

YUAN MENG

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EDUCATION

University of Southern California

Ph.D. Candidate, Computer Engineering

Ming Hsieh Department of Electrical and Computer Engineering

August 2019 - May 2024 (expected)

Advisor: Viktor Prasanna

Rensselaer Polytechnic Institute

B.S., Dual Major: Electrical Engineering & Computer and Systems Engineering

Department of Electrical, Computer, and Systems Engineering

September 2015 - May 2019

Overall GPA: 3.8/4.0

RESEARCH INTERESTS

- Algorithm hardware co-optimizations for deep learning
- Parallel and distributed reinforcement learning
- Dynamic systems using heterogeneous platforms (CPU, GPU, and FPGA)

RESEARCH EXPERIENCE

Acceleration and Design Automation of Deep Learning

Graduate Research Assistant

Ongoing

@FPGA/Parallel Computing Lab, USC

- Designed a unified hardware overlay supporting dynamic mapping of different convolution algorithms across CNN layers for low-latency inference. (FPGA '21, IC3 '22)
- Proposed a polynomial-time PBQP optimal solution to the algorithm mapping problem on series-parallel CNN graphs. (FPGA '21)
- Proposed a compute-saving kn2row-based algorithm hardware co-design methodology that reduced zero-computation by more than 90% for fractionally-strided convolution in upsampling and generative CNNs. (HiPC '21)

High-Performance Reinforcement Learning (RL)

Graduate Research Assistant

Ongoing

@FPGA/Parallel Computing Lab, USC

- Proposed the first CPU-FPGA system design for dynamic Monte-Carlo Tree Search applications, and achieved 3× higher throughput than state-of-the-art CPU-only implementations. (FPL '22, FPGA '23)
- Proposed a novel mapping framework for Deep RL on CPU-GPU-FPGA heterogeneous platforms with on-chip Replay Management to alleviate memory bottleneck, and achieved up to 4 times higher throughput than existing CPU-GPU frameworks. (CF '22, TPDS)
- Implemented a pipelined architecture on FPGA for Table-based Q learning that improves resource efficiency by 12× ~ 90× compared to state-of-the-art hardware designs (IPDPSW '20)
- Designed and developed a systolic-array-based architecture to accelerate Proximal Policy Optimization on CPU-FPGA heterogeneous platforms. (FCCM '20, TPDS)

Mesh Adaptation using FPGAs

Undergraduate Research Assistant

Fall 2018

@Scientific Computation Research Center, RPI

- Implemented and optimized a parameterized 2-D mesh adaptation accelerator on FPGAs with High Level Synthesis, evaluated algorithm efficiency and optimization methods.
- Developed and explored parameterized OpenCL kernels implementing tensor operations, including array reductions and sliding average on cloud FPGA nodes.

PUBLICATIONS

Journal Papers:

Chi Zhang, **Yuan Meng** and Viktor Prasanna “A Framework for Mapping DRL Algorithms with Prioritized Replay Buffer onto Heterogeneous Platforms.” IEEE Transactions on Parallel and Distributed Systems (TPDS)

Yuan Meng, Sanmukh Kuppannagari, Rajgopal Kannan and Viktor Prasanna “PPOAccel: A High-Throughput Acceleration Framework for Proximal Policy Optimization.” IEEE Transactions on Parallel and Distributed Systems (TPDS)

Selected Conference Papers:

Yuan Meng, Rajgopal Kannan and Viktor Prasanna “A Framework for Monte-Carlo Tree Search on CPU-FPGA Heterogeneous Platform via Dynamic Tree Management.” The 2023 ACM/SIGDA International Symposium on Field-Programmable Gate Arrays (FPGA 2023)

Yuan Meng, Hongjiang Men and Viktor Prasanna “Accelerator Design and Exploration for Deformable Convolution Networks.” The 36th IEEE Workshop on Signal Processing Systems (SiPS 2022)

Yuan Meng, Rajgopal Kannan and Viktor Prasanna “Accelerating Monte-Carlo Tree Search on CPU-FPGA Heterogeneous Platform.” The 22nd International Conference on Field Programmable Logic & Applications (FPL 2022)

Yuan Meng, Chi Zhang, and Viktor Prasanna, “FPGA acceleration of deep reinforcement learning using on-chip replay management.” Proceedings of the 19th ACM International Conference on Computing Frontiers (CF 2022). **(Best Paper Award)**

Yuan Meng, Sanmukh Kuppannagari, Rajgopal Kannan and Viktor Prasanna “How to Avoid Zero-Spacing in Fractionally-Strided Convolution? A Hardware-Algorithm Co-Design Methodology.” High Performance Computing, Data, and Analytics (HiPC 2021).

