

# Notes on The Nonexistence of Certain Statistical Procedures in Nonparametric problems

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## 1 Theorems

Let  $\mathcal{F}$  be a given set of distribution functions  $F, G, \dots$  of a real variable, it must satisfy that:

1. For every  $F \in \mathcal{F}$ ,  $\mu_F = \int_{-\infty}^{\infty} z dF$  exists and is finite.
2. For every real  $m$ , there is an  $F \in \mathcal{F}$  with  $\mu_F = m$ .
3.  $\mathcal{F}$  is **convex**, that is, if  $F, G \in \mathcal{F}$ ,  $\pi$  is a positive fraction, and  $H = \pi F(1 - \pi)G$  then  $H \in \mathcal{F}$ .

Let  $X_1, X_2, \dots \sim F$  denote an infinite sequence of independent RVs, i.e.  $\Pr(X_i \leq z) = F(z)$ . Suppose that a (randomized, sequential) sampling procedure is given, i.e. a set of rules for observing  $X_1, X_2, \dots$  one by one up to a certain stage  $N$  s.t. at each stage the decision whether to continue depends (randomly) on the observed values in hand at that stage. The given procedure is assumed to be closed:

$$P_F(N < \infty) = 1, \quad (1)$$

for each  $F \in \mathcal{F}$ .

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Denote the total outcome of the sampling procedure a random variable,  $V$ , i.e.  $V = (X_1, X_2, \dots, X_N)$ . As in (1), for any event  $A$  defined on the sample space of  $V$ ,  $P_F(A)$  will denote the probability of  $A$  when  $F$  obtains, i.e., when each  $X_i$  is distributed according to  $F$ .

If  $\varphi$  is a real valued function of  $V$ ,  $E_F[\varphi]$  denotes the expected value of  $\varphi$  (if it exists) when  $F$  obtains.

For any real number  $m$ , let  $\mathcal{F}_m$  denote the set of all  $F \in \mathcal{F}$  with  $\mu_F = m$ .

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### 1.1 Theorem I

For each bounded real valued function  $\varphi$  on the sample space of  $V$ ,  $\inf_{F \in \mathcal{F}_m} E_F[\varphi]$  and  $\sup_{F \in \mathcal{F}_m} E_F[\varphi]$  are independent of  $m$ .

In other words, even if  $\mu_F$  is known to equal one of two given values  $m_1$  and  $m_2$ , the sample  $V$  cannot provide effective discrimination between the two hypothetical values.

Let  $H$  be the hypothesis that  $\mu_F = 0$  (i.e.,  $F \in \mathcal{F}_0$ ); i.e. the **null hypothesis**. For any test  $t$ , let  $\beta_F(t)$  denote the probability of rejecting  $H$  in using  $t$  when  $F$  obtains, i.e.  $\beta_F(t)$  denotes the **power function** of  $t$  - the probability that the test correctly rejects the null hypothesis when the alternative hypothesis is true.

1.  $t$  is a **somewhere unbiased** level- $\alpha$  test if  $\beta_F \leq \alpha$  for  $F \in \mathcal{F}_0$  and, for some  $m \neq 0$ ,  $\beta_F \geq \alpha$  for  $F \in \mathcal{F}_m$
2.  $t$  is a **similar** level- $\alpha$  test if  $\beta_F = \alpha$  for each  $F \in \mathcal{F}_0$

Note: level- $\alpha$  test, refers to the probability of rejecting the null hypothesis when the null hypothesis is true, i.e. the false positive rate, a.k.a. type I error.

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Let  $\varphi(V)$  denote the probability prescribed by  $t$  of rejecting  $H$  (the null hypothesis) on observation of  $V$  yields the following corollary.

## 1.2 Corollary 1

If  $t$  is a somewhere unbiased level- $\alpha$  test of  $H$ , or a similar level- $\alpha$  test of  $H$ , then  $\beta_F(t) = \alpha$  for all  $F \in \mathcal{F}$ .

