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PROGRAMMING WITH REFINEMENT TYPES

AN INTRODUCTION TO LIQUIDHASKELL

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1

Introduction

One of the amazing things about Haskell is its brainy type system that allows one to enforce a variety of invariants at compile time, thereby nipping in the bud a large swathe of run-time **errors**.

Well-Typed Programs Do Go Wrong!

Alas, well-typed programs *do* go quite wrong, in a variety of ways.

DIVISION BY ZERO This innocuous function computes the average of a list of integers: AAAA

```
average    :: [Int] -> Int
average xs = sum xs `div` 10
```

We get the desired result on a non-empty list of numbers:

```
ghci> average [10, 20, 30, 40]
25
```

Question 1:

What should be the predicate of `div` to make it impossible to divide by zero?

```
{-@ div :: Int -> {v:Int | v > 0} -> Int @-} {-@ div :: Int -> {v:Int | v  
/= 0} -> Int @-} Submit
```

—

```
-- module Demo.Lib where
```

```
-- {-@ type Pos = {v:Int | 0 < v} @-}
-- {-@ incr :: Pos -> Pos @-}
-- incr :: Int -> Int
-- incr x = x - 1
--
```

2

Introduction

Welcome to the LiquidHaskell Short Tutorial, where you will learn the basic workings of LiquidHaskell and complete some exercises. The full version of the tutorial can be found in the [project's website](#).

One of the great things about Haskell is its brainy type system that allows one to enforce a variety of invariants at compile time, thereby nipping in the bud a large swathe of run-time **errors**.

Well-Typed Programs Do Go Wrong

Alas, well-typed programs *do* go quite wrong, in a variety of ways.

DIVISION BY ZERO This innocuous function computes the average of a list of integers:

```
average    :: [Int] -> Int
average xs = sum xs `div` length xs
```

We get the desired result on a non-empty list of numbers:

```
ghci> average [10, 20, 30, 40]
25
```

Question 1:

What should be the predicate of `div` to make it impossible to divide by zero?

```
{-@ div :: Int -> {v:Int | v > 0} -> Int @-} {-@ div :: Int -> {v:Int | v  
/= 0} -> Int @-} Submit
```

```

<h2 style="color: #2980b9;">Question 1:</h2>
<p style="color: #2c3e50; font-size: 16px;">But, are there any inputs for which it crashes?</p>
<label style="display: block; margin-bottom: 10px; color: #2c3e50;">
  <input type="radio" name="q1" value="3"> Yes, e.g., the list [1]
</label>
<label style="display: block; margin-bottom: 10px; color: #2c3e50;">
  <input type="radio" name="q1" value="4"> Yes, e.g., the list []
</label>
<label style="display: block; margin-bottom: 10px; color: #2c3e50;">
  <input type="radio" name="q1" value="5"> No, it should not crash
</label>
<button onclick="checkAnswer(1)" style="padding: 10px; background-color: #3498db; color: white; border: none;">
<p id="result1" style="margin-top: 10px; font-weight: bold; color: #3498db;"></p>
<input type="hidden" id="correctAnswer1" value="4">

```

Toggle Collapsible Div

```

<h2>Collapsible Content</h2>
<p>This is the content of the collapsible div. You can add any content here.</p>
</div>

```

1

HEART BLEEDS

For certain kinds of programs, there is a fate worse than death. `text` is a high-performance string processing library for Haskell, that is used, for example, to build web services.

```

ghci> :m +Data.Text Data.Text.Unsafe
ghci> let t = pack "Voltage"
ghci> takeWord16 5 t
"Volta"

```

A cunning adversary can use invalid, or rather, *well-crafted*, inputs that go well outside the size of the given text to read extra bytes and thus *extract secrets* without anyone being any the wiser.

```

ghci> takeWord16 20 t
"Voltage\1912\3148\SOH\NUL\15928\2486\SOH\NUL"

```

The above call returns the bytes residing in memory *immediately after* the string `Voltage`. These bytes could be junk, or could be either the name of your favorite TV show, or, more worryingly, your bank account password.

¹ If we call it with an empty list, we get a rather unpleasant crash: `*** Exception: divide by zero`. We could write `average` more *defensively*, returning a `Maybe` or `Either` value. However, this merely kicks the can down the road. Ultimately, we will want to extract the `Int` from the `Maybe` and if the inputs were invalid to start with, then at that point we'd be stuck.

Refinement Types

Refinement types allow us to enrich Haskell's type system with *predicates* that precisely describe the sets of *valid* inputs and outputs of functions, values held inside containers, and so on. These predicates are drawn from special *logics* for which there are fast *decision procedures* called SMT solvers.

By combining types with predicates you can specify *contracts* which describe valid inputs and outputs of functions. The refinement type system *guarantees at compile-time* that functions adhere to their contracts. That is, you can rest assured that the above calamities *cannot occur at run-time*.

LIQUIDHASKELL is a Refinement Type Checker for Haskell, and in this tutorial we'll describe how you can use it to make programs better and programming even more fun.

As a glimpse of what LiquidHaskell can do, the average example can be specified to inform that return needs to be different than zero, and LiquidHaskell will check if the implementation complies with it. Run the example and read the error message.

```
{-@ average' :: [Int] -> {v: Int | v /= 0} @-}
average'    :: [Int] -> Int
average' xs = sum xs `div` length xs
```

In this tutorial you will learn how to add and reason about refinement types in Haskell, and how it can increase the reliability of Haskell problems.

To get started, open the [Web Demo](#) and see what is the result when you Check the code from the first example.

3

Logic & SMT

As we shall see shortly, a refinement type is:

Refinement Types = Types + Logical Predicates

Let us begin by quickly recalling what we mean by “logical predicates” in the remainder of this tutorial. ¹ To this end, we will describe *syntax*, that is, what predicates *look* like, and *semantics*, which is a fancy word for what predicates *mean*.

Syntax

A *logical predicate* is, informally speaking, a Boolean valued term drawn from a *restricted* subset of Haskell. In particular, the expressions are drawn from the following grammar comprising *constants*, *expressions* and *predicates*.

A CONSTANT² *c* is simply one of the numeric values:

```
c := 0, 1, 2, ...
```

A VARIABLE *v* is one of *x*, *y*, *z*, etc., these will refer to (the values of) binders in our source programs.

```
v := x, y, z, ...
```

AN EXPRESSION *e* is one of the following forms; that is, an expression is built up as linear arithmetic expressions over variables and constants and uninterpreted function applications.

¹ If you are comfortable with this material, e.g. if you know what the “S”, “M” and “T” stand for in SMT, and what QF-UFLIA stands for (i.e. the quantifier free theory of linear arithmetic and uninterpreted functions), then feel free skip to the next chapter.

² When you see := you should read it as “is defined to be”

```

e := v          -- variable
  | c          -- constant
  | (e + e)     -- addition
  | (e - e)     -- subtraction
  | (c * e)     -- multiplication by constant
  | (v e1 e2 ... en) -- uninterpreted function application
  | (if p then e else e) -- if-then-else

```

EXAMPLES OF EXPRESSIONS include the following:

- $x + y - z$
- $2 * x$
- $1 + \text{size } x$

A RELATION is one of the usual (arithmetic) comparison operators:

```

r := ==        -- equality
  | /=        -- disequality
  | >=        -- greater than or equal
  | <=        -- less than or equal
  | >         -- greater than
  | <         -- less than

```

A PREDICATE is either an atomic predicate, obtained by comparing two expressions, or, an application of a predicate function to a list of arguments, or the Boolean combination of the above predicates with the operators `&&` (and), `||` (or), `==>` (implies³), `<=>` (if and only if⁴), and `not`.

³ Read $p \Rightarrow q$ as “if p then q ”

⁴ Read $p \Leftrightarrow q$ as “if p then q and if q then p ”

```

p := (e r e)    -- binary relation
  | (v e1 e2 ... en) -- predicate (or alias) application
  | (p && p)     -- and
  | (p || p)     -- or
  | (p => p) | (p ==> p) -- implies
  | (p <=> p)    -- iff
  | (not p)     -- negation
  | true | True
  | false | False

```

EXAMPLES OF PREDICATES include the following:

- $x + y \leq 3$
- `null x`
- $x < 10 \implies y < 10 \implies x + y < 20$
- $0 < x + y \iff 0 < y + x$

Semantics

The syntax of predicates tells us what they *look* like, that is, what we can *write down* as valid predicates. Next, let us turn our attention to what a predicate *means*. Intuitively, a predicate is just a Boolean valued Haskell function with `&&`, `||`, not being the usual operators and `=>` and `<=>` being two special operators.

THE IMPLICATION operator `=>` is equivalent to the following Haskell function. (For now, ignore the signature: it just says the output is a `Bool` that is equal to the *logical* implication between the inputs `p` and `q`.)

```
{-@ (==>) :: p:Bool -> q:Bool -> {v:Bool | v <=> (p ==> q)} @-}
False ==> False = True
False ==> True  = True
True  ==> True  = True
True  ==> False = False
```

THE IF-AND-ONLY-IF operator `<=>` is equivalent to the Haskell function:⁵

```
{-@ (<=>) :: p:Bool -> q:Bool -> {v:Bool | v <=> (p <=> q)} @-}
False <=> False = True
False <=> True  = False
True  <=> True  = True
True  <=> False = False
```

⁵ An observant reader may notice that `<=>` is the same as `==` if the arguments are of type `Bool`

AN ENVIRONMENT is a mapping from variables to their Haskell types. For example, let `G` be an environment defined as

```
x :: Int
y :: Int
z :: Int
```

which maps each variable `x`, `y` and `z` to the type `Int`.

AN ASSIGNMENT under an environment, is a mapping from variables to values of the type specified in the environment. For example,

```
x := 1
y := 2
z := 3
```

is an assignment under G that maps x , y and z to the `Int` values 1, 2 and 3 respectively.

A PREDICATE EVALUATES to either `True` or `False` under a given assignment. For example, the predicate

```
x + y > 10
```

evaluates to `False` given the above assignment but evaluates to `True` under the assignment

```
x := 10
y := 10
z := 20
```

A PREDICATE IS SATISFIABLE in an environment if *there exists* an assignment (in that environment) that makes the predicate evaluate to `True`. For example, in G the predicate

```
x + y == z
```

is satisfiable, as the above assignment makes the predicate evaluate to `True`.

A PREDICATE IS VALID in an environment if *every* assignment in that environment makes the predicate evaluate to `True`. For example, the predicate

```
x < 10 || x == 10 || x > 10
```

is valid under G as no matter what value we assign to x , the above predicate will evaluate to `True`.

Verification Conditions

LiquidHaskell works without actually *executing* your programs. Instead, it checks that your program meets the given specifications in roughly two steps.

1. First, LH combines the code and types down to a set of *Verification Conditions* (VC) which are predicates that are valid *only if* your program satisfies a given property.⁶
2. Next, LH *queries* an [SMT solver](#) to determine whether these VCs are valid. If so, it says your program is *safe* and otherwise it *rejects* your program.

⁶ The process is described at length in [this paper](#)

THE SMT SOLVER DECIDES whether a predicate (VC) is valid *without enumerating* and evaluating all assignments. Indeed, it is impossible to do so as there are usually infinitely many assignments once the predicates refer to integers or lists and so on. Instead, the SMT solver uses a variety of sophisticated *symbolic algorithms* to deduce whether a predicate is valid or not. This process is the result of decades of work in mathematical logic and decision procedures; the [Ph.D thesis of Greg Nelson](#) is an excellent place to learn more about these beautiful algorithms.

WE RESTRICT THE LOGIC to ensure that all our VC queries fall within the *decidable fragment*. This makes LiquidHaskell extremely automatic – there is *no* explicit manipulation of proofs, just the specification of properties via types and of course, the implementation via Haskell code! This automation comes at a price: all our refinements *must* belong to the logic above. Fortunately, with a bit of creativity, we can say a *lot* in this logic.⁷

⁷ In particular, we will use the uninterpreted functions to create many sophisticated abstractions.

Examples: Propositions

Finally, let's conclude this quick overview with some examples of predicates, in order to build up our own intuition about logic and validity. Each of the below is a predicate from our refinement logic. However, we write them as raw Haskell expressions that you may be more familiar with right now, and so that we can start to use LiquidHaskell to determine whether a predicate is indeed valid or not.

LET ‘TRUE’ BE A REFINED TYPE for Bool valued expressions that *always* evaluate to True. Similarly, we can define FALSE for Bool valued expressions that *always* evaluate to False:⁸

⁸ This syntax will be discussed in greater detail [soon](#)

```
{-@ type TRUE = {v:Bool | v    } @-}
{-@ type FALSE = {v:Bool | not v} @-}
```

Thus, a *valid predicate* is one that has the type TRUE. The simplest example of a valid predicate is just True:

```
{-@ ex0 :: TRUE @-}
ex0 = True
```

of course, False is *not valid*

```
{-@ ex0' :: TRUE @-}
ex0' = False
```

We can get more interesting predicates if we use variables. For example, the following is valid predicate says that a Bool variable is either True or False.

```
{-@ ex1 :: Bool -> TRUE @-}
ex1 b = b || not b
```

Of course, a variable cannot be both True and False, and so the below predicate is valid:

```
{-@ ex2 :: Bool -> FALSE @-}
ex2 b = b && not b
```

The next few examples illustrate the ==> operator. You should read $p \implies q$ as *if* p is true *then* q must also be true. Thus, the below predicates are valid as if both a and b are true, then well, a is true, and b is true.

```
{-@ ex3 :: Bool -> Bool -> TRUE @-}
ex3 a b = (a && b) ==> a
```

```
{-@ ex4 :: Bool -> Bool -> TRUE @-}
ex4 a b = (a && b) ==> b
```

Exercise 3.1 (Implications and Or). *Of course, if we replace the && with || the result is not valid. Can you shuffle the variables around – without changing the operators – to make the formula valid?*

```
{-@ ex3' :: Bool -> Bool -> TRUE @-}
ex3' a b = (a || b) ==> a
```

The following predicates are valid because they encode **modus ponens**: if you know that a implies b and you know that a is true, then it must be the case that b is also true:

```
{-@ ex6 :: Bool -> Bool -> TRUE @-}
ex6 a b = (a && (a ==> b)) ==> b
```

```
{-@ ex7 :: Bool -> Bool -> TRUE @-}
ex7 a b = a ==> (a ==> b) ==> b
```

Recall that $p \iff q$ (read p if and only if q) evaluates to `True` exactly when p and q evaluate to the *same* values (`True` or `False`). It is used to encode *equalities* between predicates. For example, we can write down **De Morgan's laws** as the valid predicates:

```
{-@ exDeMorgan1 :: Bool -> Bool -> TRUE @-}
exDeMorgan1 a b = not (a || b) <=> (not a && not b)
```

Exercise 3.2 (DeMorgan's Law). *The following version of DeMorgan's law is wrong. Can you fix it to get a valid formula?*

```
{-@ exDeMorgan2 :: Bool -> Bool -> TRUE @-}
exDeMorgan2 a b = not (a && b) <=> (not a && not b)
```

Examples: Arithmetic

Next, let's look at some predicates involving arithmetic. The simplest ones don't have any variables, for example:

```
{-@ ax0 :: TRUE @-}
ax0 = 1 + 1 == 2
```

Again, a predicate that evaluates to `False` is *not* valid:

```
{-@ ax0' :: TRUE @-}
ax0' = 1 + 1 == 3
```

SMT SOLVERS DETERMINE VALIDITY *without* enumerating assignments. For example, consider the predicate:

```
{-@ ax1 :: Int -> TRUE @-}
ax1 x = x < x + 1
```

It is trivially valid; as via the usual laws of arithmetic, it is equivalent to $0 < 1$ which is True independent of the value of x . The SMT solver is able to determine this validity without enumerating the infinitely many possible values for x . This kind of validity checking lies at the heart of LiquidHaskell.

