

HTML HW4

$$1. w(t+1) \leftarrow w(t) - \eta \nabla (E_{in}(w(t)) + \frac{\lambda}{N} (w(t))^T \cdot w(t))$$

$$\Rightarrow w(t+1) \leftarrow w(t) - \eta \nabla E_{in}(w(t)) - \eta \frac{2\lambda}{N} w(t)$$

$$\Rightarrow w(t+1) \leftarrow \left(1 - \frac{2\eta\lambda}{N}\right) \cdot w(t) - \eta \nabla E_{in}(w(t)) \quad \#$$

$$2. \text{ To find } \min_{w \in \mathbb{R}} \frac{1}{N} \sum_{n=1}^N (w - y_n)^2 + \frac{\lambda}{N} w^2 \Rightarrow \text{find } w^* \text{ satisfy } \nabla_w \left(\frac{1}{N} \sum_{n=1}^N (w - y_n)^2 + \frac{\lambda}{N} w^2 \right) = 0$$

$$\nabla_w \left(\frac{1}{N} \sum_{n=1}^N (w - y_n)^2 + \frac{\lambda}{N} w^2 \right) = \frac{1}{N} \sum_{n=1}^N (2w - 2y_n) + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow \sum_{n=1}^N 2w + 2\lambda w = \sum_{n=1}^N 2y_n \Rightarrow w(N + \lambda) = \sum_{n=1}^N y_n \Rightarrow w^* = \frac{\sum_{n=1}^N y_n}{N + \lambda}$$

$$C = (w^*)^2 = \left[\frac{\sum_{n=1}^N y_n}{N + \lambda} \right]^2$$

$$3. w = V \cdot \tilde{w} \Rightarrow \tilde{w} = V^{-1} w$$

$$1\text{f } \lambda \min \frac{1}{N} \sum_{n=1}^N (\tilde{w}^T \phi(x_n) - y_n)^2 + \frac{\lambda}{N} (\tilde{w}^T \tilde{w})$$

$$= \min \frac{1}{N} \sum_{n=1}^N \left[(V^{-1} w)^T \cdot V \cdot x_n - y_n \right]^2 + \frac{\lambda}{N} (V^{-1} w)^T (V^{-1} w)$$

$$= \min \frac{1}{N} \sum_{n=1}^N \left[w^T (V^{-1})^T \cdot V \cdot x_n - y_n \right]^2 + \frac{\lambda}{N} w^T (V^{-1})^T V^{-1} w$$

$$= \min \frac{1}{N} \sum_{n=1}^N (w^T x_n - y_n)^2 + \frac{\lambda}{N} w^T (V^{-1})^2 \cdot w$$

$$\Rightarrow V = (V^{-1})^2 \quad \#$$

$$4. \min \mathbb{E} \left[\frac{1}{N} \sum_{n=1}^N (w^T \cdot (X_n + \epsilon) - y_n)^2 \right] = \min \mathbb{E} \left[\frac{1}{N} \sum_{n=1}^N (w^T x_n + w^T \epsilon - y_n)^2 \right]$$

$$= \min \mathbb{E} \left[\frac{1}{N} \sum_{n=1}^N \left[(w^T x_n - y_n)^2 + 2 \cdot (w^T x_n - y_n) \cdot w^T \epsilon + (w^T \epsilon)^2 \right] \right]$$

$$= \min \frac{1}{N} \sum_{n=1}^N (w^T x_n - y_n)^2 + \mathbb{E} \left[\frac{2}{N} \cdot \sum_{n=1}^N (w^T x_n - y_n) \cdot w^T \epsilon + \frac{1}{N} \sum_{n=1}^N (w^T \epsilon)^2 \right]$$

$$\left(\mathbb{E}(\epsilon) = \mu = 0, \mathbb{E}(\epsilon^2) = \text{Var}(\epsilon) + [\mathbb{E}(\epsilon)]^2 = \sigma^2 \right)$$

$$\Rightarrow \min \frac{1}{N} \sum_{n=1}^N (w^T x_n - y_n)^2 + 0 + \sigma^2 \cdot \|w\|^2$$

$$\Rightarrow \frac{\lambda}{N} = \sigma^2 \Rightarrow \lambda = N\sigma^2 \quad \#$$

