

$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Solutions ( $S_1$  and  $S_2$ ) for the equation  $\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}, s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2} :$$

natural frequencies, Np/s

$$\alpha = \frac{R}{2L} : \text{neper frequency (damping factor),}$$

Np/s (nepers per second)

$$\omega_0 = \frac{1}{\sqrt{LC}} : \text{resonant frequency (undamped}$$

natural frequency), rad/s

## Second Order Equation – Solution $i$

There are two possible **solution for  $i$**

$$i_1 = A_1 e^{s_1 t} \text{ and } i_2 = A_2 e^{s_2 t}$$

A complete or total solution would therefore require **a linear combination of  $i_1$  and  $i_2$** .

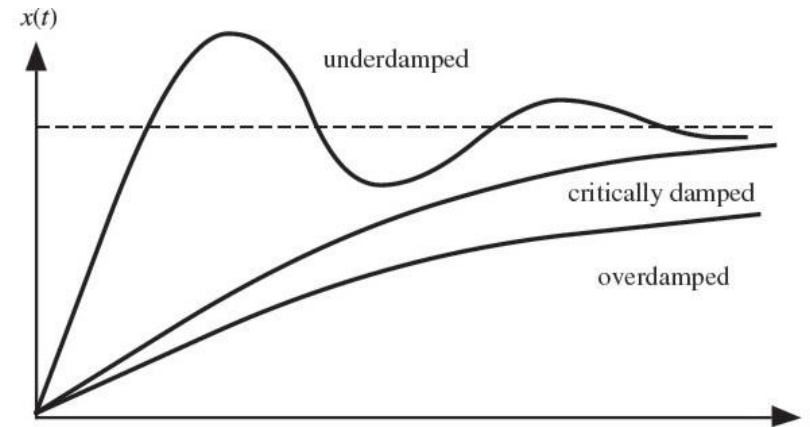
Thus, the natural response of the series RLC circuit is

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}, \text{ find } A_1 \text{ and } A_2 \text{ from the initial values.}$$

## Second Order Equation – Solution $S_1$ and $S_2$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$



### Three types of solutions:

1.  $\alpha > \omega_0$ , overdamped case: system moves slowly toward equilibrium.
2.  $\alpha = \omega_0$ , critically damped case: system moves quickly to equilibrium, but will oscillate around the equilibrium point.
3.  $\alpha < \omega_0$ , underdamped case: the system will oscillate, but its amplitude gradually decreases until it rests.

## Second Order Equation – Solution $S_1$ and $S_2$

### Case 1: Overdamped

$$\alpha > \omega_0 \text{ implies } C > \frac{4L}{R^2} \quad \left( \alpha = \frac{R}{2L} > \omega_0 = \frac{1}{\sqrt{LC}} \right)$$

Both roots  $S_1$  and  $S_2$  are **negative and real**

The response is  $i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$  which decays and approaches zero as  $t$  increases.

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

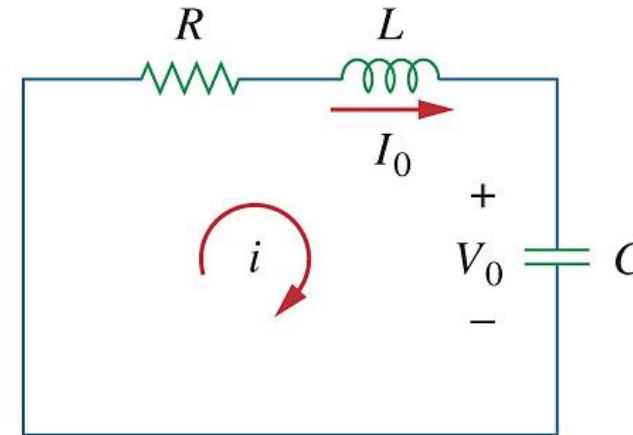
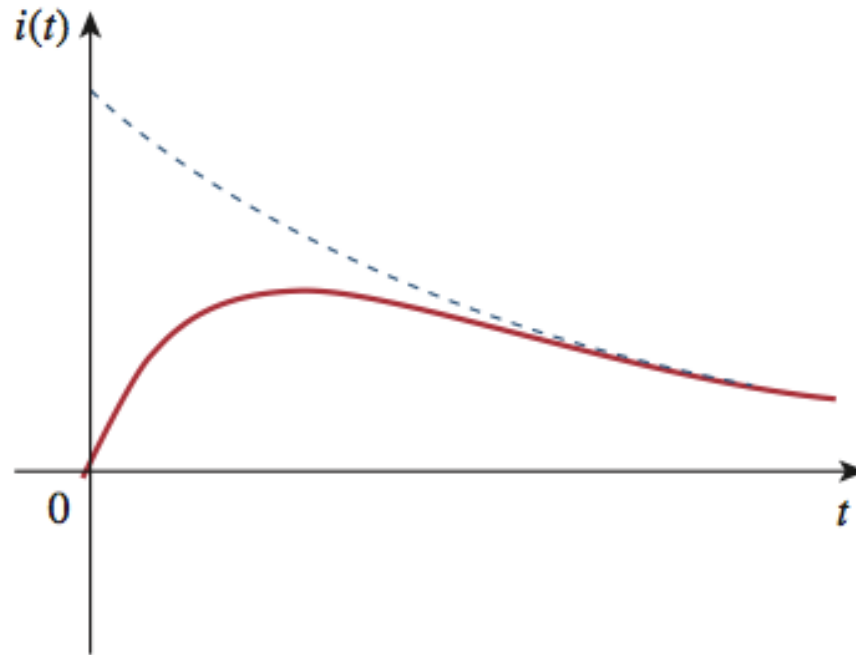
where

$$A_1 = \frac{i'(0^+) - s_2 i(0^+)}{s_1 - s_2}$$

$$A_2 = \frac{s_1 i(0^+) - i'(0^+)}{s_1 - s_2}$$

Both  $S_1$  and  $S_2$  real  
 $S_1 < 0, S_2 < 0$   
 $S_1 \neq S_2$





1. no oscillation
2. Region 1:  $i(t)$  changes due to initially stored energy in  $L$  and  $C$
3. Region 2: steady state value should be 0 due to “zero input response”
4.  $\alpha \uparrow$  (more damping)  $\rightarrow$  reaches steady state faster

## Second Order Equation – Solution $S_1$ and $S_2$

### Case 2: Critically damped

2. If  $\alpha = \omega_0$ ,  $s_1 = s_2 = -\alpha$ , we have the *critically damped* case,

$$i(t) = (B_1 t + B_2)e^{-\alpha t}$$

where

$$B_1 = i'(0^+) + \alpha i(0^+)$$

$$B_2 = i(0^+)$$

$$\begin{aligned} S_1 &< 0, S_2 < 0 \\ S_1 &= S_2 \end{aligned}$$

$$\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0 \quad \text{when } \alpha = \omega_0 = R/2L$$

$$\frac{d^2 i}{dt^2} + 2\alpha \frac{di}{dt} + \alpha^2 i = 0 \rightarrow \frac{d}{dt} \left( \frac{di}{dt} + \alpha i \right) + \alpha \left( \frac{di}{dt} + \alpha i \right) = 0$$

$$f = \left( \frac{di}{dt} + \alpha i \right)$$

$$\frac{d}{dt} \left( \frac{di}{dt} + \alpha i \right) + \alpha \left( \frac{di}{dt} + \alpha i \right) = 0 \rightarrow \frac{df}{dt} + \alpha f = 0$$

We get a first-order differential equation with solution  $f = A_1 e^{-\alpha t}$

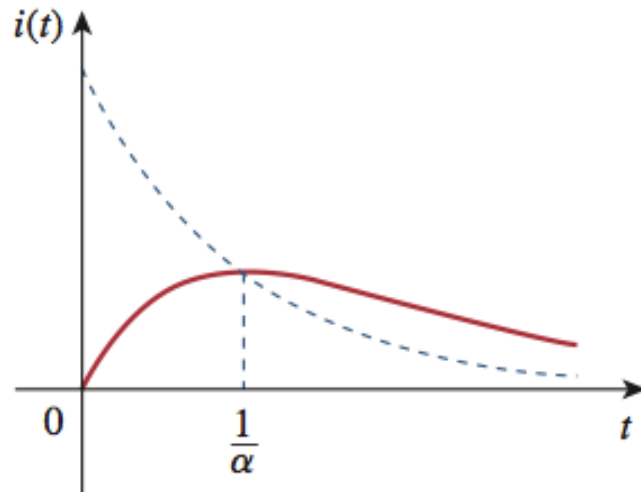
$$\frac{di}{dt} + \alpha i = A_1 e^{-\alpha t} \rightarrow e^{\alpha t} \frac{di}{dt} + e^{\alpha t} \alpha i = A_1$$

$$\rightarrow \frac{d}{dt} (e^{\alpha t} i) = A_1$$

Integrating both sides of the eq.  $\frac{d}{dt}(e^{\alpha t}i) = A_1$

Then, we get  $e^{\alpha t}i = A_1t + A_2$

and finally it becomes  $i(t) = (A_2 + A_1t)e^{-\alpha t}$



1. (no) oscillation
2. region 1:  $i(t)$  reaches a maximum value at  $t = 1/\alpha$
3. region 2: decays all the way to zero
4.  $\alpha \uparrow$  (more damping)  $\rightarrow$  reaches steady state faster

## Second Order Equation – Solution $S_1$ and $S_2$

### Case 3: Underdamped

3. If  $\alpha < \omega_0$ ,  $s_1 = -\alpha + j\omega_d$ ,  $s_2 = -\alpha - j\omega_d$ , where  $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$   
 $\omega_d$  is called the *damping frequency*

We have the underdamped case,

$$i(t) = e^{-\alpha t} (C_1 \cos \omega_d t + C_2 \sin \omega_d t)$$

where

$$C_1 = i(0^+)$$

$$C_2 = \frac{i'(0^+) + \alpha i(0^+)}{\omega_d}$$

$S_1, S_2$  are  
complex conjugates

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \quad s_1 = -\alpha + j\omega_d, \quad s_2 = -\alpha - j\omega_d$$

$$\begin{aligned} i(t) &= A_1 e^{-(\alpha - j\omega_d)t} + A_2 e^{-(\alpha + j\omega_d)t} \\ &= e^{-\alpha t} (A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t}) \end{aligned}$$

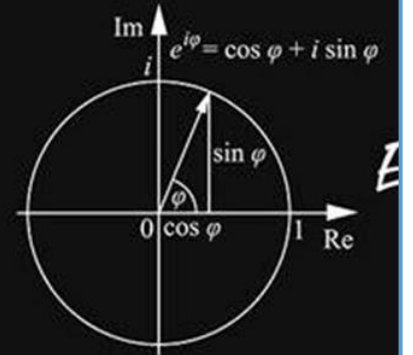
$$e^{j\omega_d t} = \cos \omega_d t + j \sin \omega_d t$$

$$e^{-j\omega_d t} = \cos \omega_d t - j \sin \omega_d t$$

Using Euler's identities,

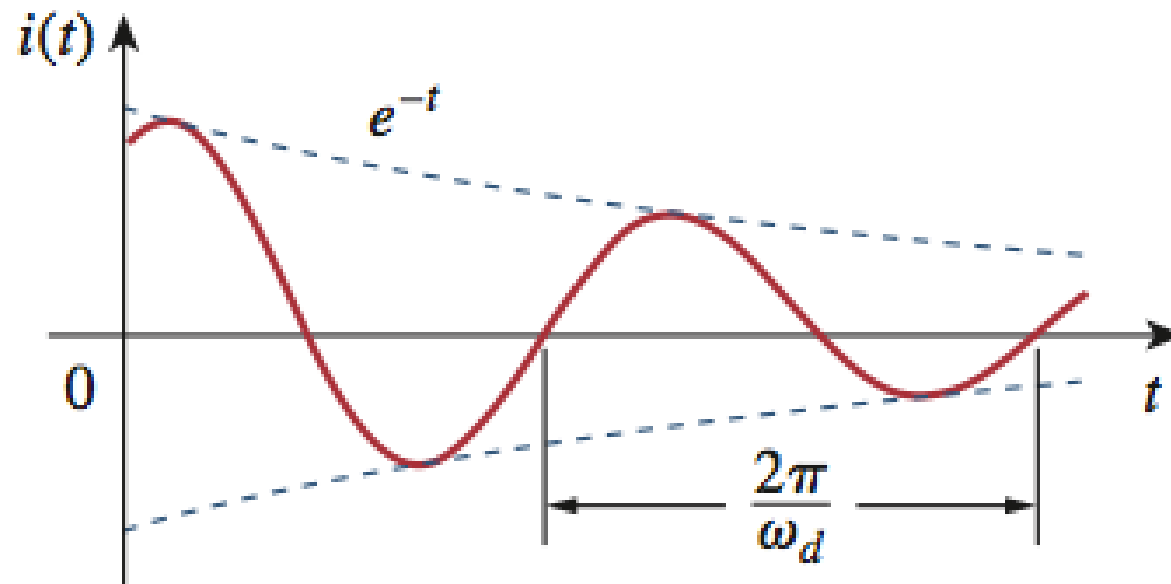
$$e^{j\theta} = \cos \theta + j \sin \theta,$$

$$e^{-j\theta} = \cos \theta - j \sin \theta$$



$$\begin{aligned} i(t) &= e^{-\alpha t} [A_1 (\cos \omega_d t + j \sin \omega_d t) + A_2 (\cos \omega_d t - j \sin \omega_d t)] \\ &= e^{-\alpha t} [(A_1 + A_2) \cos \omega_d t + j(A_1 - A_2) \sin \omega_d t] \end{aligned}$$

➡  $i(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$



$$i(t) = e^{-\alpha t}(B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

1. Oscillatory response
2.  $\alpha \uparrow$  (more damping)  $\rightarrow$  reaches steady state faster
3.  $\pm e^{-\alpha t}$ : envelope
4.  $\omega_d$ : oscillation frequency

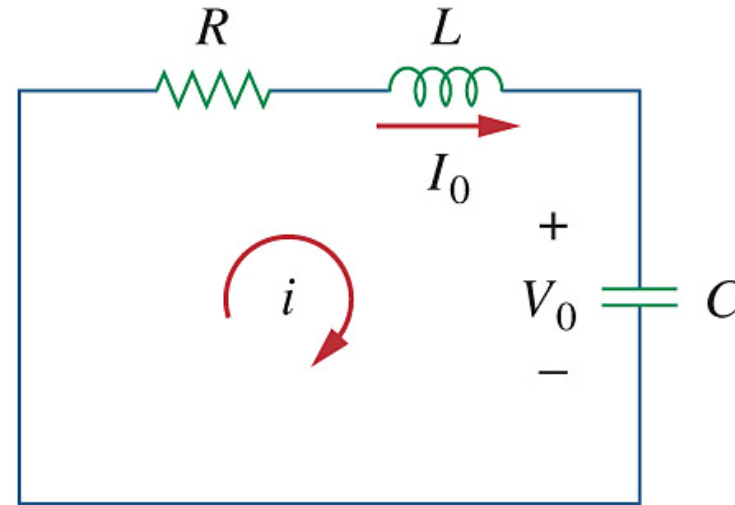
## Second Order Equation – Other parameters

Once the inductor current  $i(t)$  is found, other circuit quantities can be found,

$$v_R(t) = i(t)R$$

$$v_L(t) = L \frac{di(t)}{dt}$$

$$v_C(t) = \frac{1}{C} \int_0^t i(t) dt + v_C(0)$$





**Practice Problem 8.4** The circuit in Fig. 8.12 has reached steady state at  $t = 0^-$ . If the make-before-break switch moves to position  $b$  at  $t = 0$ , calculate  $i(t)$  for  $t > 0$ .