WE CAN COMBINE ARITHMETIC AND PROPOSITIONAL

operators, as shown in the following examples:

```
{-@ ax2 :: Int -> TRUE @-}
ax2 x = (x < 0) ==> (0 <= 0 - x)

{-@ ax3 :: Int -> Int -> TRUE @-}
ax3 x y = (0 <= x) ==> (0 <= y) ==> (0 <= x + y)

{-@ ax4 :: Int -> Int -> TRUE @-}
ax4 x y = (x == y - 1) ==> (x + 2 == y + 1)

{-@ ax5 :: Int -> Int -> Int -> TRUE @-}
ax5 x y z = (x <= 0 && x >= 0)
            ==> (y == x + z)
            ==> (y == z)
```

Exercise 3.3 (Addition and Order). *The formula below is not valid. Do you know why? Change the hypothesis i.e. the thing to the left of the \Rightarrow to make it a valid formula.*

```
{-@ ax6 :: Int -> Int -> TRUE @-}
ax6 x y = True ==> (x <= x + y)
```

Examples: Uninterpreted Function

We say that function symbols are *uninterpreted* in the refinement logic, because the SMT solver does not “know” how functions are defined. Instead, the only thing that the solver knows is the *axiom of congruence* which states that any function f , returns equal outputs when invoked on equal inputs.

WE TEST THE AXIOM OF CONGRUENCE by checking that the following predicate is valid:

```
{-@ congruence :: (Int -> Int) -> Int -> Int -> TRUE @-}
congruence f x y = (x == y) ==> (f x == f y)
```

Again, remember we are *not evaluating* the code above; indeed we *cannot* evaluate the code above because we have no definition of *f*. Still, the predicate is valid as the congruence axiom holds for any possible interpretation of *f*.

Here is a fun example; can you figure out why this predicate is indeed valid? (The SMT solver can...)

```
{-@ fx1 :: (Int -> Int) -> Int -> TRUE @-}
fx1 f x = (x == f (f (f x)))
          ==> (x == f (f (f (f (f x))))))
          ==> (x == f x)
```

To get a taste of why uninterpreted functions will prove useful, let's write a function to compute the size of a list:

```
{-@ measure size @-}
{-@ size :: [a] -> Nat @-}
size      :: [a] -> Int
size []   = 0
size (x:xs) = 1 + size xs
```

We can now verify that the following predicates are *valid*:

```
{-@ fx0 :: [a] -> [a] -> TRUE @-}
fx0 xs ys = (xs == ys) ==> (size xs == size ys)
```

Note that to determine that the above is valid, the SMT solver does not need to know the *meaning* or *interpretation* of *size* – merely that it is a function. When we need some information about the definition, of *size* we will put it inside the predicate. For example, in order to prove that the following is valid:

```
{-@ fx2 :: a -> [a] -> TRUE @-}
fx2 x xs = 0 < size ys
  where
    ys = x : xs
```

LiquidHaskell actually asks the SMT solver to prove the validity of a VC predicate which states that sizes are non-negative and that since *ys* equals *x:xs*, the size of *ys* is one more than *xs*.⁹

⁹ Fear not! We will describe how this works **soon**

```

{-@ fx2VC :: _ -> _ -> _ -> TRUE @-}
fx2VC x xs ys = (0 <= size xs)
               ==> (size ys == 1 + size xs)
               ==> (0 < size ys)

```

Recap

This chapter describes exactly what we, for the purposes of this book, mean by the term *logical predicate*.

1. We defined a grammar – a restricted subset of Haskell corresponding to Bool valued expressions.
2. The restricted grammar lets us use SMT solvers to decide whether a predicate is *valid* that is, evaluates to True for *all* values of the variables.
3. Crucially, the SMT solver determines validity *without enumerating* and evaluating the predicates (which would take forever!) but instead by using clever symbolic algorithms.

Next, let's see how we can use logical predicates to *specify* and *verify* properties of real programs.

4

Refinement Types

WHAT IS A REFINEMENT TYPE? In a nutshell,

Refinement Types = Types + Predicates

That is, refinement types allow us to decorate types with *logical predicates*, which you can think of as *boolean-valued* Haskell expressions, that constrain the set of values described by the type. This lets us specify sophisticated invariants of the underlying values.

Defining Types

Let us define some refinement types:¹

```
{-@ type Zero    = {v:Int | v == 0} @-}
{-@ type NonZero = {v:Int | v /= 0} @-}
```

¹ You can read the type of Zero as: “v is an Int *such that* v equals 0” and NonZero as : “v is an Int *such that* v does not equal 0”

THE VALUE VARIABLE *v* denotes the set of valid inhabitants of each refinement type. Hence, Zero describes the *set of* Int values that are equal to 0, that is, the singleton set containing just 0, and NonZero describes the set of Int values that are *not* equal to 0, that is, the set {1, -1, 2, -2, ...} and so on. ²

² We will use @-marked comments to write refinement type annotations in the Haskell source file, making these types, quite literally, machine-checked comments!

TO USE these types we can write:

```
{-@ zero :: Zero @-}
zero = 0 :: Int

{-@ one, two, three :: NonZero @-}
```

```
one   = 1 :: Int
two   = 2 :: Int
three = 3 :: Int
```

Errors

If we try to say nonsensical things like:

```
nonsense :: Int
nonsense = one'
  where
    {-@ one' :: Zero @-}
    one' = 1
```

LiquidHaskell will complain with an error message:

```
../liquidhaskell-tutorial/src/03-basic.lhs:72:3-6: Error: Liquid Type Mismatch
```

```
72 |   one' = 1 :: Int
    |     ^^^^

Inferred type
  VV : {VV : Int | VV == (1 : int)}

not a subtype of Required type
  VV : {VV : Int | VV == 0}
```

The message says that the expression `1 :: Int` has the type

```
{v:Int | v == 1}
```

which is *not* (a subtype of) the *required* type

```
{v:Int | v == 0}
```

as 1 is not equal to 0.

Subtyping

What is this business of *subtyping*? Suppose we have some more refinements of `Int`

```
{-@ type Nat    = {v:Int | 0 <= v}      @-}
{-@ type Even   = {v:Int | v mod 2 == 0 } @-}
{-@ type Lt100  = {v:Int | v < 100}     @-}
```

WHAT IS THE TYPE OF zero? Zero of course, but also Nat:

```
{-@ zero' :: Nat @-}
zero'     = zero
```

and also Even:

```
{-@ zero'' :: Even @-}
zero''    = zero
```

and also any other satisfactory refinement, such as ³

```
{-@ zero''' :: Lt100 @-}
zero'''    = zero
```

³ We use a different names `zero'`, `zero''` etc. as (currently) LiquidHaskell supports *at most* one refinement type for each top-level name.

SUBTYPING AND IMPLICATION

Zero is the most precise type for `0 :: Int`, as it is a *subtype* of `Nat`, `Even` and `Lt100`. This is because the set of values defined by Zero is a *subset* of the values defined by `Nat`, `Even` and `Lt100`, as the following *logical implications* are valid:

- $v = 0 \Rightarrow 0 \leq v$
- $v = 0 \Rightarrow v \bmod 2 = 0$
- $v = 0 \Rightarrow v < 100$

IN SUMMARY the key points about refinement types are:

1. A refinement type is just a type *decorated* with logical predicates.
2. A term can have *different* refinements for different properties.
3. When we *erase* the predicates we get the standard Haskell types.⁴

⁴ Dually, a standard Haskell type has the trivial refinement `true`. For example, `Int` is equivalent to `{v:Int | true}`.

Writing Specifications

Let's write some more interesting specifications.

TYPING DEAD CODE We can wrap the usual error function in a function `die` with the type:

```
{-@ die :: {v:String | false} -> a @-}
die msg = error msg
```

The interesting thing about `die` is that the input type has the refinement `false`, meaning the function must only be called with Strings that satisfy the predicate `false`. This seems bizarre; isn't it *impossible* to satisfy `false`? Indeed! Thus, a program containing `die` typechecks *only* when LiquidHaskell can prove that `die` is *never called*. For example, LiquidHaskell will *accept*

```
cannotDie = if 1 + 1 == 3
             then die "horrible death"
             else ()
```

by inferring that the branch condition is always `False` and so `die` cannot be called. However, LiquidHaskell will *reject*

```
canDie = if 1 + 1 == 2
           then die "horrible death"
           else ()
```

as the branch may (will!) be `True` and so `die` can be called.

Refining Function Types: Pre-conditions

Let's use `die` to write a *safe division* function that *only accepts* non-zero denominators.

```
divide'    :: Int -> Int -> Int
divide' n 0 = die "divide by zero"
divide' n d = n `div` d
```

From the above, it is clear to *us* that `div` is only called with non-zero divisors. However, LiquidHaskell reports an error at the call to "`die`" because, what if `divide'` is actually invoked with a `0` divisor?

We can specify that will not happen, with a *pre-condition* that says that the second argument is non-zero:

```
{-@ divide :: Int -> NonZero -> Int @-}
divide _ 0 = die "divide by zero"
divide n d = n `div` d
```

To VERIFY that `divide` never calls `die`, LiquidHaskell infers that `"divide by zero"` is not merely of type `String`, but in fact has the refined type $\{v:\text{String} \mid \text{false}\}$ in the context in which the call to `die` occurs. LiquidHaskell arrives at this conclusion by using the fact that in the first equation for `divide` the *denominator* is in fact

```
0 :: {v: Int | v == 0}
```

which *contradicts* the pre-condition (i.e. input) type. Thus, by contradiction, LiquidHaskell deduces that the first equation is *dead code* and hence `die` will not be called at run-time.

ESTABLISHING PRE-CONDITIONS

The above signature forces us to ensure that that when we *use* `divide`, we only supply provably `NonZero` arguments. Hence, these two uses of `divide` are fine:

```
avg2 x y = divide (x + y) 2
avg3 x y z = divide (x + y + z) 3
```

Exercise 4.1 (List Average). Consider the function `avg`:

1. Why does LiquidHaskell flag an error at `n`?
2. How can you change the code so LiquidHaskell verifies it?

```
avg      :: [Int] -> Int
avg xs   = divide total n
  where
    total = sum xs
    n     = length xs
```

Refining Function Types: Post-conditions

Next, let's see how we can use refinements to describe the *outputs* of a function. Consider the following simple *absolute value* function

```
abs          :: Int -> Int
abs n
  | 0 < n    = n
  | otherwise = 0 - n
```

We can use a refinement on the output type to specify that the function returns non-negative values

```
{-@ abs :: Int -> Nat @-}
```

LiquidHaskell *verifies* that `abs` indeed enjoys the above type by deducing that `n` is trivially non-negative when $0 < n$ and that in the otherwise case, the value $0 - n$ is indeed non-negative.⁵

⁵ LiquidHaskell is able to automatically make these arithmetic deductions by using an [SMT solver](#) which has built-in decision procedures for arithmetic, to reason about the logical refinements.

Testing Values: Booleans and Propositions

In the above example, we *compute* a value that is guaranteed to be a `Nat`. Sometimes, we need to *test* if a value satisfies some property, e.g., is `NonZero`. For example, let's write a command-line *calculator*:

```
calc = do putStrLn "Enter numerator"
         n <- readLn
         putStrLn "Enter denominator"
         d <- readLn
         putStrLn (result n d)
         calc
```

which takes two numbers and divides them. The function `result` checks if `d` is strictly positive (and hence, non-zero), and does the division, or otherwise complains to the user:

```
result n d
  | isPositive d = "Result = " ++ show (n `divide` d)
  | otherwise   = "Humph, please enter positive denominator!"
```

Finally, `isPositive` is a test that returns a `True` if its input is strictly greater than `0` or `False` otherwise:

```
isPositive :: Int -> Bool
isPositive x = x > 0
```

To `VERIFY` the call to divide inside `result` we need to tell Liquid-Haskell that the division only happens with a `NonZero` value `d`. However, the non-zero-ness is established via the *test* that occurs inside the guard `isPositive d`. Hence, we require a *post-condition* that states that `isPositive` only returns `True` when the argument is positive:

```
{-@ isPositive :: x:Int -> {v:Bool | v <=> x > 0} @-}
```

In the above signature, the output type (post-condition) states that `isPositive x` returns `True` if and only if `x` was in fact strictly greater than 0. In other words, we can write post-conditions for plain-old `Bool`-valued *tests* to establish that user-supplied values satisfy some desirable property (here, `Pos` and hence `NonZero`) in order to then safely perform some computation on it.

