

## GPT Structure

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- 2 Math format
- 3 Prediction
  - Random prediction
- 4 Fine-tuning
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## Training datasets

OpenAI has made significant contributions to the field of AI research and development, especially in the area of language models. Its flagship product, GPT, has revolutionized the way people use AI technology and has paved the way for future development in AI.

Setting Training sequence  $T = 3$ , then training datasets are as follows:

Table: Training datasets.

Meaning	Input	Goal output
tokens code	OpenAI has made 1 2 3	has made significant 2 3 4
tokens code	language models. 12 13 14	models. Its 13 14 15
tokens code	, has revolutionized 16 2 17	revolutionized the 2 17 18
	...	...

Table: The code is the number of the token in the directory.



## Optimization goals

Optimization goals in GPT<sup>1</sup>:

Let dataset be  $\mathcal{X}$ , then

$$\prod_i^N P(x_i | x_{i-T:i-1})$$

Optimization goals in reality:

Let dataset be  $\mathcal{X} = \{X_1, \dots, X_N\}$ , where  $X_i = \{x_1^{(i)}, \dots, x_T^{(i)}\}$ , then

$$\prod_{i=1}^N P(X_i | x_1^{(i)}),$$

where

$$\begin{aligned} P(X_i | x_1^{(i)}) &= \prod_{j=1}^T P(x_j^{(i)} | x_{1:j-1}^{(i)}) \\ &= P(x_T^{(i)} | x_{1:T-1}^{(i)}) P(x_{T-1}^{(i)} | x_{1:T-2}^{(i)}) \cdots P(x_2^{(i)} | x_1^{(i)}) \end{aligned}$$

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<sup>1</sup>Language Models are Unsupervised Multitask Learners. OpenAI blog. 2019.



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## Math format

Let  $X \in \{0, 1\}^{T \times d}$  for input, where  $d$  is the dimension of tokens and  $T$  is the length of inputs. Then the **embedding layer** is defined as:

$$\text{Enc}(X) = XE_1, \quad (1)$$

where  $E \in \mathbb{R}^{d \times D}$ .

The Enc module plus **positional encoding** reconstruct a new Enc module:

$$\text{Enc}(X) = XE_1 + PE_2, \quad (2)$$

where  $P \in \{0, 1\}^{T \times T}$ ,  $P_{i,i} = 1$ ,  $P_{i \neq j} = 0$  and  $E_2 \in \mathbb{R}^{T \times D}$

**Remark:**  $\text{Enc}(X) : \{0, 1\}^{T \times d} \rightarrow \mathbb{R}^{T \times D}$ .

Let  $X \in \mathbb{R}^{T \times D}$  for the middle input, where  $D$  is the dimension of middle layer.

The **norm layer** is defined as:

$$\text{Norm}(X) := \frac{X - \mathbb{E}X}{\text{Var}(X)}, \quad (3)$$

where  $\mathbb{E}(X), \text{Var}(X) \in \mathbb{R}^{T \times D}$ .

**Norm:**  $\text{ATT} : \mathbb{R}^{T \times D} \rightarrow \mathbb{R}^{T \times D}$ .



## Math format

Let  $H$  be the head number of multi-head attention, for the  $h$ -th head  $W_{K,h} \in \mathbb{R}^{D \times D_K}$ ,  $W_{Q,h} \in \mathbb{R}^{D \times D_K}$ ,  $W_{V,h} \in \mathbb{R}^{D \times D_V}$  and  $W_O \in \mathbb{R}^{HD_V \times D}$ . Then the **multi-head attention** is defined as:

- Single head attention:

$$S_h = \text{Softmax}\left(\frac{XW_{Q,h}(XW_{K,h})^T}{\sqrt{D_K}}\right)XW_{V,h}, \quad (4)$$

- Masked single head attention:

$$S_h = \text{Softmax}\left(\frac{\text{Mask}(XW_{Q,h}(XW_{K,h})^T)}{\sqrt{D_K}}\right)XW_{V,h}, \quad (5)$$

where  $\text{Mask}(X)$  is an assignment operator, defined as  $X_{i>j} = -\infty$ .