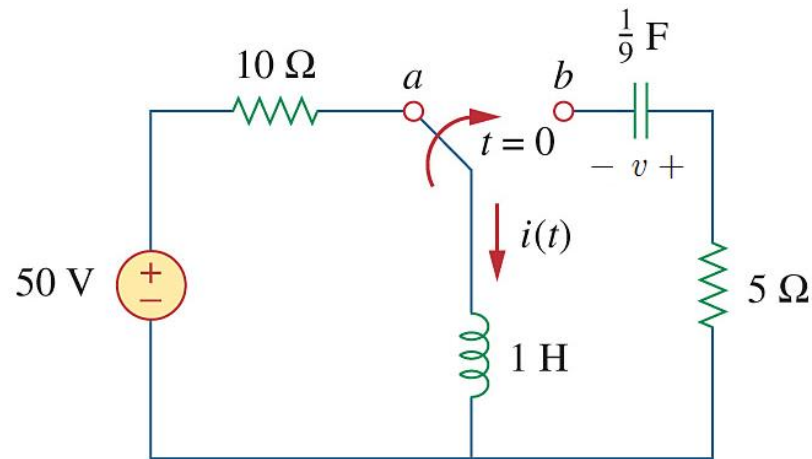


Figure 8.12

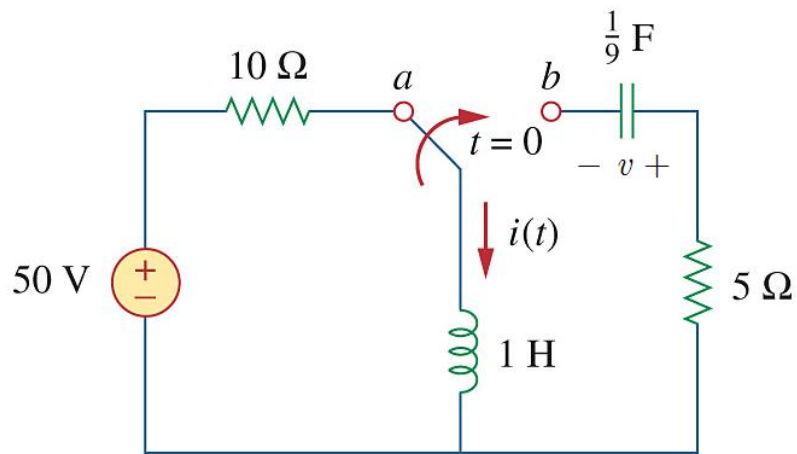


Figure 8.12

$$i(t) = e^{-2.5t} \left( A_1 \cos \frac{\sqrt{11}}{2} t + A_2 \sin \frac{\sqrt{11}}{2} t \right)$$

$$i(0^+) = A_1 \Rightarrow A_1 = i(0^+) = 5$$

$$\begin{aligned} i'(0^+) &= -2.5A_1 + \frac{\sqrt{11}}{2} A_2 \Rightarrow A_2 = \frac{i'(0^+) + 2.5A_1}{\sqrt{11}/2} \\ &= \frac{-25 + 2.5 \times 5}{\sqrt{11}/2} = -\frac{25}{\sqrt{11}} \end{aligned}$$

$$i(t) \approx e^{-2.5t} (5 \cos 1.6583t - 7.5378 \sin 1.6583t) \text{ (A)}$$

$$\begin{aligned} i(t) &= e^{-\alpha t} [A_1 (\cos \omega_d t + j \sin \omega_d t) + A_2 (\cos \omega_d t - j \sin \omega_d t)] \\ &= e^{-\alpha t} [(A_1 + A_2) \cos \omega_d t + j(A_1 - A_2) \sin \omega_d t] \end{aligned}$$

$$\Rightarrow i(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

(i)  $A_1 + A_2 = 5$

(ii)  $j(A_1 - A_2) = -7.54 \rightarrow A_1 - A_2 = +j7.54$

**$A_2 = 2.5 - j3.77$  and  $A_1 = 2.5 + j3.77$**

### Initial Conditions:

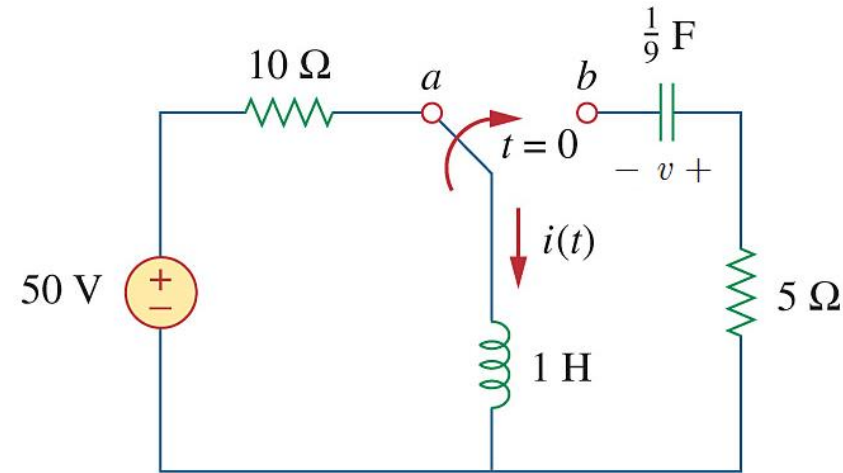
$$i(0^+) = i(0^-) = \frac{50}{10} = 5 \text{ (A)}$$

$$v(0^+) = v(0^-) = 0 \text{ (V)}$$

$$1 \times \frac{di(t)}{dt} + i(t) \times 5 + v(t) = 0, i(t) = \frac{1}{9} \frac{dv(t)}{dt}$$

$$\begin{aligned} i'(0^+) &= -5i(0^+) - v(0^+) = -5 \times 5 - 0 \\ &= -25 \text{ (A/s)} \end{aligned}$$

i)  $t > 0$



$$1 \times \frac{d^2 i(t)}{dt^2} + \frac{di(t)}{dt} \times 5 + \frac{dv(t)}{dt} = 0$$

$$1 \times \frac{d^2 i(t)}{dt^2} + \frac{di(t)}{dt} \times 5 + \frac{1}{1/9} i(t) = 0$$

$$\frac{d^2 i(t)}{dt^2} + 5 \frac{di(t)}{dt} + 9i(t) = 0$$

$$s = \frac{-5 \pm \sqrt{5^2 - 4 \times 1 \times 9}}{2 \times 1} = \frac{-5 \pm j\sqrt{11}}{2}$$

$$i(t) = e^{-2.5t} \left( A_1 \cos \frac{\sqrt{11}}{2} t + A_2 \sin \frac{\sqrt{11}}{2} t \right)$$

$$i(0^+) = A_1 \Rightarrow A_1 = i(0^+) = 5$$

$$i'(0^+) = -2.5A_1 + \frac{\sqrt{11}}{2} A_2 \Rightarrow A_2 = \frac{i'(0^+) + 2.5A_1}{\sqrt{11}/2}$$

$$= \frac{-25 + 2.5 \times 5}{\sqrt{11}/2} = -\frac{25}{\sqrt{11}}$$

$$i(t) \approx e^{-2.5t} (5 \cos 1.6583t - 7.5378 \sin 1.6583t) \text{ (A)}$$

$$i(0^+) = A_1 \Rightarrow A_1 = i(0^+) = 5$$

$$i'(0^+) = -2.5A_1 + \frac{\sqrt{11}}{2} A_2 \Rightarrow A_2 = \frac{i'(0^+) + 2.5A_1}{\sqrt{11}/2}$$

$$= \frac{-25 + 2.5 \times 5}{\sqrt{11}/2} = -\frac{25}{\sqrt{11}}$$

$$i(t) \approx e^{-2.5t} (5 \cos 1.6583t - 7.5378 \sin 1.6583t) \text{ (A)}$$

$$\begin{aligned} i(t) &= e^{-\alpha t} [A_1 (\cos \omega_d t + j \sin \omega_d t) + A_2 (\cos \omega_d t - j \sin \omega_d t)] \\ &= e^{-\alpha t} [(A_1 + A_2) \cos \omega_d t + j(A_1 - A_2) \sin \omega_d t] \end{aligned}$$

$$\Rightarrow i(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

$$(i) \quad A_1 + A_2 = 5$$

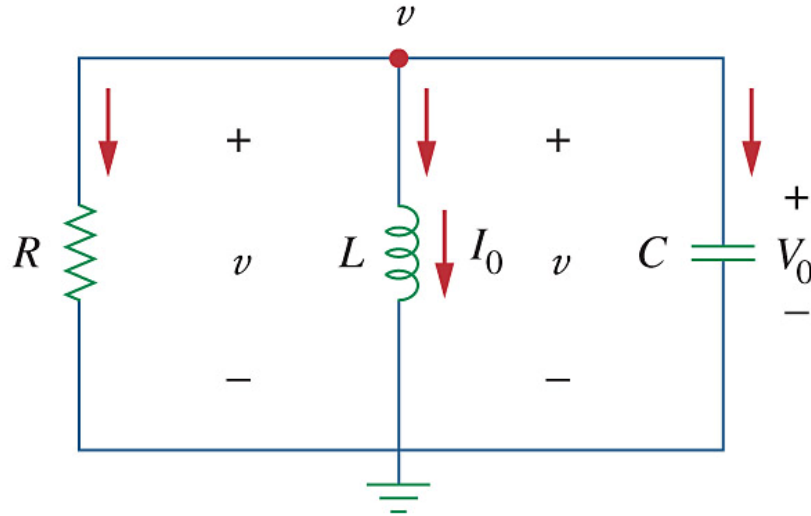
$$(ii) \quad j(A_1 - A_2) = -7.54 \rightarrow A_1 - A_2 = +j7.54$$

$$\mathbf{A_2 = 2.5 - j3.77 \text{ and } A_1 = 2.5 + j3.77}$$

## Steps for source-free 2<sup>nd</sup> order circuit

1. Plot the circuit at  $t < 0$ , find initial conditions,  $i(0^+)$ ,  $v(0^+)$
2. Plot the circuit at  $t > 0$ , express  $di/dt$  or  $dv/dt$  in terms of  $i_L$  and  $v_C$ , find initial conditions  $di(0^+)/dt$ ,  $dv(0^+)/dt$
3. Express the circuit in 2<sup>nd</sup> order D.E. with only one parameter (either  $i$  or  $v$ ) and solve it.
4. Solve the coefficients using initial conditions.

## 8.4 The Source-Free Parallel *RLC* Circuit

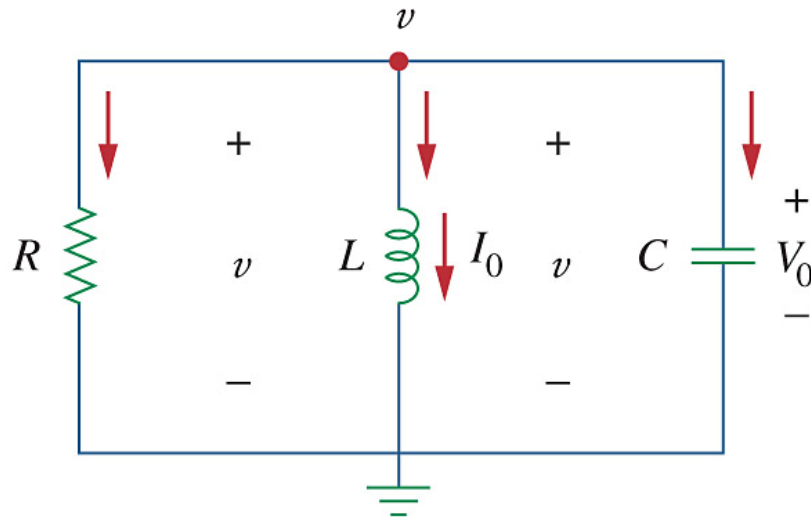


RLC are in parallel (the same voltage). The energy initially stored in C and L:

$$i(0) = I_0 = \frac{1}{L} \int_{-\infty}^0 v(t) dt$$

$$v(0) = V_0$$





By KCL:  $\frac{v}{R} + \frac{1}{L} \int_{-\infty}^t v dt + C \frac{dv}{dt} = 0$

$$\frac{1}{R} \frac{dv}{dt} + \frac{1}{L} v + C \frac{d^2 v}{dt^2} = 0$$

$$\frac{d^2 v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

The characteristic equation is  $\mathbf{s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0}$

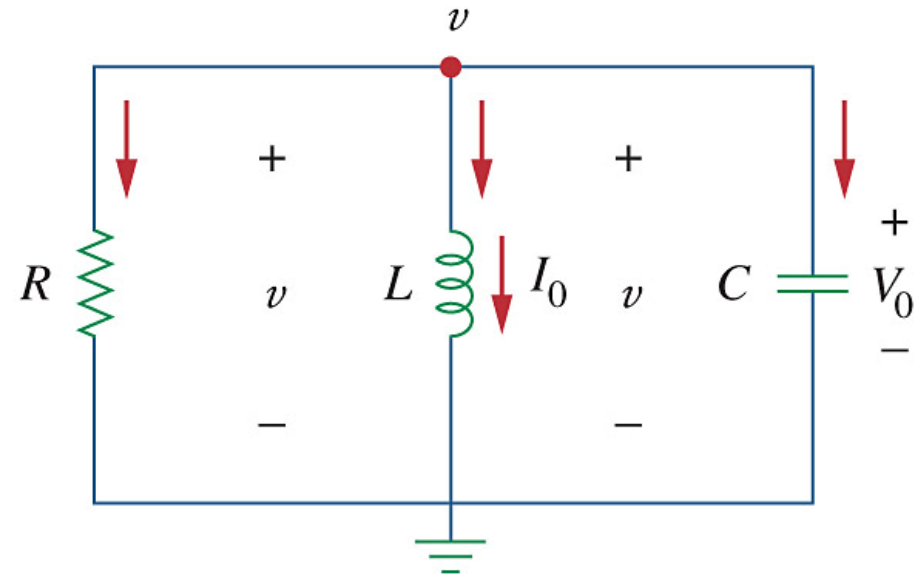
The initial conditions are

$$v(0^+) = v(0^-) = V_0$$

$$v'(0^+) = -\frac{1}{C} \left( v(0^+) / R + i(0^+) \right) \quad \text{from} \quad \frac{v}{R} + i + C \frac{dv}{dt} = 0$$

$$= -\frac{1}{C} \left( v(0^-) / R + i(0^-) \right)$$

$$= -\frac{1}{C} (V_0 / R + I_0)$$



$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$

$$s = \frac{-1/(RC) \pm \sqrt{1/(RC)^2 - 4 \times 1 \times (1/(LC))}}{2 \times 1}$$

$$= -\frac{1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$

$$= -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\alpha = \frac{1}{2RC}$$

