

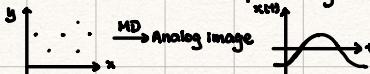
Signal: a function of an independent variable that typically carries some form of information.

continuous-time \int_{MD}^{1D}

discrete-time \sum_{MD}^{1D}

Continuous-time signal: a signal whose independent variable is a real number.

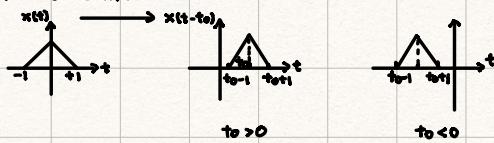
The independent variable \rightarrow Time, $t \xrightarrow{1D}$ speech signal, Air pressure at different altitudes for an airplane.



discrete-time signal: a signal whose independent variable is an integer.

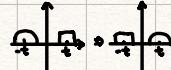
These transformations can be applied to the independent variable.

① Time Shift

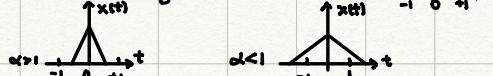


② Time reversal

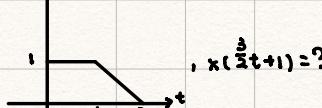
$x(-t)$ is the mirrored image of $x(t)$ with respect to the vertical axis



③ time scaling $x(t) \Rightarrow x(\alpha t)$ $\alpha > 0$



example: $x(t)$



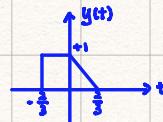
$$x\left(\frac{3}{2}t+1\right) = ?$$

④

$$x(t) = \begin{cases} 0 & t < 0 \\ 1 & 0 < t < 1 \\ -t & 1 < t < 2 \\ 0 & t > 2 \end{cases}$$

$$x\left(\frac{3}{2}t+1\right) = \begin{cases} 0 & \frac{3}{2}t+1 < 0 \\ 1 & 0 < \frac{3}{2}t+1 < 1 \\ -\frac{3}{2}t-1 & 1 < \frac{3}{2}t+1 < 2 \\ 0 & \frac{3}{2}t+1 > 2 \end{cases}$$

$$x\left(\frac{3}{2}t+1\right) = \begin{cases} 0 & t < -\frac{2}{3} \\ 1 & -\frac{2}{3} < t < 0 \\ -\frac{3}{2}t-1 & 0 < t < \frac{2}{3} \\ 0 & t > \frac{2}{3} \end{cases}$$



* verify by choosing random numbers

⑤

$$y(t) \Rightarrow x\left(\frac{3}{2}t\right) \Rightarrow x\left(\frac{3}{2}(t+\frac{2}{3})\right)$$



$$y(t) \Rightarrow x\left(\frac{3}{2}t+\frac{2}{3}\right) \Rightarrow x\left(\frac{3}{2}(t+\frac{2}{3})\right) \times$$



Example 2:

With the same figure, $y(t) = x\left(-\frac{3}{2}t+1\right) = ?$

Ans:

⑥

$$x\left(\frac{3}{2}t\right) \Rightarrow x\left(\frac{3}{2}t+1\right) = x\left(\frac{3}{2}(t-\frac{2}{3})\right) \Rightarrow x\left(-\frac{3}{2}t+1\right)$$



3

time-scaling \rightarrow time-shifting* \rightarrow time reversal

*: considering the effect of the scaling factor.

Periodicity: $x(t)$ is a periodic signal if for every t , there is a T that satisfies $x(t) = x(t+T)$. T is called the period.