Exercise 4.2 (Propositions). *What happens if you delete the type for `isPositive`? Can you change the type for `isPositive` (i.e. write some other type) while preserving safety?*

Exercise 4.3 (Assertions). *Consider the following `assert` function, and two use sites. Write a suitable refinement type signature for `lAssert` so that `lAssert` and `yes` are accepted but `no` is rejected.*

```
{-@ lAssert :: Bool -> a -> a @-}
lAssert True x = x
lAssert False _ = die "yikes, assertion fails!"

yes = lAssert (1 + 1 == 2) ()
no  = lAssert (1 + 1 == 3) ()
```

Hint: You need a pre-condition that `lAssert` is only called with `True`.

Putting It All Together

Let's wrap up this introduction with a simple `truncate` function that connects all the dots.

```
truncate :: Int -> Int -> Int
truncate i max
  | i' <= max' = i
  | otherwise = max' * (i `divide` i')
  where
    i'      = abs i
    max'    = abs max
```

The expression `truncate i n` evaluates to `i` when the absolute value of `i` is less than the upper bound `max`, and otherwise *truncates* the value at the maximum `n`. LiquidHaskell verifies that the use of `divide` is safe by inferring that:

1. `max' < i'` from the branch condition,
2. `0 <= i'` from the `abs` post-condition, and
3. `0 <= max'` from the `abs` post-condition.

From the above, LiquidHaskell infers that `i' /= 0`. That is, at the call site `i' :: NonZero`, thereby satisfying the pre-condition for `divide` and verifying that the program has no pesky divide-by-zero errors.

Recap

This concludes our quick introduction to Refinement Types and LiquidHaskell. Hopefully you have some sense of how to

1. **Specify** fine-grained properties of values by decorating their types with logical predicates.
2. **Encode** assertions, pre-conditions, and post-conditions with suitable function types.
3. **Verify** semantic properties of code by using automatic logic engines (SMT solvers) to track and establish the key relationships between program values.

5

Polymorphism

Refinement types shine when we want to establish properties of *polymorphic* datatypes and higher-order functions. Rather than be abstract, let's illustrate this with a [classic](#) use-case.

ARRAY BOUNDS VERIFICATION aims to ensure that the indices used to retrieve values from an array are indeed *valid* for the array, i.e. are between 0 and the *size* of the array. For example, suppose we create an array with two elements:

```
twoLangs = fromList ["haskell", "javascript"]
```

Lets attempt to look it up at various indices:

```
eeks      = [ok, yup, nono]
  where
    ok      = twoLangs ! 0
    yup     = twoLangs ! 1
    nono    = twoLangs ! 3
```

If we try to *run* the above, we get a nasty shock: an exception that says we're trying to look up `twoLangs` at index 3 whereas the size of `twoLangs` is just 2.

```
Prelude> :l 03-poly.lhs
[1 of 1] Compiling VectorBounds      ( 03-poly.lhs, interpreted )
Ok, modules loaded: VectorBounds.
*VectorBounds> eeks
Loading package ... done.
*** Exception: ./Data/Vector/Generic.hs:249 (!): index out of bounds (3,2)
```

IN A SUITABLE EDITOR e.g. Vim or Emacs, or if you push the “play” button in the online demo, you will literally see the error *without* running the code. Lets see how LiquidHaskell checks ok and yup but flags nono, and along the way, learn how it reasons about *recursion*, *higher-order functions*, *data types* and *polymorphism*.

Specification: Vector Bounds

First, let’s see how to *specify* array bounds safety by *refining* the types for the [key functions](#) exported by `Data.Vector`, i.e. how to

1. *define* the size of a Vector
2. *compute* the size of a Vector
3. *restrict* the indices to those that are valid for a given size.

IMPORTS

We can write specifications for imported modules – for which we *lack* the code – either directly in the client’s source file or better, in `.spec` files which can be reused across multiple client modules.

INCLUDE directories can be specified when checking a file. Suppose we want to check some file `target.hs` that imports an external dependency `Data.Vector`. We can write specifications for `Data.Vector` inside `include/Data/Vector.spec` which contains:

```
-- | Define the size
measure vlen :: Vector a -> Int

-- | Compute the size
assume length :: x:Vector a -> {v:Int | v = vlen x}

-- | Lookup at an index
assume (!) :: x:Vector a -> {v:Nat | v < vlen x} -> a
```

Using this new specification is now a simple matter of telling LiquidHaskell to include this file:

```
$ liquid -i include/ target.hs
```

LiquidHaskell ships with specifications for `Prelude`, `Data.List`, and `Data.Vector` which it includes by default.

MEASURES are used to define *properties* of Haskell data values that are useful for specification and verification. Think of `vlen` as the *actual* size of a `Vector` regardless of how the size was computed.

ASSUMES are used to *specify* types describing the semantics of functions that we cannot verify e.g. because we don't have the code for them. Here, we are assuming that the library function `Data.Vector.length` indeed computes the size of the input vector. Furthermore, we are stipulating that the lookup function `(!)` requires an index that is between 0 and the real size of the input vector `x`.

DEPENDENT REFINEMENTS are used to describe relationships *between* the elements of a specification. For example, notice how the signature for `length` names the input with the binder `x` that then appears in the output type to constrain the output `Int`. Similarly, the signature for `(!)` names the input vector `x` so that the index can be constrained to be valid for `x`. Thus, dependency lets us write properties that connect *multiple* program values.

ALIASES are extremely useful for defining *abbreviations* for commonly occurring types. Just as we enjoy abstractions when programming, we will find it handy to have abstractions in the specification mechanism. To this end, LiquidHaskell supports *type aliases*. For example, we can define `Vectors` of a given size `N` as:

```
{-@ type VectorN a N = {v:Vector a | vlen v == N} @-}
```

and now use this to type `twoLangs` above as:

```
{-@ twoLangs :: VectorN String 2 @-}
twoLangs      = fromList ["haskell", "javascript"]
```

Similarly, we can define an alias for `Int` values between `Lo` and `Hi`:

```
{-@ type Btwn Lo Hi = {v:Int | Lo <= v && v < Hi} @-}
```

after which we can specify `(!)` as:

```
(!) :: x:Vector a -> Btwn 0 (vlen x) -> a
```

Verification: Vector Lookup

Let's try to write some functions to sanity check the specifications. First, find the starting element – or head of a Vector

```
head    :: Vector a -> a
head vec = vec ! 0
```

When we check the above, we get an error:

```
src/03-poly.lhs:127:23: Error: Liquid Type Mismatch
  Inferred type
    VV : Int | VV == ?a && VV == 0

  not a subtype of Required type
    VV : Int | VV >= 0 && VV < vlen vec

  In Context
    VV  : Int | VV == ?a && VV == 0
    vec : Vector a | 0 <= vlen vec
    ?a  : Int | ?a == (0 : int)
```

LiquidHaskell is saying that 0 is *not* a valid index as it is not between 0 and vlen vec. Say what? Well, what if vec had *no* elements! A formal verifier doesn't make *off by one* errors.

To Fix the problem we can do one of two things.

1. *Require* that the input vec be non-empty, or
2. *Return* an output if vec is non-empty, or

Here's an implementation of the first approach, where we define and use an alias NEVector for non-empty Vectors

```
{-@ type NEVector a = {v:Vector a | 0 < vlen v} @-}

{-@ head' :: NEVector a -> a @-}
head' vec = vec ! 0
```

Exercise 5.1 (Vector Head). *Replace the undefined with an implementation of head' ' which accepts all Vectors but returns a value only when the input vec is not empty.*

```
head''      :: Vector a -> Maybe a
head'' vec = undefined
```

Exercise 5.2 (Unsafe Lookup). *The function `unsafeLookup` is a wrapper around the `(!)` with the arguments flipped. Modify the specification for `unsafeLookup` so that the implementation is accepted by `LiquidHaskell`.*

```
{-@ unsafeLookup :: Int -> Vector a -> a @-}
unsafeLookup index vec = vec ! index
```

Exercise 5.3 (Safe Lookup). *Complete the implementation of `safeLookup` by filling in the implementation of `ok` so that it performs a bounds check before the access.*

```
{-@ safeLookup :: Vector a -> Int -> Maybe a @-}
safeLookup x i
  | ok      = Just (x ! i)
  | otherwise = Nothing
where
  ok      = undefined
```

Inference: Our First Recursive Function

Ok, let's write some code! Let's start with a recursive function that adds up the values of the elements of an `Int` vector.

```
-- >>> vectorSum (fromList [1, -2, 3])
-- 2
vectorSum      :: Vector Int -> Int
vectorSum vec  = go 0 0
  where
    go acc i
      | i < sz    = go (acc + (vec ! i)) (i + 1)
      | otherwise = acc
    sz           = length vec
```

Exercise 5.4 (Guards). *What happens if you replace the guard with `i <= sz`?*

Exercise 5.5 (Absolute Sum). *Write a variant of the above function that computes the `absoluteSum` of the elements of the vector.*

```
-- >>> absoluteSum (fromList [1, -2, 3])
-- 6
{-@ absoluteSum :: Vector Int -> Nat @-}
absoluteSum      = undefined
```

INFERENCE

LiquidHaskell verifies `vectorSum` – or, to be precise, the safety of the vector accesses `vec ! i`. The verification works out because LiquidHaskell is able to *automatically infer* ¹

¹ In your editor, click on `go` to see the inferred type.

```
go :: Int -> {v:Int | 0 <= v && v <= sz} -> Int
```

which states that the second parameter `i` is between `0` and the length of `vec` (inclusive). LiquidHaskell uses this and the test that `i < sz` to establish that `i` is between `0` and `(vlen vec)` to prove safety.

Note you need to run liquid with the option `--no-termination` or make sure your source file has `{-@ LIQUID "--no-termination" @-}`, otherwise the code `forgo'` fails the now default termination check. We will come back to this example later to see how to verify termination using metrics.

Exercise 5.6 (Off by one?). *Why does the type of `go` have `v <= sz` and not `v < sz`?*

Higher-Order Functions: Bottling Recursion in a loop

Let's refactor the above low-level recursive function into a generic higher-order loop.

```
loop :: Int -> Int -> a -> (Int -> a -> a) -> a
loop lo hi base f = go base lo
  where
    go acc i
      | i < hi    = go (f i acc) (i + 1)
      | otherwise = acc
```

We can now use `loop` to implement `vectorSum`:

```
vectorSum'      :: Vector Int -> Int
vectorSum' vec  = loop 0 n 0 body
  where
    body i acc = acc + (vec ! i)
    n         = length vec
```

INFERENCE is a convenient option. LiquidHaskell finds:

```
loop :: lo:Nat -> hi:{Nat|lo <= hi} -> a -> (Btwn lo hi -> a -> a) -> a
```

In English, the above type states that

- lo the loop *lower* bound is a non-negative integer
- hi the loop *upper* bound is a greater then or equal to lo,
- f the loop *body* is only called with integers between lo and hi.

It can be tedious to have to keep typing things like the above. If we wanted to make loop a public or exported function, we could use the inferred type to generate an explicit signature.

At the call loop 0 n 0 body the parameters lo and hi are instantiated with 0 and n respectively, which, by the way is where the inference engine deduces non-negativity. Thus LiquidHaskell concludes that body is only called with values of i that are *between* 0 and (vlen vec), which verifies the safety of the call vec ! i.

Exercise 5.7 (Using Higher-Order Loops). *Complete the implementation of absoluteSum' below. When you are done, what is the type that is inferred for body?*

```
-- >>> absoluteSum' (fromList [1, -2, 3])
-- 6
{-@ absoluteSum' :: Vector Int -> Nat @-}
absoluteSum' vec = loop 0 n 0 body
  where
    body i acc = undefined
    n          = length vec
```

Exercise 5.8 (Dot Product). *The following uses loop to compute dotProducts. Why does LiquidHaskell flag an error? Fix the code or specification so that LiquidHaskell accepts it.*

```
-- >>> dotProduct (fromList [1,2,3]) (fromList [4,5,6])
-- 32
{-@ dotProduct :: x:Vector Int -> y:Vector Int -> Int @-}
dotProduct x y = loop 0 sz 0 body
  where
    body i acc = acc + (x ! i) * (y ! i)
    sz          = length x
```

Refinements and Polymorphism

While the standard `Vector` is great for *dense* arrays, often we have to manipulate *sparse* vectors where most elements are just `0`. We might represent such vectors as a list of index-value tuples:

```
{-@ type SparseN a N = [(Btwn 0 N, a)] @-}
```

Implicitly, all indices *other* than those in the list have the value `0` (or the equivalent value for the type `a`).

THE ALIAS `SparseN` is just a shorthand for the (longer) type on the right, it does not *define* a new type. If you are familiar with the *index-style* length encoding e.g. as found in [DML](#) or [Agda](#), then note that despite appearances, our `Sparse` definition is *not* indexed.

SPARSE PRODUCTS

Let's write a function to compute a sparse product

```
{-@ sparseProduct :: x:Vector _ -> SparseN _ (vlen x) -> _ @-}
sparseProduct x y = go 0 y
  where
    go n [] = n
    go n ((i,v):y') = go (n + (x!i) * v) y'
```

LiquidHaskell verifies the above by using the specification to conclude that for each tuple (i, v) in the list `y`, the value of `i` is within the bounds of the vector `x`, thereby proving `x ! i` safe.

FOLDS

The sharp reader will have undoubtedly noticed that the sparse product can be more cleanly expressed as a [fold](#):

```
foldl' :: (a -> b -> a) -> a -> [b] -> a
```

We can simply fold over the sparse vector, accumulating the sum as we go along

```
{-@ sparseProduct' :: x:Vector _ -> SparseN _ (vlen x) -> _ @-}
sparseProduct' x y = foldl' body 0 y
  where
    body sum (i, v) = sum + (x ! i) * v
```


LiquidHaskell digests this without difficulty. The main trick is in how the polymorphism of `foldl'` is instantiated.

1. GHC infers that at this site, the type variable `b` from the signature of `foldl'` is instantiated to the Haskell type `(Int, a)`.
2. Correspondingly, LiquidHaskell infers that in fact `b` can be instantiated to the *refined* `(Btwn 0 (vlen x), a)`.

Thus, the inference mechanism saves us a fair bit of typing and allows us to reuse existing polymorphic functions over containers and such without ceremony.