Neper frequency (damping factor) Np/s

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

Resonant frequency (undamped natural frequency) rad/s

Finally, we get solutions

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}, s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

Natural frequency Np/s

There are three types of solutions:

(1) Overdamped case

$$\text{If } \alpha > \omega_0, s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

(2) Critically damped case

$$\text{If } \alpha = \omega_0, s_1 = s_2 = -\alpha$$

$$v(t) = (B_1 t + B_2) e^{-\alpha t}$$

(3) Underdamped case

$$\text{If } \alpha < \omega_0, s_1 = -\alpha + j\omega_d, s_2 = -\alpha - j\omega_d$$

$$v(t) = e^{-\alpha t} (C_1 \cos \omega_d t + C_2 \sin \omega_d t)$$

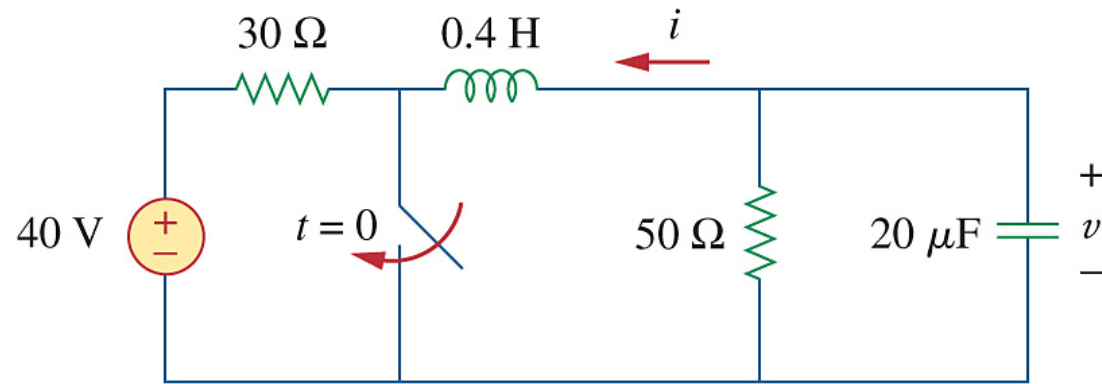
Once the capacitor voltage  $v(t)$  is found, other circuit quantities can be found

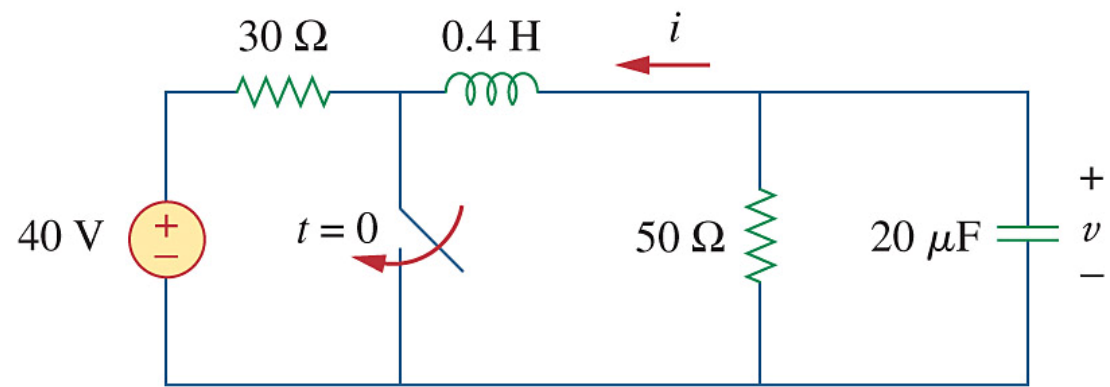
$$i_R(t) = \frac{v(t)}{R}$$

$$i_L(t) = \frac{1}{L} \int_0^t v(t) dt + i_L(0)$$

$$i_C(t) = C \frac{dv(t)}{dt}$$

**Example 8.6** Find  $v(t)$  for  $t > 0$  in the  $RLC$  circuit of Fig. 8.15.





$$\frac{1}{LC} = \frac{1}{0.4 \times 20 \times 10^{-6}} = 125000$$

$$\frac{1}{RC} = \frac{1}{50 \times 20 \times 10^{-6}} = 1000$$

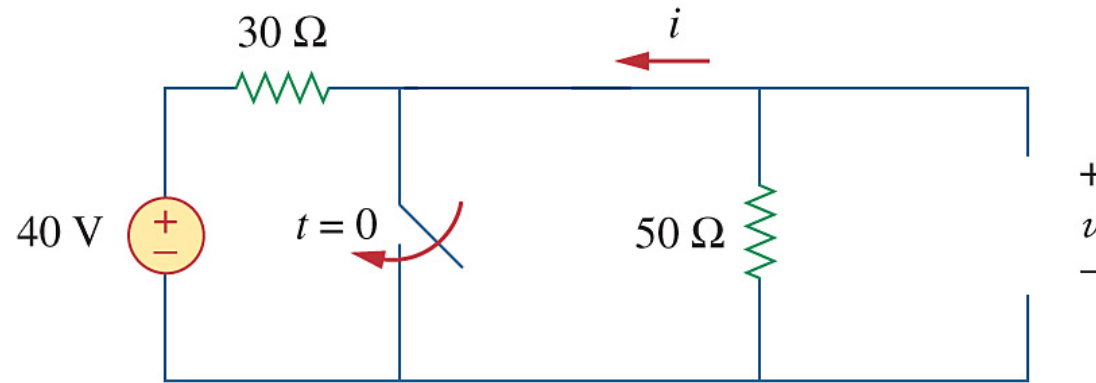
~707

$$s_{1,2} = \frac{-1000 \pm \sqrt{1000^2 - 4 \times 1 \times 125000}}{2 \times 1}$$

$$s_1 = -146.5 \text{ and } s_2 = -853.5$$

(i)  $t < 0$

Equivalent Circuit

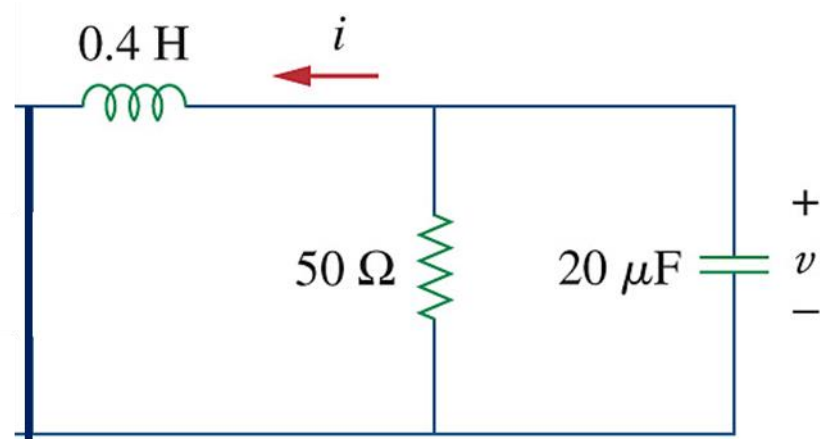


$$v(0^+) = v(0^-) = 40 \times \frac{50}{30 + 50} = 25 \text{ (V)}$$

$$i(0^+) = i(0^-) = -\frac{40}{30 + 50} = -0.5 \text{ (A)}$$



(ii)  $t > 0$



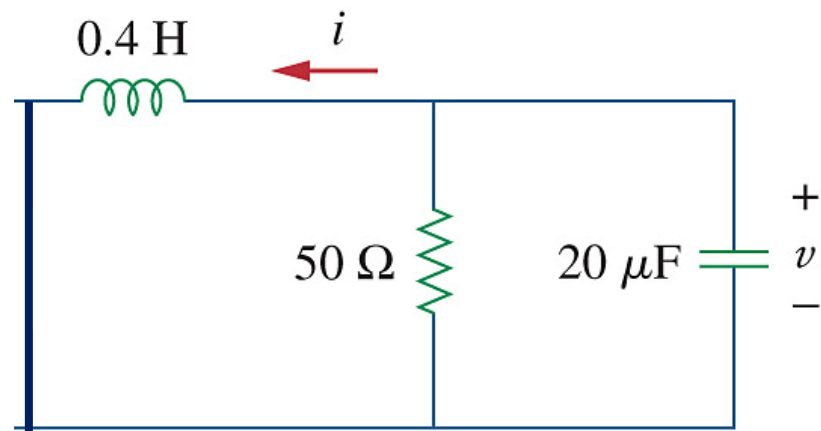
By KCL:

$$\frac{1}{L} \int v dt + \frac{v}{R} + C \frac{dv}{dt} = 0$$

$$\text{At } t=0+, i(0+) + \frac{v(0+)}{50} + 20 \times 10^{-6} \frac{dv(0+)}{dt} = 0$$

$$v'(0+) = -\frac{1}{C} (v(0+) / R + i(0+))$$

$$= -\frac{1}{20 \times 10^{-6}} (25 / 50 + (-0.5)) = 0 \text{ (V/s)}$$



By KCL:

$$\frac{1}{L} \int v \, dt + \frac{v}{R} + C \frac{dv}{dt} = 0$$

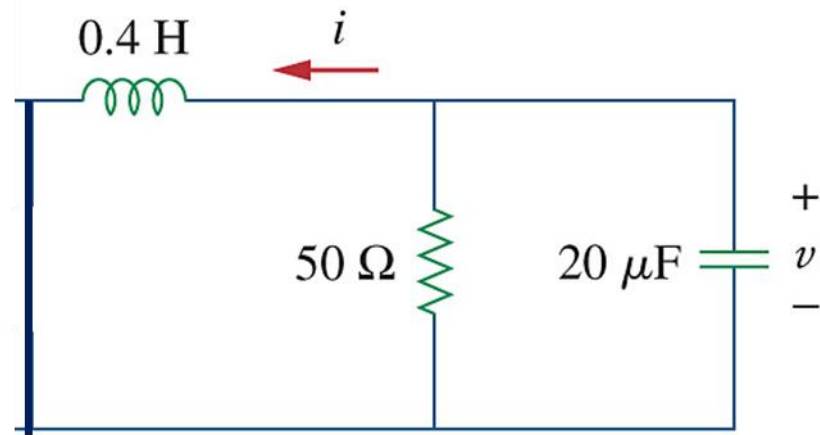
$$\frac{d^2 v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

$$\frac{1}{LC} = \frac{1}{0.4 \times 20 \times 10^{-6}} = 125000$$

$$\frac{1}{RC} = \frac{1}{50 \times 20 \times 10^{-6}} = 1000$$

$$\frac{d^2 v}{dt^2} + 1000 \frac{dv}{dt} + 125000 v = 0 \quad \sim 707$$

$$s_{1,2} = \frac{-1000 \pm \sqrt{1000^2 - 4 \times 1 \times 125000}}{2 \times 1}$$



$$S_1 = -146.5 \text{ and } S_2 = -853.5$$

$$v(t) = A_1 e^{-146.5t} + A_2 e^{-853.5t}$$

Initial conditions

$$(i) \ v(0) = A_1 + A_2 = 25$$

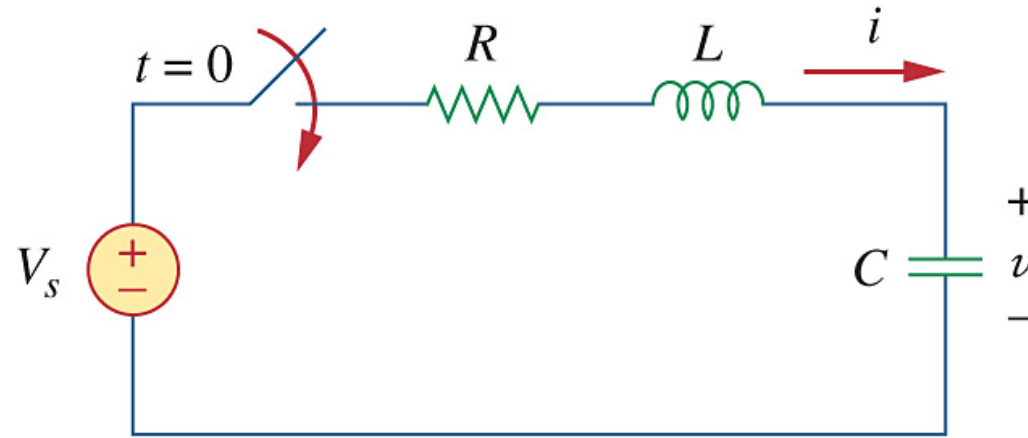
$$(ii) \ v'(0) = -146.5A_1 - 853.5A_2 = 0$$

$$\rightarrow A_1 = 30.2 \text{ and } A_2 = -5.2$$

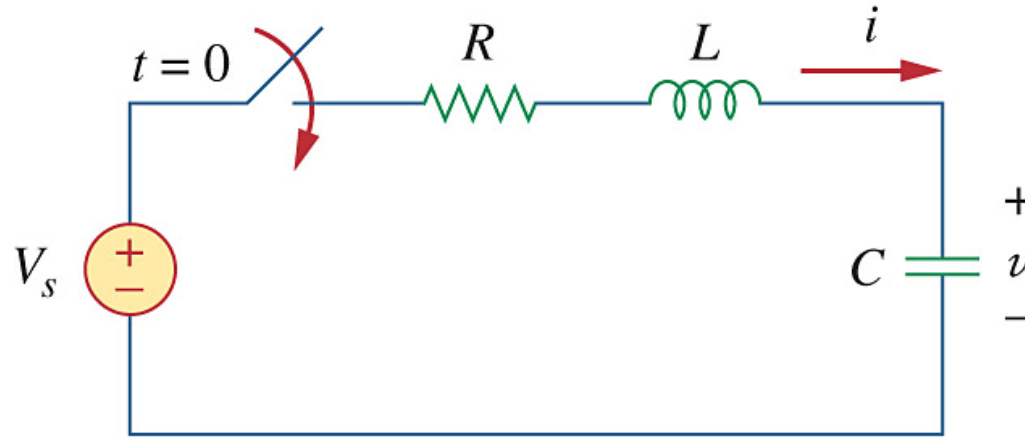
$$\text{Thus, } v(t) = 30.2e^{-146.5t} - 5.2e^{-853.5t} \text{ [V]}$$

## 8.5 Series *RLC* Circuit with Step Input

The step response is obtained by the sudden application of a dc source.



$$\begin{cases} V_s = iR + L \frac{di}{dt} + v \\ i = C \frac{dv}{dt} \end{cases}$$



$$\begin{cases} V_s = iR + L \frac{di}{dt} + v \\ i = C \frac{dv}{dt} \end{cases}$$

$$LC \frac{d^2 v}{dt^2} + RC \frac{dv}{dt} + v = V_s$$

$$\frac{d^2 v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{1}{LC} v = \frac{1}{LC} V_s$$

**The characteristic equation** for the series RLC circuit is not affected by the presence of the dc source:

the **transient response** and the **steady-state response**

**The transient response** is the component of the total response that **dies out with time**. The form of the transient response is the same as the form of the solution obtained for the source-free circuit.

