

Aula 10: Hennessy-Milner Logic with recursion (cont.)

Interaction & Concurrency Course Unit: Reactive Systems Module

May 12, 2023

Recommended reading

Chapter 6 Aceto et al. 2007.

Concepts introduced and discussed:

- mutually recursive processes,
- image finite LTS,
- bisimulation equivalence class,
- largest fixed points and invariant properties,
- characteristic formula for a process.

Some relevant definitions, examples, theorems (from Aceto et al. 2007):

- Definition 5.3 - (Image finite processes),
- Theorem 5.1 (Hennessy-Milner theorem),
- Theorem 6.2 (Invariants as largest fixed points),
- mutually recursive equational system (pp. 135),
- semantics of an equational system over a set of variables, interpreted over n-dimensional vectors of sets of processes (pp. 136, 137),
- Example 6.9,
- Example 6.10,
- Theorem 6.4 (characteristic property for a process).

Exercises suggested (from Aceto et al. 2007):

- Exercise 6.8.3,

- Exercise 6.9,

- ~~• Exercise 6.12,~~

- ~~• Exercise 6.13.~~

pg 139

References

Aceto, Luca et al. (2007). *Reactive Systems - Modelling, Specification and Verification*. Cambridge University Press.

3. Compute the least and largest solutions of the system of equations

$$\begin{aligned} X &= [a]Y \\ Y &= \langle a \rangle X \end{aligned}$$

over the transition system associated with the CCS term

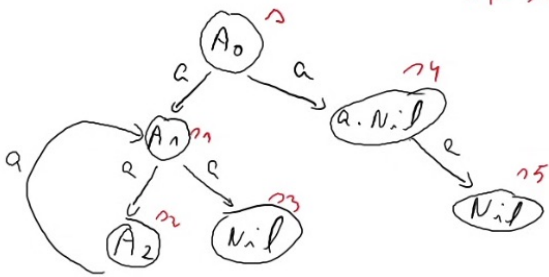
$$A_0 = a.A_1 + a.a.0$$

$$A_1 = a.A_2 + a.0$$

$$A_2 = a.A_1$$

CCS

$$\begin{aligned} A_0 &= a.A_1 + a.a.Nil \\ A_1 &= a.A_2 + a.Nil \\ A_2 &= a.A_1 \end{aligned}$$



$\neq X$

maior
ponto fixo

$$\begin{aligned} X &= [a]Y \\ Y &= \langle a \rangle X \end{aligned}$$

$$Proc = \{ \tau, \tau_1, \tau_2, \tau_3, \tau_4, \tau_5 \}$$

$$[X] = Proc$$

$$\langle Y \rangle = Proc$$

$$\begin{aligned} ([X], \langle Y \rangle) &= ([X], [X]) \\ (Proc, Proc) &= ([X], [X]) \end{aligned}$$

$$= (\{ \tau, \tau_1, \tau_2, \tau_3, \tau_4, \tau_5 \}, \{ \tau, \tau_1, \tau_2, \tau_3, \tau_4, \tau_5 \})$$

$$\begin{aligned} (Proc, \{ \tau, \tau_1, \tau_2, \tau_3, \tau_4 \}) &= ([X], \{ \tau, \tau_1, \tau_2, \tau_3, \tau_4 \}) \\ &= \{ \tau, \tau_2, \tau_3, \tau_5 \}, \{ \tau, \tau_1, \tau_2, \tau_3, \tau_4 \} \end{aligned}$$

→ fazer o mesmo para o menor ponto fixo.