Recap

This chapter gave you an idea of how one can use refinements to verify size related properties, and more generally, to specify and verify properties of recursive and polymorphic functions. Next, let's see how we can use LiquidHaskell to prevent the creation of illegal values by refining data type definitions.

6

Refined Datatypes

So far, we have seen how to refine the types of *functions*, to specify, for example, pre-conditions on the inputs, or post-conditions on the outputs. Very often, we wish to define *datatypes* that satisfy certain invariants. In these cases, it is handy to be able to directly refine the data definition, making it impossible to create illegal inhabitants.

Sparse Vectors Revisited

As our first example of a refined datatype, let's revisit the sparse vector representation that we [saw earlier](#). The `SparseN` type alias we used got the job done, but is not pleasant to work with because we have no way of determining the *dimension* of the sparse vector. Instead, let's create a new datatype to represent such vectors:

```
data Sparse a = SP { spDim    :: Int
                    , spElems :: [(Int, a)] }
```

Thus, a sparse vector is a pair of a dimension and a list of index-value tuples. Implicitly, all indices *other* than those in the list have the value 0 or the equivalent value type `a`.

LEGAL

Sparse vectors satisfy two crucial properties. First, the dimension stored in `spDim` is non-negative. Second, every index in `spElems` must be valid, i.e. between 0 and the dimension. Unfortunately, Haskell's type system does not make it easy to ensure that *illegal vectors are not representable*.¹

¹ The standard approach is to use abstract types and [smart constructors](#) but even then there is only the informal guarantee that the smart constructor establishes the right invariants.

DATA INVARIANTS LiquidHaskell lets us enforce these invariants with a refined data definition:

```
{-@ data Sparse a = SP { spDim    :: Nat
                        , spElems :: [(Btwn 0 spDim, a)] } @-}
```

Where, as before, we use the aliases:

```
{-@ type Nat      = {v:Int | 0 <= v}      @-}
{-@ type Btwn Lo Hi = {v:Int | Lo <= v && v < Hi} @-}
```

REFINED DATA CONSTRUCTORS The refined data definition is internally converted into refined types for the data constructor SP:

```
-- Generated Internal representation
data Sparse a where
  SP :: spDim:Nat
      -> spElems:[(Btwn 0 spDim, a)]
      -> Sparse a
```

In other words, by using refined input types for SP we have automatically converted it into a *smart* constructor that ensures that *every* instance of a Sparse is legal. Consequently, LiquidHaskell verifies:

```
okSP :: Sparse String
okSP = SP 5 [ (0, "cat")
             , (3, "dog") ]
```

but rejects, due to the invalid index:

```
badSP :: Sparse String
badSP = SP 5 [ (0, "cat")
              , (6, "dog") ]
```

FIELD MEASURES It is convenient to write an alias for sparse vectors of a given size N. We can use the field name spDim as a *measure*, like vlen. That is, we can use spDim inside refinements²

```
{-@ type SparseN a N = {v:Sparse a | spDim v == N} @-}
```

SPARSE PRODUCTS

Let's write a function to compute a sparse product

² Note that *inside* a refined data definition, a field name like spDim refers to the value of the field, but *outside* it refers to the field selector measure or function.

```

{-@ dotProd :: x:Vector Int -> SparseN Int (vlen x) -> Int @-}
dotProd x (SP _ y) = go 0 y
  where
    go sum ((i, v) : y') = go (sum + (x ! i) * v) y'
    go sum []             = sum

```

LiquidHaskell verifies the above by using the specification to conclude that for each tuple (i, v) in the list y , the value of i is within the bounds of the vector x , thereby proving $x ! i$ safe.

FOLDED PRODUCT We can port the fold-based product to our new representation:

```

{-@ dotProd' :: x:Vector Int -> SparseN Int (vlen x) -> Int @-}
dotProd' x (SP _ y) = foldl' body 0 y
  where
    body sum (i, v) = sum + (x ! i) * v

```

As before, LiquidHaskell checks the above by **automatically instantiating refinements** for the type parameters of `foldl'`, saving us a fair bit of typing and enabling the use of the elegant polymorphic, higher-order combinators we know and love.

Exercise 6.1 (Sanitization). *★ Invariants are all well and good for data computed inside our programs. The only way to ensure the legality of data coming from outside, i.e. from the “real world”, is to write a sanitizer that will check the appropriate invariants before constructing a Sparse vector. Write the specification and implementation of a sanitizer `fromList`, so that the following typechecks:*

Hint: You need to check that *all* the indices in `elts` are less than `dim`; the easiest way is to compute a new `Maybe [(Int, a)]` which is `Just` the original pairs if they are valid, and `Nothing` otherwise.

```

fromList      :: Int    -> [(Int, a)] -> Maybe (Sparse a)
fromList dim elts = undefined

{-@ test1 :: SparseN String 3 @-}
test1      = fromJust $ fromList 3 [(0, "cat"), (2, "mouse")]

```

Exercise 6.2 (Addition). *Write the specification and implementation of a function `plus` that performs the addition of two Sparse vectors of the same dimension, yielding an output of that dimension. When you are done, the following code should typecheck:*

```

plus    :: (Num a) => Sparse a -> Sparse a -> Sparse a
plus x y = undefined

{-@ test2 :: SparseN Int 3 @-}
test2    = plus vec1 vec2
  where
    vec1 = SP 3 [(0, 12), (2, 9)]
    vec2 = SP 3 [(0, 8), (1, 100)]

```

Ordered Lists

As a second example of refined data types, let's consider a different problem: representing *ordered* sequences. Here's a type for sequences that mimics the classical list:

```

data IncList a =
  Emp
  | (:<) { hd :: a, tl :: IncList a }

infixr 9 :<

```

The Haskell type above does not state that the elements are in order of course, but we can specify that requirement by refining *every* element in *tl* to be *greater than* *hd*:

```

{-@ data IncList a =
  Emp
  | (:<) { hd :: a, tl :: IncList {v:a | hd <= v}} @-}

```

REFINED DATA CONSTRUCTORS Once again, the refined data definition is internally converted into a “smart” refined data constructor

```

-- Generated Internal representation
data IncList a where
  Emp  :: IncList a
  (:<) :: hd:a -> tl:IncList {v:a | hd <= v} -> IncList a

```

which ensures that we can only create legal ordered lists.

```

okList  = 1 :< 2 :< 3 :< Emp      -- accepted by LH
badList = 2 :< 1 :< 3 :< Emp      -- rejected by LH

```

It's all very well to *specify* ordered lists. Next, let's see how it's equally easy to *establish* these invariants by implementing several textbook sorting routines.

INSERTION SORT

First, let's implement insertion sort, which converts an ordinary list `[a]` into an ordered list `IncList a`.

```
insertSort      :: (Ord a) => [a] -> IncList a
insertSort []   = Emp
insertSort (x:xs) = insert x (insertSort xs)
```

The hard work is done by `insert` which places an element into the correct position of a sorted list. LiquidHaskell infers that if you give `insert` an element and a sorted list, it returns a sorted list.

```
insert          :: (Ord a) => a -> IncList a -> IncList a
insert y Emp    = y :< Emp
insert y (x :< xs)
  | y <= x      = y :< x :< xs
  | otherwise   = x :< insert y xs
```

Exercise 6.3 (Insertion Sort). *Complete the implementation of the function below to use `foldr` to eliminate the explicit recursion in `insertSort`.*

```
insertSort'    :: (Ord a) => [a] -> IncList a
insertSort' xs = foldr f b xs
  where
    f          = undefined    -- Fill this in
    b          = undefined    -- Fill this in
```

MERGE SORT Similarly, it is easy to write merge sort, by implementing the three steps. First, we write a function that *splits* the input into two equal sized halves:

```
split          :: [a] -> ([a], [a])
split (x:y:zs) = (x:xs, y:ys)
  where
    (xs, ys)   = split zs
split xs       = (xs, [])
```

Second, we need a function that *combines* two ordered lists

```

merge      :: (Ord a) => IncList a -> IncList a -> IncList a
merge xs Emp = xs
merge Emp ys  = ys
merge (x :< xs) (y :< ys)
  | x <= y    = x :< merge xs (y :< ys)
  | otherwise = y :< merge (x :< xs) ys
merge _ _    = Emp

```

Finally, we compose the above steps to divide (i.e. split) and conquer (sort and merge) the input list:

```

mergeSort :: (Ord a) => [a] -> IncList a
mergeSort [] = Emp
mergeSort [x] = x :< Emp
mergeSort xs = merge (mergeSort ys) (mergeSort zs)
  where
    (ys, zs) = split xs

```

Exercise 6.4 (QuickSort). ★★ *Why is the following implementation of quickSort rejected by LiquidHaskell? Modify it so it is accepted.*

Hint: Think about how append should behave so that the quickSort has the desired property. That is, suppose that ys and zs are already in *increasing order*. Does that mean that append x ys zs are *also* in increasing order? No! What other requirement do you need? bottle that intuition into a suitable *specification* for append and then ensure that the code satisfies that specification.

```

quickSort      :: (Ord a) => [a] -> IncList a
quickSort []   = Emp
quickSort (x:xs) = append x lessers greater
  where
    lessers      = quickSort [y | y <- xs, y < x]
    greater      = quickSort [z | z <- xs, z >= x]

{-@ append :: x:a -> IncList a
        -> IncList a
        -> IncList a

    @-}
append z Emp      ys = z :< ys
append z (x :< xs) ys = x :< append z xs ys

```



```

    , right :: BSTR a root } @-}

{-@ type BSTL a X = BST {v:a | v < X}          @-}
{-@ type BSTR a X = BST {v:a | X < v}          @-}

```

REFINED DATA CONSTRUCTORS As before, the above data definition creates a refined smart constructor for BST

```

data BST a where
  Leaf :: BST a
  Node :: r:a -> BST {v:a | v < r}
        -> BST {v:a | r < v}
        -> BST a

```

which *prevents* us from creating illegal trees

```

badBST = Node 66
        (Node 4
         (Node 1 Leaf Leaf)
         (Node 69 Leaf Leaf)) -- Out of order, rejected
        (Node 99
         (Node 77 Leaf Leaf)
         Leaf)

```

Exercise 6.5 (Duplicates). *Can a BST Int contain duplicates?*

MEMBERSHIP

Lets write some functions to create and manipulate these trees. First, a function to check whether a value is in a BST:

```

mem :: (Ord a) => a -> BST a -> Bool
mem _ Leaf = False
mem k (Node k' l r)
  | k == k' = True
  | k < k'  = mem k l
  | otherwise = mem k r

```

SINGLETON Next, another easy warm-up: a function to create a BST with a single given element:

```
one  :: a -> BST a
one x = Node x Leaf Leaf
```

INSERTION Lets write a function that adds an element to a BST.⁴

```
add  :: (Ord a) => a -> BST a -> BST a
add k' Leaf      = one k'
add k' t@(Node k l r)
  | k' < k        = Node k (add k' l) r
  | k < k'        = Node k l (add k' r)
  | otherwise     = t
```

⁴ While writing this exercise I inadvertently swapped the k and k' which caused LiquidHaskell to protest.

MINIMUM For our next trick, let's write a function to delete the *minimum* element from a BST. This function will return a *pair* of outputs – the smallest element and the remainder of the tree. We can say that the output element is indeed the smallest, by saying that the remainder's elements exceed the element. To this end, let's define a helper type: ⁵

```
data MinPair a = MP { mElt :: a, rest :: BST a }
```

⁵ This helper type approach is rather verbose. We should be able to just use plain old pairs and specify the above requirement as a *dependency* between the pairs' elements. Later, we will see how to do so using [abstract refinements](#).

We can specify that `mElt` is indeed smaller than all the elements in `rest` via the data type refinement:

```
{-@ data MinPair a = MP { mElt :: a, rest :: BSTR a mElt } @-}
```

Finally, we can write the code to compute `MinPair`

```
delMin  :: (Ord a) => BST a -> MinPair a
delMin (Node k Leaf r) = MP k r
delMin (Node k l r)    = MP k' (Node k l' r)
  where
    MP k' l'          = delMin l
delMin Leaf           = die "Don't say I didn't warn ya!"
```

Exercise 6.6 (Delete). Use `delMin` to complete the implementation of `del` which deletes a given element from a BST, if it is present.

```
del  :: (Ord a) => a -> BST a -> BST a
del k' t@(Node k l r) = undefined
del _ Leaf           = Leaf
```

Exercise 6.7 (Safely Deleting Minimum). ★ *The function `delMin` is only sensible for non-empty trees. [Read ahead](#) to learn how to specify and verify that it is only called with such trees, and then apply that technique here to verify the call to `die` in `delMin`.*

Exercise 6.8 (BST Sort). *Complete the implementation of `toInclList` to obtain a BST based sorting routine `bstSort`.*

```
bstSort  :: (Ord a) => [a] -> InclList a
bstSort  = toInclList . toBST

toBST    :: (Ord a) => [a] -> BST a
toBST    = foldr add Leaf

toInclList :: BST a -> InclList a
toInclList (Node x l r) = undefined
toInclList Leaf        = undefined
```

Hint: This exercise will be a lot easier *after* you finish the `quickSort` exercise. Note that the signature for `toInclList` does not use `Ord` and so you *cannot* (and *need not*) use a sorting procedure to implement it.

Recap

In this chapter we saw how LiquidHaskell lets you refine data type definitions to capture sophisticated invariants. These definitions are internally represented by refining the types of the data constructors, automatically making them “smart” in that they preclude the creation of illegal values that violate the invariants. We will see much more of this handy technique in future chapters.

One recurring theme in this chapter was that we had to create new versions of standard datatypes, just in order to specify certain invariants. For example, we had to write a special list type, with its own *copies* of `nil` and `cons`. Similarly, to implement `delMin` we had to create our own pair type.

THIS DUPLICATION of types is quite tedious. There should be a way to just slap the desired invariants on to *existing* types, thereby facilitating their reuse. In a few chapters, we will see how to achieve this reuse by [abstracting refinements](#) from the definitions of datatypes or functions in the same way we abstract the element type `a` from containers like `[a]` or `BST a`.

7

Boolean Measures

In the last two chapters, we saw how refinements could be used to reason about the properties of basic `Int` values like vector indices, or the elements of a list. Next, let's see how we can describe properties of aggregate structures like lists and trees, and use these properties to improve the APIs for operating over such structures.

