# AULAS PRÁTICAS

### lacture 1

### EXPRICIO 1

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad Similar$$

$$z = \begin{pmatrix} 0 & -1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$H = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$H(0) = \frac{1}{\sqrt{2}} \left( \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} \right) \left( \frac{1}{\sqrt{2}} \right)$$

$$=\frac{1}{\sqrt{2}}\left(\begin{array}{c} 1\\ 1\\ 1\end{array}\right)$$

$$= \left( \frac{1}{2} \right)^2$$

$$=\frac{1}{\sqrt{2}}\left(\begin{array}{c}1\\0\end{array}\right)+\frac{1}{\sqrt{2}}\left(\begin{array}{c}0\\1\end{array}\right)$$

Bimilar para HIN> > EStado 1->

$$H\left(\frac{\sqrt{2}}{\sqrt{2}}\left(1\sqrt{2}-10>\right)\right)=(ACOPOR)$$

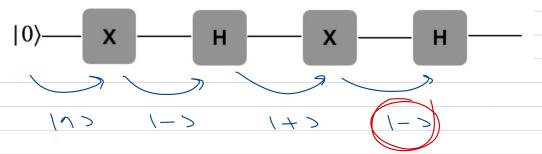
#### Exercício z

$$=\frac{1}{12}\left(\begin{array}{ccc} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{array}\right) \cdot \frac{1}{12}\left(\begin{array}{ccc} 1 & 1 & 1 \\ 1 & 1 & 1 \end{array}\right)$$

$$=\frac{1}{2}\left(\begin{array}{cc}2&0\\0&2\end{array}\right)$$

$$= \begin{pmatrix} 0 & 0 \end{pmatrix} \rightarrow 0$$
 Obtenos o estado I

## Exercico 3



#### CNOT

# Exercicio 9

# Gate Ry

$$\begin{pmatrix} SEV(\frac{2}{6}) & -2EV(\frac{2}{6}) \end{pmatrix} \begin{pmatrix} O \end{pmatrix} = \begin{pmatrix} SEV(\frac{2}{6}) \end{pmatrix}$$

$$= \begin{pmatrix} \cos\left(\frac{\theta}{2}\right) \\ -\cos\left(\frac{\theta}{2}\right) & + & \cos\left(\frac{\theta}{2}\right) & + & \cos\left(\frac{\theta}{2}$$

Mais - exes

# Exercicio 10

$$\frac{105}{105} + \frac{105}{105}$$

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# Algoritmo de Grover

$$\frac{\sqrt{2a'}}{1+1} = \frac{1}{\sqrt{2a'}} = \frac{$$

$$|\psi\rangle = \cos\theta |\varpi\rangle + \sin\theta |\omega\rangle$$

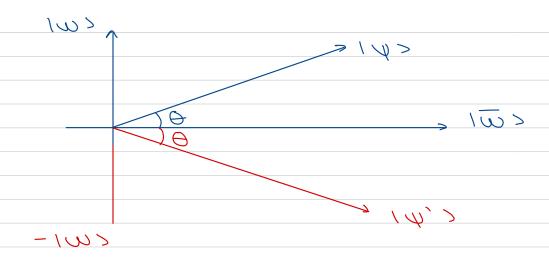
$$|\omega\rangle$$

$$5 \times 7 (102 + 125) = 3 (102 - 125)$$

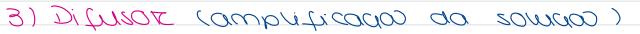
 $\frac{\sqrt{2}}{\sqrt{2}}$  [1000...0> + 1000...1> + ... + 1111...1>]

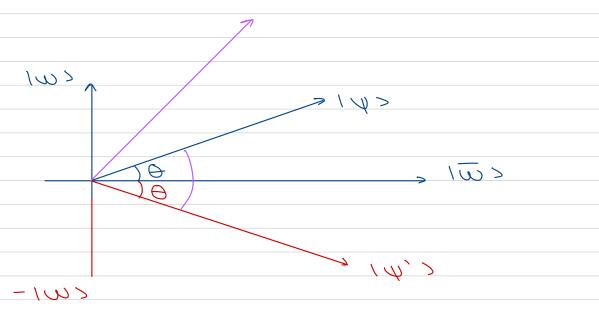
$$|\psi\rangle |-\rangle = |\psi\rangle |\nabla |(0\rangle - (1\rangle)$$

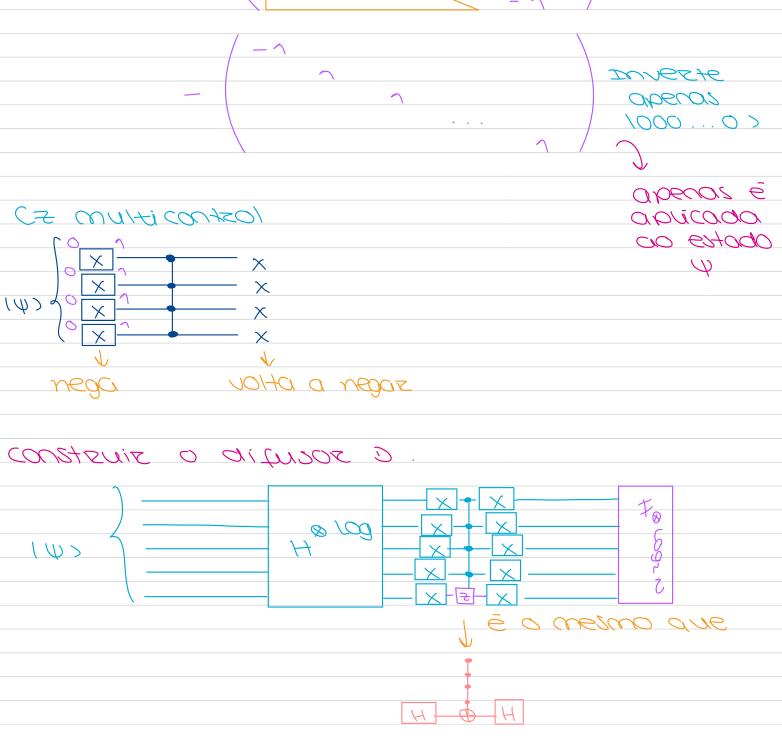
#### Dracle é uma multicontrol civot



(acabare)







MOTRIZ

= H@rads v (S 10><01 - II) H@rads v = S H@rads v 10><01 + @rads v - II

D= 2 10 x 0 1 - I