The transient response

$$v_t(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \quad (\text{Overdamped})$$

$$v_t(t) = (A_1 + A_2 t) e^{-\alpha t} \quad (\text{Critically damped})$$

$$v_t(t) = (A_1 \cos \omega_d t + A_2 \sin \omega_d t) e^{-\alpha t} \quad (\text{Underdamped})$$

The steady-state response  $v_{ss}(t) = v(\infty) = V_s$

The total response:  $v(t) = v_t(t) + v_{ss}(t)$

## The complete solutions

It can be shown that the solution has three possible forms:

(1) Overdamped

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + V_s$$

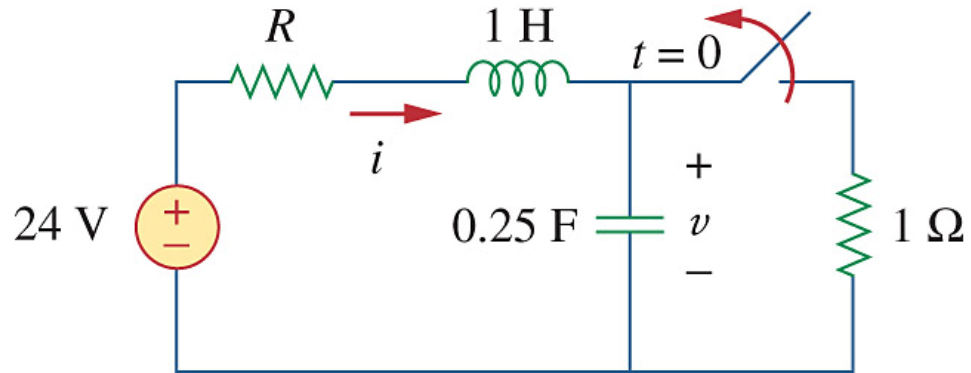
(2) Critically damped

$$v(t) = (A_1 + A_2 t) e^{-\alpha t} + V_s$$

(3) Underdamped

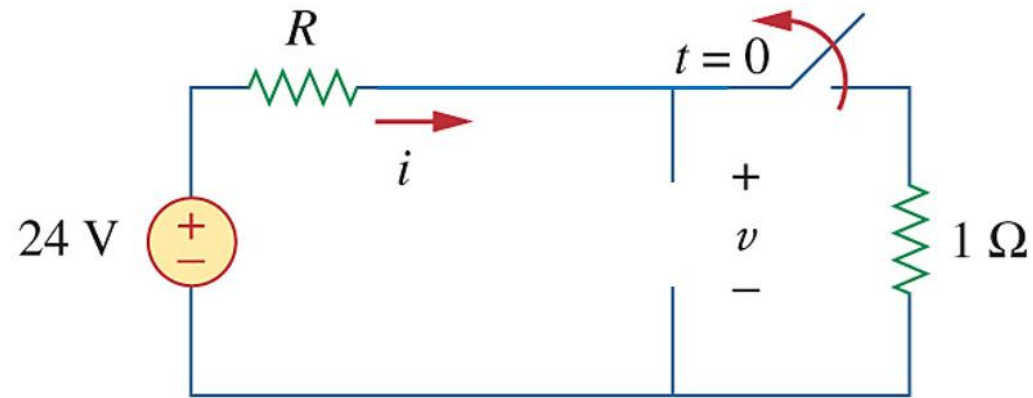
$$v(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t) + V_s$$

**Example 8.7** For the circuit in Fig. 8.19, find  $v(t)$  for  $t > 0$ . Consider these cases:  
 $R = 5\ \Omega$ ,  $R = 4\ \Omega$ ,  $R = 1\ \Omega$ .





# (1) $t < 0$ , initial conditions

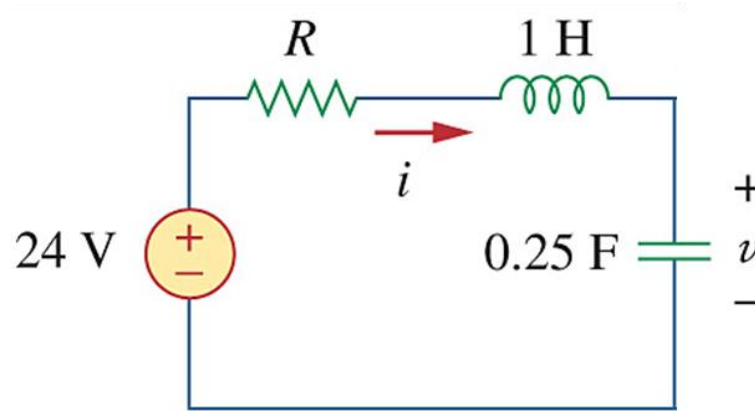


(a)  $R = 5$

$$i(0^-) = \frac{24}{R+1} = 4 \text{ [A]}$$

$$v(0^-) = 24 \times \frac{1}{R+1} = 4 \text{ [V]}$$

**(ii)  $t > 0$  – find  $i(t)$  first**



$$-24 + 5i + 1 \frac{di}{dt} + 4 \int i dt = 0 \rightarrow \frac{d^2 i}{dt^2} + 5 \frac{di}{dt} + 4i = 0$$

$$s^2 + 5s + 4 = 0 \Rightarrow s_1 = -1, s_2 = -4$$

$$i(t) = A_1 e^{-t} + A_2 e^{-4t}$$

Initial conditions:

(i)  $i(0) = 4 \text{ [A]}$

(ii)  $i'(0) = ?$

Initial conditions:

(i)  $i(0) = 4 \text{ [A]}$

(ii)  $i'(0) = ?$

$$\text{At } t = 0, -24 + 5i(0) + 1 \frac{di(0)}{dt} + v(0) = 0$$

$$\rightarrow di(0)/dt = 0 \text{ [A/s]}$$

Using the initial conditions we can find two constants  $A_1 = 16/3$  and  $A_2 = -4/3$

$$i(t) = A_1 e^{-t} + A_2 e^{-4t} = \frac{16}{3} e^{-t} - \frac{4}{3} e^{-4t} \text{ [A]}$$

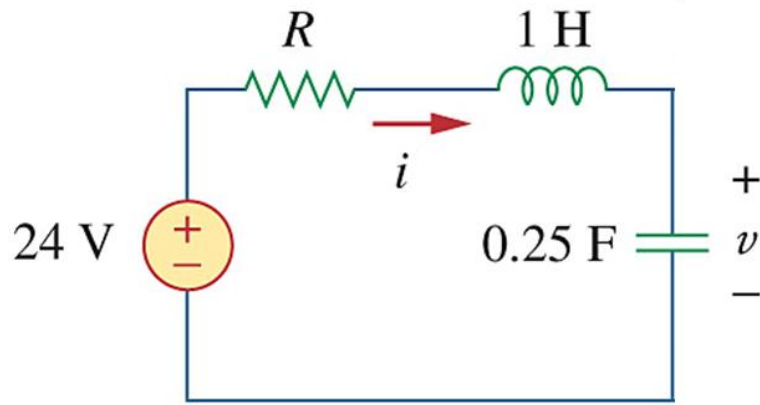
IV of the capacitor  $i(t) = C \frac{dv(t)}{dt}$

$$\rightarrow v(t) = \frac{1}{C} \int_0^t i(\tau) d\tau + v(0)$$

$$v(t) = -\frac{64}{3}e^{-t} + \frac{4}{3}e^{-4t} + 20 + v(0)$$

$$\mathbf{v(t) = -\frac{64}{3}e^{-t} + \frac{4}{3}e^{-4t} + 24 [V]}$$

(iii)  $t > 0$  – find  $v(t)$  directly



$$i(0^+) = i(0^-) = \frac{24}{R+1}$$

$$v(0^+) = v(0^-) = 24 \times \frac{1}{R+1}$$

$$i(t) = 0.25 \frac{dv(t)}{dt} \Rightarrow v'(0^+) = \frac{1}{0.25} i(0^+)$$

$$\frac{d^2v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{1}{LC} v = \frac{1}{LC} V_s$$

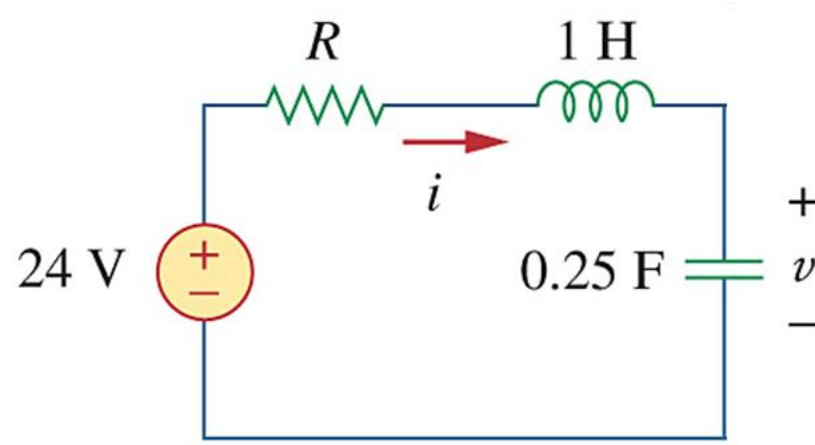
(a)  $R = 5 \Omega$

$$i(0^+) = 4 \text{ A}, v(0^+) = 4 \text{ V}, v'(0^+) = 16 \text{ V/s}$$

$$\frac{d^2v}{dt^2} + 5 \frac{dv}{dt} + 4v = 96$$

$$s^2 + 5s + 4 = 0 \Rightarrow s_1 = -1, s_2 = -4$$

➡  $v_n(t) = A_1 e^{-t} + A_2 e^{-4t}$



$$v_f(t) = B \Rightarrow B = 96 / 4 = 24 \quad \leftarrow \quad \frac{d^2v}{dt^2} + 5\frac{dv}{dt} + 4v = 96$$

$$v(t) = v_n(t) + v_f(t) = A_1 e^{-t} + A_2 e^{-4t} + 24$$

$$v(0^+) = A_1 + A_2 + 24 = 4$$

$$v'(0^+) = -A_1 - 4A_2 = 16$$

$$A_1 = -\frac{64}{3}, \quad A_2 = \frac{4}{3}$$

$$v(t) = -\frac{64}{3} e^{-t} + \frac{4}{3} e^{-4t} + 24 \text{ (V)}$$

$$i(t) = \frac{16}{3} e^{-t} - \frac{4}{3} e^{-4t} \text{ (A)}$$

$$(b) R = 4 \, \Omega$$

$$i(0^+) = 4.8 \, \text{A}, v(0^+) = 4.8 \, \text{V}, v'(0^+) = 19.2 \, \text{V/s}$$

$$\frac{d^2v}{dt^2} + 4\frac{dv}{dt} + 4v = 96$$

$$s^2 + 4s + 4 = 0 \Rightarrow s_1 = s_2 = -2$$

$$v_n(t) = (A_1 + A_2 t)e^{-2t}$$

$$v_f(t) = B \Rightarrow B = 96 / 4 = 24$$

$$v(t) = v_n(t) + v_f(t) = (A_1 + A_2 t)e^{-2t} + 24$$

$$v(0^+) = A_1 + 24 = 4.8$$

$$v'(0^+) = A_2 - 2A_1 = 19.2$$

$$A_1 = A_2 = -19.2$$

$$\begin{aligned} v(t) &= (-19.2 - 19.2t)e^{-2t} + 24 \, (\text{V}) \\ i(t) &= 4.8(1 + 2t)e^{-2t} \, (\text{A}) \end{aligned}$$

$$(c) R = 1 \, \Omega$$

$$i(0^+) = 12 \, \text{A}, v(0^+) = 12 \, \text{V}, v'(0^+) = 48 \, \text{V/s}$$

$$\frac{d^2v}{dt^2} + \frac{dv}{dt} + 4v = 96$$

$$s^2 + s + 4 = 0 \Rightarrow s_{1,2} = -\frac{1}{2} \pm j \frac{\sqrt{15}}{2}$$

$$v_n(t) = e^{-t/2} \left( A_1 \cos \frac{\sqrt{15}}{2} t + A_2 \sin \frac{\sqrt{15}}{2} t \right)$$

$$v_f(t) = B \Rightarrow B = 96 / 4 = 24$$

$$v(t) = v_n(t) + v_f(t)$$

$$= e^{-t/2} \left( A_1 \cos \frac{\sqrt{15}}{2} t + A_2 \sin \frac{\sqrt{15}}{2} t \right) + 24$$