**Remark:**  $S_h : \mathbb{R}^{T \times D} \rightarrow \mathbb{R}^{T \times D_V}$ .

- Concatenate & Residual

$$\text{ATT}(X) := X + [S_1, \dots, S_h, \dots, S_H]W_O, \quad (6)$$

where  $\text{Softmax}(X)$  is row-wise.

**Remark:**  $\text{ATT} : \mathbb{R}^{T \times D} \rightarrow \mathbb{R}^{T \times D}$ .



# Math format

The **MLP** layer is defined as:

$$\text{MLP}(X) := X + f_L(X) \circ \sigma \circ \dots \circ \sigma \circ f_1(X), \quad (7)$$

where  $f_i(X) := XW_i + b_i$ ,  $b_i \in \mathbb{R}^{D_i}$ ,  $W_1 \in \mathbb{R}^{D \times D_1}$ ,  $W_i \in \mathbb{R}^{D_{i-1} \times D_i}$  and  $W_L \in \mathbb{R}^{D_{L-1} \times D}$ .

**Remark:**  $\text{ATT} : \mathbb{R}^{T \times D} \rightarrow \mathbb{R}^{T \times D}$ .

For each element  $x$ , the **active function**  $\sigma$  is defined as:

$$\begin{aligned} \text{GeLU}(x) &:= xP(X \leq x) \\ &= x \int_{-\infty}^x \frac{\exp(\frac{-(t-\mu)^2}{2\sigma^2})}{\sqrt{2\pi}\sigma} dt \\ &\simeq 0.5x(1 + \tanh(\sqrt{\frac{2}{\pi}}(x + 0.044715x^3))). \end{aligned} \quad (8)$$





# Math format

The **block** in GPT is defined as:

$$\text{Block}(X) := \text{MLP} \circ \text{Norm} \circ \text{ATT} \circ \text{Norm}(X) \quad (9)$$

The **embedding** is defined as:

$$X^e := \text{Norm} \circ \text{Block}_M \cdots \text{Block}_1 \circ \text{Enc}(X). \quad (10)$$

The **GPT** architecture is defined as:

$$\text{GPT}(X) := \arg \max_{\text{index}} X^l = X^e W_{\text{head}}, \quad (11)$$

where  $W_{\text{head}} \in \mathbb{R}^{D \times d}$ .

**Remark:**  $\text{ATT} : \{0, 1\}^{T \times d} \rightarrow \mathbb{R}^{T \times d}$ .



# GPT parameters

Table: Parameter setting.

Parameter	GPT-2(125M)	GPT-3/3.5(175B)	GPT-4(1800B)
d (vocab_size)	50304	*	*
T (block_size)	1024	2048	8000(p.t.)->32000(f.t.)
D (n_embd)	768	12288	*
$D_V$ (n_embd)	$768/12=64$	$12288/96=128$	*
$D_K$ (n_embd)	$768/12=64$	$12288/96=128$	*
H (n_head)	12	96	*
L (MLP layer)	2	2	*
$W_1$ (first layer)	$\mathbb{R}^{4D \times D}$	$\mathbb{R}^{4D \times D}$	*
$W_2$ (second layer)	$\mathbb{R}^{D \times 4D}$	$\mathbb{R}^{D \times 4D}$	*
M (n_layer)	12	96	120
N(data_number)	40G	570G	*



# Loss functions

Then the loss function is:

$$-\sum_{i=1}^T \sum_{j=1}^d P_{ij} \log \text{Softmax}(X^l)_{ij} \quad (12)$$

, where  $P_i$  is the probability of the next token. or

$$-\sum_{i=1}^T \log \text{Softmax}(X^l)_{ij_{\text{true}}} \quad (13)$$

, where  $j_{\text{true}}$  is the next token in the directory.

How to train GPT?

Training with or without  $</s>$  ? The influence is small.



## Why decoder can reflect the optimization goals

GPT can predict the next token based on former tokens.