Yuan Meng, Sanmukh Kuppannagari, Rajgopal Kannan and Viktor Prasanna, “DYNAMAP: Dynamic Algorithm Mapping Framework for Low Latency CNN Inference.” The 2021 ACM/SIGDA International Symposium on Field-Programmable Gate Arrays (FPGA 2021).

Yuan Meng, Sanmukh Kuppannagari, Rajgopal Kannan and Viktor Prasanna, “How to Efficiently Train Your AI Agent? Characterizing and Evaluating Deep Reinforcement Learning on Heterogeneous Platforms.” 24th IEEE High Performance Extreme Computing Conference (HPEC 2020). **(Outstanding Student Paper Award)**

Yuan Meng, Sanmukh Kuppannagari, and Viktor Prasanna. “Accelerating Proximal Policy Optimization on CPU-FPGA Heterogeneous Platforms.” 28th IEEE International Symposium on Field-Programmable Custom Computing Machines (FCCM 2020).

Yuan Meng, Sanmukh Kuppannagari, Rachit Rajat, Ajitesh Srivastava, Rajgopal Kannan, Viktor Prasanna “QTAcel: A Generic FPGA based Design for Q-Table based Reinforcement Learning Accelerators.” 2020 IEEE International Parallel and Distributed Processing Symposium Workshops (IPDPSW 2020).

AWARDS & HONOURS

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| - Finalist, Ming Hsieh Institute Scholarship <i>University of Southern California</i> | 2022-2023 |
| - Best Paper Award <i>ACM International Conference on Computing Frontiers</i> | 2022 |
| - Outstanding Student Paper Award <i>IEEE High Performance Extreme Computing Conference</i> | 2020 |

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| - Annenberg Fellowship <i>University of Southern California</i> | 2019-2020 |
| - Dean's Honor List <i>Rensselaer Polytechnic Institute</i> | 2015-2019 |

WORK EXPERIENCE

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|---|---------------------------|
| Graduate Teaching Assistant <i>University of Southern California</i> | Fall 2020 - Spring 2021 |
| <ul style="list-style-type: none"> Parallel and Distributed Computing Accelerated Computing using FPGAs Parallel Programming | |
| Electronics Engineer Co-op <i>Hasbro, Inc.</i> | January 2018 - June 2018 |
| <ul style="list-style-type: none"> Prototyping for Animatronics and games Research on embedded voice recognition and computer vision applications in toys | |
| Undergraduate Teaching Assistant/Mentor <i>Rensselaer Polytechnic Institute</i> | Spring 2017 - Spring 2019 |
| <ul style="list-style-type: none"> Embedded Control Foundation of Computer Science | |

TECHNICAL STRENGTHS

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| Programming Languages | Python, C/C++, PostgreSQL Scripting |
| Parallel Programming | CUDA, OpenMP, MPI, SYCL-OneAPI |
| Hardware Design | VIVADO & VITIS HLS, OpenCL, Verilog |
| Embedded Prototyping | Arduino, stm32 microprocessors, Raspberry Pi |
| Other Software & Tools | OpenAI Gym, PyTorch, PyOpenCL, CAD (NX, AutoCAD), SPICE |

MENTORING

- Tiffany Liu - Parallel algorithm and implementation of multi-agent Q learning (QRTS)
- Peter Wang, Tianxin Zhu (Undergraduate Student) - Multi-Core acceleration of AlphaZero using adaptive parallelism [Submitting to IA3, SC 2023]
- Samuel Wiggins (PhD Student) - Acceleration of communication in multi-agent reinforcement learning [Accepted to DATA 2023]
- Haomei Liu (Undergraduate Student) - End to End Framework for CNN Acceleration on FPGAs with Dynamic Algorithm Mapping [Accepted to IC3 2022]
- Hongjiang Men (Master Student) - Accelerator Design For Deformable Convolution Networks using high-bandwidth memory [Accepted to SiPS 2022]
- Nathaniel Peura (Master Student) - FGYM: Framework for benchmarking FPGA-accelerated Reinforcement Learning under VITIS software development flow [Accepted to FPL 2021 DEMO]
- Sarah Chow (Undergraduate Student) - HLS-accelerated Deep Neural Network Inference