$$v(0^+) = A_1 + 24 = 12$$

$$v'(0^+) = -\frac{1}{2}A_1 + \frac{\sqrt{15}}{2}A_2 = 48$$

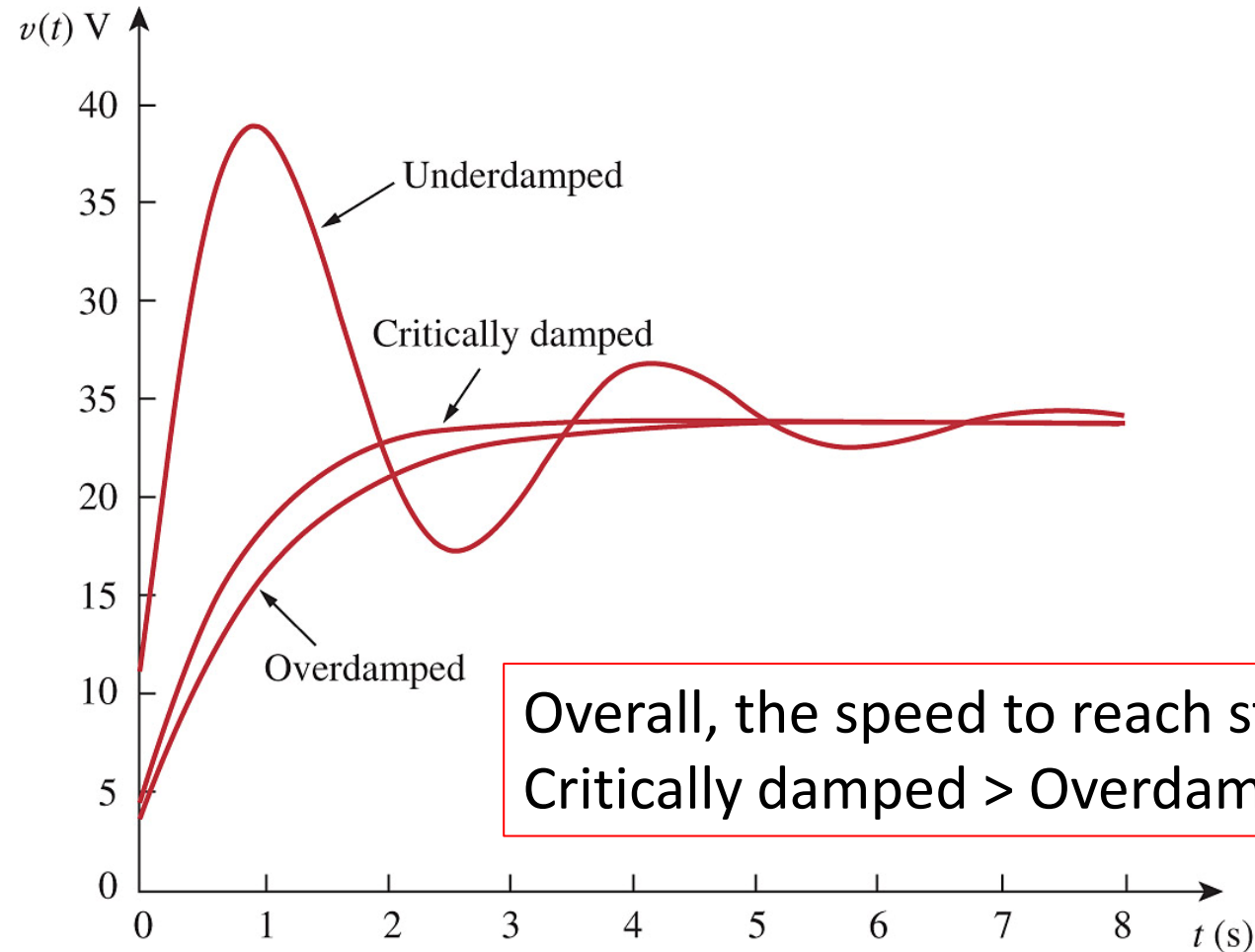
$$A_1 = -12, A_2 = \frac{84}{\sqrt{15}} \approx 21.689$$

$$v(t) = e^{-t/2} \left( -12 \cos \frac{\sqrt{15}}{2} t + \frac{84}{\sqrt{15}} \sin \frac{\sqrt{15}}{2} t \right) + 24 \text{ (V)}$$

$$i(t) = e^{-t/2} \left( 12 \cos \frac{\sqrt{15}}{2} t + \frac{12}{\sqrt{15}} \sin \frac{\sqrt{15}}{2} t \right) \text{ (A)}$$

R	5Ω	4Ω	1Ω
α (R/2L)	2.5	2	0.5
V <sub>f</sub>	24V	24V	24V
	Overdamped	Critically damped	Underdamped

Plots of the three responses. The critically damped response approaches the step input 24 V the fastest.



Overall, the speed to reach steady state value:  
Critically damped > Overdamped > Underdamped

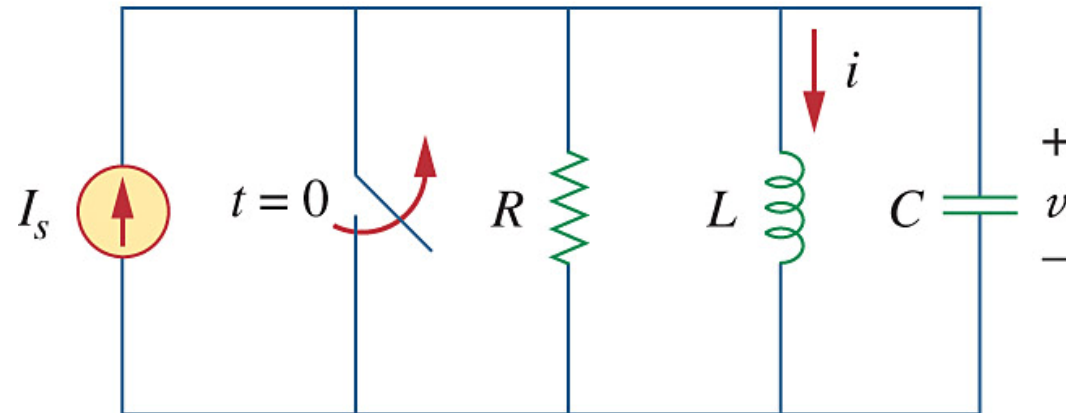
## Steps for 2<sup>nd</sup> order circuit with *step input*

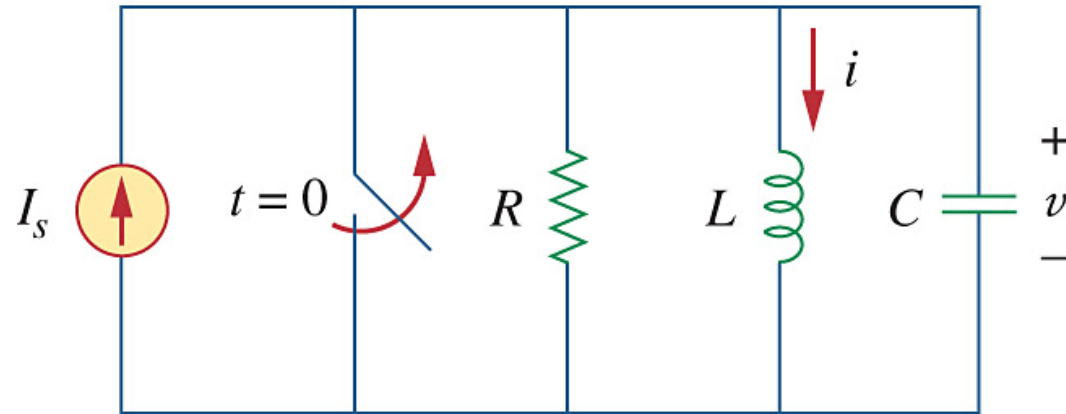
1. Plot the circuit at  $t < 0$ , find initial conditions,  $i(0^+)$ ,  $v(0^+)$
2. Plot the circuit at  $t > 0$ , express  $di/dt$  or  $dv/dt$  in terms of  $i_L$  and  $v_C$ , find initial conditions  $di(0^+)/dt$ ,  $dv(0^+)/dt$
3. Express the circuit in 2<sup>nd</sup> order D.E. with only one parameter (either  $i$  or  $v$ ) and solve it.
4. Plot the circuit at  $t \rightarrow \infty$ , find steady state values  $i(\infty)$ ,  $v(\infty)$  (or just solve forced response)
5. Solve the coefficients using initial conditions.

## 8.6 Parallel *RLC* Circuit with Step Input

Consider the circuit below. We want to find  $i$  due to a sudden application of a DC current.

At  $t > 0$ , apply KCL





$$I_s = \frac{v}{R} + i + C \frac{dv}{dt}, \quad v = L \frac{di}{dt}$$

$$LC \frac{d^2 i}{dt^2} + \frac{L}{R} \frac{di}{dt} + i = I_s \quad \Rightarrow \quad \frac{d^2 i}{dt^2} + \frac{1}{RC} \frac{di}{dt} + \frac{1}{LC} i = \frac{1}{LC} I_s$$

**Again, the characteristic equation** for the parallel RLC circuit is not affected by the presence of the dc source.

It can be shown that the solution has three possible forms:

(1) Overdamped

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + I_s$$

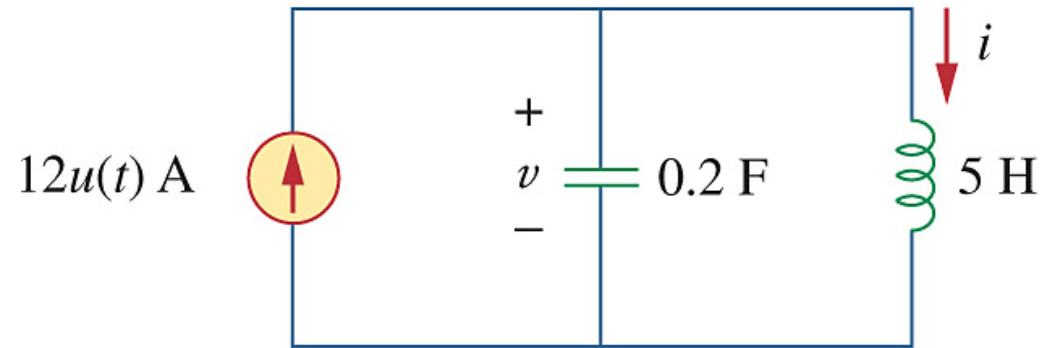
(2) Critically damped

$$i(t) = (A_1 + A_2 t) e^{-\alpha t} + I_s$$

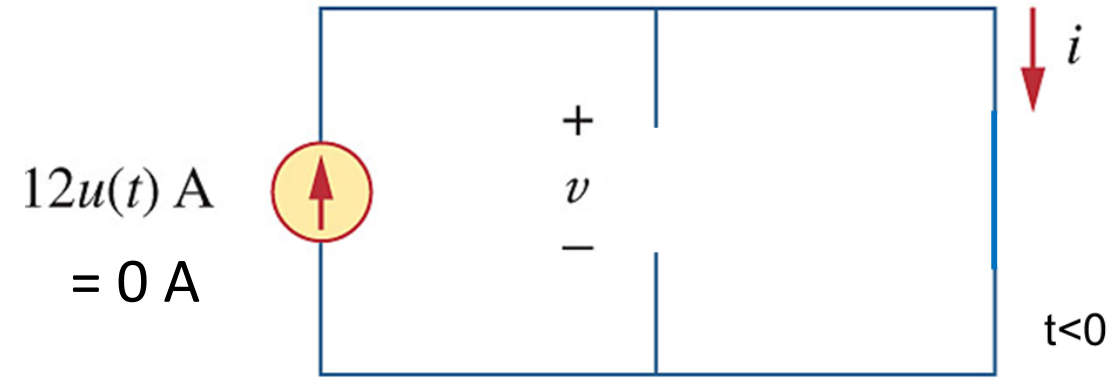
(3) Underdamped

$$i(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t) + I_s$$

**Practice Problem 8.8** Find  $i(t)$  and  $v(t)$  for  $t > 0$  in the circuit of Fig. 8.24.



**(i)  $t < 0$  initial conditions**



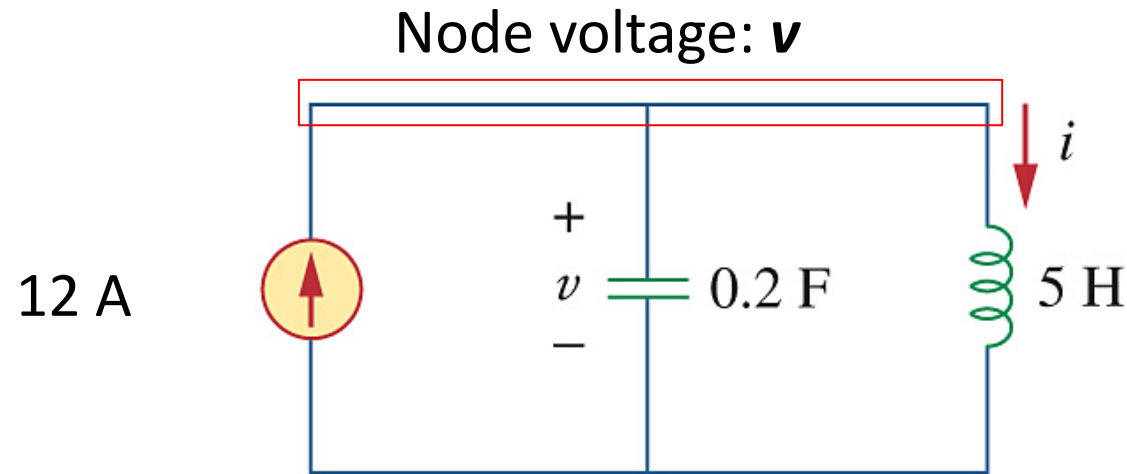
There is no source at  $t < 0$

$$i(0^-) = 0$$

$$v(0^-) = 0$$



(ii)  $t > 0$  – find voltage first



By KCL:

$$-12 + C \frac{dv}{dt} + \frac{1}{L} \int v dt = 0 \rightarrow \frac{d^2 v}{dt^2} + v = 0$$

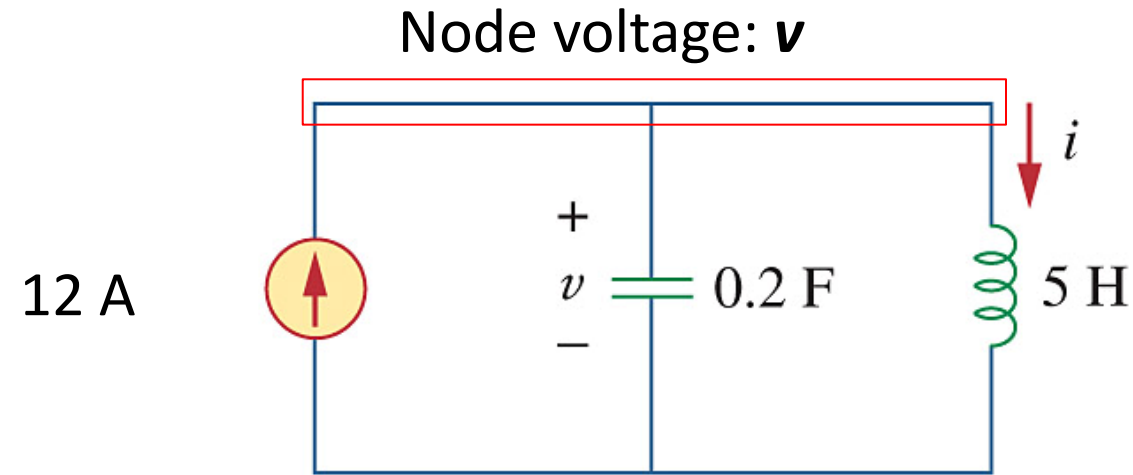
$$s^2 + 1 \Rightarrow s_{1,2} = \pm j$$

$$v(t) = A_1 \cos t + A_2 \sin t$$

Initial Conditions:

(i)  $v(0) = A_1 = 0$

(ii)  $v'(0) = A_2 = ?$



$$v(t) = A_1 \cos t + A_2 \sin t$$

Initial Conditions:

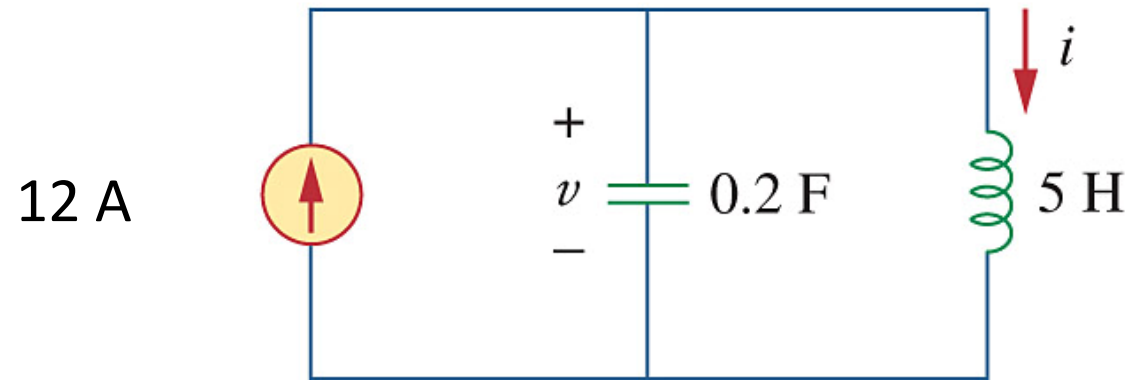
$$(i) \ v(0) = A_1 = 0$$

$$(ii) \ v'(0) = A_2 = 60 \quad \leftarrow -12 + 0.2 \frac{dv(0)}{dt} + i(0) = 0$$

$$v(t) = 60 \sin t \text{ [V]}$$

$$i_L(t) = \frac{1}{5} \int 60 \sin t \, dt + i_L(0) = 12(1 - \cos t) \text{ [A]}$$

(iii)  $t > 0$  – find current first



$$12 = 0.2 \frac{dv}{dt} + i, \quad v = 5 \frac{di}{dt}$$

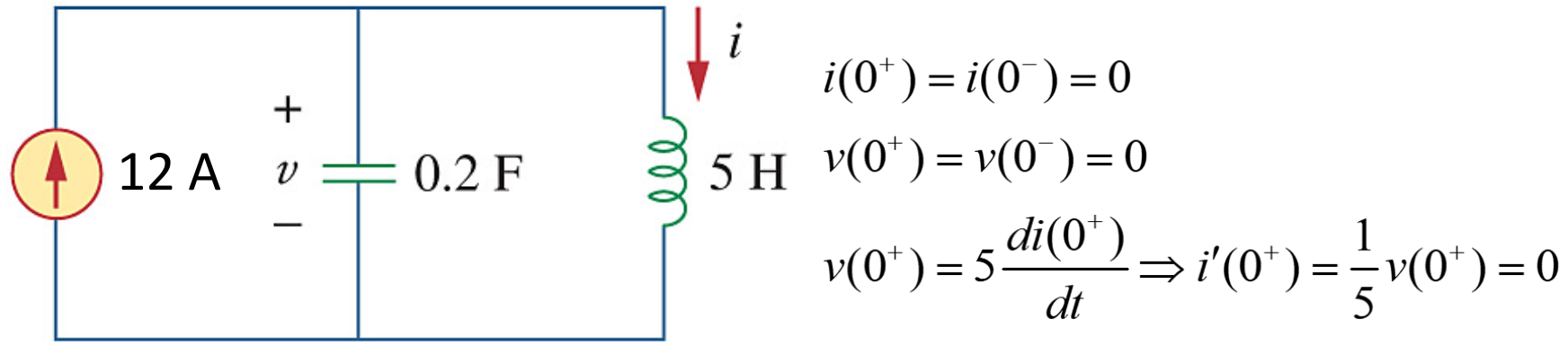
$$\frac{d^2 i}{dt^2} + i = 12$$

$$s^2 + 1 \Rightarrow s_{1,2} = \pm j$$

$$i_n(t) = A_1 \cos t + A_2 \sin t$$

$$i_p(t) = 12$$

$$i(t) = i_n(t) + i_p(t) = A_1 \cos t + A_2 \sin t + 12$$



$$i(0^+) = A_1 + 12 = 0$$

$$i'(0^+) = -A_2 = 0$$

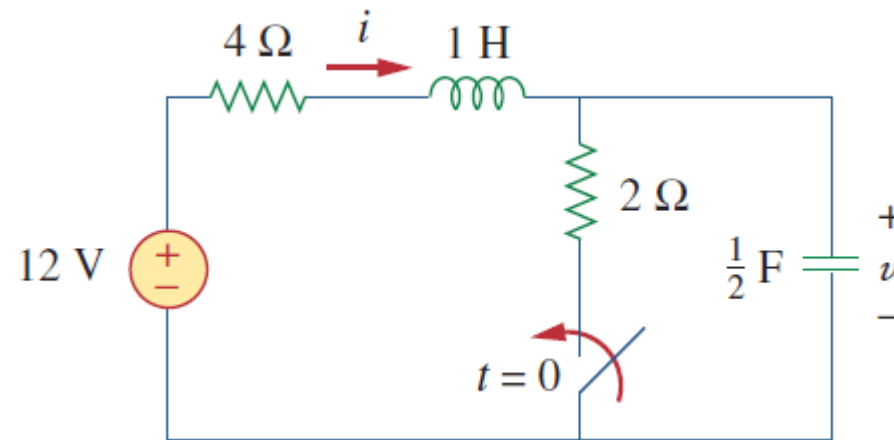
$$A_1 = -12, A_2 = 0$$

$$i(t) = -12 \cos t + 12 = 12(1 - \cos t) \text{ (A)}$$

$$v(t) = 5 \frac{di(t)}{dt} = 60 \sin t \text{ (V)}$$

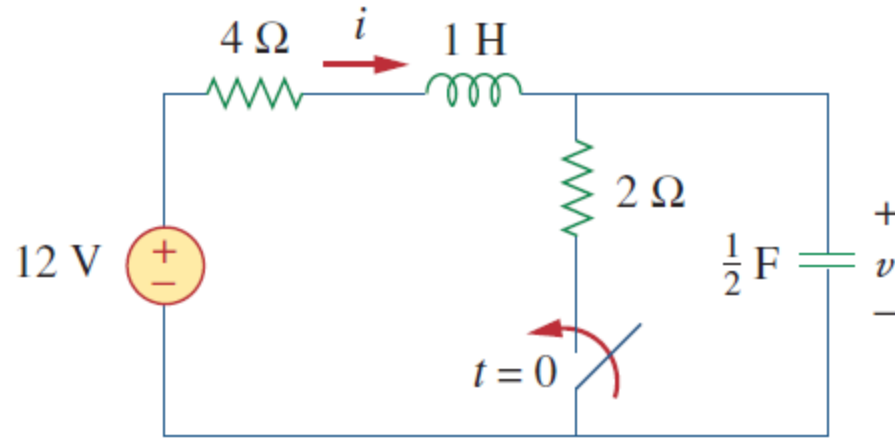
## 8.7 General Second-Order Circuits

We are prepared to apply the ideas to any second-order circuit having one or more independent sources with constant values  
→ **Mesh and Nodal Analysis to a RLC circuit.**

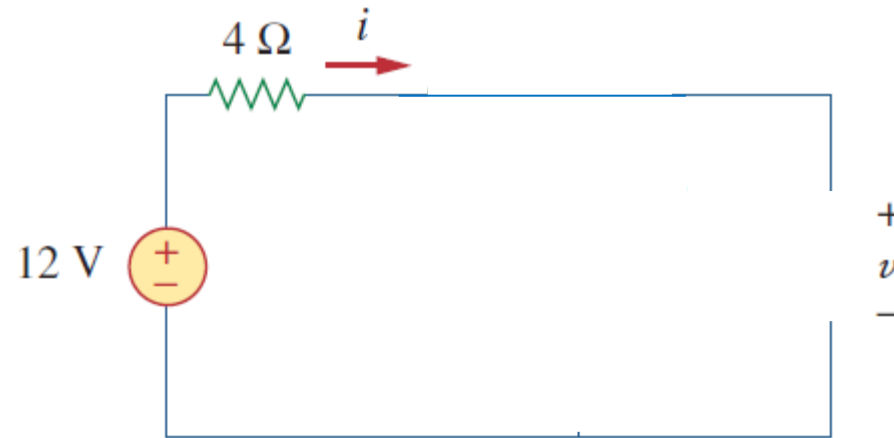


**RLC general second-order circuit**

**Example 8.9.** Find the complete response  $v$  and then  $i$  for  $t > 0$  in the circuit



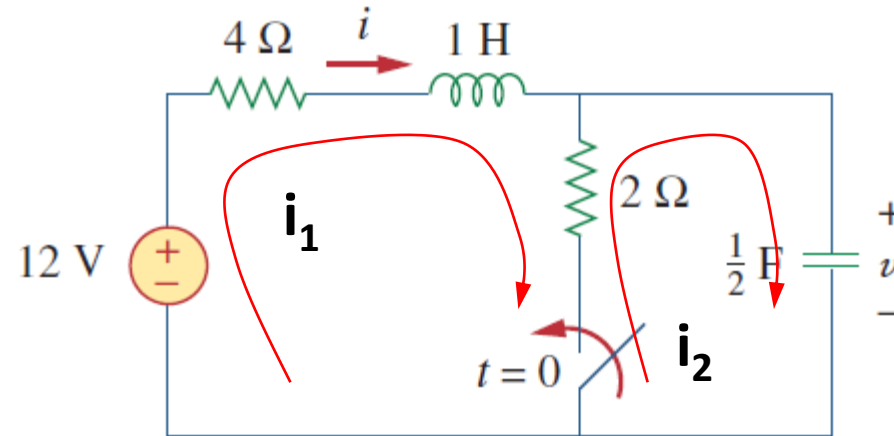
(i)  $t < 0$



(i) Find a current  $i$ :

- Initial conditions:  $i(0) = 0$  A;  $v(0) = 12$  V

(ii)  $t > 0$



(i) Find a current  $i$ :

By KVL

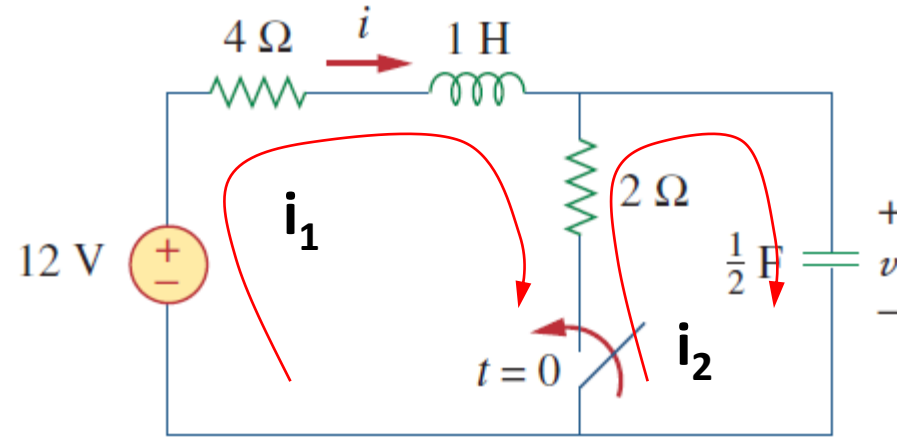
$$-12 + 4i_1 + \frac{di_1}{dt} + 2(i_1 - i_2) = 0 \rightarrow 2i_2 = -12 + 6i_1 + \frac{di_1}{dt}$$

$$2(i_2 - i_1) + 2 \int i_2 dt = 0$$

$$\frac{d^2 i_1}{dt^2} + 5 \frac{di_1}{dt} + 6i_1 = 12 \rightarrow s^2 + 5s + 6 = 0$$



(ii)  $t > 0$



$$S^2 + 5S + 6 = 0, S_1 = -2 \text{ and } S_2 = -3$$

$$i_1(t) = A_1 e^{-2t} + A_2 e^{-3t} + i_{f1} \text{ where } i_{f1} = 2$$

Using initial conditions,

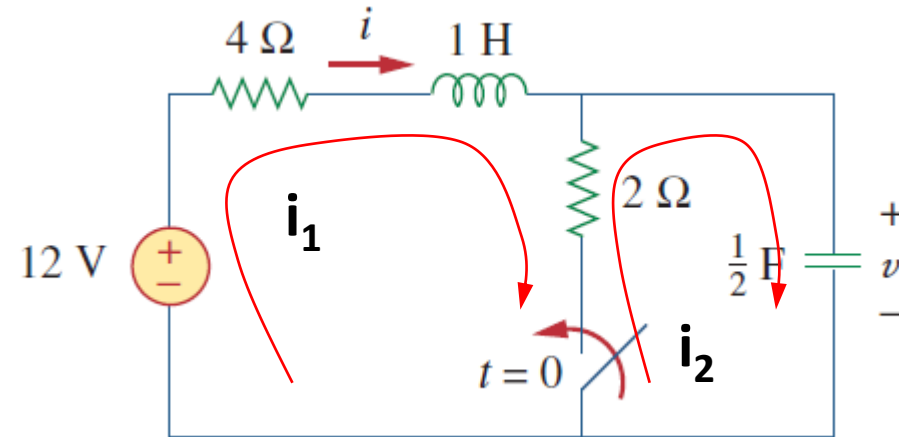
$$(i) \quad i_1(0) = A_1 + A_2 + 2 = 0$$

$$(ii) \quad i'_1(0) = -2A_1 - 3A_2 = 0$$

$$-12 + 4i_1(0) + \frac{di_1(0)}{dt} + v(0) = 0 \rightarrow \frac{di_1(0)}{dt} = 0$$