5. To find $\min_{y \in \mathbb{R}} \frac{1}{N} \sum_{n=1}^N (y - y_n)^2 + \frac{\alpha k}{N} \Omega(y) \Rightarrow \nabla_y \left(\frac{1}{N} \sum_{n=1}^N (y - y_n)^2 + \frac{\alpha k}{N} \Omega(y) \right) = 0$

$\Rightarrow \frac{1}{N} \left(\sum_{n=1}^N 2y - 2y_n \right) + \frac{\alpha k}{N} \Omega'(y) = 0$. Let $\Omega(y) = (y + a)^2$

$\Rightarrow 2y - \frac{2}{N} \sum_{n=1}^N y_n + \frac{\alpha k}{N} \cdot 2(y + a) = 0$

$\Rightarrow \left(1 + \frac{\alpha k}{N} \right) \cdot y - \frac{1}{N} \sum_{n=1}^N y_n + \frac{\alpha k \cdot a}{N} = 0$

$\Rightarrow \left(\frac{N + \alpha k}{N} \right) \cdot \left(\frac{\sum_{n=1}^N y_n + a}{N + \alpha k} \right) - \frac{1}{N} \sum_{n=1}^N y_n + \frac{\alpha k \cdot a}{N} = 0$

$\Rightarrow \frac{1}{N} \sum_{n=1}^N y_n + \frac{a}{N} - \frac{1}{N} \sum_{n=1}^N y_n + \frac{\alpha k \cdot a}{N} = 0$

$\Rightarrow \frac{a}{N} = -\frac{\alpha k a}{N} \Rightarrow a = -\frac{1}{k} \Rightarrow \Omega(y) = \left(y - \frac{1}{k} \right)^2$ #

6. $\nabla_w \tilde{E}_{aug}(w) = \nabla E_{in}(w^*) + \frac{1}{2} H \cdot 2(w - w^*) + \frac{2\lambda}{N} w$

To minimize $\Rightarrow \nabla_w \tilde{E}_{aug}(w) = 0$

$\Rightarrow \frac{1}{2} H \cdot 2(w - w^*) + \frac{2\lambda}{N} w = 0$

$\Rightarrow \left(H + \frac{2\lambda}{N} I \right) w = H w^* \Rightarrow w = \left(H + \frac{2\lambda}{N} I \right)^{-1} H w^*$ #

7. If we choose positive one as validation, the label of validation set is positive, the Aminority is positive, the error = $\frac{1}{N} \sum_{i=1}^N 0 = 0$

If we choose negative one as validation, the label of validation set is negative, the Aminority is negative, the error = $\frac{1}{N} \sum_{i=1}^N 0 = 0$

The $E_{locv}(A_{minority}) = \frac{N}{2N} \times 0 + \frac{N}{2N} \times 0 = 0$ #

HTML HW 4

8. $(x_1, y_1) = (2, 0)$ as validation. $(x_2, y_2) = (p, 2)$, $(x_3, y_3) = (-2, 0)$ as training

To minimize $\frac{1}{2}[(w_0 - y_2)^2 + (w_0 - y_3)^2] \Rightarrow (w_0 - y_2) + (w_0 - y_3) = 0 \Rightarrow w_0 = \frac{1}{2}(y_2 + y_3)$

$$E_{\text{loocv}}(\text{constant}) = \frac{1}{3} \left[\underbrace{\left(\frac{1}{2}(2+0) - 0 \right)^2}_{(x_1, y_1) \text{ as val}} + \underbrace{\left(\frac{1}{2}(0+0) - 2 \right)^2}_{(x_2, y_2) \text{ as val}} + \underbrace{\left(\frac{1}{2}(0+2) - 0 \right)^2}_{(x_3, y_3) \text{ as val}} \right]$$

$$= \frac{1}{3}(1 + 4 + 1) = 2$$

For linear, $\begin{cases} y_2 = w_0 + w_1 x_2 \\ y_3 = w_0 + w_1 x_3 \end{cases} \Rightarrow w_1 = \frac{y_3 - y_2}{x_3 - x_2}, w_0 = \frac{y_2 x_3 - y_3 x_2}{x_3 - x_2}$