Partial Functions

As a motivating example, let us return to the problem of ensuring the safety of division. Recall that we wrote:

```
{-@ divide :: Int -> NonZero -> Int @-}  
divide _ 0 = die "divide-by-zero"  
divide x n = x `div` n
```

THE PRECONDITION asserted by the input type `NonZero` allows LiquidHaskell to prove that the `die` is *never* executed at run-time, but consequently, requires us to establish that wherever `divide` is *used*, the second parameter be provably non-zero. This requirement is not onerous when we know what the divisor is *statically*

```
avg2 x y = divide (x + y) 2  
avg3 x y z = divide (x + y + z) 3
```

However, it can be more of a challenge when the divisor is obtained *dynamically*. For example, let's write a function to find the number of elements in a list

```
size      :: [a] -> Int
size []   = 0
size (_:xs) = 1 + size xs
```

and use it to compute the average value of a list:

```
avgMany xs = divide total elems
  where
    total = sum xs
    elems = size xs
```

Uh oh. LiquidHaskell wags its finger at us!

```
src/04-measure.lhs:77:27-31: Error: Liquid Type Mismatch
  Inferred type
    VV : Int | VV == elems

  not a subtype of Required type
    VV : Int | 0 /= VV

  In Context
    VV    : Int | VV == elems
    elems : Int
```

WE CANNOT PROVE that the divisor is NonZero, because it *can be* 0 – when the list is *empty*. Thus, we need a way of specifying that the input to `avgMany` is indeed non-empty!

Lifting Functions to Measures

How shall we tell LiquidHaskell that a list is *non-empty*? Recall the notion of measure previously **introduced** to describe the size of a `Data.Vector`. In that spirit, let's write a function that computes whether a list is not empty:

```
notEmpty    :: [a] -> Bool
notEmpty []  = False
notEmpty (_:_) = True
```

A MEASURE is a *total* Haskell function,

1. With a *single* equation per data constructor, and
2. Guaranteed to *terminate*, typically via structural recursion.

We can tell LiquidHaskell to *lift* a function meeting the above requirements into the refinement logic by declaring:

```
{-@ measure notEmpty @-}
```

NON-EMPTY LISTS can now be described as the *subset* of plain old Haskell lists `[a]` for which the predicate `notEmpty` holds

```
{-@ type NEList a = {v:[a] | notEmpty v} @-}
```

We can now refine various signatures to establish the safety of the list-average function.

SIZE returns a non-zero value *if* the input list is not-empty. We capture this condition with an **implication** in the output refinement.

```
{-@ size :: xs:[a] -> {v:Nat | notEmpty xs => v > 0} @-}
```

AVERAGE is only sensible for non-empty lists. Happily, we can specify this using the refined `NEList` type:

```
{-@ average :: NEList Int -> Int @-}
average xs = divide total elems
  where
    total  = sum xs
    elems  = size xs
```

Exercise 7.1 (Average, Maybe). *Fix the code below to obtain an alternate variant `average'` that returns `Nothing` for empty lists:*

```
average'      :: [Int] -> Maybe Int
average' xs
  | ok        = Just $ divide (sum xs) elems
  | otherwise = Nothing
  where
    elems     = size xs
    ok        = True    -- What expression goes here?
```

Exercise 7.2 (Debugging Specifications). *An important aspect of formal verifiers like LiquidHaskell is that they help establish properties not just of your implementations but equally, or more importantly, of your specifications. In that spirit, can you explain why the following two variants of size are rejected by LiquidHaskell?*

```
{-@ size1    :: xs:NEList a -> Pos @-}
size1 []     = 0
size1 (_,xs) = 1 + size1 xs

{-@ size2    :: xs:[a] -> {v:Int | notEmpty xs => v > 0} @-}
size2 []     = 0
size2 (_,xs) = 1 + size2 xs
```

A Safe List API

Now that we can talk about non-empty lists, we can ensure the safety of various list-manipulating functions which are only well-defined on non-empty lists and crash otherwise.

HEAD AND TAIL are two of the canonical *dangerous* functions, that only work on non-empty lists, and burn horribly otherwise. We can type them simple as:

```
{-@ head     :: NEList a -> a @-}
head (x:_)  = x
head []     = die "Fear not! 'twill ne'er come to pass"

{-@ tail     :: NEList a -> [a] @-}
tail (_,xs) = xs
tail []     = die "Relaxeth! this too shall ne'er be"
```

LiquidHaskell uses the precondition to deduce that the second equations are *dead code*. Of course, this requires us to establish that *callers* of head and tail only invoke the respective functions with non-empty lists.

Exercise 7.3 (Safe Head). *Write down a specification for null such that safeHead is verified. Do not force null to only take non-empty inputs, that defeats the purpose. Instead, its type should say that it works on all lists and returns False if and only if the input is non-empty.*

Hint: You may want to refresh your memory about implies ==> and <=> from the [chapter on logic](#).


```

safeHead    :: [a] -> Maybe a
safeHead xs
  | null xs  = Nothing
  | otherwise = Just $ head xs

{-@ null      :: [a] -> Bool @-}
null []      = True
null (_:_)   = False

```

GROUPS

Lets use the above to write a function that chunks sequences into non-empty groups of equal elements:

```

{-@ groupEq    :: (Eq a) => [a] -> [NEList a] @-}
groupEq []     = []
groupEq (x:xs) = (x:ys) : groupEq zs
  where
    (ys, zs)    = span (x ==) xs

```

By using the fact that *each element* in the output returned by `groupEq` is in fact of the form `x:ys`, LiquidHaskell infers that `groupEq` returns a `[NEList a]` that is, a list of *non-empty lists*.

TO ELIMINATE STUTTERING from a string, we can use `groupEq` to split the string into blocks of repeating Chars, and then just extract the first Char from each block:

```

-- >>> eliminateStutter "ssstringssss liiiiiike thisss"
-- "strings like this"
eliminateStutter xs = map head $ groupEq xs

```

LiquidHaskell automatically instantiates the type parameter for `map` in `eliminateStutter` to `notEmpty v` to deduce that `head` is only called on non-empty lists.

`FOLDL1` is one of my favorite folds; it uses the first element of the sequence as the initial value. Of course, it should only be called with non-empty sequences!

```

{-@ foldl1     :: (a -> a -> a) -> NEList a -> a @-}
foldl1 f (x:xs) = foldl f x xs
foldl1 _ []     = die "foldl1"

```

```
foldl1      :: (a -> b -> a) -> a -> [b] -> a
foldl1 _ acc []      = acc
foldl1 f acc (x:xs) = foldl1 f (f acc x) xs
```

To SUM a non-empty list of numbers, we can just perform a `foldl1` with the `+` operator: Thanks to the precondition, `LiquidHaskell` will prove that the die code is indeed dead. Thus, we can write

```
{-@ sum :: (Num a) => NEList a -> a @-}
sum []  = die "cannot add up empty list"
sum xs  = foldl1 (+) xs
```

Consequently, we can only invoke `sum` on non-empty lists, so:

```
sumOk  = sum [1,2,3,4,5]  -- is accepted by LH, but
sumBad = sum []           -- is rejected by LH
```

Exercise 7.4 (Weighted Average). *The function below computes a weighted average of its input. Unfortunately, `LiquidHaskell` is not very happy about it. Can you figure out why, and fix the code or specification appropriately?*

```
{-@ wtAverage :: NEList (Pos, Pos) -> Int @-}
wtAverage wxs = divide totElems totWeight
  where
    elems      = map (\(w, x) -> w * x) wxs
    weights    = map (\(w, _) -> w      ) wxs
    totElems   = sum elems
    totWeight  = sum weights
    sum        = foldl1 (+)

map      :: (a -> b) -> [a] -> [b]
map _ [] = []
map f (x:xs) = f x : map f xs
```

Hint: On what variables are the errors? How are those variables' values computed? Can you think of a better specification for the function(s) doing those computations?

Exercise 7.5 (Mitchell's Risers). *Non-empty lists pop up in many places, and it is rather convenient to have the type system track non-emptiness without having to make up special types. Consider the `risers` function, popularized by [Neil Mitchell](#). `safeSplit` requires its input be non-empty;*

but *LiquidHaskell* believes that the call inside `risers` fails this requirement. Fix the specification for `risers` so that it is verified.

```
{-@ risers      :: (Ord a) => [a] -> [[a]] @-}
risers         :: (Ord a) => [a] -> [[a]]
risers []      = []
risers [x]     = [[x]]
risers (x:y:etc)
  | x <= y     = (x:s) : ss
  | otherwise  = [x] : (s : ss)
  where
    (s, ss)    = safeSplit $ risers (y:etc)

{-@ safeSplit  :: NEList a -> (a, [a]) @-}
safeSplit (x:xs) = (x, xs)
safeSplit _      = die "don't worry, be happy"
```

Recap

In this chapter we saw how *LiquidHaskell* lets you

1. Define structural properties of data types,
2. Use *refinements* over these properties to describe key invariants that establish, at compile-time, the safety of operations that might otherwise fail on unexpected values at run-time, all while,
3. Working with *plain Haskell types*, here, Lists, without having to [make up new types](#) which can have the unfortunate effect of adding a multitude of constructors and conversions which often clutter implementations and specifications.

Of course, we can do a lot more with measures, so let's press on!

8

Numeric Measures

Many of the programs we have seen so far, for example those in [here](#), suffer from *indexitis*. This is a term coined by [Richard Bird](#) which describes a tendency to perform low-level manipulations to iterate over the indices into a collection, opening the door to various off-by-one errors. Such errors can be eliminated by instead programming at a higher level, using a [wholemeal approach](#) where the emphasis is on using aggregate operations, like `map`, `fold` and `reduce`.

WHOLEMEAL PROGRAMMING IS NO PANACEA as it still requires us to take care when operating on *different* collections; if these collections are *incompatible*, e.g. have the wrong dimensions, then we end up with a fate worse than a crash, a possibly meaningless result. Fortunately, LiquidHaskell can help. Lets see how we can use measures to specify dimensions and create a dimension-aware API for lists which can be used to implement wholemeal dimension-safe APIs.¹

¹ In a [later chapter](#) we will use this API to implement K-means clustering.

Wholemeal Programming

Indexitis begone! As an example of wholemeal programming, let's write a small library that represents vectors as lists and matrices as nested vectors:

```
data Vector a = V { vDim  :: Int
                  , vElts :: [a]
                  }
    deriving (Eq)

data Matrix a = M { mRow  :: Int
                  , mCol  :: Int
```

```

    , mElts :: Vector (Vector a)
  }
  deriving (Eq)

```

THE DOT PRODUCT of two Vectors can be easily computed using a fold:

```

dotProd      :: (Num a) => Vector a -> Vector a -> a
dotProd vx vy = sum (prod xs ys)
  where
    prod      = zipWith (\x y -> x * y)
    xs        = vElts vx
    ys        = vElts vy

```

MATRIX MULTIPLICATION can similarly be expressed in a high-level, wholemeal fashion, by eschewing low level index manipulations in favor of a high-level *iterator* over the Matrix elements:

```

matProd      :: (Num a) => Matrix a -> Matrix a -> Matrix a
matProd (M rx _ xs) (M _ cy ys)
    = M rx cy elts
  where
    elts      = for xs (\xi ->
                        for ys (\yj ->
                            dotProd xi yj
                        )
    )

```

THE ITERATION embodied by the for combinator, is simply a map over the elements of the vector.

```

for          :: Vector a -> (a -> b) -> Vector b
for (V n xs) f = V n (map f xs)

```

WHOLEMEAL PROGRAMMING FREES us from having to fret about low-level index range manipulation, but is hardly a panacea. Instead, we must now think carefully about the *compatibility* of the various aggregates. For example,

- dotProd is only sensible on vectors of the same dimension; if one vector is shorter than another (i.e. has fewer elements) then we

will won't get a run-time crash but instead will get some gibberish result that will be dreadfully hard to debug.

- `matProd` is only well defined on matrices of compatible dimensions; the number of columns of `mx` must equal the number of rows of `my`. Otherwise, again, rather than an error, we will get the wrong output.²

² In fact, while the implementation of `matProd` breezes past GHC it is quite wrong!

Specifying List Dimensions

In order to start reasoning about dimensions, we need a way to represent the *dimension* of a list inside the refinement logic.³

³ We could just use `vDim`, but that is a cheat as there is no guarantee that the field's value actually equals the size of the list!

`MEASURES` are ideal for this task. **Previously** we saw how we could lift Haskell functions up to the refinement logic. Lets write a measure to describe the length of a list:⁴

⁴ **Recall** that these must be inductively defined functions, with a single equation per data-constructor

```
{-@ measure size @-}
{-@ size :: [a] -> Nat @-}
size []      = 0
size (_,rs) = 1 + size rs
```

MEASURES REFINE CONSTRUCTORS

As with **refined data definitions**, the measures are translated into strengthened types for the type's constructors. For example, the `size` measure is translated into:

```
data [a] where
  []  :: {v: [a] | size v = 0}
  (:) :: a -> xs:[a] -> {v:[a]|size v = 1 + size xs}
```

`MULTIPLE MEASURES` may be defined for the same data type. For example, in addition to the `size` measure, we can define a `notEmpty` measure for the list type:

```
{-@ measure notEmpty @-}
notEmpty      :: [a] -> Bool
notEmpty []   = False
notEmpty (_,_) = True
```

WE COMPOSE DIFFERENT MEASURES

simply by *conjoining* the refinements in the strengthened constructors. For example, the two measures for lists end up yielding the constructors:

```
data [a] where
  []  :: {v: [a] | not (notEmpty v) && size v = 0}
  (:) :: a
      -> xs:[a]
      -> {v:[a] | notEmpty v && size v = 1 + size xs}
```

This is a very significant advantage of using measures instead of indices as in [DML](#) or [Agda](#), as *decouples property from structure*, which crucially enables the use of the same structure for many different purposes. That is, we need not know *a priori* what indices to bake into the structure, but can define a generic structure and refine it *a posteriori* as needed with new measures.

We are almost ready to begin creating a dimension aware API for lists; one last thing that is useful is a couple of aliases for describing lists of a given dimension.