Thus,  $A_1 = -6$ ;  $A_2 = 4$

(ii)  $t > 0$

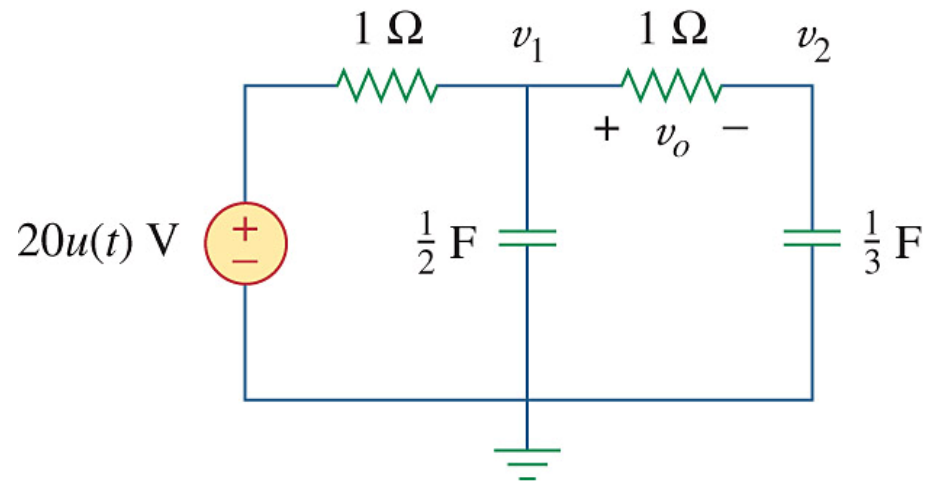


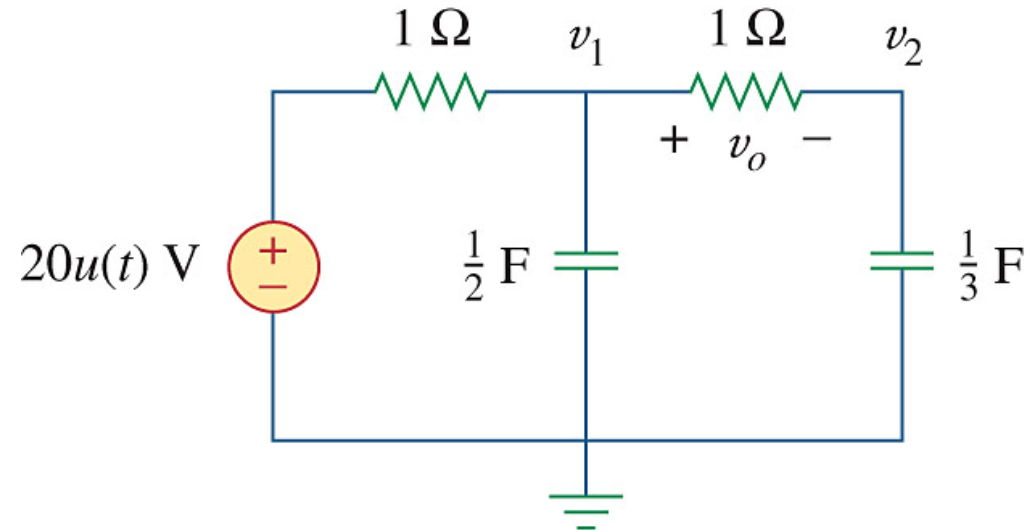
$$i_1(t) = -6e^{-2t} + 4e^{-3t} + 2 = i(t)$$

$$2i_2 = -12 + 6i_1 + \frac{di_1}{dt} \rightarrow i_2(t) = -12e^{-2t} + 6e^{-3t}$$

$$v(t) = 2 \times (i_1 - i_2) = 12e^{-2t} - 4e^{-3t} + 4 \text{ [V]}$$

**Practice Problem 8.10** For  $t > 0$ , obtain  $v_o(t)$  in the circuit of Fig. 8.32. (*Hint* : First find  $v_1$  and  $v_2$ .)





**Solution :**

$$v_1(0^+) = v_2(0^+) = 0$$

$$\frac{20 - v_1(0^+)}{1} = \frac{1}{2} \frac{dv_1(0^+)}{dt} + \frac{v_1(0^+) - v_2(0^+)}{1}$$

$$v_1'(0^+) = 2[20 - 2v_1(0^+) + v_2(0^+)] = 40 \text{ (V/s)}$$

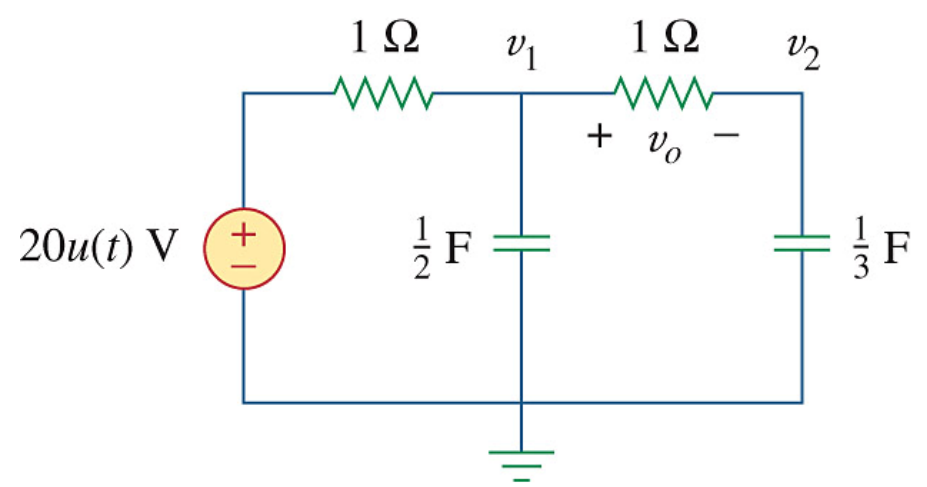


Figure 8.32 An  $RCC$  circuit.

$$v_1(\infty) = v_2(\infty) = 20 \text{ (V)}$$

$$\frac{20 - v_1}{1} = \frac{1}{2} \frac{dv_1}{dt} + \frac{v_1 - v_2}{1}, \quad \frac{v_1 - v_2}{1} = \frac{1}{3} \frac{dv_2}{dt}$$

$$\frac{d^2 v_1}{dt^2} + 7 \frac{dv_1}{dt} + 6v_1 = 120$$

$$s^2 + 7s + 6 = 0 \Rightarrow s_1 = -1, s_2 = -6$$

$$v_{1h}(t) = A_1 e^{-t} + A_2 e^{-6t}$$

$$v_{1p}(t) = 20$$

$$v_1(t) = A_1 e^{-t} + A_2 e^{-6t} + 20$$

$$v_1(0^+) = A_1 + A_2 + 20 = 0$$

$$v_1'(0^+) = -A_1 - 6A_2 = 40$$

$$A_1 = -16, A_2 = -4$$

$$v_1(t) = -16e^{-t} - 4e^{-6t} + 20$$

$$v_2(t) = -24e^{-t} + 4e^{-6t} + 20 \longleftarrow \frac{20 - v_1}{1} = \frac{1}{2} \frac{dv_1}{dt} + \frac{v_1 - v_2}{1}$$

$$v_o(t) = v_1(t) - v_2(t) = 8e^{-t} - 8e^{-6t} \text{ (V)}$$

## 8.10 Duality

- The concept of duality is a time-saving, effort-effective measure of solving circuit problems.
- Two circuits are said to be duals of one another if they are described **by the same characteristic equations with dual pairs interchanged**.
- Dual pairs are shown in Table 8.1.

**TABLE 8.1 Dual Pairs**

Resistance	Conductance
Inductance	Capacitance
Voltage	Current
Voltage source	Current source
Node	Mesh
Series path	Parallel path
Open circuit	Short circuit
KVL	KCL
Thevenin	Norton



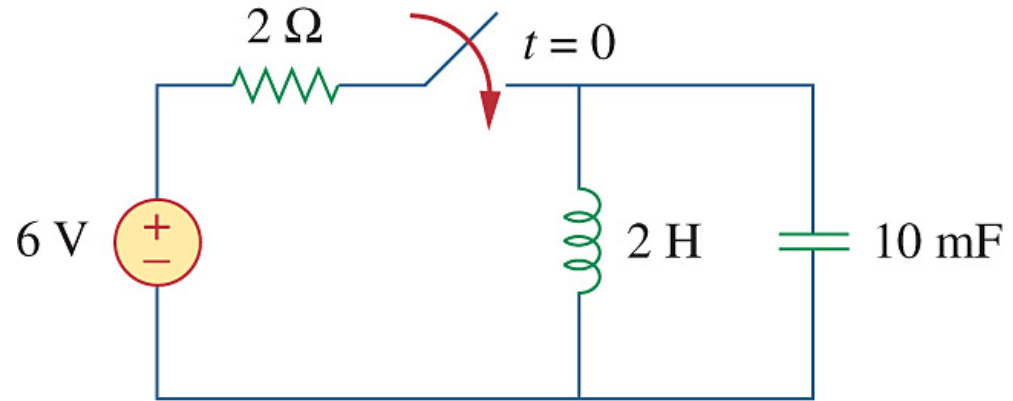
Given a planar circuit, we construct the dual circuit by taking the following steps:

1. Place a node at the center of each mesh of the given circuit. Place the reference node of the dual circuit outside the given circuit.
2. Draw lines between the nodes such that each line across an element. Replace the element by its dual.

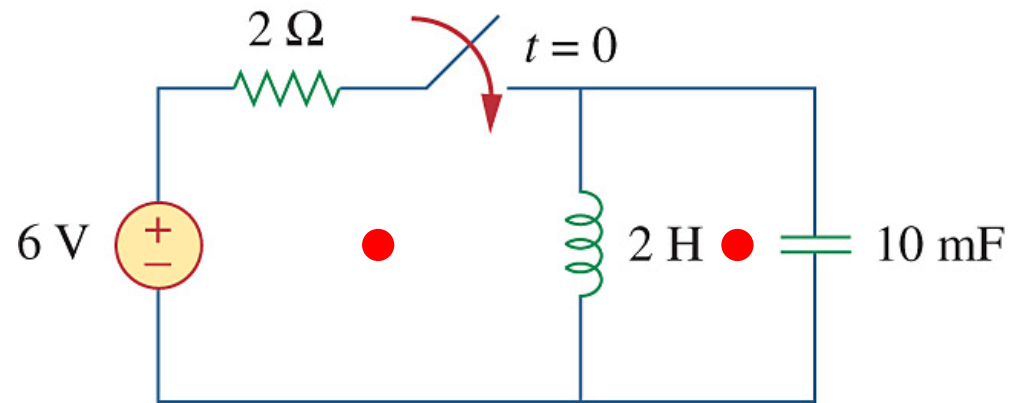
3. To determine the polarity of voltage sources and direction of current sources, follow this rule: A voltage source that produces a **positive (clockwise) mesh current** has as its dual a current source whose reference direction is from **the ground to the nonreference node**.

In case of doubt, one may verify the dual circuit by writing the nodal or mesh equations.

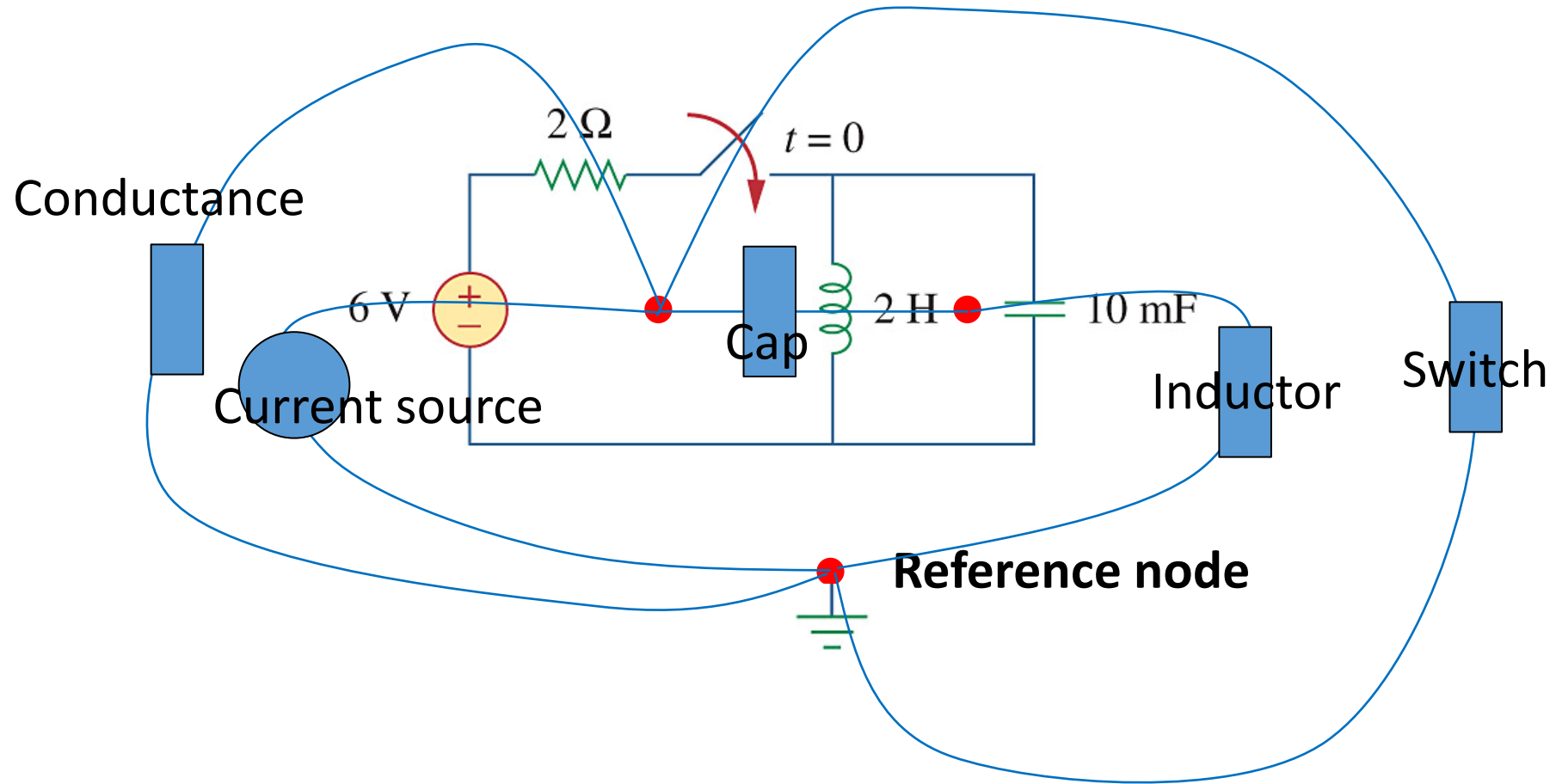
**Example 8.14** Construct the dual of the circuit in Fig. 8.44.