- ▶ MLP:  $XW = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} W = \begin{pmatrix} X_1 W \\ X_2 W \end{pmatrix}$ .
- ▶ ATT1:  $XW_Q(XW_K)^T = \begin{pmatrix} X_1 W_Q \\ X_2 W_Q \end{pmatrix} ((X_1 W_K)^T \ (X_2 W_K)^T) =$   
 $\begin{pmatrix} X_1 W_Q(X_1 W_K)^T & X_1 W_Q(X_2 W_K)^T \\ X_2 W_Q(X_1 W_K)^T & X_2 W_Q(X_2 W_K)^T \end{pmatrix} := \begin{pmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{pmatrix}$ .
- ▶ ATT2:  $\text{Mask}\left(\begin{pmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{pmatrix}\right) = \begin{pmatrix} \text{Mask}(s_{11}) & -\infty \\ s_{21} & \text{Mask}(s_{22}) \end{pmatrix}$ .
- ▶ ATT3:  
 $\text{Softmax}(\text{Mask}\left(\begin{pmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{pmatrix}\right)) = \begin{pmatrix} \text{SM}(s_{11}) & 0 \\ s_{21} & \text{SM}(s_{22}) \end{pmatrix} := \begin{pmatrix} p_{11} & 0 \\ p_{21} & p_{22} \end{pmatrix}$ .
- ▶ ATT4:  $\begin{pmatrix} p_{11} & 0 \\ p_{21} & p_{22} \end{pmatrix} \begin{pmatrix} X_1 W \\ X_2 W \end{pmatrix} = \begin{pmatrix} p_{11} X_1 W \\ p_{21} X_1 W + p_{22} X_2 W \end{pmatrix}$ .
- ▶ Norm: Normalized for a token not among tokens.



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## Prediction process

Set  $T = 5$ .

Input: OpenAI has made

Output: has made **significant**

Combine the last word of Output to Input, obtain the next Input.

Input: OpenAI has made significant

Output: has made significant contributions

Input: OpenAI has made significant contributions

Output: has made significant contributions to

Input: OpenAI has made significant contributions to

The sequence context is growing too long, which longer than the inputs length (5) in training, we must crop it at  $T$ .

Cropped input: has made significant contributions to

Output: made significant contributions to the

Cropped input: made significant contributions to the

Output: significant contributions to the field

...

Complete the sequence  $T(\text{max\_new\_tokens})$  times.



## Random prediction

Set Top\_K = 3, temperature.

Input: OpenAI

Output:  $X^I = \{0.001, 10, 6, 1, 4, \dots\}$

1 (0.001) 2 (10) 3(6) 4(1) 5 (4)

Select Top\_K: 2(10), 3(6), 5(4)

Div temperature and calculate new probability based on the Top\_K tokens:

2(10/temperature), 3(6/temperature), 5(4/temperature)

- ▶ If temperature = 1, calculate new probability with Softmax:  
2(0.97962921), 3(0.01794253), 5(0.00242826).
- ▶ If temperature = 10, calculate new probability with Softmax:  
2(0.45062671), 3(0.30206411), 5(0.24730918).

Select new code with their own new probability.

- ▶ If temperature = 1, select 3 with probability 0.01794253.
- ▶ If temperature = 10, select 3 with probability 0.30206411.

According to the directory get Random Output:

OpenAI (1) has (2) made(3) significant(4) contributions (5).



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## RLHF

RLHF<sup>2</sup>

## Step 1

**Collect demonstration data,  
and train a supervised policy.**

A prompt is  
sampled from our  
prompt dataset.



A labeler  
demonstrates the  
desired output  
behavior.



This data is used  
to fine-tune GPT-3  
with supervised  
learning.



## Step 2

**Collect comparison data,  
and train a reward model.**

A prompt and  
several model  
outputs are  
sampled.



A labeler ranks  
the outputs from  
best to worst.



This data is used  
to train our  
reward model.



## Step 3

**Optimize a policy against  
the reward model using  
reinforcement learning.**

A new prompt  
is sampled from  
the dataset.



The policy  
generates an output.



Once upon a time...

The reward model  
calculates a  
reward for  
the output.



The reward is  
used to update  
the policy  
using PPO.



Figure 2: A diagram illustrating the three steps of our method: (1) supervised fine-tuning (SFT), (2) reward model (RM) training, and (3) reinforcement learning via proximal policy optimization (PPO) on this reward model. Blue arrows indicate that this data is used to train one of our models. In Step 2, boxes A-D are samples from our models that get ranked by labelers. See Section 3 for more details on our method.