TO MAKE SIGNATURES SYMMETRIC let's define an alias for plain old (unrefined) lists:

```
type List a = [a]
```

A `ListN` is a list with exactly `N` elements, and a `ListX` is a list whose size is the same as another list `X`. Note that when defining refinement type aliases, we use uppercase variables like `N` and `X` to distinguish *value* parameters from the lowercase *type* parameters like `a`.

```
{-@ type ListN a N = {v:List a | size v = N} @-}
{-@ type ListX a X = ListN a {size X}      @-}
```

Lists: Size Preserving API

With the types and aliases firmly in our pockets, let us write dimension-aware variants of the usual list functions. The implementations are the same as in the standard library i.e. `Data.List`, but the specifications are enriched with dimension information.

Exercise 8.1 (Map). `MAP` yields a list with the same size as the input. Fix the specification of `map` so that the `prop_map` is verified.


```

{-@ map      :: (a -> b) -> xs:List a -> List b @-}
map _ []     = []
map f (x:xs) = f x : map f xs

{-@ prop_map :: List a -> TRUE @-}
prop_map xs = size ys == size xs
  where
    ys      = map id xs
    
```

Exercise 8.2 (Reverse). *★ We can reverse the elements of a list as shown below, using the tail recursive function go. Fix the signature for go so that LiquidHaskell can prove the specification for reverse.*

Hint: How big is the list returned by go?

```

{-@ reverse      :: xs:List a -> ListX a xs @-}
reverse xs       = go [] xs
  where
    go acc []     = acc
    go acc (x:xs) = go (x:acc) xs
    
```

zipWith requires both lists to have the *same* size, and produces a list with that same size.⁵

```

{-@ zipWith :: (a -> b -> c) -> xs:List a
              -> ListX b xs
              -> ListX c xs

    @-}
zipWith f (a:as) (b:bs) = f a b : zipWith f as bs
zipWith _ [] []         = []
zipWith _ _ _           = die "no other cases"
    
```

UNSAFEZIP The signature for zipWith is quite severe – it rules out the case where the zipping occurs only up to the shorter input. Here’s a function that actually allows for that case, where the output type is the *shorter* of the two inputs:

```

{-@ zip :: as:[a] -> bs:[b] -> {v:[(a,b)] | Tinier v as bs} @-}
zip (a:as) (b:bs) = (a, b) : zip as bs
zip [] _         = []
zip _ []         = []
    
```

The output type uses the predicate `Tinier Xs Ys Zs` which defines the length of `Xs` to be the smaller of that of `Ys` and `Zs`.⁶

⁵ As made explicit by the call to `die`, the input type *rules out* the case where one list is empty and the other is not, as in that case the former’s length is zero while the latter’s is not, and hence, different.

⁶ In logic, if p then q else r is the same as $p \Rightarrow q \ \&\& \ \text{not } p \Rightarrow r$.

```
{-@ predicate Tinier X Y Z = Min (size X) (size Y) (size Z) @-}
{-@ predicate Min X Y Z = (if Y < Z then X = Y else X = Z) @-}
```

Exercise 8.3 (Zip Unless Empty). *★ In my experience, zip as shown above is far too permissive and lets all sorts of bugs into my code. As middle ground, consider zipOrNull below. Write a specification for zipOrNull such that the code below is verified by LiquidHaskell.*

```
zipOrNull      :: [a] -> [b] -> [(a, b)]
zipOrNull [] _ = []
zipOrNull _ [] = []
zipOrNull xs ys = zipWith (,) xs ys

{-@ test1 :: {v: _ | size v = 2} @-}
test1      = zipOrNull [0, 1] [True, False]

{-@ test2 :: {v: _ | size v = 0} @-}
test2      = zipOrNull [] [True, False]

{-@ test3 :: {v: _ | size v = 0} @-}
test3      = zipOrNull ["cat", "dog"] []
```

Hint: Yes, the type is rather gross; it uses a bunch of disjunctions `||`, conjunctions `&&` and implications `=>`.

Lists: Size Reducing API

Next, let's look at some functions that truncate lists, in one way or another.

TAKE lets us grab the first `k` elements from a list:

```
{-@ take'      :: n:Nat -> ListGE a n -> ListN a n @-}
take' 0 _      = []
take' n (x:xs) = x : take' (n-1) xs
take' _ _      = die "won't happen"
```

The alias `ListGE a n` denotes lists whose length is at least `n`:

```
{-@ type ListGE a N = {v:List a | N <= size v} @-}
```

Exercise 8.4 (Drop). *Drop is the yang to take's yin: it returns the remainder after extracting the first `k` elements. Write a suitable specification for it so that the below typechecks.*

```

drop 0 xs      = xs
drop n (_:xs) = drop (n-1) xs
drop _ _      = die "won't happen"

{-@ test4 :: ListN String 2 @-}
test4 = drop 1 ["cat", "dog", "mouse"]

```

Exercise 8.5 (Take it easy). *The version take' above is too restrictive; it insists that the list actually have at least n elements. Modify the signature for the real take function so that the code below is accepted by LiquidHaskell.*

```

take 0 _      = []
take _ []     = []
take n (x:xs) = x : take (n-1) xs

{-@ test5 :: [ListN String 2] @-}
test5 = [ take 2 ["cat", "dog", "mouse"]
        , take 20 ["cow", "goat"]         ]

```

THE PARTITION function breaks a list into two sub-lists of elements that either satisfy or fail a user supplied predicate.

```

partition      :: (a -> Bool) -> [a] -> ([a], [a])
partition _ [] = ([], [])
partition f (x:xs)
  | f x      = (x:ys, zs)
  | otherwise = (ys, x:zs)
where
  (ys, zs)   = partition f xs

```

We would like to specify that the *sum* of the output tuple's dimensions equal the input list's dimension. Lets write measures to access the elements of the output:

```

{-@ measure fst @-}
fst (x, _) = x

{-@ measure snd @-}
snd (_, y) = y

```

We can now refine the type of partition as:

```
{-@ partition :: _ -> xs:_ -> {v:_ | Sum2 v (size xs)} @-}
```

where `Sum2 V N` holds for a pair of lists dimensions add to `N`:

```
{-@ predicate Sum2 X N = size (fst X) + size (snd X) = N @-}
```

Exercise 8.6 (QuickSort). *Use partition to implement quickSort.*

```
-- >> quickSort [1,4,3,2]
-- [1,2,3,4]

{-@ quickSort    :: (Ord a) => xs:List a -> ListX a xs @-}
quickSort []     = []
quickSort (x:xs) = undefined

{-@ test10 :: ListN String 2 @-}
test10 = quickSort (drop 1 ["cat", "dog", "mouse"])
```

Dimension Safe Vector API

We can use the dimension aware lists to create a safe vector API.

LEGAL VECTORS are those whose `vDim` field actually equals the size of the underlying list:

```
{-@ data Vector a = V { vDim  :: Nat
                      , vElts :: ListN a vDim }
  @-}
```

When `vDim` is used a selector function, it returns the `vDim` field of `x`.

```
{-@ vDim :: x:_ -> {v: Nat | v = vDim x} @-}
```

The refined data type prevents the creation of illegal vectors:

```
okVec  = V 2 [10, 20]      -- accepted by LH
badVec = V 2 [10, 20, 30]  -- rejected by LH
```

As usual, it will be handy to have a few aliases.

```
-- | Non Empty Vectors
{-@ type VectorNE a  = {v:Vector a | vDim v > 0} @-}

-- | Vectors of size N
{-@ type VectorN a N = {v:Vector a | vDim v = N} @-}

-- | Vectors of Size Equal to Another Vector X
{-@ type VectorX a X = VectorN a {vDim X}      @-}
```

To CREATE a Vector safely, we can start with the empty vector `vEmp` and then add elements one-by-one with `vCons`:

```
{-@ vEmp :: VectorN a 0 @-}
vEmp = V 0 []

{-@ vCons :: a -> x:Vector a -> VectorN a {vDim x + 1} @-}
vCons x (V n xs) = V (n+1) (x:xs)
```

To ACCESS vectors at a low-level, we can use equivalents of *head* and *tail*, which only work on non-empty Vectors:

```
{-@ vHd :: VectorNE a -> a @-}
vHd (V _ (x:_)) = x
vHd _           = die "nope"

{-@ vTl      :: x:VectorNE a -> VectorN a {vDim x - 1} @-}
vTl (V n (_,xs)) = V (n-1) xs
vTl _           = die "nope"
```

To ITERATE over a vector we can use the `for` combinator:

```
{-@ for      :: x:Vector a -> (a -> b) -> VectorX b x @-}
for (V n xs) f = V n (map f xs)
```

BINARY POINTWISE OPERATIONS should only be applied to *compatible* vectors, i.e. vectors with equal dimensions. We can write a generic binary pointwise operator:

```
{-@ vBin :: (a -> b -> c) -> x:Vector a
      -> VectorX b x
      -> VectorX c x
```

```
@-}
vBin op (V n xs) (V _ ys) = V n (zipWith op xs ys)
```

THE DOT PRODUCT of two Vectors can be now implemented in a wholemeal *and* dimension safe manner, as:

```
{-@ dotProduct :: (Num a) => x:Vector a -> VectorX a x -> a @-}
dotProduct x y = sum $ vElts $ vBin (*) x y
```

Exercise 8.7 (Vector Constructor). *Complete the specification and implementation of `vecFromList` which creates a Vector from a plain list.*

```
vecFromList    :: [a] -> Vector a
vecFromList xs = undefined

test6 = dotProduct vx vy    -- should be accepted by LH
  where
    vx = vecFromList [1,2,3]
    vy = vecFromList [4,5,6]
```

Exercise 8.8 (Flatten). *★ Write a function to flatten a nested Vector.*

```
{-@ flatten :: n:Nat
      -> m:Nat
      -> VectorN (VectorN a m) n
      -> VectorN a {m * n}

@-}
flatten = undefined
```

THE CROSS PRODUCT of two vectors can now be computed in a nice wholemeal style, by a nested iteration followed by a flatten.

```
{-@ product  :: xs:Vector _
      -> ys:Vector _
      -> VectorN _ {vDim xs * vDim ys}

@-}
product xs ys = flatten (vDim ys) (vDim xs) xys
  where
    xys = for ys $ \y ->
          for xs $ \x ->
            x * y
```

Dimension Safe Matrix API

The same methods let us create a dimension safe Matrix API which ensures that only legal matrices are created and that operations are performed on compatible matrices.

LEGAL MATRICES are those where the dimension of the outer vector equals the number of rows `mRow` and the dimension of each inner vector is `mCol`. We can specify legality in a refined data definition:

```
{-@ data Matrix a =
  M { mRow  :: Pos
    , mCol  :: Pos
    , mElts :: VectorN (VectorN a mCol) mRow
    }
  @-}
```

Notice that we avoid disallow degenerate matrices by requiring the dimensions to be positive.

```
{-@ type Pos = {v:Int | 0 < v} @-}
```

It is convenient to have an alias for matrices of a given size:

```
{-@ type MatrixN a R C = {v:Matrix a | Dims v R C } @-}
{-@ predicate Dims M R C = mRow M = R && mCol M = C @-}
```

For example, we can use the above to write type:

```
{-@ ok23 :: MatrixN _ 2 3 @-}
ok23    = M 2 3 (V 2 [ V 3 [1, 2, 3]
                      , V 3 [4, 5, 6] ])
```

Exercise 8.9 (Legal Matrix). *Modify the definitions of `bad1` and `bad2` so that they are legal matrices accepted by `LiquidHaskell`.*

```
bad1 :: Matrix Int
bad1 = M 2 3 (V 2 [ V 3 [1, 2 ]
                  , V 3 [4, 5, 6]])

bad2 :: Matrix Int
bad2 = M 2 3 (V 2 [ V 2 [1, 2]
                  , V 2 [4, 5] ])
```

Exercise 8.10 (Matrix Constructor). *★ Write a function to construct a Matrix from a nested list.*

```
matFromList    :: [[a]] -> Maybe (Matrix a)
matFromList [] = Nothing
matFromList xss@(xs:_)
  | ok          = Just (M r c vs)
  | otherwise   = Nothing
where
  r              = size xss
  c              = size xs
  ok             = undefined
  vs            = undefined
```

Exercise 8.11 (Refined Matrix Constructor). *★★ Refine the specification for matFromList so that the following is accepted by LiquidHaskell.*

```
{-@ mat23 :: Maybe (MatrixN Integer 2 2) @-}
mat23      = matFromList [ [1, 2]
                           , [3, 4] ]
```

Hint: It is easy to specify the number of rows from xss. How will you figure out the number of columns? A measure may be useful.

MATRIX MULTIPLICATION Finally, let's implement matrix multiplication. You'd think we did it already, but in fact the implementation at the top of this chapter is all wrong (run it and see!) We cannot just multiply any two matrices: the number of *columns* of the first must equal to the *rows* of the second – after which point the result comprises the dotProduct of the rows of the first matrix with the columns of the second.

```
{-@ matProduct :: (Num a) => x:Matrix a
                -> y:{Matrix a | mCol x = mRow y}
                -> MatrixN a (mRow x) (mCol y)
@-}
matProduct (M rx _ xs) my@(M _ cy _)
  = M rx cy elts
where
  elts      = for xs (\xi ->
                    for ys' (\yj ->
                        dotProduct xi yj
                    )
                )
```



```

    )
M _ _ ys' = transpose my

```

To iterate over the *columns* of the matrix `my` we just transpose it so the columns become rows.

```

-- >>> ok32 == transpose ok23
-- True
ok32 = M 3 2 (V 3 [ V 2 [1, 4]
                  , V 2 [2, 5]
                  , V 2 [3, 6] ])

```

Exercise 8.12 (Matrix Transpose). ★★ *Use the Vector API to complete the implementation of `txgo`. For inspiration, you might look at the implementation of `Data.List.transpose` from the [prelude](#). Better still, don't.*

```

{-@ transpose :: m:Matrix a -> MatrixN a (mCol m) (mRow m) @-}
transpose (M r c rows) = M c r $ txgo c r rows

{-@ txgo      :: c:Nat -> r:Nat
    -> VectorN (VectorN a c) r
    -> VectorN (VectorN a r) c
    @-}
txgo c r rows = undefined

```

Hint: As shown by `ok23` and `ok32`, transpose works by stripping out the heads of the input rows, to create the corresponding output rows.