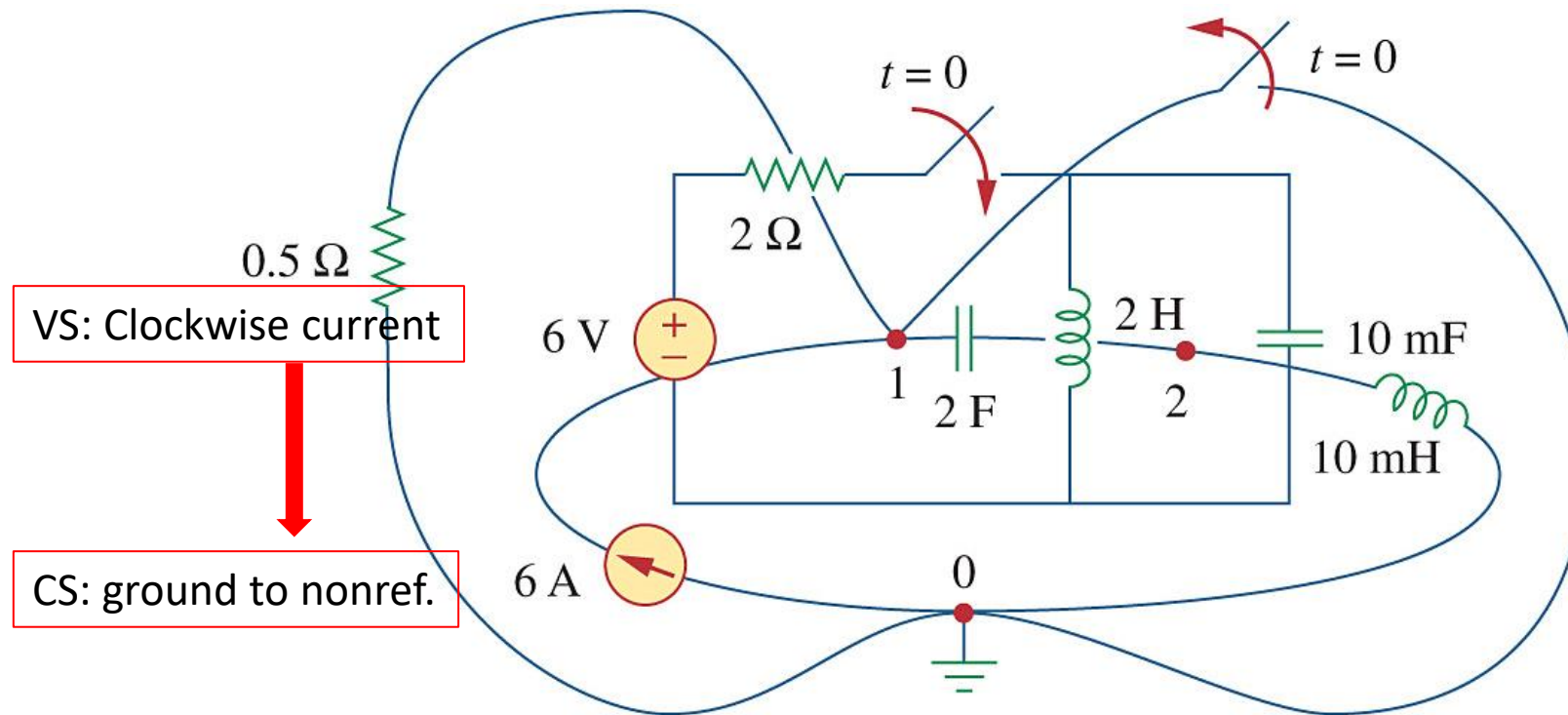
1. Place a node at the center of each mesh of the given circuit. Place the reference node of the dual circuit outside the given circuit.



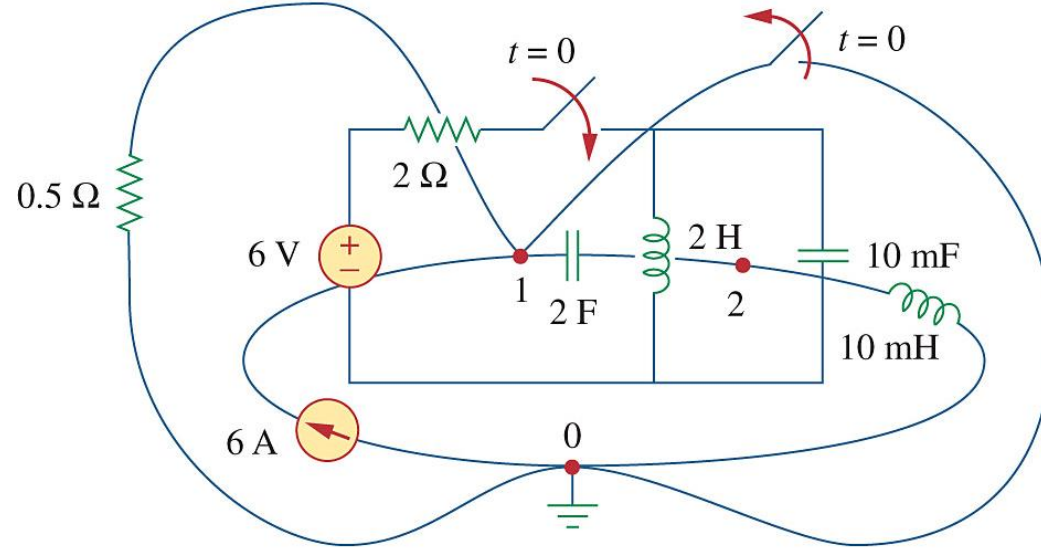
2. Draw lines between the nodes such that each line across an element. Replace the element by its dual.



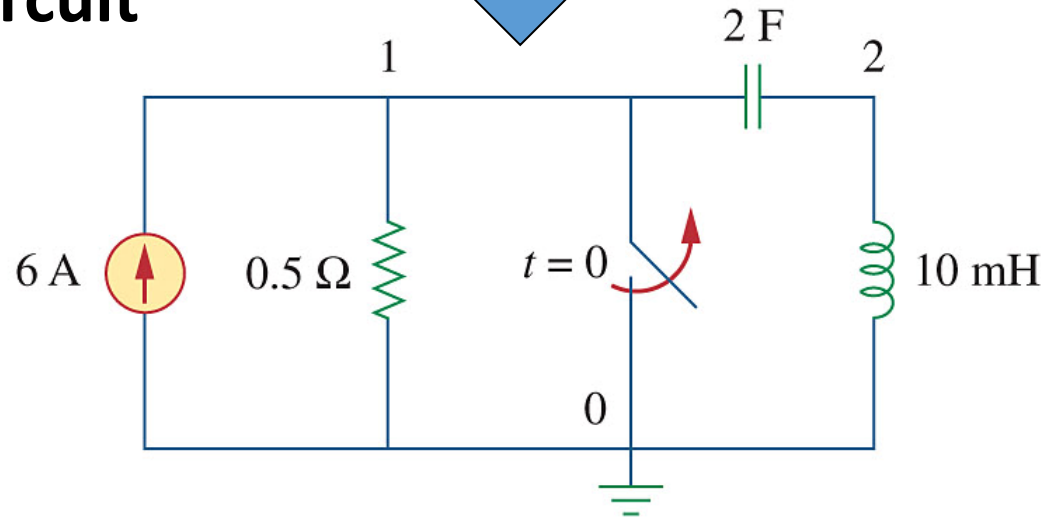
3. (i) A clockwise voltage source  $\rightarrow$  A current source: from the ground to the nonreference node.  
(ii) Open circuit  $\rightarrow$  Short circuit



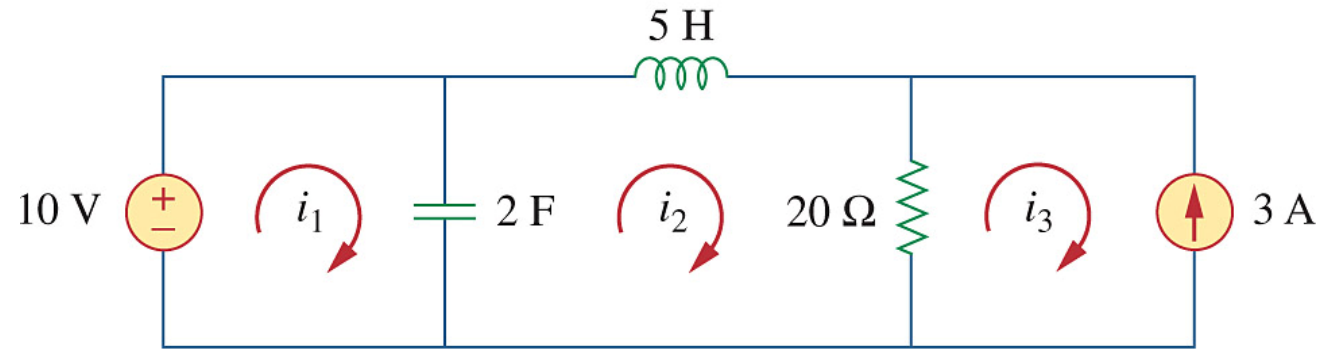
# Dual Circuit



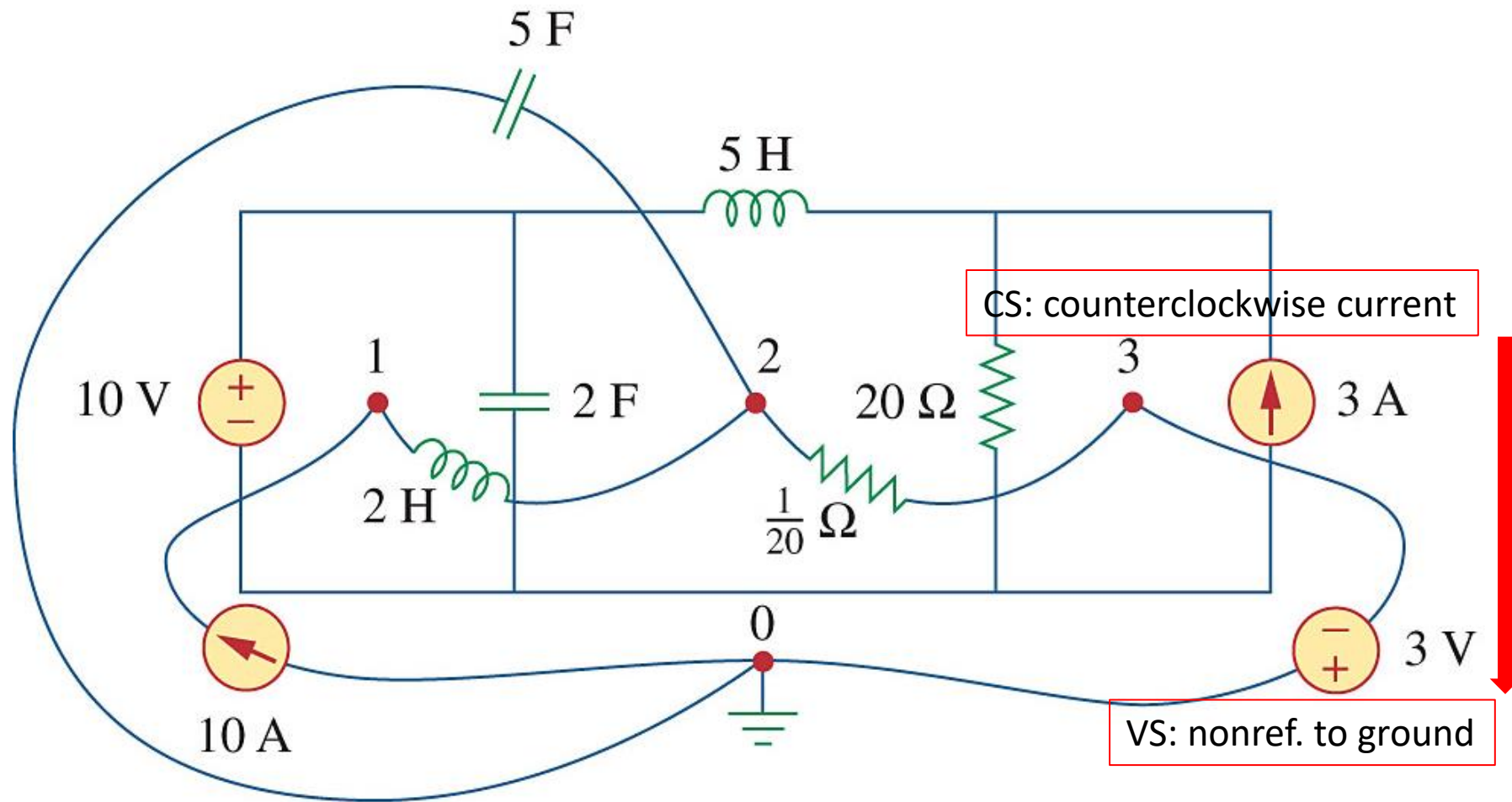
# Redrawn Circuit



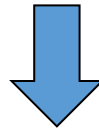
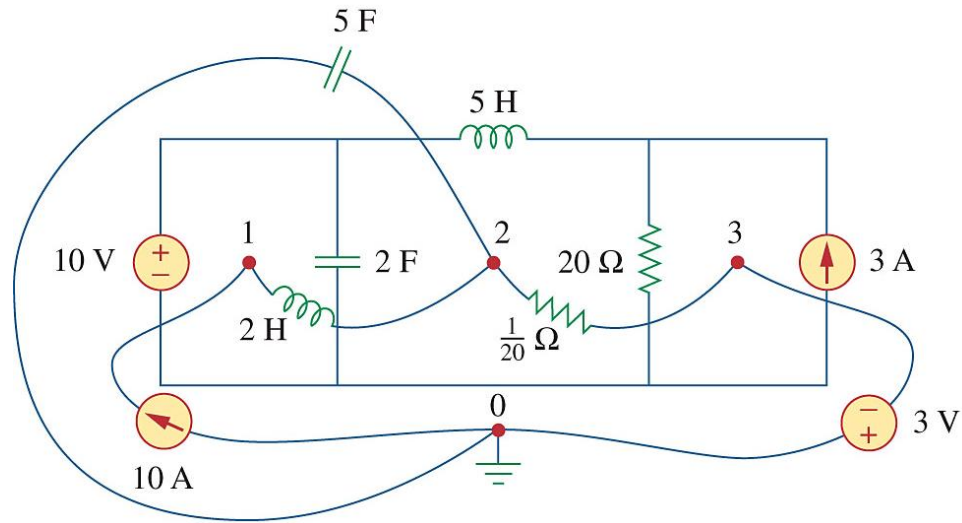
**Example 8.15** Obtain the dual of the circuit in Fig. 8.48.







## Dual Circuit



## Redrawn Circuit

