

Observations on Transient Control & Pole Location

Additional Poles/Zeros

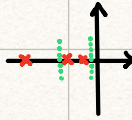
The analysis we had (Ts, Tr, %OS) is for a TF with $\begin{cases} 2 \text{ cplx. conj. poles} \\ \text{no zeros} \end{cases}$



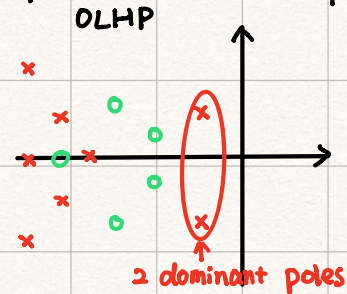
This remains approximately valid under the following assumptions:

- (1). Any additional poles are far to the left of the 2 "dominant" cplx. conj. poles (|real part| is at least 5 times larger)
- (2). The real part of all zeros is < 0 , and is much different than the real part of the 2 dominant poles.

Ex: $G(s) = \frac{(s+5)(s+3)}{(s+5)(s+3)(s+20)} \approx \frac{1}{(s+3)(s+20)} \approx \frac{1}{(s+3)}$

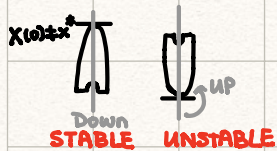


$$G(s) = \frac{(s+1)}{(s+5)(s+3)(s+20)} \approx \frac{1}{(s+5)(s+3)}$$



Stability — a Prelude

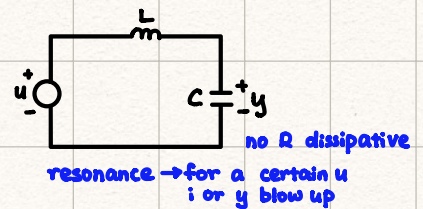
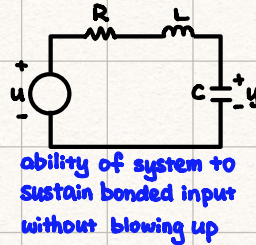
Ex 1: DOF link (internal stability)



state-space model

TF model

Ex 2: RLC & LC circuit (External BIBO stability O.I.C.)



perturbing I.C. & being able to recover

Defining stab. concepts, char. mathematically and giving tests to check them.

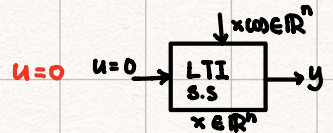
Internal Stability notion that applies to state-space models

Consider L.T.I system: $\begin{cases} \dot{x} = Ax + Bu & x \in \mathbb{R}^n, u \in \mathbb{R}^m \\ y = Cx + Du \end{cases}$ and we assume there is no input acting $u=0$

→ $x(t)$ solu. for $\forall x(0)$

Then $\dot{x} = Ax$, $x(0) \in \mathbb{R}^n$ and $y = Cx$

$$x(t) = \begin{bmatrix} x_1(t) \\ \vdots \\ x_i(t) \\ \vdots \\ x_n(t) \end{bmatrix} \in \mathbb{R}^n$$



Definition:

(a): Sys. is internally stable if:

$\forall x(0) \in \mathbb{R}^n$, state $x(t)$ is bounded for any $t \geq 0$ i.e. $\exists M > 0$, s.t. $|x_i(t)| \leq M \cdot \forall t \geq 0$ and $\forall i = \{1, \dots, n\}$

(b): Sys. is internally asymptotically stable if:

it is int. stable AND $\forall x(0) \in \mathbb{R}^n$, $x(t) \rightarrow \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = 0$ as $t \rightarrow \infty$

there exists

(c): Sys. is int. unstable if it is NOT int. stable, i.e. $\exists x(0) \in \mathbb{R}^n$, s.t. $x_i(t)$ becomes unbounded for some $i \in \{1, \dots, n\}$

$$x_i(t) \rightarrow \pm \infty$$

Want to get a test → A.