$$E_{\text{loocv}}(\text{linear}) = \frac{1}{3} \left[\underbrace{\left[\frac{-2}{-2-p} \cdot 2 + \frac{-4-0}{-2-p} - 0 \right]^2}_{(x_1, y_1) \text{ as val}} + \underbrace{\left[\frac{0-0}{-2-2} \cdot p + \frac{0-0}{-2-2} - 2 \right]^2}_{(x_2, y_2) \text{ as val}} + \underbrace{\left[\frac{2-0}{p-2} \cdot (-2) + \frac{0-4}{p-2} - 0 \right]^2}_{(x_3, y_3) \text{ as val}} \right]$$

$$= \frac{1}{3} \left[\left(\frac{-8}{-2-p} \right)^2 + 4 + \left(\frac{-8}{p-2} \right)^2 \right] = \frac{1}{3} \left[\left(\frac{64}{(p+2)^2} + 4 + \frac{64}{(p-2)^2} \right) \right]$$

$$= \frac{1}{3} \left[\frac{64[(p-2)^2 + (p+2)^2]}{(p+2)^2 \cdot (p-2)^2} + 4 \right]$$

$$E_{\text{loocv}}(\text{constant}) = E_{\text{loocv}}(\text{linear}) : 2 = \frac{1}{3} \left[\frac{64(2p^2 + 8)}{(p+2)^2 \cdot (p-2)^2} + 4 \right] \Rightarrow 2 = \frac{64 \cdot 2 \cdot (p^2 + 4)}{(p+2)^2 \cdot (p-2)^2}$$

$$\Rightarrow (p+2)^2 \cdot (p-2)^2 = 64(p^2 + 4)$$

For (a): left = 2960, right = 1463.0625

(b): left = 3856, right = 2730.0625

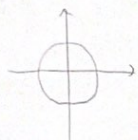
(c): left = 4880, right = 4658.0625

(d): left = 6032, right = 7439.0625

(e): left = 7412, right = 11289.0625, choose C

$$\begin{aligned}
 9. \mathbb{E} \left(\frac{1}{K} \sum_{n=N-K+1}^N (y_n - \bar{y})^2 \right) &= \mathbb{E} \left(\frac{1}{K} \sum_{n=N-K+1}^N (y_n^2 - 2y_n \bar{y} + \bar{y}^2) \right) \\
 &= \mathbb{E} \left(\frac{1}{K} \sum_{n=N-K+1}^N y_n^2 \right) - 2 \mathbb{E} \left(\frac{1}{K} \sum_{n=N-K+1}^N y_n \bar{y} \right) + \mathbb{E} \left(\frac{1}{K} \cdot K \cdot \bar{y}^2 \right) \\
 &= \sigma^2 - 2 \cdot \left[\mathbb{E}(\bar{y}) \cdot \mathbb{E} \left(\frac{1}{K} \sum_{n=N-K+1}^N y_n \right) \right] + \mathbb{E}(\bar{y}^2) \\
 \mathbb{E}(\bar{y}^2) &= \text{Var}(\bar{y}) + (\mathbb{E}(\bar{y}))^2 \stackrel{||}{=} \text{Var}(\bar{y}) \\
 \text{Var}(\bar{y}) &= \text{Var} \left(\frac{1}{N-K} \sum_{n=1}^{N-K} y_n \right) = \left(\frac{1}{N-K} \right)^2 \sum_{n=1}^{N-K} \text{Var}(y_n) = \left(\frac{1}{N-K} \right) \sigma^2 \\
 &= \sigma^2 - 0 + \left(\frac{1}{N-K} \right) \sigma^2 \quad \#
 \end{aligned}$$

10. This problem can be viewed as find "How many kinds of lines for four points?" in handout-04 page 9.



There are 2 situations that cannot be linear separable.