The smallest positive T is the fundamental period T_0 .

$$\text{e.g.: } x(t) = A \sin(\omega t + \alpha) \quad \text{V} \quad y(t) = \begin{cases} 0 & t < 0 \\ (A \sin(\omega t + \alpha)) & t \geq 0 \end{cases} \quad \text{X}$$

e.g.: Find the fundamental period of $x(t) = A \sin(\omega t + \alpha)$

$$x(t) = x(t+T)$$

$$A \sin(\omega t + \alpha) = A \sin(\omega(t+T) + \alpha)$$

$$= A \sin(\omega t + \omega T + \alpha)$$

$$\Rightarrow \sin(\beta) = \sin(\beta + \omega T) = \sin(\beta + 2\pi k), k \in \mathbb{Z}$$

$$\omega T = 2\pi k \quad \Rightarrow \quad T = \frac{2\pi k}{\omega}, k \in \mathbb{Z}$$

$$\text{If } k=1, T_0 = \frac{2\pi}{\omega}$$

Remark: If $x(t)$ and $y(t)$ are periodic signals with fundamental periods T_x and T_y , respectively, then $x(t)+y(t)$ is a periodic

signal if $\frac{T_x}{T_y}$ is a rational number. And the fundamental period of $x(t)+y(t)$ is usually the least common multiplier

(LCM) of T_x and T_y . $\text{LCM}(T_x, T_y)$

e.g.: Are these signals periodic? If so, what's the period?

1. $x(t) = \cos(t) + \sin(\pi t)$

2. $y(t) = \cos(\frac{3\pi}{4}t + \frac{\pi}{6}) + \sin(\frac{2\pi}{3}t - \frac{\pi}{4})$

1. $x(t) = x_1(t) + x_2(t) \quad T_{x_1} = 2\pi \quad T_{x_2} = 2 \Rightarrow \text{no LCM} \Rightarrow x(t) \text{ is not periodic}$

2. $y(t) = y_1(t) + y_2(t) \quad T_{y_1} = \frac{8}{3} \quad T_{y_2} = 3 \Rightarrow \frac{T_{y_1}}{T_{y_2}} = \frac{8}{9} \Rightarrow \text{rational} \Rightarrow y(t) \text{ is periodic}, T_y = \text{LCM}(T_{y_1}, T_{y_2}) = 24$

Fundamental Frequency = 1 / fundamental period = $\frac{1}{T_0}$ [Hz]

Harmonic: If $x(t) = \sin(\omega t + \alpha)$ and $x_m(t) = \sin(m\omega t + \alpha), m \in \mathbb{Z}^+$, then the frequency of $x_m(t)$ is m times larger than

that of $x(t)$, and $x_m(t)$ is referred to as the m -th harmonic of $x(t)$.

Energy and Power

Energy of $x(t)$ between t_1 and t_2 is defined as $E_x = \int_{t_1}^{t_2} |x(t)|^2 dt$.

Power of $x(t)$ between t_1 and t_2 is defined as $P_x = \frac{1}{t_2 - t_1} \int_{t_1}^{t_2} |x(t)|^2 dt$

Total energy and power of a signal are obtained when $t_1 \rightarrow -\infty$ & $t_2 \rightarrow +\infty$:

$$E_{\text{tot}} = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt$$

$$P_{\text{tot}} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

Energy signal: $x(t)$ is an energy signal if E_{tot} for $x(t)$ is finite and non-zero. The total power of an energy signal is zero.

Power signal: $x(t)$ is a power signal if P_{tot} is finite and non-zero. E_{tot} of a power signal is not finite.

Remark: Periodic signals are power signals. The total power is equal to the power over period.

example: Find P_{tot} of $x(t) = A \sin(\omega_0 t + \phi)$ $\Rightarrow t_1=0, t_2=T = \frac{2\pi}{\omega_0}$

$$\begin{aligned} P_{tot} &= \frac{1}{T} \int_0^T A^2 \sin^2(\omega_0 t + \phi) dt \\ &= \frac{A^2}{T} \int_0^T \frac{1}{2} - \frac{1}{2} \cos(2\omega_0 t + 2\phi) dt \\ &= \frac{A^2}{2T} \left(t - \frac{1}{2\omega_0} \sin(2\omega_0 t + 2\phi) \right) \Big|_0^T \\ &= \frac{A^2}{2T} [T - \frac{1}{2\omega_0} \sin(4\pi + 2\phi) - 0 + \frac{1}{2\omega_0} \sin(0 + 2\phi)] \\ &= \frac{A^2}{2} \end{aligned}$$