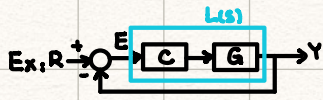
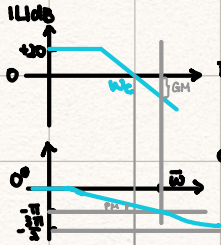


# Bode Plots and Performance Specs.

Steady-state  
Transient



Last ex:  $L(s) = \frac{10}{(s+1)(s+10)(s+100)}$



By Nyquist plot:  $\frac{1}{1+L(s)}$  in BiBo stable  $\Leftrightarrow$  all poles in OLHP

consider  $C(s)=1$   $G(s) = \frac{10}{(s+1)(s+10)(s+100)}$  Find  $e_{ss} = \lim_{t \rightarrow \infty} e(t)$  when  $r(t) = 1(t)$  and relate it the Bode plot.

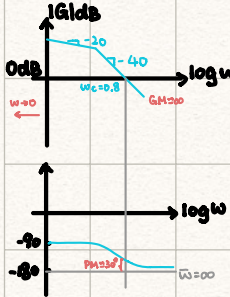
$$E(s) = \frac{1}{1+C(s)G(s)} \cdot R(s) = \frac{1}{1+L(s)} \cdot \frac{1}{s} \Rightarrow \text{poles in OLHP and 1 in } s=0$$

$$\Rightarrow \text{can apply FVT: } e_{ss} = \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s \cdot E(s) = \lim_{s \rightarrow 0} s \cdot \frac{1}{1+L(s)} \cdot \frac{1}{s} = \frac{1}{1+L(0)} \text{ D.C. gain} = \frac{1}{1+10} = \frac{1}{10} = 0.1 = 10\%$$

Bode plot:  $|L(\omega)|_{dB} = 20 \text{ dB} \Leftrightarrow |L(0)| = 10$

It's relation b/w steady-state err. of C.L. system to the DC gain of O.L system (Bode plot)

Ex 2:  $G(s) = \frac{0.8}{s(s+1/2)}$ ;  $C(s) = 1$ ;  $|G(0)| = \infty$



$|G(\omega)|_{dB} = \infty$   $e_{ss} = \frac{1}{|G(0)|} = 0$

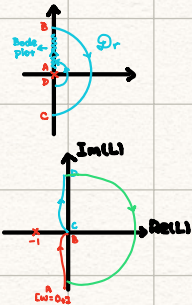
$R(s) = \frac{1}{s}$

transient specs.

Design  $C(s)$  s.t. when  $r(t) = 1(t)$   $e_{ss} = 0$  (asy. tracking of step) and a certain %OS &  $T_s$  are met in step response  $y(t)$

If only asy. track spec was imposed, we could use IMP to design  $C(s)$

$C(s) = 1$  satisfies the IMP as long as feedback loop is BiBo stable. We check that based on Nyquist plot.



$\Rightarrow n=0$  (#ORHP poles in  $C(s)$ )  $N=0$  (encircle of -1 critical pt.)

$(-0.5 + j0.5) \rightarrow (-0.5 - j0.5)$

at  $x$ :  $s = \epsilon e^{j\theta}$ ;  $\theta = \frac{\pi}{2} \rightarrow \frac{\pi}{2} + \frac{\pi}{2} \Rightarrow G(s) = \frac{0.8}{\epsilon e^{j\theta} \cdot \frac{1}{2}} = \frac{1.6}{\epsilon} e^{-j\theta} \rightarrow \text{semicircle w } \infty \text{ radius}$   
( $\theta$  goes from  $-\frac{\pi}{2}$  to  $\frac{\pi}{2}$  through 0)

$\Rightarrow N=0 \Rightarrow$  Feedback loop is BiBo stable



$e_{ss} = 0$   $e(t) = r(t) - y(t) \Rightarrow y(t) \rightarrow 1, t \rightarrow \infty$

2nd order syst. spec  $\left\{ \begin{array}{l} \%OS = e^{-\pi \zeta / \sqrt{1-\zeta^2}} \\ T_s \approx \frac{4}{\omega_n \zeta} \end{array} \right.$   $\frac{C(s)}{1+C(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$

As guideline:  $PM \propto \zeta$   $T_s \propto \frac{1}{\omega_c} \rightarrow \text{gain cross-over freq (where } |L|_{dB} = 0 \text{ dB)}$



$\Rightarrow$  instead of %OS,  $T_s$  specs we use  $\left\{ \begin{array}{l} \omega_c \\ PM \end{array} \right.$  as specs on top of s.s. specs. (DC gain  $L(0)$ )

where  $PM \approx 40 \sim 45\%$  desired  $\omega_c \stackrel{NEW}{=} 2 \Rightarrow T_s \downarrow \text{half (in ex 2)} \Rightarrow PM \stackrel{NEW}{=} 10^\circ$