<sup>2</sup>Training language models to follow instructions with human feedback. NeurIPS. 2022.

## RLHF

Why fine-tune on LLM in Step1 ?

How to calculate the gradient based on the generated sequence ?

Let  $\mathcal{G} : \{</s>, X\} \rightarrow \{Y, </e>\} := \{</s>, x_1, \dots, x_T\} \rightarrow \{x_{T+1}, \dots, </e>\}$ . (Without gradient)

Let  $\mathcal{F} : \{</s>, x_1, \dots, x_t\} \rightarrow \{x_1, \dots, x_{t+1}\}$ . (With gradient)

**Loss function in Step 2:** train RM.

$$\text{loss}(\theta) = -\frac{1}{C_K^2} \mathbb{E}_{(X, Y_w, Y_l) \sim D} [\log(\sigma(r_\theta(X, Y_w) - r_\theta(X, Y_l)))]. \quad (14)$$

**Loss function in Step 3:** RLHF(reinforcement learning with human feedback).

$$\begin{aligned} \text{objective}(\phi) = & \mathbb{E}_{(X, Y) \sim D_{\pi_\phi^{\text{RL}}}} [r_\theta(X, Y) - \beta \log(\pi_\phi^{\text{RL}}(Y|X)/\pi^{\text{SFT}}(Y|X))] + \\ & \gamma \mathbb{E}_{X \sim D_{\text{pretrain}}} [\log(\pi_\phi^{\text{RL}}(X))]. \end{aligned} \quad (15)$$



## RLHF

- ▶  $\pi_{\phi}^{\text{RL}}(Y|X)$ :
  - ▶  $\mathcal{G} : X \rightarrow Y$ .
  - ▶  $\mathcal{F} : [< /s>, X, Y] \rightarrow [X, Y, < /e>]$ .
  - ▶ Obtain the probability of  $Y$ .
- ▶  $\pi_{\phi}^{\text{RL}}(X)$ :
  - ▶  $\mathcal{F} : [< /s>, X] \rightarrow [X, < /e>]$ .

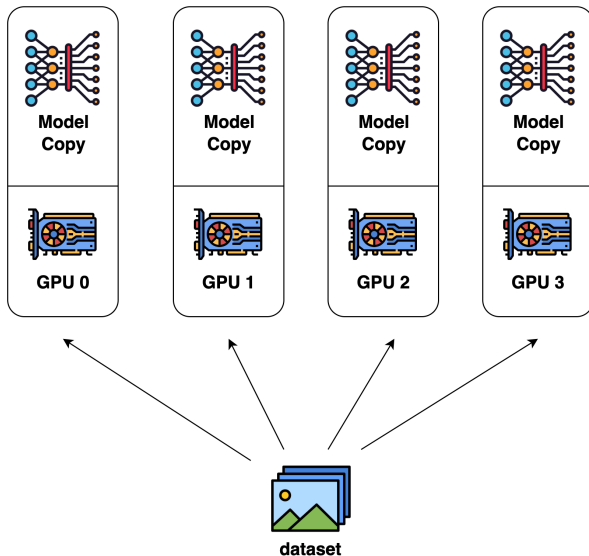


# Contents

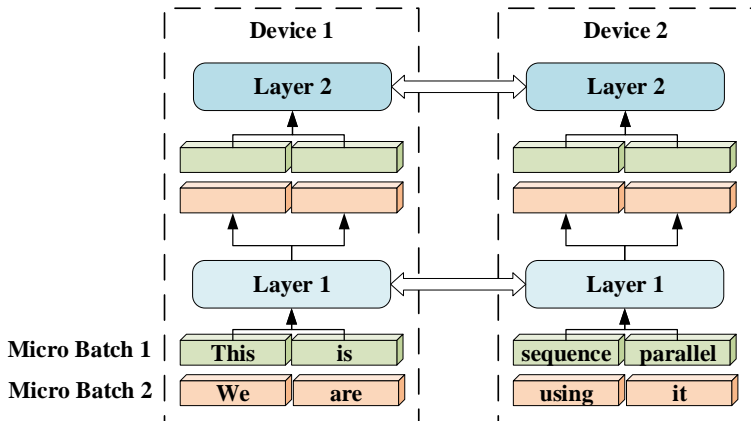
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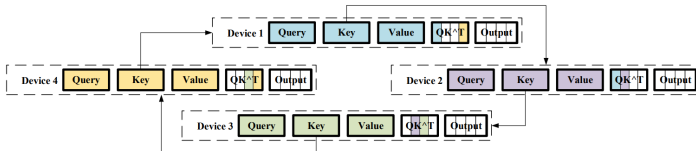
# Data Parallel