Recap

In this chapter, we saw how to use measures to describe numeric properties of structures like lists (`Vector`) and nested lists (`Matrix`).

1. Measures are *structurally recursive* functions, with a single equation per data constructor,
2. Measures can be used to create refined data definitions that prevent the creation of illegal values,
3. Measures can then be used to enable safe wholemeal programming, via dimension-aware APIs that ensure that operators only apply to compatible values.

We can use numeric measures to encode various other properties of data structures. We will see examples ranging from high-level [AVL trees](#), to low-level safe [pointer arithmetic](#).

9

Elemental Measures

Often, correctness requires us to reason about the *set of elements* represented inside a data structure, or manipulated by a function. Examples of this abound: for example, we'd like to know that:

- *sorting* routines return permutations of their inputs – i.e. return collections whose elements are the same as the input set,
- *resource* management functions do not inadvertently create duplicate elements or drop elements from set of tracked resources.
- *syntax-tree* manipulating procedures create well-scoped trees where the set of used variables are contained within the set of variables previously defined.

SMT SOLVERS support very expressive logics. In addition to linear arithmetic and uninterpreted functions, they can [efficiently decide](#) formulas over sets. Next, let's see how LiquidHaskell lets us exploit this fact to develop types and interfaces that guarantee invariants over the set of elements of a structures.

Talking about Sets

First, we need a way to talk about sets in the refinement logic. We could roll our own special Haskell type but for now, let's just use the `Set` a type from the prelude's `Data.Set`.¹

LIQUIDHASKELL LIFTS the basic set operators from `Data.Set` into the refinement logic. That is, the prelude defines the following *logical* functions that correspond to the *Haskell* functions of the same name:

¹ See [this](#) for a brief description of how to work directly with the set operators natively supported by LiquidHaskell.

```

measure empty      :: Set a
measure singleton  :: a -> Set a
measure member     :: a -> Set a -> Bool
measure union      :: Set a -> Set a -> Set a
measure intersection :: Set a -> Set a -> Set a
measure difference :: Set a -> Set a -> Set a

```

INTERPRETED OPERATORS

The above operators are *interpreted* by the SMT solver. That is, just like the SMT solver “knows”, via the axioms of the theory of arithmetic that:

$$x = 1 + 1 \Rightarrow x = 2$$

is a valid formula, i.e. holds for all x , the solver “knows” that:

$$x = (\text{singleton } 1) \Rightarrow y = (\text{singleton } 2) \Rightarrow x = (\text{intersection } x (\text{union } y x))$$

This is because, the above formulas belong to a decidable Theory of Sets reduces to McCarthy’s more general [Theory of Arrays](#).²

² See [this recent paper](#) to learn how modern SMT solvers prove equalities like the above.

Proving QuickCheck Style Properties

To get the hang of what’s going on, let’s do a few warm up exercises, using LiquidHaskell to prove various simple theorems about sets and operations over them.

WE REFINED THE SET API to make it easy to write down theorems. That is, we give the operators in `Data.Set` refinement type signatures that precisely track their set-theoretic behavior:

```

empty      :: {v:Set a | v = empty}
member     :: x:a
           -> s:Set a
           -> {v:Bool | v <=> member x s}

singleton  :: x:a -> {v:Set a | v = singleton x}

union      :: x:Set a
           -> y:Set a
           -> {v:Set a | v = union x y}

intersection :: x:Set a
           -> y:Set a

```

```

-> {v:Set a | v = intersection x y}

difference  :: x:Set a
            -> y:Set a
            -> {v:Set a | v = difference x y}

```

WE CAN ASSERT THEOREMS as [QuickCheck](#) style *properties*, that is, as functions from arbitrary inputs to a Bool output that must always be True. Lets define aliases for the Booleans that are always True or False

```

{-@ type True  = {v:Bool |    v} @-}
{-@ type False = {v:Bool | not v} @-}

```

We can use True to state theorems. For example, the unexciting arithmetic equality above becomes:

```

{-@ prop_one_plus_one_eq_two :: _ -> True @-}
prop_one_plus_one_eq_two x   = (x == 1 + 1) `implies` (x == 2)

```

Where implies is just the implication function over Bool

```

{-@ implies      :: p:Bool -> q:Bool -> Implies p q @-}
implies False _  = True
implies _      True = True
implies _      _  = False

```

and Implies p q is defined as

```

{-@ type Implies P Q = {v:_ | v <=> (P => Q)} @-}

```

Exercise 9.1 (Bounded Addition). *Write and prove a QuickCheck style theorem that: $\forall x, y. x < 100 \wedge y < 100 \Rightarrow x + y < 200$.*

```

{-@ prop_x_y_200 :: _ -> _ -> True @-}
prop_x_y_200 x y = False -- fill in the theorem body

```

THE COMMUTATIVITY OF INTERSECTION can be easily stated and proved as a QuickCheck style theorem:

```

{-@ prop_intersection_comm :: _ -> _ -> True @-}
prop_intersection_comm x y
  = (x `intersection` y) == (y `intersection` x)

```

THE ASSOCIATIVITY OF UNION can similarly be confirmed:

```
{-@ prop_union_assoc :: _ -> _ -> _ -> True @-}
prop_union_assoc x y z
  = (x `union` (y `union` z)) == (x `union` y) `union` z
```

THE DISTRIBUTIVITY LAWS for Boolean Algebra can be verified by writing properties over the relevant operators. For example, let's check that intersection distributes over union:

```
{-@ prop_intersection_dist :: _ -> _ -> _ -> True @-}
prop_intersection_dist x y z
  = x `intersection` (y `union` z)
    ==
    (x `intersection` y) `union` (x `intersection` z)
```

NON-THEOREMS should be rejected. So, while we're at it, let's make sure LiquidHaskell doesn't prove anything that *isn't* true ...

```
{-@ prop_cup_dif_bad :: _ -> _ -> True @-}
prop_cup_dif_bad x y
  = pre `implies` (x == ((x `union` y) `difference` y))
  where
    pre = True -- Fix this with a non-trivial precondition
```

Exercise 9.2 (Set Difference). *Why does the above property fail?*

1. Use QuickCheck (or your own little grey cells) to find a counterexample for the property `prop_cup_dif_bad`.
2. Use the counterexample to assign `pre` a non-trivial (i.e. other than `False`) condition so that the property can be proved.

Thus, LiquidHaskell's refined types offer a nice interface for interacting with the SMT solvers in order to *prove* theorems, while letting us use QuickCheck to generate counterexamples.³

³ The [SBV](#) and [Leon](#) projects describe a different DSL based approach for using SMT solvers from Haskell and Scala respectively.

Content-Aware List API

Lets return to our real goal, which is to verify properties of programs. First, we need a way to refine the list API to precisely track the set of elements in a list.

THE ELEMENTS OF A LIST can be described by a simple recursive measure that walks over the list, building up the set:

```
{-@ measure elts @-}
elts      :: (Ord a) => [a] -> Set a
elts []   = empty
elts (x:xs) = singleton x `union` elts xs
```

Lets write a few helpful aliases for various refined lists that will then make the subsequent specifications pithy and crisp.

- A list with elements S

```
{-@ type ListS a S = {v:[a] | elts v = S} @-}
```

- An *empty* list

```
{-@ type ListEmp a = ListS a {Set_empty 0} @-}
```

- A list whose contents *equal* those of list X

```
{-@ type ListEq a X = ListS a {elts X} @-}
```

- A list whose contents are a *subset* of list X

```
{-@ type ListSub a X = {v:[a] | Set_sub (elts v) (elts X)} @-}
```

- A list whose contents are the union of lists X and Y

```
{-@ type ListUn a X Y = ListS a {Set_cup (elts X) (elts Y)} @-}
```

- A list whose contents are exactly X and the contents of Y

```
{-@ type ListUn1 a X Y = ListS a {Set_cup (Set_sng X) (elts Y)} @-}
```

THE MEASURES STRENGTHENS the data constructors for lists. That is we get the automatically refined types for “nil” and “cons”:

```
data [a] where
  [] :: ListEmp a
  (:) :: x:a -> xs:[a] -> ListUn1 a x xs
```

Lets take our new vocabulary out for a spin!

THE APPEND function returns a list whose elements are the *union* of the elements of the input Lists:

```
{-@ append'      :: xs:_ -> ys:_ -> ListUn a xs ys @-}
append' []      ys = ys
append' (x:xs) ys = x : append' xs ys
```

Exercise 9.3 (Reverse). Write down a type for `revHelper` so that `reverse'` is verified by *LiquidHaskell*.

```
{-@ reverse' :: xs:[a] -> ListEq a xs @-}
reverse' xs = revHelper [] xs

revHelper acc []      = acc
revHelper acc (x:xs) = revHelper (x:acc) xs
```

Exercise 9.4 (Halve). ★ Write down a specification for `halve` such that the subsequent “theorem” `prop_halve_append` is proved by *LiquidHaskell*.

```
halve      :: Int -> [a] -> ([a], [a])
halve 0 xs  = ([], xs)
halve n (x:y:zs) = (x:xs, y:ys) where (xs, ys) = halve (n-1) zs
halve _ xs   = ([], xs)

{-@ prop_halve_append :: _ -> _ -> True @-}
prop_halve_append n xs = elts xs == elts xs'
  where
    xs'      = append' ys zs
    (ys, zs) = halve n xs
```

Hint: You may want to remind yourself about the *dimension-aware* signature for `partition` from [the earlier chapter](#).

Exercise 9.5 (Membership). Write down a signature for `elem` that suffices to verify `test1` and `test2`.

```
{-@ elem      :: (Eq a) => a -> [a] -> Bool @-}
elem _ []     = False
elem x (y:ys) = x == y || elem x ys

{-@ test1 :: True @-}
test1      = elem 2 [1, 2, 3]

{-@ test2 :: False @-}
test2      = elem 2 [1, 3]
```


Permutations

Next, let's use the refined list API to prove that various sorting routines return *permutations* of their inputs, that is, return output lists whose elements are the *same as* those of the input lists.⁴

INSERTION SORT is the simplest of all the list sorting routines; we build up an (ordered) output list inserting each element of the input list into the appropriate position of the output:

```
insert x []      = [x]
insert x (y:ys)
  | x <= y      = x : y : ys
  | otherwise   = y : insert x ys
```

Thus, the output of `insert` has all the elements of the input `xs`, plus the new element `x`:

```
{-@ insert :: x:a -> xs:[a] -> ListUn1 a x xs @-}
```

The above signature lets us prove that the output of the sorting routine indeed has the elements of the input:

```
{-@ insertSort :: (Ord a) => xs:[a] -> ListEq a xs @-}
insertSort []      = []
insertSort (x:xs) = insert x (insertSort xs)
```

Exercise 9.6 (Merge). Fix the specification of `merge` so that the subsequent property `prop_merge_app` is verified by *LiquidHaskell*.

```
{-@ merge :: xs:[a] -> ys:[a] -> [a] @-}
merge [] ys      = ys
merge xs []      = xs
merge (x:xs) (y:ys)
  | x <= y        = x : merge xs (y:ys)
  | otherwise     = y : merge (x:xs) ys

{-@ prop_merge_app :: _ -> _ -> True @-}
prop_merge_app xs ys = elts zs == elts zs'
  where
    zs      = append' xs ys
    zs'     = merge xs ys
```

⁴ Since we are focusing on the elements, let's not distract ourselves with the **ordering invariant** and reuse plain old lists. See [this](#) for how to specify and verify order with plain old lists.

Exercise 9.7 (Merge Sort). ★★ *Once you write the correct type for merge above, you should be able to prove the unexpected signature for mergeSort below.*

1. *Make sure you are able verify the given signature.*
2. *Obviously we don't want mergeSort to return the empty list, so there's a bug. Find and fix it, so that you cannot prove that the output is empty, but can instead prove that the output is `ListEq a xs`.*

```
{-@ mergeSort :: (Ord a) => xs:[a] -> ListEmp a @-}
mergeSort [] = []
mergeSort xs = merge (mergeSort ys) (mergeSort zs)
  where
    (ys, zs) = halve mid xs
    mid      = length xs `div` 2
```

Uniqueness

Often, we want to enforce the invariant that a particular collection contains *no duplicates*; as multiple copies in a collection of file handles or system resources can create unpleasant leaks. For example, the `xmonad` window manager creates a sophisticated *zipper* data structure to hold the list of active user windows and carefully maintains the invariant that that the zipper contains no duplicates. Next, let's see how to specify and verify this invariant using LiquidHaskell, first for lists, and then for a simplified zipper.