The corollary illustrates that all tests of the value of  $\mu$ , assuming that it exists, are unsuccessful.

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Let  $I$  denotes a confidence set for  $\mu_F$ , i.e.  $I$  is a (randomized) function of  $V$ .

For any real  $m$ , let  $C[m]$  denote the event that  $I$

## 1.3 Corollary II

If  $P_F(C[\mu_F]) \geq 1 - \alpha$  for all  $F \in \mathcal{F}$ , then  $P_F(C[m]) \geq 1 - \alpha$  for all  $m$  and all  $F \in \mathcal{F}$ .

*Proof.* For each  $m$ , let  $p_m(V) = P(C[m] | V) = P_F(C[m])$ ,  $0 \leq p \leq 1$ . Consider a fixed  $m$ , since  $\mu_F = m$ , for all  $F \in \mathcal{F}_m$ , we have that  $P_F(C[\mu_F]) = P_F(C[m]) = E_F[p_m] \geq 1 - \alpha$  for  $F \in \mathcal{F}_m$ . By Theorem I, for each bounded real valued function  $\varphi$  on the sample space of  $V$ ,  $\inf_{F \in \mathcal{F}_m} E_F[\varphi]$  and  $\sup_{F \in \mathcal{F}_m} E_F[\varphi]$  are independent of  $m$ . Hence,  $P_F(C[m]) = E_F[p_m] \geq 1 - \alpha$  for all  $F \in \mathcal{F}$ . Proof is complete for arbitrary  $m$ .  $\square$

## 1.4 Corollary III

Suppose that there exists at least one  $F \in \mathcal{F}$  such that  $P_F(I \text{ is a set bounded from below}) = 1$ . Then  $\inf_{p \in \mathcal{F}} \{P_F(C[\mu_F])\} = 0$ .

*Proof.* For each  $n = 1, 2, \dots$

Let  $B_n$  denote the event that  $I \in [-n, \infty)$  - i.e.,  $I$  is bounded from below;

Let  $q_n(V)$  denote the probability of  $B_n$  given  $V$ ;  $0 \leq q_n \leq q_{n+1} \leq 1$ .

Let  $\bar{B}_n$  denote the complement of  $B_n$ , i.e. the event that  $I \in (-\infty, -n]$ ;

Let  $1 - q_n(V)$  denote the probability of  $\bar{B}_n$  given  $V$ .

Let  $F$  be a distribution in  $\mathcal{F}$  s.t.  $I$  is bounded from below w.p. 1 when  $F$  obtains. By the Monotone Convergence Theorem, we can swap the expectation and the limit:  $E_F[\lim_n q_n] = \lim_n E_F[q_n] = \lim_n P_F(B_n) = P_F(I \text{ is bounded from below}) = 1 \implies \lim_n q_n(V) = 1$  except on a set of points  $V$  of  $P_F$ -measure zero.

For any  $m < -n$ ,  $p_m(V) = \Pr(m \in I | V) \leq \Pr(\bar{B}_n | V) = 1 - q_n(V)$ , thus, except on a  $P_F$ -null set,

$$\lim_{m \rightarrow -\infty} p_m(V) = 0. \quad (2)$$

Since  $P_F(C[m]) = E_F[p_m]$  for all  $m$ , it follows from (2), by Lebesgue's theorem for boundedly convergent sequences (Bounded Convergence Theorem - corollary of Dominated Convergence Theorem), that

$$\lim_{m \rightarrow -\infty} P_F(C[m]) = \lim_{m \rightarrow -\infty} E_F[p_m] = E_F \left[ \lim_{m \rightarrow -\infty} p_m \right] = 0. \quad (3)$$

By Corollary 2:  $\inf_{G \in \mathcal{F}} \{P_G(C[\mu_G])\} = \inf_{G \in \mathcal{F}} \inf_m \{P_G(C[m])\}$ . It follows from (3) that the common value of these infima is zero.  $\square$