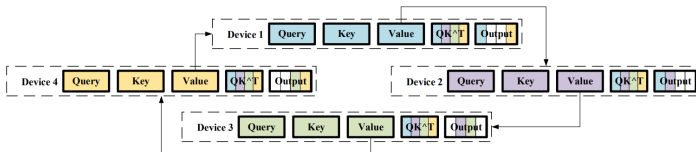
# Sequence Parallel



# Sequence Parallel

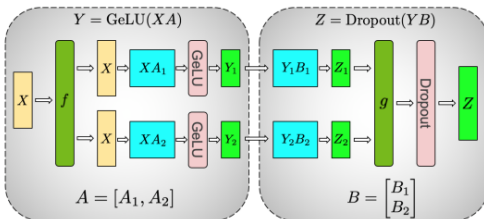


(a) Transmitting key embeddings among devices to calculate attention scores

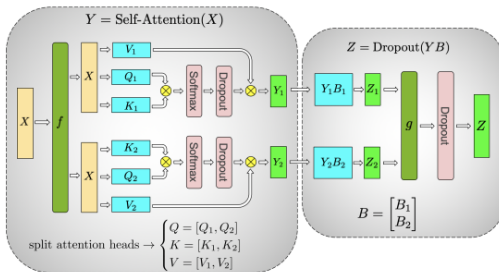


(b) Transmitting value embeddings among devices to calculate the output of attention layers

# Tensor Parallel



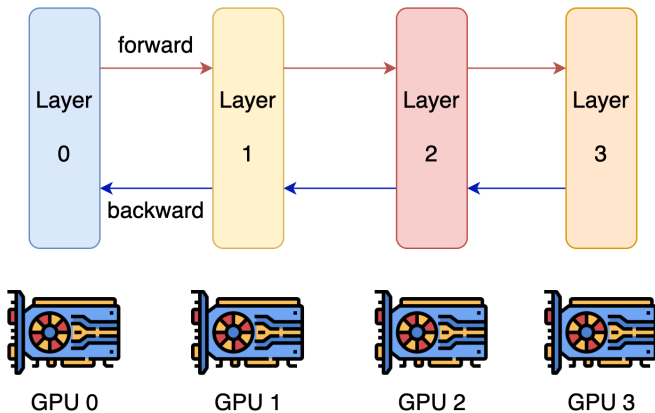
(a) MLP



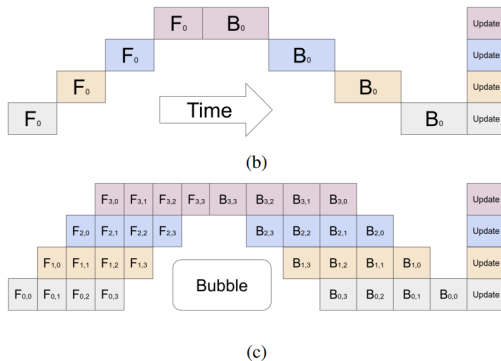
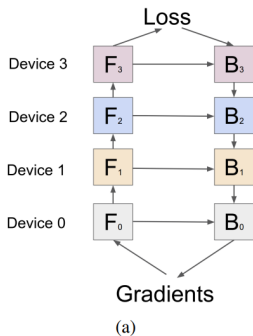
(b) Self-Attention



# Model Parallel



## Pipeline Parallel



# GPT-4 Training

## GPT-4<sup>3</sup>

- ▶ 8-way tensor parallelism.
- ▶ 15-way pipeline parallelism.
- ▶ 25,000 A100 GPU for 90 to 100 days at about 32% to 36% MFU.
- ▶ Vision: the architecture is similar to Flamingo.
- ▶ ...

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<sup>3</sup>Gpt-4 technical report. 2023.



**THANKS!**