$$\left(\begin{array}{c} \text{X} \quad \text{O} \\ \text{O} \quad \text{X} \end{array}, \begin{array}{c} \text{O} \quad \text{X} \\ \text{X} \quad \text{O} \end{array} \right) \Rightarrow E_{in} = \frac{1}{4} \text{ for each situation.}$$

$$\text{So, the expectation is } \frac{1}{16} \times \frac{1}{4} \times 2 = \frac{1}{32} \quad \#$$

$$\begin{aligned}
 11. E_{out}(g) &= P(y=+1) \cdot P(g(x)=-1 | y=+1) + P(y=-1) \cdot P(g(x)=+1 | y=-1) \\
 &= p \cdot \epsilon_+ + (1-p) \cdot \epsilon_-
 \end{aligned}$$

g be as good as the constant classifier g_- in terms of E_{out}

$$\Rightarrow E_{out}(g) = p \cdot \epsilon_+ + (1-p) \cdot \epsilon_- = E_{out}(g_-) = p$$

$$\Rightarrow p(\epsilon_+ - \epsilon_-) + \epsilon_- = p$$

$$\Rightarrow \epsilon_- = p(1 - \epsilon_+ + \epsilon_-)$$

$$\Rightarrow p = \frac{\epsilon_-}{1 - \epsilon_+ + \epsilon_-} \quad \#$$


```
#data pre-processing for Q12-Q16

from liblinear.liblinearutil import *
f = open('hw4_train.dat.txt', 'r')
train_data = f.read().splitlines()
f.close()
f = open('hw4_test.dat.txt', 'r')
test_data = f.read().splitlines()
f.close()

train_x = []
train_y = []
for line in train_data:
    line = line.split(' ')
    x = []
    for i in range(6):
        x.append(float(line[i]))
    train_x.append(x)
    train_y.append(float(line[6]))

test_x = []
test_y = []
for line in test_data:
    line = line.split(' ')
    x = []
    for i in range(6):
        x.append(float(line[i]))
    test_x.append(x)
    test_y.append(float(line[6]))

import numpy as np
from sklearn.preprocessing import PolynomialFeatures
poly = PolynomialFeatures(3)
train_x_trans = poly.fit_transform(np.array(train_x))
test_x_trans = poly.fit_transform(np.array(test_x))
lamb = [10**(-4), 10**(-2), 10**(0), 10**(2), 10**(4)]
C = [1/(2*l) for l in lamb]
```

```

#Q12
for c in C:
    m = train(train_y, train_x_trans, (f'-s 0 -c {str(c)} -e 0.000001'))
    p_label, p_acc, p_val = predict(test_y, test_x_trans, m)

#Q13
for c in C:
    m = train(train_y, train_x_trans, (f'-s 0 -c {str(c)} -e 0.000001'))
    p_label, p_acc, p_val = predict(train_y, train_x_trans, m)

#Q14
for c in C:
    m = train(train_y[:120], train_x_trans[:120], (f'-s 0 -c {str(c)} -e 0.000001'))
    p_label, p_acc, p_val = predict(train_y[120:], train_x_trans[120:], m)

m = train(train_y[:120], train_x_trans[:120], (f'-s 0 -c {C[3]} -e 0.000001'))
p_label, p_acc, p_val = predict(test_y, test_x_trans, m)

#Q15
m = train(train_y, train_x_trans, (f'-s 0 -c {C[3]} -e 0.000001'))
p_label, p_acc, p_val = predict(test_y, test_x_trans, m)

#Q16
train_x_cv = [train_x_trans[:40], train_x_trans[40:80], train_x_trans[80:120], train_x_trans[120:160],
train_x_trans[160:]]
train_y_cv = [train_y[:40], train_y[40:80], train_y[80:120], train_y[120:160], train_y[160:]]
for c in C:
    E = 0
    for i in range(5):
        train_y_tmp = []
        train_x_tmp = []
        val_y_tmp = train_y_cv[i]
        val_x_tmp = train_x_cv[i]
        for j in range(5):
            if j!=i:
                train_y_tmp.extend(train_y_cv[j])
                train_x_tmp.extend(train_x_cv[j])

        m = train(train_y_tmp, train_x_tmp, (f'-s 0 -c {c} -e 0.000001'))
        p_label, p_acc, p_val = predict(val_y_tmp, val_x_tmp, m)
        E += (1-p_acc[0])/100)
    print(C.index(c), E/5)

```