TO SPECIFY UNIQUENESS we need a way of saying that a list has *no duplicates*. There are many ways to do so; the simplest is a *measure*:

```
{-@ measure unique @-}
unique      :: (Ord a) => [a] -> Bool
unique []   = True
unique (x:xs) = unique xs && not (member x (elts xs))
```

We can use the above to write an alias for duplicate-free lists

```
{-@ type UList a = {v:[a] | unique v }@-}
```

Lets quickly check that the right lists are indeed unique

```

{-@ isUnique    :: UList Int @-}
isUnique = [1, 2, 3]      -- accepted by LH

{-@ isNotUnique :: UList Int @-}
isNotUnique = [1, 2, 3, 1] -- rejected by LH

```

THE `FILTER` function returns a *subset* of its elements, and hence, *preserves* uniqueness. That is, if the input is unique, the output is too:

```

{-@ filter      :: (a -> Bool)
    -> xs:UList a
    -> {v:ListSub a xs | unique v}

    @-}
filter _ []     = []
filter f (x:xs)
  | f x         = x : xs'
  | otherwise   = xs'
where
  xs'           = filter f xs

```

Exercise 9.8 (Filter). *It seems a bit draconian to require that `filter` only be called with unique lists. Write down a more permissive type for `filter'` below such that the subsequent uses are verified by LiquidHaskell.*

```

filter' _ []     = []
filter' f (x:xs)
  | f x         = x : xs'
  | otherwise   = xs'
where
  xs'           = filter' f xs

{-@ test3 :: UList _ @-}
test3      = filter' (> 2) [1,2,3,4]

{-@ test4 :: [_] @-}
test4      = filter' (> 3) [3,1,2,3]

```

Exercise 9.9 (Reverse). ★ *When we reverse their order, the set of elements is unchanged, and hence unique (if the input was unique). Why does LiquidHaskell reject the below? Can you fix things so that we can prove that the output is a `UList a`? (When you are done, you should be able to remove the assume from the signature below, and still have LH verify the code.)*

```

{-@ assume reverse    :: xs:UList a -> UList a    @-}
reverse :: [a] -> [a]
reverse      = go []
  where
    {-@ go      :: acc:[a] -> xs:[a] -> [a] @-}
    go acc []   = acc
    go acc (x:xs) = go (x:acc) xs

```

THE NUB function constructs a unique list from an arbitrary input by traversing the input and tossing out elements that are already seen:

```

{-@ nub          :: [a] -> UList a @-}
nub xs          = go [] xs
  where
    {-@ go :: UList a -> xs:[a] -> UList a / [len xs] @-}
    go seen []      = seen
    go seen (x:xs)
      | x `isin` seen = go seen      xs
      | otherwise    = go (x:seen) xs

```

The key membership test is done by `isin`, whose output is `True` exactly when the element is in the given list.⁵

⁵ Which should be clear by now, if you did a certain exercise above

```

-- FIXME
{-@ predicate In X Xs = Set_mem X (elts Xs) @-}

{-@ isin :: x:_ -> ys:_ -> {v:Bool | v <=> In x ys } @-}
isin x (y:ys)
  | x == y    = True
  | otherwise = x `isin` ys
isin _ []    = False

```

Exercise 9.10 (Append). ★ *Why does appending two ULists not return a UList? Fix the type signature below so that you can prove that the output is indeed unique.*

```

{-@ append      :: UList a -> UList a -> UList a @-}
append []      ys = ys
append (x:xs) ys = x : append xs ys

```

Exercise 9.11 (Range). ★★ *range i j returns the list of Int between i and j. LiquidHaskell refuses to acknowledge that the output is indeed a UList. Fix the code so that LiquidHaskell verifies that it implements the given signature (and of course, computes the same result.)*

```

{-@ type Btwn I J = {v:_ | I <= v && v < J} @-}

{-@ range      :: i:Int -> j:Int -> UList (Btwn i j) @-}
range i j
  | i < j      = i : range (i + 1) j
  | otherwise = []

```

Hint: This may be easier to do *after* you read this chapter [about lemmas](#).

Unique Zippers

A [zipper](#) is an aggregate data structure that is used to arbitrarily traverse the structure and update its contents. For example, a zipper for a list is a data type that contains an element (called focus) that we are currently focus-ed on, a list of elements to the left of (i.e. before) the focus, and a list of elements to the right (i.e. after) the focus.

```

data Zipper a = Zipper {
  focus  :: a
, left   :: [a]
, right  :: [a]
}

```

xMONAD is a wonderful tiling window manager, that uses a [zipper](#) to store the set of windows being managed. xmonad requires the crucial invariant that the values in the zipper be unique, that is, be free of duplicates.

WE REFINE ZIPPER to capture the requirement that legal zippers are unique. To this end, we state that the left and right lists are unique, disjoint, and do not contain focus.

```

{-@ data Zipper a = Zipper {
  focus :: a
, left  :: {v: UList a | not (In focus v)}
, right :: {v: UList a | not (In focus v) && Disj v left }
} @-}

{-@ predicate Disj X Y = Disjoint (elts X) (elts Y) @-}

```

OUR REFINED ZIPPER CONSTRUCTOR makes *illegal states unrepresentable*. That is, by construction, we will ensure that every Zipper is free of duplicates. For example, it is straightforward to create a valid Zipper from a unique list:

```
{-@ differentiate    :: UList a -> Maybe (Zipper a) @-}
differentiate []    = Nothing
differentiate (x:xs) = Just $ Zipper x [] xs
```

Exercise 9.12 (Deconstructing Zippers). *★ Dually, the elements of a unique zipper tumble out into a unique list. Strengthen the types of reverse and append above so that LiquidHaskell accepts the below signatures for integrate:*

```
{-@ integrate      :: Zipper a -> UList a @-}
integrate (Zipper x l r) = reverse l `append` (x : r)
```

WE CAN SHIFT THE FOCUS element to the left or right while preserving the uniqueness invariant. Here's the code that shifts the focus to the left:

```
focusLeft          :: Zipper a -> Zipper a
focusLeft (Zipper t (l:ls) rs) = Zipper l ls (t:rs)
focusLeft (Zipper t [] rs)     = Zipper x xs []
  where
    (x:xs)                = reverse (t:rs)
```

To shift to the right, we simply *reverse* the elements and shift to the left:

```
focusRight  :: Zipper a -> Zipper a
focusRight  = reverseZipper . focusLeft . reverseZipper

reverseZipper :: Zipper a -> Zipper a
reverseZipper (Zipper t ls rs) = Zipper t rs ls
```

TO FILTER elements from a zipper, we need to take care when the focus itself, or all the elements get eliminated. In the latter case, there is no Zipper and so the operation returns a Maybe:

```
filterZipper :: (a -> Bool) -> Zipper a -> Maybe (Zipper a)
filterZipper p (Zipper f ls rs)
  = case filter p (f:rs) of
```

```

f':rs' -> Just $ Zipper f' (filter p ls) rs'
[]      -> case filter p ls of
          f':ls' -> Just $ Zipper f' ls' []
          []      -> Nothing

```

Thus, by using LiquidHaskell’s refinement types, and the SMT solvers native reasoning about sets, we can ensure the key uniqueness invariant holds in the presence of various tricky operations that are performed over Zippers.

Recap

In this chapter, we saw how SMT solvers can let us reason precisely about the actual *contents* of data structures, via the theory of sets. In particular, we saw how to:

- *Lift set-theoretic primitives* to refined Haskell functions from the `Data.Set` library,
- *Define measures* like `elts` that characterize the set of elements of structures, and `unique` that describe high-level application specific properties about those sets,
- *Specify and verify* that implementations enjoy various functional correctness properties, e.g. that sorting routines return permutations of their inputs, and various zipper operators preserve uniqueness.

Next, we present a variety of longer *case-studies* that illustrate the techniques developed so far on particular application domains.

Case Study: Okasaki's Lazy Queues

Lets start with a case study that is simple enough to explain without pages of code, yet complex enough to show off whats cool about dependency: Chris Okasaki's beautiful [Lazy Queues](#). This structure leans heavily on an invariant to provide fast *insertion* and *deletion*. Let's see how to enforce that invariant with LiquidHaskell.

Queues

A [queue](#) is a structure into which we can insert and remove data such that the order in which the data is removed is the same as the order in which it was inserted.

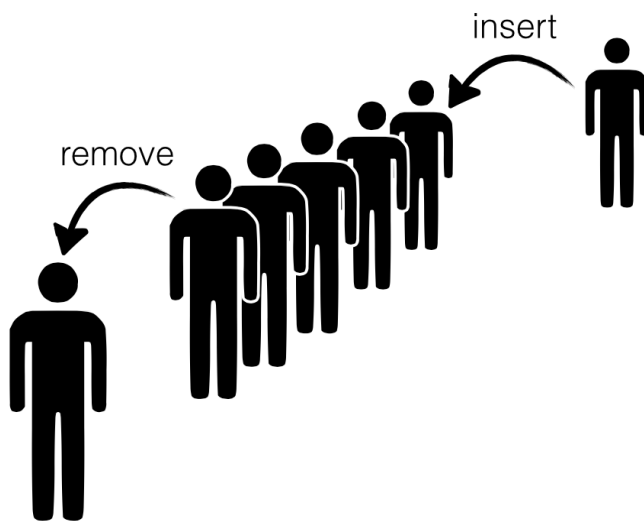


Figure 10.1: A Queue is a structure into which we can insert and remove elements. The order in which the elements are removed is the same as the order in which they were inserted.

TO EFFICIENTLY IMPLEMENT a queue we need to have rapid access to both the front as well as the back because we remove elements from

former and insert elements into the latter. This is quite straightforward with explicit pointers and mutation – one uses an old school linked list and maintains pointers to the head and the tail. But can we implement the structure efficiently without having stoop so low?

CHRIS OKASAKI came up with a very cunning way to implement queues using a *pair* of lists – let's call them front and back which represent the corresponding parts of the Queue.

- To insert elements, we just *cons* them onto the back list,
- To remove elements, we just *un-cons* them from the front list.

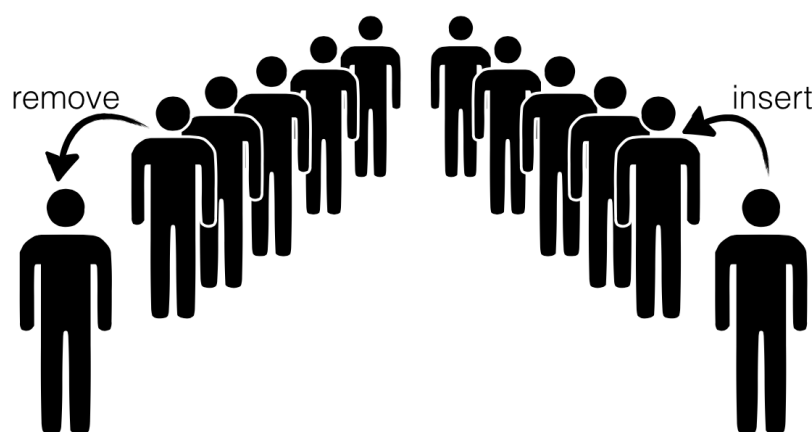


Figure 10.2: We can implement a Queue with a pair of lists; respectively representing the front and back.

THE CATCH is that we need to shunt elements from the back to the front every so often, e.g. we can transfer the elements from the back to the front, when:

1. a remove call is triggered, and
2. the front list is empty.

OKASAKI'S FIRST INSIGHT was to note that every element is only moved *once* from the back to the front; hence, the time for insert and remove could be $O(1)$ when *amortized* over all the operations. This is perfect, *except* that some set of unlucky remove calls (which occur when the front is empty) are stuck paying the bill. They have a rather high latency up to $O(n)$ where n is the total number of operations.

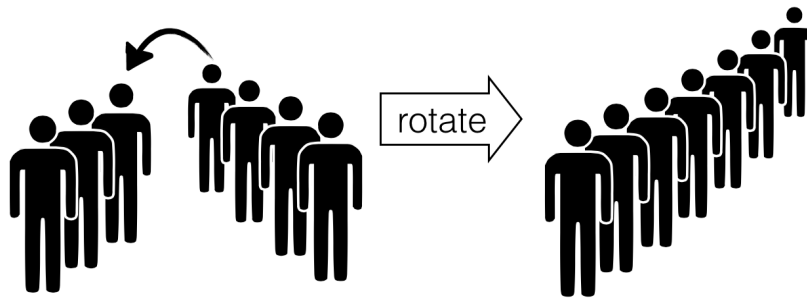


Figure 10.3: Transferring Elements from back to front.

OKASAKI'S SECOND INSIGHT saves the day: he observed that all we need to do is to enforce a simple *balance invariant*:

$$\text{Size of front} \geq \text{Size of back}$$

If the lists are lazy i.e. only constructed as the head value is demanded, then a single remove needs only a tiny $O(\log n)$ in the worst case, and so no single remove is stuck paying the bill.

LET'S IMPLEMENT QUEUES and ensure the crucial invariant(s) with LiquidHaskell. What we need are the following ingredients:

1. A type for Lists, and a way to track their size,
2. A type for Queues which encodes the balance invariant
3. A way to implement the insert, remove and transfer operations.

Sized Lists

The first part is super easy. Let's define a type:

```
data SList a = SL { size :: Int, elems :: [a] }
```

We have a special field that saves the size because otherwise, we have a linear time computation that wrecks Okasaki's careful analysis. (Actually, he presents a variant which does *not* require saving the size as well, but that's for another day.)

How can we be sure that size is indeed the *real size* of elems? Let's write a function to *measure* the real size:

```

{-@ measure realSize @-}
realSize      :: [a] -> Int
realSize []    = 0
realSize (_,xs) = 1 + realSize xs

```

Now, we can simply specify a *refined* type for `SList` that ensures that the *real* size is saved in the size field:

```

{-@ data SList a = SL {
    size  :: Nat
    , elems :: {v:[a] | realSize v = size}
  }
@-}

```

As a sanity check, consider this:

```

okList  = SL 1 ["cat"]    -- accepted
badList = SL 1 []         -- rejected

```

LET'S DEFINE AN ALIAS for lists of a given size `N`:

```

{-@ type SListN a N = {v:SList a | size v = N} @-}

```

Finally, we can define a basic API for `SList`.

To CONSTRUCT LISTS, we use `nil` and `cons`:

```

{-@ nil :: SListN a 0 @-}
nil = SL 0 []

{-@ cons :: a -> xs:SList a -> SListN a {size xs + 1} @-}
cons x (SL n xs) = SL (n+1) (x:xs)

```

Exercise 10.1 (Destructing Lists). *We can destruct lists by writing a `hd` and `tl` function as shown below. Fix the specification or implementation such that the definitions typecheck.*

```

{-@ tl      :: xs:SList a -> SListN a {size xs - 1} @-}
tl (SL n (_,xs)) = SL (n-1) xs
tl _              = die "empty SList"

{-@ hd      :: xs:SList a -> a @-}

```

```
hd (SL _ (x:_)) = x
hd _           = die "empty SList"
```

Hint: When you are done, okHd should be verified, but badHd should be rejected.

```
{-@ okList :: SListN String 1 @-}

okHd = hd okList      -- accepted

badHd = hd (tl okList) -- rejected
```

Queue Type

It is quite straightforward to define the Queue type, as a pair of lists, front and back, such that the latter is always smaller than the former:

```
{-@ data Queue a = Q {
    front :: SList a
  , back  :: SListLE a (size front)
}
@-}

data Queue a = Q
  { front :: SList a
  , back  :: SList a
  }
```

THE ALIAS `SListLE a L` corresponds to lists with at most `N` elements:

```
{-@ type SListLE a N = {v:SList a | size v <= N} @-}
```

As a quick check, notice that we *cannot represent illegal Queues*:

```
okQ = Q okList nil  -- accepted, |front| > |back|

badQ = Q nil okList -- rejected, |front| < |back|
```